

Lecture -02: Introduction to Neural Networks

What are Neural Networks ?

Biological Neuron vs. Artificial Neuron

Biological Neuron	Artificial Neuron
Dendrites (input)	Input
Soma (cell body)	Node
Axon (output)	Output
Synapse	Interconnections
Adaptation-based learning	Model-based learning

Neural Network Learning Algorithms (1)

- Two main algorithms:
 - **Perceptron**: Initial algorithm for learning simple neural networks (with no hidden layer) developed in the 1950's.
 - **Backpropagation**: More complex algorithm for learning multi-layer neural networks developed in the 1980's.

Neural Network Learning Algorithms (2)

- Neural Networks are one of the most important class of learning algorithms in ML.
- The learned classification model is an **algebraic function**.
- The function is *linear* for **Perceptron algorithm**, *non-linear* for **Backpropagation algorithm**
- Both features and the output classes are allowed to be real valued

Perceptron: The First Neural Network

Types of Artificial Neural Networks

- ANN can be categorized based on number of hidden layers contained in ANN architecture

01

One Layer Neural Network (Perceptron)

- Contains 0 hidden layers

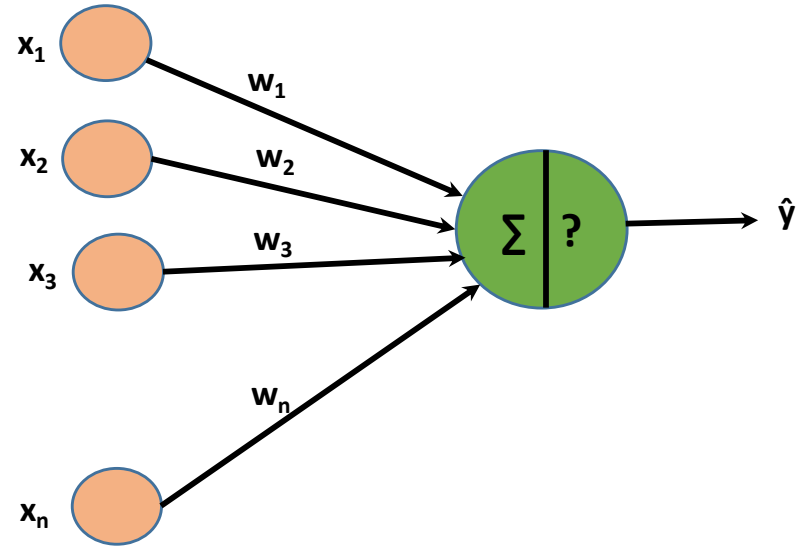
02

Multi Layer Neural Network

- Regular Neural Network
 - Contains 1 hidden layer
- Deep Neural Network
 - Contains >1 hidden layers

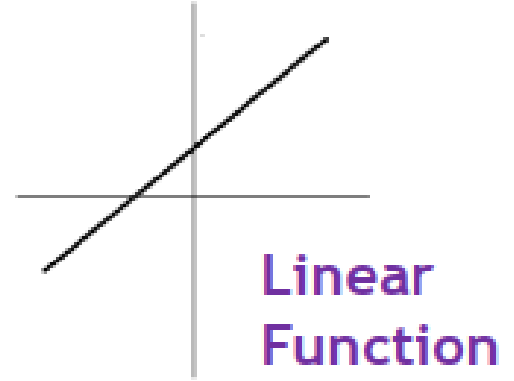
One layer Artificial Neural Network (Perceptron)

- Multiple input nodes
- Single output node
 - Takes weighted sum of the inputs
 - Unit function calculates the output for the network



