

Lecture Notes: Compiled by Maqsood Ahmad (A.P. Maths.) for students of CUI, Lahore. (FA20-BSM-A, SP20-BSE-A & B).

Change of basis and Transition Matrix:

Exercise 4.8:- Question 1-27; Question 1-15(very simple) ; **Question 15 to 19 (similar)**

Question 20 to 23 (similar); Question 24, 25, 26, 27 (similar).

■ **Coordinates**

If V is an n -dimensional vector space, we know that V has a basis S with n vectors in it; thus far we have not paid much attention to the order of the vectors in S . However, in the discussion of this section we speak of an **ordered basis** $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ for V ; thus $S_1 = \{\mathbf{v}_2, \mathbf{v}_1, \dots, \mathbf{v}_n\}$ is a different ordered basis for V .

If $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is an ordered basis for the n -dimensional vector space V , then by Theorem 4.8 every vector \mathbf{v} in V can be uniquely expressed in the form

$$\mathbf{v} = a_1 \mathbf{v}_1 + a_2 \mathbf{v}_2 + \dots + a_n \mathbf{v}_n,$$

where a_1, a_2, \dots, a_n are real numbers. We shall refer to

$$[\mathbf{v}]_S = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}$$

as the **coordinate vector of \mathbf{v} with respect to the ordered basis S** . The entries of $[\mathbf{v}]_S$ are called the **coordinates of \mathbf{v} with respect to S** .

Example 1: Given $S = \left\{ \mathbf{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \mathbf{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \mathbf{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ is set of standard basis for R^3 . **Find**
coordinates of $\mathbf{v} = \begin{bmatrix} 9 \\ 2 \\ 7 \end{bmatrix}$ with respect to S . OR $[\mathbf{v}]_S = ?$

Solution:- $\mathbf{v} = a_1 \mathbf{e}_1 + a_2 \mathbf{e}_2 + a_3 \mathbf{e}_3$

$$\begin{bmatrix} 9 \\ 2 \\ 7 \end{bmatrix} = a_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + a_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + a_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} a_1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ a_2 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ a_3 \end{bmatrix} = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$$

Coordinates of v w.r.t. $S=[v]_S = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 9 \\ 2 \\ 7 \end{bmatrix}$

Next example shows the cost we have to bear in absence of standard basis

Examlle 2(LC) : Given $T = \left\{ v_1 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, v_2 = \begin{bmatrix} 6 \\ 4 \\ 2 \end{bmatrix}, v_3 = \begin{bmatrix} 4 \\ -1 \\ 8 \end{bmatrix} \right\}$ be ordered basis.

Find coordinates of $v = \begin{bmatrix} 9 \\ 2 \\ 7 \end{bmatrix}$ with respect to T . OR $[v]_T = ?$

Solution: Consider $v = a_1 v_1 + a_2 v_2 + a_3 v_3 \dots \dots \dots (1)$, Our goal is to find scalars a_1, a_2 and a_3 .

$$(1) \Rightarrow \begin{bmatrix} 9 \\ 2 \\ 7 \end{bmatrix} = a_1 \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} + a_2 \begin{bmatrix} 6 \\ 4 \\ 2 \end{bmatrix} + a_3 \begin{bmatrix} 4 \\ -1 \\ 8 \end{bmatrix}$$

$$\begin{bmatrix} 9 \\ 2 \\ 7 \end{bmatrix} = \begin{bmatrix} a_1 \\ 2a_1 \\ -a_1 \end{bmatrix} + \begin{bmatrix} 6a_2 \\ 4a_2 \\ 2a_2 \end{bmatrix} + \begin{bmatrix} 4a_3 \\ -a_3 \\ 8a_3 \end{bmatrix} \Rightarrow \begin{bmatrix} 9 \\ 2 \\ 7 \end{bmatrix} = \begin{bmatrix} a_1 + 6a_2 + 4a_3 \\ 2a_1 + 4a_2 - a_3 \\ -a_1 + 2a_2 + 8a_3 \end{bmatrix}$$

Equating both sides we get,

$$a_1 + 6a_2 + 4a_3 = 9 \quad ; \quad 2a_1 + 4a_2 - a_3 = 2 \quad ; \quad -a_1 + 2a_2 + 8a_3 = 7$$

