Name: Syed Mohammond Saadaan Hallan

Roh no: Sp 22-8CB-003

Date: 20-04-2023

Section: C

Course: Linear Algebra

Instructor: Dr. Magsood Ahmed

## ASSIGNMENT-2

Hence proved.

$$\underline{U} = \begin{bmatrix} 2u_1 + 3u_2 \\ -u_1 \\ u_2 \end{bmatrix}, \quad Y = \begin{bmatrix} 2v_1 + 3v_2 \\ -v_1 \\ v_2 \end{bmatrix}$$

$$\underline{\mathbf{u}} \oplus \underline{\mathbf{v}} = \begin{pmatrix} 2\mathbf{u}_1 + 3\mathbf{u}_1 \\ -\mathbf{u}_1 \\ \mathbf{u}_2 \end{pmatrix} \oplus \begin{pmatrix} 2\mathbf{v}_1 + 3\mathbf{v}_2 \\ -\mathbf{v}_1 \\ \mathbf{v}_2 \end{pmatrix}$$

$$= \begin{bmatrix} 2(u_1 + v_1) + 3(u_2 + v_2) \\ -(u_1 + v_1) \\ 2u_1 + v_2 \end{bmatrix} \in W$$

Hence W is closed wirt addition

$$c \circ \underline{u} = c \begin{bmatrix} 2u_1 + 3u_2 \\ -u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 2(cu_1) + 3(cu_2) \\ -cu_1 \\ cu_2 \end{bmatrix} \in \mathcal{W}$$

Hence Wis closed with respect to multiplication

## in If yes, find the basis of subspace W

Let 
$$W \in W$$
  
So,  $W = \begin{pmatrix} 2x+2y \\ -x \\ y \end{pmatrix} = \begin{pmatrix} 2x \\ -x \\ 0 \end{pmatrix} + \begin{pmatrix} 3y \\ 0 \\ y \end{pmatrix}$ 

$$= x \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} + y \begin{pmatrix} 3 \\ 0 \\ 1 \end{pmatrix}$$

$$\downarrow_{V_1}$$

$$\downarrow_{V_2}$$

Therefore, the bosts of subspace W is 
$$S = \left\{ \begin{array}{c} U_1 = \begin{pmatrix} 2 \\ -1 \\ 0 \end{array} \right\}, \begin{array}{c} U_2 \begin{pmatrix} 3 \\ 0 \\ 1 \end{array} \right\}$$

The given set S form the basis for M22, if:

(1) S is Linearly Independent

So, 
$$V_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$
,  $V_2 \begin{bmatrix} 1 \\ 2 \\ 1 \\ 3 \end{bmatrix}$ ,  $V_3 \begin{bmatrix} 2 \\ 1 \\ 3 \\ 2 \end{bmatrix}$ ,  $V_4 \begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix}$ 

(1) Checking LI of S.

Consider:  

$$Q_1V_1 + Q_2V_2 + Q_3V_3 + Q_4V_4 = Q$$

Hence, 
$$q_1 = q_2 = q_3 = q_n = 0$$
  
So it is linearly Independent.

If you the Express the rector  $A = \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$  on a linear Combination of the rectors in S.

$$Q_1V_1 + Q_2V_2 + Q_3V_3 + Q_4V_n = V$$

So, 
$$\{A1b\} = \{ 1 & 1 & 2 & 1 & 1 & 6 \\ 1 & 2 & 1 & 1 & 6 \\ 1 & 1 & 3 & 2 & 2 \\ 1 & 3 & 2 & 2 & 0 \end{bmatrix}$$

LHS = R.HS

Question 4: For which real velocity of a do the polynomial form basis for rector space P. (1)?

$$V_1 = \begin{pmatrix} Q \\ -1 \\ -1/2 \end{pmatrix}, \quad V_2 = \begin{pmatrix} -1/2 \\ a \\ -1/2 \end{pmatrix}, \quad V_3 \begin{pmatrix} -1/2 \\ -1/2 \\ Q \end{pmatrix}$$

To find the basis for vector space P2(4)

$$[A/0] = \begin{cases} a & -1/2 & -1/2 \\ -1/2 & a & -1/2 \\ -1/2 & -1/2 \end{cases} 0$$

$$\begin{bmatrix} -1/2 & -1/2 & a \\ -1/2 & -1/2 & a \end{bmatrix} 0$$

This method would become difficult to find values of a so, we use another way.

As we know, AX = Q, where  $|A| \neq 0$  is linearly independent. So

$$|A| = \begin{vmatrix} \alpha & -1/2 & -1/2 \\ -1/2 & \alpha & -1/2 \end{vmatrix} \Rightarrow \begin{vmatrix} \alpha - \frac{1}{2} & -1/2 & -1/2 \\ \alpha - \frac{1}{2} & \alpha & -1/2 \end{vmatrix} = \begin{vmatrix} \alpha - \frac{1}{2} & \alpha & -1/2 \\ \alpha - \frac{1}{2} & \alpha & -1/2 \end{vmatrix} = \begin{vmatrix} \alpha - \frac{1}{2} & \alpha & -1/2 \\ \alpha - \frac{1}{2} & \alpha & -1/2 \end{vmatrix}$$

$$|A| = \begin{vmatrix} a-1 & -1/2 & -1/2 \\ a-1 & a & -1/2 \\ a-1 & -1/2 & a \end{vmatrix} C_1 + C_3$$

$$= (a-1) \begin{vmatrix} 1 & -\frac{1}{2} & -\frac{1}{2} \\ 1 & q & -\frac{1}{2} \end{vmatrix} = > (q-1) \begin{vmatrix} 1 & -\frac{1}{2} & -\frac{1}{2} \\ 0 & \frac{30+1}{2} & 0 \\ 1 & -\frac{1}{2} & q \end{vmatrix} = > (q-1) \begin{vmatrix} 1 & -\frac{1}{2} & -\frac{1}{2} \\ 0 & \frac{30+1}{2} & 0 \\ 0 & 0 & \frac{30+1}{2} \end{vmatrix} R_2 - R_1$$

Taking (9-1) common from ei

Expanding from C<sub>1</sub>  $= (a-1) \left( 1 \left( (a+1/2)^2 - 0 \right) + 0 + 0 \right) = (a-1) \left( a+\frac{1}{2} \right)^2$ 

if 1A1=0 then A 55 2.0

So  $(a-1)(a+1/2)^2 = 6$ 

[a=1] ;  $(a+1)^2=0 \Rightarrow [a=-1/2]$ 

So, given set will be l.I for all the values of  $q \in \mathbb{R}$  other than -1/2 & 1

(ii) Number of elements in set = 3 Dimension of rector space = 3

This gaurantee that span S = Pr (t)

Hence, given rectors from the books for P2(t) or TR3