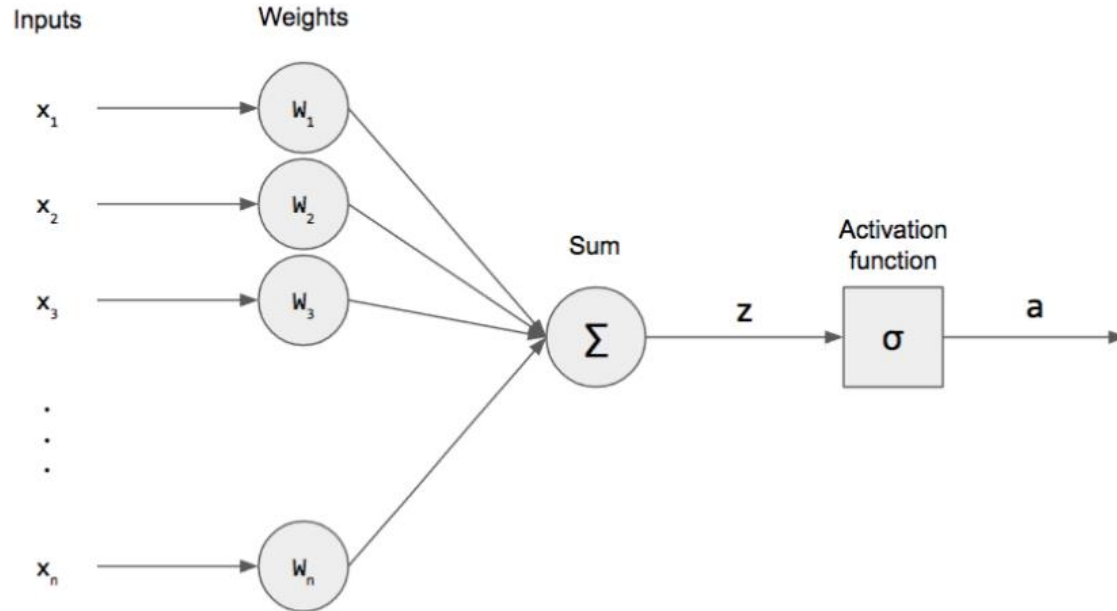
Unit Function

- Linear Function
 - Simply output the weighted sum



Unit Function

- Linear Function
 - Weighted sum followed by an activation function



Perceptron Example

- To categorize a 2x2 pixel binary image to:
 - “Bright” and “Dark”
- The rule is:
 - If it contains 2, 3 or 4 white pixels, it is “**bright**”
 - If it contains 0 or 1 white pixels, it is “**dark**”
- Perceptron architecture:
 - Four input units, one for each pixel
 - One output unit: +1 for bright, -1 for dark

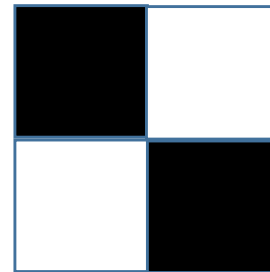
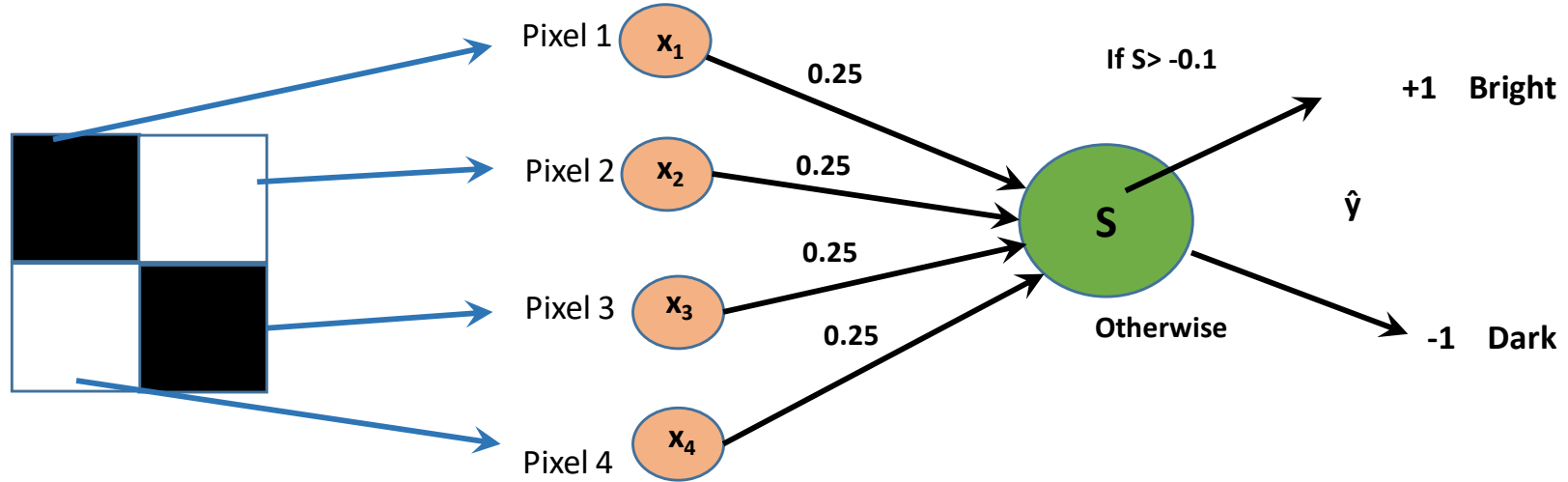