Observe: The problem of **linear combination** boils down to a problem of **non-homogeneous** system of linear equations. I believe you can find scalars using Gauss-Elimination method. Here we go.

$$[A|b] = \left[\begin{array}{ccc|c} 1 & 6 & 4 & 9 \\ 2 & 4 & -1 & 2 \\ -1 & 2 & 8 & 7 \end{array} \right] \begin{array}{l} R_2 - 2R_1 \\ R_3 + R_1 \end{array} \sim \left[\begin{array}{ccc|c} 1 & 6 & 4 & 9 \\ 0 & -8 & -9 & -16 \\ 0 & 8 & 12 & 16 \end{array} \right]$$

$$R_3 + R_2 \sim \left[\begin{array}{ccc|c} 1 & 6 & 4 & 9 \\ 0 & -8 & -9 & -16 \\ 0 & 0 & 3 & 0 \end{array} \right] \begin{array}{l} \frac{R_2}{-8} \\ \frac{R_3}{3} \end{array} \sim \left[\begin{array}{ccc|c} 1 & 6 & 4 & 9 \\ 0 & 1 & 9/8 & 2 \\ 0 & 0 & 1 & 0 \end{array} \right]$$

Now rewrite this equivalent simple system,

$$a_3 = 0; \quad a_2 + \frac{9}{8}a_3 = 2; \quad a_1 + 6a_2 + 4a_3 = 9$$

Using backward substitution, we get $a_3 = 0$; $a_2 = 2$; $a_1 = -3$

$$\text{Hence } v = \begin{bmatrix} 9 \\ 2 \\ 7 \end{bmatrix} = -3 \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} + 2 \begin{bmatrix} 6 \\ 4 \\ 2 \end{bmatrix} + 0 \begin{bmatrix} 4 \\ -1 \\ 8 \end{bmatrix}.$$

$$[v]_T = \begin{bmatrix} 9 \\ 2 \\ 7 \end{bmatrix}_T = \begin{bmatrix} -3 \\ 2 \\ 0 \end{bmatrix}$$

Example 3: (a) $S = \{e_1 = t, e_2 = 1\}$ standard basis for vector space $P_1(t)$.

Find coordinates of $v = 5t - 2$. OR $[v]_S = ?$

Solution:

$$v = 5(t) - 2(1) = a_1 e_1 + a_2 e_2$$

Coordinates of v w.r.t. $S = [v]_S = \begin{bmatrix} 5 \\ -2 \end{bmatrix}$

(b) $T = \{v_1 = t + 1, v_2 = t - 1\}$ ordered basis for vector space $P_1(t)$.

$v = 5t - 2$; Find coordinates of v , OR $[v]_T = ?$

$$v = a_1 v_1 + a_2 v_2 \dots \dots (1)$$

$$5t - 2 = a_1(t + 1) + a_2(t - 1)$$

$$5t - 2 = (a_1 + a_2)t + (a_1 - a_2)$$

Equating coefficients of like powers

$$a_1 + a_2 = 5 \quad ; \quad a_1 - a_2 = -2$$

Coordinates of v w.r.t. $T = [v]_T = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 3/2 \\ 7/2 \end{bmatrix}$

■ Transition Matrices

We now look at the relationship between two coordinate vectors for the same vector v with respect to different bases. Thus, let $S = \{v_1, v_2, \dots, v_n\}$ and $T = \{w_1, w_2, \dots, w_n\}$ be two ordered bases for the n -dimensional vector space V . If v is any vector in V , then

$$S = \{v_1, v_2, v_3\} ; T = \{w_1, w_2, w_3\}$$

$$v = c_1 w_1 + c_2 w_2 + c_3 w_3 \dots \dots (1); [v]_T = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$$

Write (1) w.r.t. S basis; $[v]_S = [c_1 w_1 + c_2 w_2 + c_3 w_3]_S$

$$[v]_S = [c_1 w_1]_S + [c_2 w_2]_S + [c_3 w_3]_S$$

$$[v]_S = c_1 [w_1]_S + c_2 [w_2]_S + c_3 [w_3]_S$$

$$[v]_S = \begin{bmatrix} [w_1]_S & [w_2]_S & [w_3]_S \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = [?] [v]_T$$

$$[v]_S = P_{S \leftarrow T} [v]_T$$

$$\text{i.e. } [?] = P_{S \leftarrow T} = \begin{bmatrix} [w_1]_S & [w_2]_S & [w_3]_S \end{bmatrix}$$

