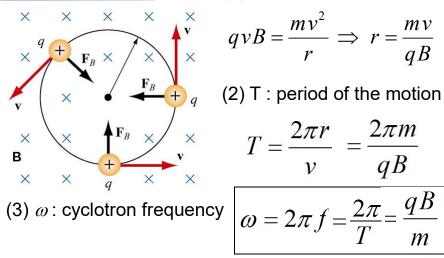


What Kind of Motion in Uniform B Field?

Cyclotron Motion

(1) r: radius of the circle



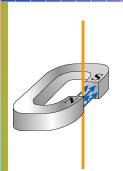
$$qvB = \frac{mv^2}{r} \implies r = \frac{mv}{qB}$$

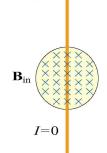
(2) T: period of the motion

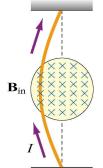
$$T = \frac{2\pi r}{v} = \frac{2\pi m}{qB}$$

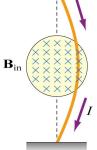
$$\omega = 2\pi f = \frac{2\pi}{T} = \frac{qB}{m}$$

Magnetic Force on **Current-Carrying Wire**









Current is moving charges, and we know that moving charges feel a force in a magnetic field

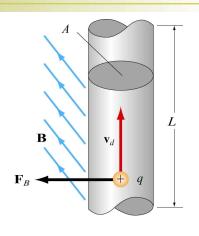
Magnetic Force on **Current-Carrying Wire**

$$\vec{\mathbf{F}}_{B} = q\vec{\mathbf{v}} \times \vec{\mathbf{B}}$$

$$= (\mathbf{C}) \frac{\mathbf{m}}{\mathbf{s}} \times \vec{\mathbf{B}}$$

$$= \frac{(\mathbf{C})}{\mathbf{s}} \mathbf{m} \times \vec{\mathbf{B}}$$

$$\vec{\mathbf{F}}_{B} = I(\vec{\mathbf{L}} \times \vec{\mathbf{B}})$$

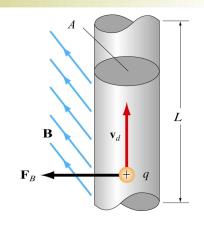


Summary Magnetic Force

$$\vec{\mathbf{F}}_{B} = q\vec{\mathbf{v}} \times \vec{\mathbf{B}}$$

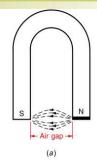
$$d\mathbf{F}_{R} = Id\mathbf{\vec{s}} \times \mathbf{B}$$

$$d\vec{\mathbf{F}}_{B} = Id\vec{\mathbf{s}} \times \vec{\mathbf{B}}$$
$$\vec{\mathbf{F}}_{B} = I\left(\vec{\mathbf{L}} \times \vec{\mathbf{B}}\right)$$



Air Gap of a Magnet

- The air space between the poles of a magnet is its air gap.
- The shorter the air gap, the stronger the field in the gap for a given pole strength.



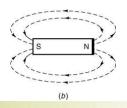


Fig. 1: The horseshoe magnet in (a) has a smaller air gap than the bar magnet in (b).

Air Gap of a Magnet

- The shorter the air gap, the more intense the field. Eliminating the air gap eliminates the external field. This concentrates the lines within the field.
- Magnets are sometimes stored with "keepers" that eliminate the external field.

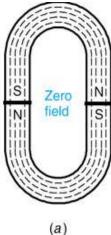


Fig. 2: Example of a closed magnetic ring without any air gap. (a) Two PM horseshoe magnets with opposite poles touching.

Air Gap of a Magnet

- A toroid coil has very little external field.
- Toroid cores (doughnut shaped) are used to greatly reduce unwanted magnetic induction.

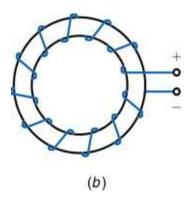


Fig. 3(b): Toroid magnet.