Image of 4 pixels

Perceptron Example



$$S = 0.25 * x_1 + 0.25 * x_2 + 0.25 * x_3 + 0.25 * x_4$$

Perceptron Example

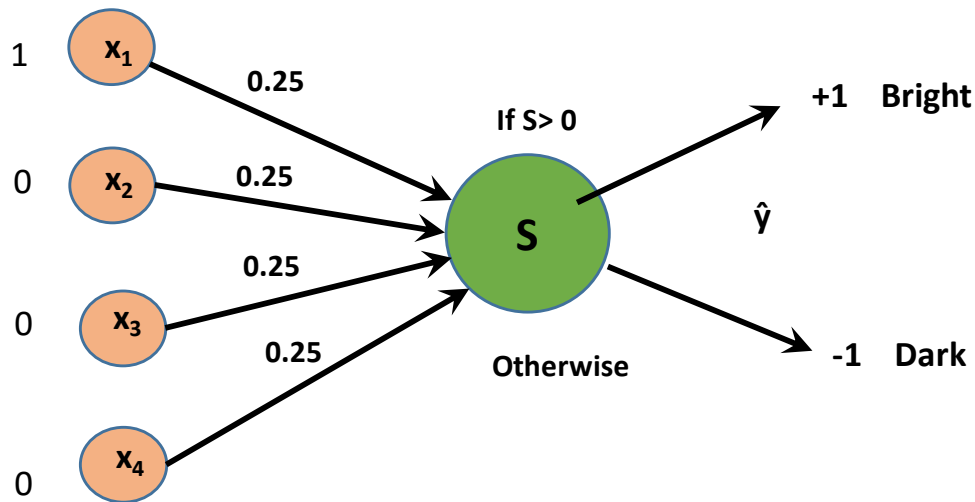
- Calculation (Step-1):

- $x_1 = 1$
- $x_2 = 0$
- $x_3 = 0$
- $x_4 = 0$

$$S = 0.25*(1) + 0.25*(0) + 0.25*(0) + 0.25*(0) = 0.25$$

- $0.25 > 0$, so the output of ANN is +1

- So the image is categorized as “Bright”
- Target : “Dark”



Perceptron Training Rule (How to update weights)

- When $t(E)$ is different from $o(E)$
 - Add Δ_i to weight w_i
 - Where $\Delta_i = \eta(t(E) - o(E)) x_i \rightarrow \eta$ is learning rate (Usually very small value)
 - Do this for every weight in the network
 - Let $\eta=0.1$

Calculating the error values

$$\begin{aligned}\Delta_1 &= \eta(t(E) - o(E)) * x_1 \\ &= 0.1(-1-1) * 1 = -0.2\end{aligned}$$

$$\begin{aligned}\Delta_2 &= \eta(t(E) - o(E)) * x_2 \\ &= 0.1(-1-1) * 0 = 0\end{aligned}$$

$$\begin{aligned}\Delta_3 &= \eta(t(E) - o(E)) * x_3 \\ &= 0.1(-1-1) * 0 = 0\end{aligned}$$

$$\begin{aligned}\Delta_4 &= \eta(t(E) - o(E)) * x_4 \\ &= 0.1(-1-1) * 0 = 0\end{aligned}$$