$$\text{Recall, } [v]_S = ? = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \text{ Implies } a_1 v_1 + a_2 v_2 + a_3 v_3 = v \text{ --- } (*)$$

$$[w_1]_S = ? = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \text{ Implies } a_1 v_1 + a_2 v_2 + a_3 v_3 = w_1 \text{ --- (1)}$$

$$[w_2]_S = ? = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} \text{ Implies } b_1 v_1 + b_2 v_2 + b_3 v_3 = w_2 \text{ --- (2)}$$

$$[w_3]_S = ? = \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix} \text{ Implies } d_1 v_1 + d_2 v_2 + d_3 v_3 = w_3 \text{ --- (3)}$$

$$[?] = P_{S \leftarrow T} = \begin{bmatrix} [w_1]_S & [w_2]_S & [w_3]_S \end{bmatrix}$$

$$[?] = P_{S \leftarrow T} = \begin{bmatrix} a_1 & b_1 & d_1 \\ a_2 & b_2 & d_2 \\ a_3 & b_3 & d_3 \end{bmatrix}$$

$$P_{S \leftarrow T} = \begin{bmatrix} v_1 & v_2 & v_3 & | & w_1 & | & w_2 & | & w_3 \end{bmatrix}$$

Formula (1) $[v]_S = P_{S \leftarrow T} [v]_T$ (Transition from T to S basis.)

Formula (2) $[v]_T = Q_{T \leftarrow S} [v]_S$ (Transition from S to T basis.)

$$S = \{v_1, v_2, v_3\}; \quad T = \{w_1, w_2, w_3\}$$

$$v = c_1 v_1 + c_2 v_2 + c_3 v_3 \text{ --- (1); } [v]_S = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$$

Write (1) w.r.t. T basis; $[v]_T = [c_1 v_1 + c_2 v_2 + c_3 v_3]_T$

$$[v]_T = [c_1 v_1]_T + [c_2 v_2]_T + [c_3 v_3]_T$$

$$[v]_T = c_1 [v_1]_T + c_2 [v_2]_T + c_3 [v_3]_T$$

$$[v]_T = [[v_1]_T \quad [v_2]_T \quad [v_3]_T] \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = [?] [v]_S$$

$$[v]_T = Q_{T \leftarrow S} [v]_S$$

$$\text{i.e. } [?] = Q_{T \leftarrow S} = [[v_1]_T \quad [v_2]_T \quad [v_3]_T]$$

$$[v_1]_T = ? = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \text{ Implies } v_1 = a_1 w_1 + a_2 w_2 + a_3 w_3 \quad \text{--- (1)}$$

$$[v_2]_T = ? = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} \text{ Implies } v_2 = b_1 w_1 + b_2 w_2 + b_3 w_3 \quad \text{--- (2)}$$

$$[v_3]_T = ? = \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix} \text{ Implies } v_3 = d_1 w_1 + d_2 w_2 + d_3 w_3 \quad \text{--- (3)}$$

$$Q_{T \leftarrow S} = [w_1 \quad w_2 \quad w_3 \quad | \quad v_1 \quad | \quad v_2 \quad | \quad v_3]$$

Alternate formula of Formula (2):- We know

$$[v]_S = P_{S \leftarrow T} [v]_T$$

$$P^{-1}_{S \leftarrow T} [v]_S = P^{-1}_{S \leftarrow T} P_{S \leftarrow T} [v]_T$$

$$P^{-1}_{S \leftarrow T} [v]_S = [v]_T \quad (\text{Transition from S to T basis.})$$

$$[v]_T = Q_{T \leftarrow S} [v]_S$$

$$Q_{T \leftarrow S} = P^{-1}_{S \leftarrow T}$$

How to find transition matrix , We explain through example

$$\text{Example 1:- } S = \{v_1, v_2, v_3\} \text{ and } T = \{w_1, w_2, w_3\}; v_1 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, v_2 = \begin{bmatrix} 6 \\ 4 \\ 2 \end{bmatrix}, v_3 = \begin{bmatrix} 4 \\ 0 \\ 8 \end{bmatrix}.$$

$$w_1 = \begin{bmatrix} 3 \\ -2 \\ 1 \end{bmatrix}, w_2 = \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix}, w_3 = \begin{bmatrix} -2 \\ 4 \\ 10 \end{bmatrix} \text{ Find transition matrices } P_{S \leftarrow T} \text{ and } Q_{T \leftarrow S}.$$

$$\text{Solution: } [v_1 \quad v_2 \quad v_3 \quad | \quad w_1 \quad | \quad w_2 \quad | \quad w_3] \rightarrow \left[\begin{array}{ccc|ccc} 1 & 6 & 4 & 3 & 3 & -2 \\ 2 & 4 & 0 & -2 & 1 & 4 \\ -1 & 2 & 8 & 1 & 2 & 10 \end{array} \right]$$

$$RREF \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -5 & -3/4 & 12 \\ 0 & 1 & 0 & 2 & 5/8 & -5 \\ 0 & 0 & 1 & -1 & 0 & 4 \end{array} \right]$$

$$\Rightarrow P_{S \leftarrow T} = [[w_1]_S \quad [w_2]_S \quad [w_3]_S] = \begin{bmatrix} -5 & -3/4 & 12 \\ 2 & 5/8 & -5 \\ -1 & 0 & 4 \end{bmatrix}$$

Now to find $Q_{T \leftarrow S}$ we proceed as

$$[v_1 \quad v_2 \quad v_3 \mid w_1 \mid w_2 \mid w_3] \rightarrow \left[\begin{array}{ccc|ccc} 3 & 3 & -2 & 1 & 6 & 4 \\ -2 & 1 & 4 & 2 & 4 & -1 \\ 1 & 2 & 10 & -1 & 2 & 8 \end{array} \right]$$

$$RREF \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -10/11 & -12/11 & 15/11 \\ 0 & 1 & 0 & 12/11 & 32/11 & 4/11 \\ 0 & 0 & 1 & -5/22 & -3/11 & 13/22 \end{array} \right]$$

$$Q_{T \leftarrow S} = [[v_1]_T \quad [v_2]_T \quad [v_3]_T] = \begin{bmatrix} -10/11 & -12/11 & 15/11 \\ 12/11 & 32/11 & 4/11 \\ -5/22 & -3/11 & 13/22 \end{bmatrix}$$

Example2:- Let $Q_{T \leftarrow S} = \begin{bmatrix} -3 = a_1 & 2 = b_1 \\ 2 = a_2 & -1 = b_2 \end{bmatrix} = [[v_1]_T \quad [v_2]_T]$

$T = \{w_1 = t - 1, w_2 = t + 1\}$. Find $S\{v_1, v_2\}$.

Solution: $v_1 = a_1 w_1 + a_2 w_2$ then $[v_1]_T = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$

$$v_1 = -3w_1 + 2w_2 = -3(t - 1) + 2(t + 1) = -t + 5$$

$v_2 = b_1 w_1 + b_2 w_2$ then $[v_2]_T = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$

$$v_2 = 2w_1 - 1w_2 = 2(t - 1) - 1(t + 1) = t - 3$$

16. Let

$$S = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \right\}$$

and

$$T = \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$$

be ordered bases for R^3 . Let

$$\mathbf{v} = \begin{bmatrix} 1 \\ 3 \\ 8 \end{bmatrix} \quad \text{and} \quad \mathbf{w} = \begin{bmatrix} -1 \\ 8 \\ -2 \end{bmatrix}.$$

Follow the directions for (a) through (f) in Exercise 15.

17. Let $S = \{t^2 + 1, t - 2, t + 3\}$ and $T = \{2t^2 + t, t^2 + 3, t\}$ be ordered bases for P_2 . Let $\mathbf{v} = 8t^2 - 4t + 6$ and $\mathbf{w} = 7t^2 - t + 9$. Follow the directions for (a) through (f) in Exercise 15.

- (a) Find the coordinate vectors of \mathbf{v} and \mathbf{w} with respect to the basis T . (d) Find the coordinate vectors of \mathbf{v} and \mathbf{w} with respect to S directly.
- (b) What is the transition matrix $P_{S \leftarrow T}$ from the T - to the S -basis? (e) Find the transition matrix $Q_{T \leftarrow S}$ from the S - to the T -basis.
- (c) Find the coordinate vectors of \mathbf{v} and \mathbf{w} with respect to S , using $P_{S \leftarrow T}$. (f) Find the coordinate vectors of \mathbf{v} and \mathbf{w} with respect to T , using $Q_{T \leftarrow S}$. Compare the answers with those of (a).