Calculating the New Weights

$$w'_1 = w_1 + \Delta_1 = 0.25 - 0.2 = 0.05$$

$$w'_2 = w_2 + \Delta_2 = 0.25 + 0 = 0.25$$

$$w'_3 = w_3 + \Delta_3 = 0.25 + 0 = 0.25$$

$$w'_4 = w_4 + \Delta_4 = 0.25 + 0 = 0.25$$

Perceptron Example

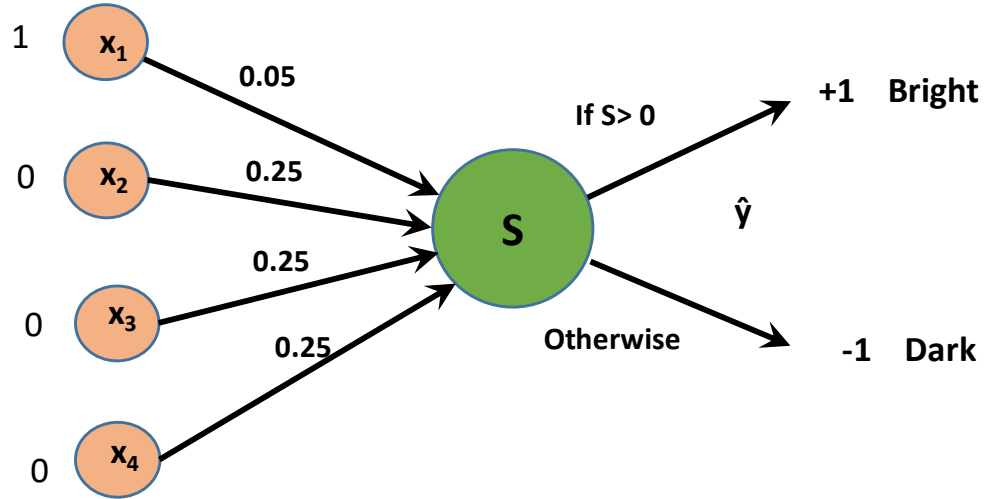
- Calculation (Step-2):

- $x_1 = 1$
- $x_2 = 0$
- $x_3 = 0$
- $x_4 = 0$

$$S = 0.05*(1) + 0.25*(0) + 0.25*(0) + 0.25*(0) = 0.05$$

- $0.05 > 0$, so the output of ANN is +1

- So the image is categorized as "Bright"
- Target : "Dark"



Perceptron Training Rule (How to update weights)

- When $t(E)$ is different from $o(E)$
 - Add Δ_i to weight w_i
 - Where $\Delta_i = \eta(t(E) - o(E)) x_i \rightarrow \eta$ is learning rate (Usually very small value)
 - Do this for every weight in the network
 - Let $\eta=0.1$

Calculating the error values

$$\begin{aligned}\Delta_1 &= \eta (t(E) - o(E)) * x_1 \\ &= 0.1 (-1 - 1) * 1 = -0.2\end{aligned}$$

$$\begin{aligned}\Delta_2 &= \eta (t(E) - o(E)) * x_2 \\ &= 0.1 (-1 - 1) * 0 = 0\end{aligned}$$

$$\begin{aligned}\Delta_3 &= \eta (t(E) - o(E)) * x_3 \\ &= 0.1 (-1 - 1) * 0 = 0\end{aligned}$$

$$\begin{aligned}\Delta_4 &= \eta (t(E) - o(E)) * x_4 \\ &= 0.1 (-1 - 1) * 0 = 0\end{aligned}$$