Exercise 4.8

Q17 ①

$$S = \{t^2+1, t-2, t+3\}$$

$$T = \{2t^2+t, t^2+3, t\} \text{ ordered basis for } \mathbb{R}_2$$

$\underline{v}_1 = t^2+1, \underline{v}_2 = t-2, \underline{v}_3 = t+3$

$\underline{w}_1 = 2t^2+t, \underline{w}_2 = t^2+3, \underline{w}_3 = t$

★ We know $\mathbb{R}_2(t) = \{a_2 t^2 + a_1 t + a_0 : a_i \in \mathbb{R}\}$
 = All polynomials of degree less or equal to 2.

We know $\mathbb{R}_2(t) \cong \mathbb{R}^3$ using isomorphism

$f: \mathbb{R}_2 \rightarrow \mathbb{R}^3; f(a_2 t^2 + a_1 t + a_0) = \begin{bmatrix} a_2 \\ a_1 \\ a_0 \end{bmatrix}$ Applicable in whole Linear Algebra course

Solution 1 \Rightarrow $\underline{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \underline{v}_2 = \begin{bmatrix} 0 \\ 1 \\ -2 \end{bmatrix}, \underline{v}_3 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$

$\underline{w}_1 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \underline{w}_2 = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}, \underline{w}_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

Now completely proceed like Q16

Q17

$$S = \left\{ \underset{\substack{\uparrow \\ v_1}}{t^2+1}, \underset{\substack{\uparrow \\ v_2}}{t-2}, \underset{\substack{\uparrow \\ v_3}}{t+3} \right\}, T = \left\{ \underset{\substack{\uparrow \\ w_1}}{2t^2+t}, \underset{\substack{\uparrow \\ w_2}}{t^2+3}, \underset{\substack{\uparrow \\ w_3}}{t} \right\}$$

(a) Given $\underline{v} = 8t^2 - 4t + 6$, $\underline{w} = 7t^2 - t + 9$

$[\underline{v}]_T, [\underline{w}]_T = ?$

$$a_1 \underline{w}_1 + a_2 \underline{w}_2 + a_3 \underline{w}_3 = \underline{v}$$

$$a_1(2t^2+t) + a_2(t^2+3) + a_3 t = 8t^2 - 4t + 6$$

$$(2a_1 + a_2)t^2 + (a_1 + a_3)t + 3a_2 = 8t^2 - 4t + 6$$

Equating Co-efficients of like powers, we get

$$\left. \begin{aligned} 2a_1 + a_2 &= 8 \quad \text{--- (1)} \\ a_1 + a_3 &= -4 \quad \text{--- (2)} \\ 3a_2 &= 6 \quad \text{--- (3)} \end{aligned} \right\} \text{Simple Non-homogeneous system.}$$

(3) $\Rightarrow \boxed{a_2 = 2}$ put in (1) $\boxed{a_1 = 3}$ put in (2) $\boxed{a_3 = -7}$

$$[\underline{v}]_T = \begin{bmatrix} 3 \\ 2 \\ -7 \end{bmatrix} = \text{Coordinate vector of } \underline{v} \text{ w.r.t. } T \text{ basis.}$$

\rightarrow Prove yourself $[\underline{w}]_T = \begin{bmatrix} 2 \\ 3 \\ -3 \end{bmatrix}$

(b) The transition matrix $P_{S \leftarrow T}$ from T to S is matrix with columns as follows

$$P_{S \leftarrow T} = \left[[\underline{w}_1]_S \quad [\underline{w}_2]_S \quad [\underline{w}_3]_S \right], \text{ where}$$

$$\underline{w}_1 = a_1 \underline{v}_1 + a_2 \underline{v}_2 + a_3 \underline{v}_3$$

$$\underline{w}_2 = b_1 \underline{v}_1 + b_2 \underline{v}_2 + b_3 \underline{v}_3$$

$$\underline{w}_3 = c_1 \underline{v}_1 + c_2 \underline{v}_2 + c_3 \underline{v}_3$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} \overset{w_1}{1} & \overset{w_2}{0} & \overset{w_3}{0} & 2 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 1 \\ 1 & -2 & 3 & 10 & 3 & 0 \end{array} \right]$$