Calculating the New Weights

$$w'_1 = w_1 + \Delta_1 = 0.05 - 0.2 = -0.15$$

$$w'_2 = w_2 + \Delta_2 = 0.25 + 0 = 0.25$$

$$w'_3 = w_3 + \Delta_3 = 0.25 + 0 = 0.25$$

$$w'_4 = w_4 + \Delta_4 = 0.25 + 0 = 0.25$$

Perceptron Example

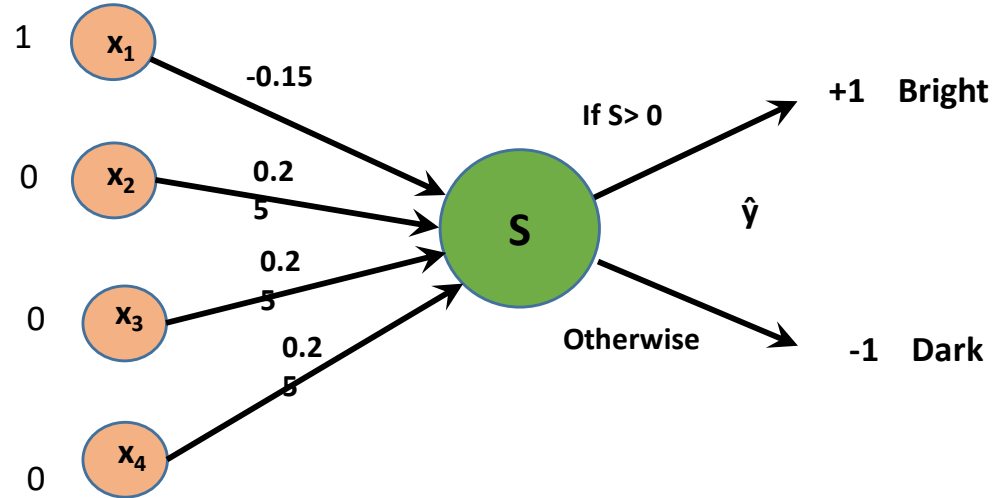
- Calculation (Step-3):

- $X_1 = 1$
- $X_2 = 0$
- $X_3 = 0$
- $X_4 = 0$

$$S = -0.15 * (1) + 0.25 * (0) + 0.25 * (0) + 0.25 * (0) = -0.15$$

- - $0.15 < 0$, so the output of ANN is -1

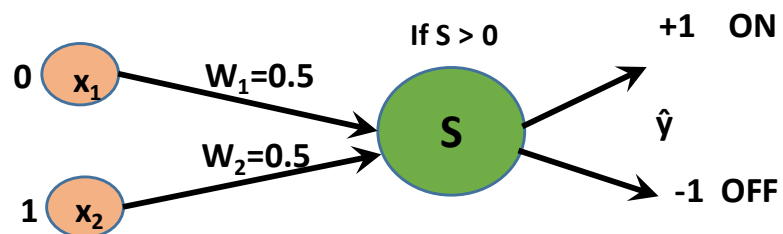
- So the image is categorized as "Dark"
- Target : "Dark"



Another Example (AND)

X_1	X_2	$X_1 \text{ AND } X_2$
0	0	0
0	1	0
1	0	0
1	1	1

- $X_1 = 0$
- $X_2 = 1$,
- $\eta = 0.1$
- $t(E) = -1$

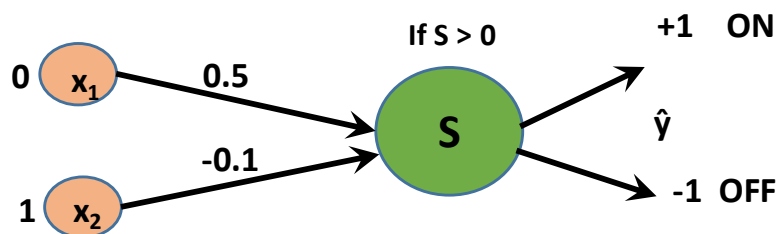


Weights	Step-1	Step-2	Step-3	Step-4
w_1	0.5	0.5	0.5	0.5
w_2	0.5	0.3	0.1	-0.1
Weighted Sum	0.5	0.3	0.1	-0.1
Observed Output	+1	+1	+1	-1

Another Example (AND)

X_1	X_2	$X_1 \text{ AND } X_2$
0	0	0
0	1	0
1	0	0
1	1	1

- $X_1 = 1$
- $X_2 = 0$,
- $\eta = 0.1$
- $t(E) = -1$

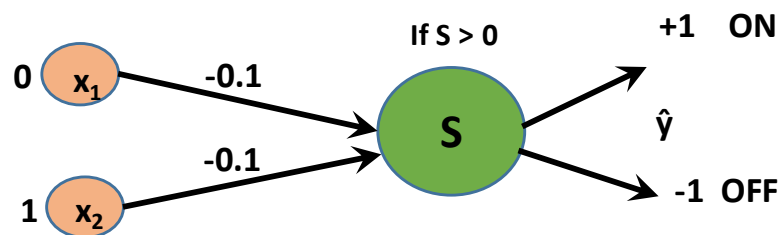


Weights	Step-1	Step-2	Step-3	Step-4
w1	0.5	0.3	0.1	-0.1
w2	-0.1	-0.1	-0.1	-0.1
Weighted Sum	0.5	0.3	0.1	-0.1
Observed Output	+1	+1	+1	-1

Another Example (AND)