$$\begin{array}{c} \underline{u}_1 \quad \underline{u}_2 \quad \underline{u}_3 \quad | \quad \underline{w}_1 \quad \underline{w}_2 \quad \underline{w}_3 \\ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 1 & -2 & 3 \end{bmatrix} \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array} \begin{array}{c} \\ \\ \\ \end{array}$$

$$\text{RREF} \begin{bmatrix} 1 & 0 & 0 & | & 2 & 1 & 0 \\ 0 & 1 & 0 & | & 1 & -2/5 & 3/5 \\ 0 & 0 & 1 & | & 0 & 2/5 & 2/5 \end{bmatrix}$$

$$P_{S \leftarrow T} = \begin{bmatrix} 2 & 1 & 0 \\ 1 & -2/5 & 3/5 \\ 0 & 2/5 & 2/5 \end{bmatrix}$$

© Find $[\underline{v}]_S$ & $[\underline{w}]_S$ using $P_{S \leftarrow T}$

We know $[\underline{v}]_S = P_{S \leftarrow T} [\underline{v}]_T$ ($[\underline{v}]_T$ is computed in part a)

$$= \begin{bmatrix} 2 & 1 & 0 \\ 1 & -2/5 & 3/5 \\ 0 & 2/5 & 2/5 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 8 \\ -2 \\ -2 \end{bmatrix}$$

likewise $[\underline{w}]_S = P_{S \leftarrow T} [\underline{w}]_T$

$$= \begin{bmatrix} 2 & 1 & 0 \\ 1 & -2/5 & 3/5 \\ 0 & 2/5 & 2/5 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \\ -3 \end{bmatrix} = \begin{bmatrix} 7 \\ -1 \\ 0 \end{bmatrix}$$

(d) $\{\underline{v}\}_S, \{\underline{w}\}_S = ?$ Directly

$$\underline{v} = a_1 \underline{v}_1 + a_2 \underline{v}_2 + a_3 \underline{v}_3$$

$$8t^2 - 4t + 6 = a_1(t^2 + 1) + a_2(t - 2) + a_3(t + 3)$$

$$8t^2 - 4t + 6 = a_1 t^2 + (a_2 + a_3)t + (a_1 - 2a_2 + 3a_3)$$

Equating Co-efficients of like Powers, we get

$$\boxed{a_1 = 8} \quad \text{--- (1)} \quad \boxed{a_2 + a_3 = -4} \quad \text{--- (2)} \quad \boxed{a_1 - 2a_2 + 3a_3 = 6} \quad \text{--- (3)}$$

This Non-homogeneous system is simple and can easily be solved.

Put value of a_1 in (3) we have

$$-2a_2 + 3a_3 = -2 \quad \text{--- (4)}$$

Solve (2) & (4)

$$2a_2 + 2a_3 = -8$$

$$-2a_2 + 3a_3 = -2$$

$$5a_3 = -10 \Rightarrow \boxed{a_3 = -2}$$

$$\text{and } \boxed{a_2 = -2}$$

$$\{\underline{v}\}_S = \begin{bmatrix} 8 \\ -2 \\ -2 \end{bmatrix} \quad \text{Same as in part (c)}$$

Similarly Verify yourself

$$\{\underline{w}\}_S = ? \Rightarrow \boxed{a_1 \underline{v}_1 + a_2 \underline{v}_2 + a_3 \underline{v}_3 = \underline{w}}$$

$$\{\underline{w}\}_S = \begin{bmatrix} 7 \\ -1 \\ 0 \end{bmatrix}$$

© The transition matrix $Q_{T \leftarrow S}$ is matrix ④
 defined as $Q_{T \leftarrow S} = \begin{bmatrix} [\underline{u}_1]_T & [\underline{u}_2]_T & [\underline{u}_3]_T \end{bmatrix}$

which can be achieved by solving following
 three non-homogeneous simultaneously.