X_1	X_2	$X_1 \text{ AND } X_2$
0	0	0
0	1	0
1	0	0
1	1	1

- $X_1 = 1$
- $X_2 = 1$,
- $\eta = 0.1$
- $t(E) = +1$



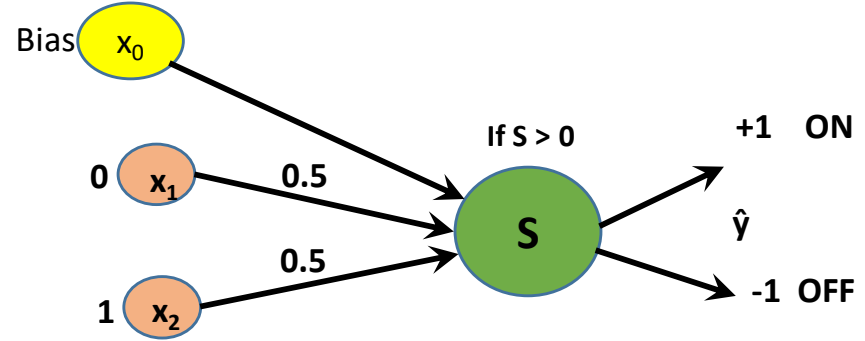
Weights	Step-1	Step-2
w1	-0.1	0.1
w2	-0.1	0.1
Weighted Sum	-0.2	0.2
Observed Output	-1	+1

Use of Bias

- Bias is just like an intercept added in a linear equation.

$$\text{output} = \text{sum}(\text{weights} * \text{inputs}) + \text{bias}$$

- The output is calculated by multiplying the inputs with their weights and then passing it through an activation function like the Sigmoid function, etc. Here, bias acts like a constant which helps the model to fit the given data.

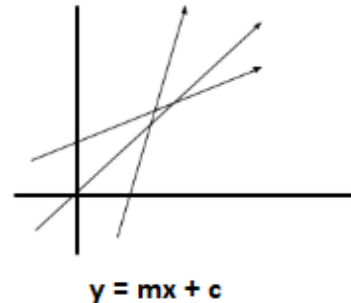
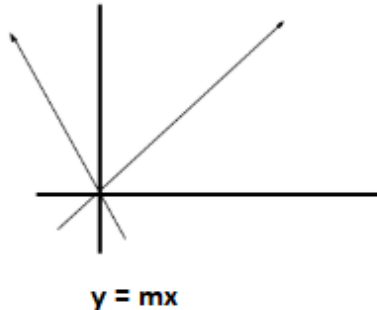


Use of Bias

- A simpler way to understand bias is through a constant c of a linear function

$$y = mx + c$$

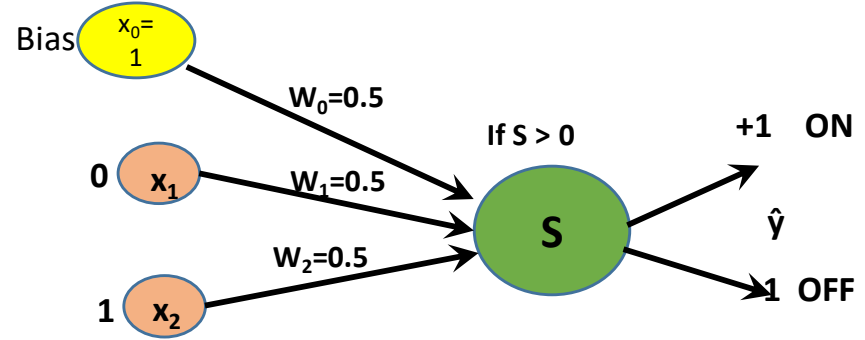
- It allows us to move the line down and up fitting the prediction with the data better. If the constant c is absent then the line will pass through the origin $(0, 0)$ and we will get a poorer fit.