$$\underline{u}_1 = a_1 \underline{w}_1 + a_2 \underline{w}_2 + a_3 \underline{w}_3$$

$$\underline{u}_2 = b_1 \underline{w}_1 + b_2 \underline{w}_2 + b_3 \underline{w}_3$$

$$\underline{u}_3 = c_1 \underline{w}_1 + c_2 \underline{w}_2 + c_3 \underline{w}_3$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} \underline{w}_1 & \underline{w}_2 & \underline{w}_3 & \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \\ 2 & 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 1 \\ 0 & 3 & 0 & 1 & -2 & 3 \end{array} \right]$$

$$\text{RREF} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{1}{3} & \frac{1}{3} & -\frac{1}{2} \\ 0 & 1 & 0 & \frac{1}{3} & -\frac{2}{3} & 1 \\ 0 & 0 & 1 & -\frac{1}{3} & \frac{2}{3} & \frac{3}{2} \end{array} \right]$$

$$Q_{T \leftarrow S} = \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & -\frac{1}{2} \\ \frac{1}{3} & -\frac{2}{3} & 1 \\ -\frac{1}{3} & \frac{2}{3} & \frac{3}{2} \end{bmatrix}$$

(f) Find $\begin{bmatrix} v \\ - \end{bmatrix}_T = ?$ ~~$\begin{bmatrix} w \\ - \end{bmatrix}_T = ?$~~

using $\mathcal{O}_{T \leftarrow S}$

We know $\begin{bmatrix} v \\ - \end{bmatrix}_T = \mathcal{O}_{T \leftarrow S} \begin{bmatrix} v \\ - \end{bmatrix}_S$

$$\begin{bmatrix} v \\ - \end{bmatrix}_T = \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & -\frac{1}{2} \\ \frac{1}{3} & -\frac{2}{3} & 1 \\ -\frac{1}{3} & \frac{2}{3} & \frac{3}{2} \end{bmatrix} \begin{bmatrix} 8 \\ -2 \\ -2 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \\ -7 \end{bmatrix}$$

Similarly

$$\begin{bmatrix} w \\ - \end{bmatrix}_T = \mathcal{O}_{T \leftarrow S} \begin{bmatrix} w \\ - \end{bmatrix}_S$$

$$= \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & -\frac{1}{2} \\ \frac{1}{3} & -\frac{2}{3} & 1 \\ -\frac{1}{3} & \frac{2}{3} & \frac{3}{2} \end{bmatrix} \begin{bmatrix} 7 \\ -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ -3 \end{bmatrix}$$

19. Let

$$S = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 2 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix} \right\}$$

and

$$T = \left\{ \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right\}$$

be ordered bases for M_{22} . Let

$$v = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \quad \text{and} \quad w = \begin{bmatrix} 1 & 2 \\ -2 & 1 \end{bmatrix}.$$

Follow the directions for (a) through (f) in Exercise 15.

Solution Part(b):

$$\begin{bmatrix} v_1 & v_2 & v_3 & v_4 & | & w_1 & | & w_2 & | & w_3 & | & w_4 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 & | & 1 & | & 0 & | & 0 & | & 1 \\ 0 & 1 & 2 & 0 & | & 1 & | & 0 & | & 0 & | & 0 \\ 0 & 1 & 0 & 1 & | & 0 & | & 1 & | & 0 & | & 0 \\ 0 & 0 & 1 & 1 & | & 0 & | & 0 & | & 1 & | & 0 \end{bmatrix}$$

$$RREF \sim \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1/3 & 2/3 & -2/3 & 0 \\ 0 & 0 & 1 & 0 & 1/3 & -1/3 & 1/3 & 0 \\ 0 & 0 & 0 & 1 & -1/3 & 1/3 & 2/3 & 0 \end{array} \right]$$

$$P_{S \leftarrow T} = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 1/3 & 2/3 & -2/3 & 0 \\ 1/3 & -1/3 & 1/3 & 0 \\ -1/3 & 1/3 & 2/3 & 0 \end{bmatrix}$$

$$\text{Part (d):} \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 & 2 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 1 \end{array} \right]$$

$$RREF \sim \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 0 & 1 & 2 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & -1 & -2 & 0 \end{array} \right]$$

$$Q_{T \leftarrow S} = \begin{bmatrix} 0 & 1 & 2 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 1 & -1 & -2 & 0 \end{bmatrix}$$

HOME WORK part (Complete question 19)

22. Let

$$S = \{[-1 \ 2 \ 1], [0 \ 1 \ 1], [-2 \ 2 \ 1]\}$$

and

$$T = \{[-1 \ 1 \ 0], [0 \ 1 \ 0], [0 \ 1 \ 1]\}$$

be ordered bases for R_3 . If \mathbf{v} is in R_3 and

$$[\mathbf{v}]_S = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix},$$

determine $[\mathbf{v}]_T$.