Example (AND) with Bias

X_1	X_2	$X_1 \text{ AND } X_2$
0	0	0
0	1	0
1	0	0
1	1	1

- $X_1 = 0$
- $X_2 = 1$,
- $\eta = 0.1$
- $t(E) = -1$

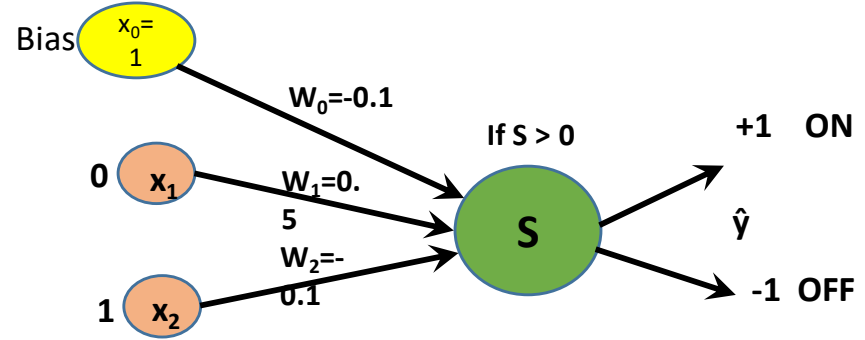


Weights	Step-1	Step-2	Step-3	Step-4
w_0	0.5	0.3	0.1	-0.1
w_1	0.5	0.5	0.5	0.5
w_2	0.5	0.3	0.1	-0.1
Weighted Sum	1	0.6	0.2	-0.2
Observed Output	+1	+1	+1	-1

Example (AND) with Bias

X_1	X_2	$X_1 \text{ AND } X_2$
0	0	0
0	1	0
1	0	0
1	1	1

- $X_1 = 1$
- $X_2 = 0$,
- $\eta = 0.1$
- $t(E) = -1$

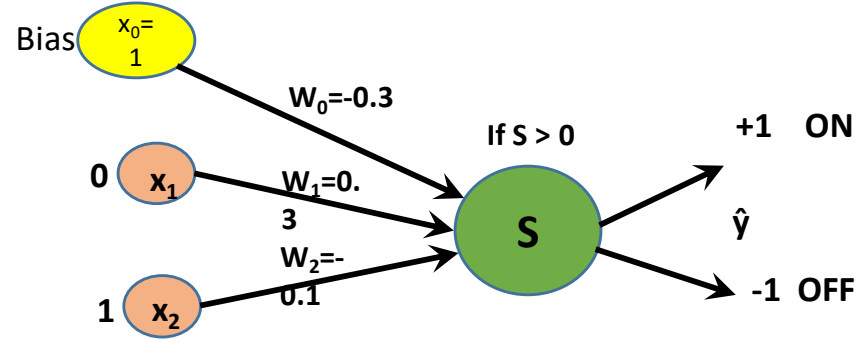


Weights	Step-1	Step-2
w_0	-0.1	-0.3
w_1	0.5	0.3
w_2	-0.1	-0.1
Weighted Sum	0.4	0
Observed Output	+1	-1

Example (AND) with Bias

X_1	X_2	$X_1 \text{ AND } X_2$
0	0	0
0	1	0
1	0	0
1	1	1

- $X_1 = 1$
- $X_2 = 1$,
- $\eta = 0.1$
- $t(E) = +1$



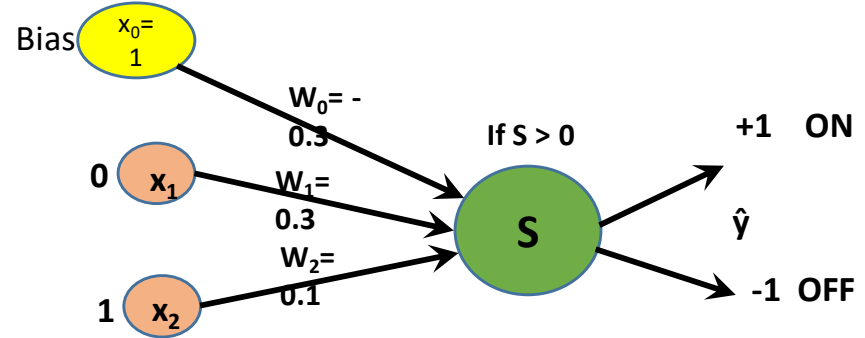
Weights	Step-1	Step-2
w_0	-0.3	-0.1
w_1	0.3	0.5
w_2	-0.1	0.1
Weighted Sum	0	0.5
Observed Output	-1	+1

Example (AND) with Bias

After 2 Epochs

X_1	X_2	$X_1 \text{ AND } X_2$
0	0	0
0	1	0
1	0	0
1	1	1

- $X_1 = 0$
- $X_2 = 1$,
- $\eta = 0.1$
- $t(E) = -1$



Final Weights

Weights	
w_0	- 0.3
w_1	0.3
w_2	0.1

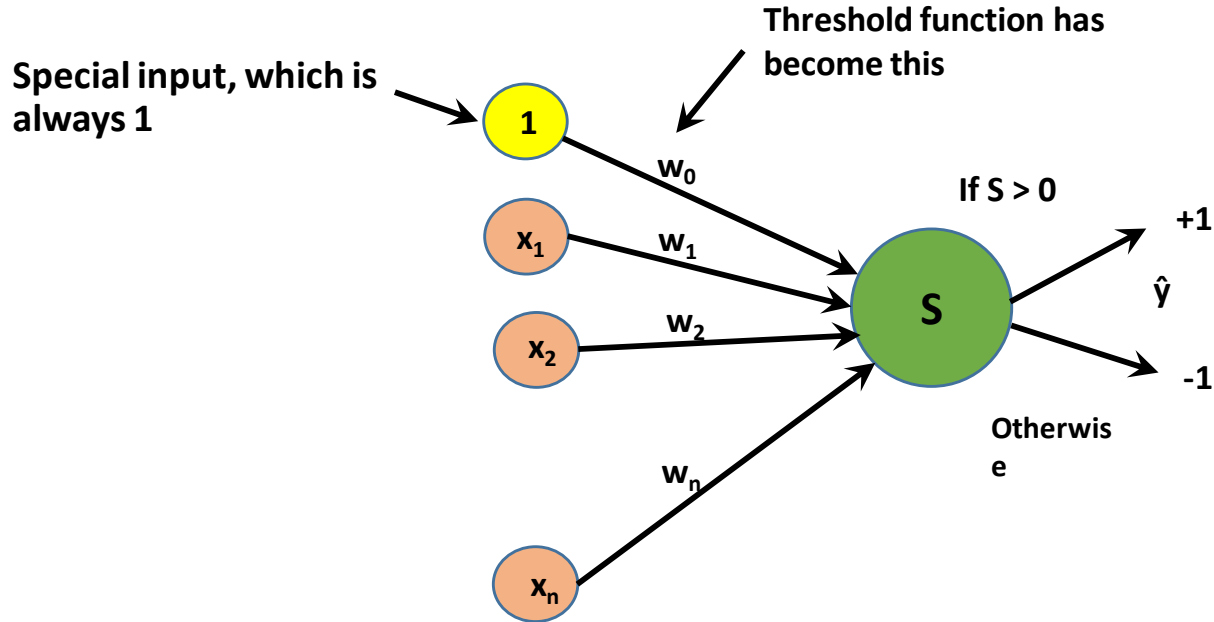
Learning in Perceptron



Need To Learn

- Both the **weights** between input and output units
- And the value for the bias
- **Make Calculations easier by:**
 - Thinking of the bias as a weight from a special input unit where the output from the unit is always 1
- **Exactly the same result:**
 - But we only have to worry about learning weights

New Representation for Perceptron



$$S = w_0 + w_1 * x_1 + w_2 * x_2 \dots \dots w_n * x_n$$

Learning Algorithm

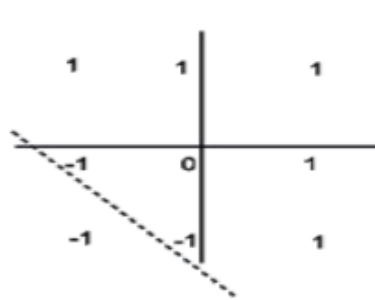
- **Weights are randomly initialized.**
- **For each training example E**
 - Calculate the observed output from Perceptron, $o(E)$
 - If the target output $t(E)$ is different to $o(E)$
 - Then update all the weights so that $o(E)$ becomes closer to $t(E)$
- **This process is done for every example**
- **It is not necessary to stop when all examples are used.**
 - Repeat the cycle again (an epoch) until network produces the correct output

Limitations of Perceptron

- The perceptron can only learn simple problems. this is only useful if the problem is linearly separable.
- A linearly separable problem is one in which the classes can be separated by a single hyperplane.



AND VALUES



OR VALUES



XOR VALUES

Any Questions?