Solution: (Alternate solution) Since $R_3 \cong R^3$; $S = \left\{ v_1 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, v_3 = \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix} \right\}$;

$$T = \left\{ w_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, w_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, w_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$$

$$[v]_S = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$$

We know coordinates of v w.r.t. S basis can be written as

$$a_1 v_1 + a_2 v_2 + a_3 v_3 = v$$

$$2 \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} + 0 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix} = v$$

$$\begin{bmatrix} -4 \\ 6 \\ 3 \end{bmatrix} = v$$

$[v]_T = ? =$ coordinates of v w.r.t. T basis

$$b_1 w_1 + b_2 w_2 + b_3 w_3 = v \quad \text{--- (1)}$$

$$[A|b] = \left[\begin{array}{ccc|c} -1 & 0 & 0 & -4 \\ 1 & 1 & 1 & 6 \\ 0 & 0 & 1 & 3 \end{array} \right] \xrightarrow{RREF} \approx \left[\begin{array}{ccc|c} 1 & 0 & 0 & 4 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 3 \end{array} \right]$$

$$\text{RREF} \quad \dots [v]_T = \begin{bmatrix} 4 \\ -1 \\ 3 \end{bmatrix}$$

24. Let $S = \{v_1, v_2, v_3\}$ and $T = \{w_1, w_2, w_3\}$ be ordered bases for R^3 , where

$$v_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \quad v_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \quad v_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

Suppose that the transition matrix from T to S is

$$P_{S \leftarrow T} = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 1 \\ -1 & -1 & 1 \end{bmatrix}.$$

Determine T .

Solution: $P_{S \leftarrow T} = [[w_1]_S \quad [w_2]_S \quad [w_3]_S] = \begin{bmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 1 \\ -1 & -1 & 1 \end{bmatrix}$

$$a_1 v_1 + a_2 v_2 + a_3 v_3 = w_1 \Rightarrow 1 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - 1 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = w_1 \Rightarrow \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix} = w_1$$

$$b_1 v_1 + b_2 v_2 + b_3 v_3 = w_2 \Rightarrow 1 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - 1 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = w_2 \Rightarrow \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} = w_2$$

$$c_1 v_1 + c_2 v_2 + c_3 v_3 = w_3 \Rightarrow 2 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = w_3 \Rightarrow \begin{bmatrix} 3 \\ 1 \\ 3 \end{bmatrix} = w_3.$$

27. Let $S = \{\mathbf{v}_1, \mathbf{v}_2\}$ and $T = \{\mathbf{w}_1, \mathbf{w}_2\}$ be ordered bases for P_1 , where

$$\mathbf{w}_1 = t - 1, \quad \mathbf{w}_2 = t + 1.$$

If the transition matrix from T to S is $\begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$,
determine S .

Solution: Recall $P_n(t) \cong R^{n+1}$, implies $P_1(t) \cong R^2$

Given $T = \left\{ \mathbf{w}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \mathbf{w}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ and $P_{S \leftarrow T} = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$.

To determine basis set $S = \{\mathbf{v}_1, \mathbf{v}_2\}$ we need $Q_{T \leftarrow S}$.

We know $Q_{T \leftarrow S} = P_{S \leftarrow T}^{-1}$.

$$P_{S \leftarrow T}^{-1} = \begin{bmatrix} -3 & 2 \\ 2 & -1 \end{bmatrix}$$

$$Q_{T \leftarrow S} = [[\mathbf{v}_1]_T \quad [\mathbf{v}_2]_T] = \begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \end{bmatrix} = \begin{bmatrix} -3 & 2 \\ 2 & -1 \end{bmatrix}$$

$$a_1 \mathbf{w}_1 + a_2 \mathbf{w}_2 = \mathbf{v}_1 \Rightarrow -3 \begin{bmatrix} 1 \\ -1 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \mathbf{v}_1 \Rightarrow \begin{bmatrix} -1 \\ 5 \end{bmatrix} = \mathbf{v}_1 = -t + 5$$

$$b_1 \mathbf{w}_1 + b_2 \mathbf{w}_2 = \mathbf{v}_2 \Rightarrow 2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} - 1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \mathbf{v}_2 \Rightarrow \begin{bmatrix} 1 \\ -3 \end{bmatrix} = \mathbf{v}_2 = t - 3$$