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Types of Magnets

- There are two main classes of magnets:
 - An electromagnet is made up of coils of wire, and must have an external source of current to maintain a magnetic field.
 - Applications: buzzers, chimes, relays (switches whose contacts open or close by electromagnetism), tape recording.
 - A permanent magnet retains its magnetic field indefinitely.

Types of Magnets

- Classification of Magnetic and Nonmagnetic Materials
 - Magnetic materials:
 - Ferromagnetic materials include iron, steel, nickel, cobalt, and certain alloys. They become strongly magnetized in the same direction as the magnetizing field, with high values of permeability.
 - Paramagnetic materials include aluminum, platinum, manganese, and chromium. They become weakly magnetized in the same direction as the magnetizing field. The permeability is slightly more than 1.

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Types of Magnets

- Diamagnetic materials include copper, zinc, mercury, gold, silver, and others. They become weakly magnetized in the opposite direction from the magnetizing field. The permeability is less than 1.
- Nonmagnetic materials:
 - air, paper, wood, and plastics

Ferrites

- **Ferrites** are nonmetallic materials that have the ferromagnetic properties of iron.
 - They have high permeability.
 - However, a ferrite is a non-conducting ceramic material.
 - Common applications include ferrite cores in the coils for RF transformers, and ferrite beads, which concentrate the magnetic field of the wire on which they are strung.



http://www.mag-inc.com/ferrites/ferrites.asp

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Magnetic Shielding

- Shielding is the act of preventing one component from affecting another through their common electric or magnetic fields.
- Examples:
 - The braided copper wire shield around the inner conductor of a coaxial cable
 - A shield of magnetic material enclosing a cathode-ray tube.

How does Magnetic Shielding Work?

- When magnetic lines of flux encounter high permeability material, the magnetic forces are both absorbed by the material and redirected away from its target.
- The most effective shields are constructed as enclosures such as boxes or better yet, cylinders with end caps.

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What is EMI?

- EMI is the abbreviation for Electro Magnetic Interference.
- EMI is an electrical or magnetic disturbance that causes unwanted interference.

P1

A proton is moving in a circular orbit of radius *14 cm* in a uniform magnetic field of magnitude *0.35 T*, directed perpendicular to the velocity of the proton. Find the orbital speed of the proton.

Solution:

Because,

$$r = \frac{mv}{qB} \implies v = \frac{rqB}{m} = \frac{(0.14 \text{ m})(1.60 \times 10^{-19} \text{ C})(0.35 \text{ T})}{(1.67 \times 10^{-27} \text{ kg})}$$
$$= \frac{(0.14 \text{ m})(1.60 \times 10^{-19} \text{ C})(0.35 \text{ kg/C.s})}{(1.67 \times 10^{-27} \text{ kg})}$$

NOTE

$$v = 4.7 \text{x} 10^6 \text{ m/s}$$

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P2

A proton moves in a direction perpendicular to a uniform magnetic field B at 1.00×10^7 m/s and experiences an acceleration of 2.00×10^{13} m/s² in the +x direction when its velocity is in the +z direction. Determine the magnitude and direction of the field.

Solution:

F = ma =
$$(1.67 \times 10^{-27} \text{ kg})(2.00 \times 10^{13} \text{ m/s}^2)$$

= $3.34 \times 10^{-14} \text{ N}$

$$F = qvBsin90^{\circ} => B = \frac{F}{qv} = \frac{(3.34 \times 10^{-14} \text{ N})}{(1.60 \times 10^{-19} \text{ C})(1.00 \times 10^{7} \text{ m/s})}$$
$$= 2.09 \times 10^{-2} \text{ N.s/C.m} = 2.09 \times 10^{-2} \text{ N/A.m}$$
$$= 2.09 \times 10^{-2} \text{ T} = 20.9 \times 10^{-3} \text{ T}$$
$$= 20.9 \text{ mT}$$

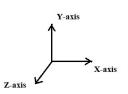
P2 (Continue...)

From FIGURE, the right-hand rule shows that B must be in the -y direction to yield a force in the +x direction when v is in the z direction. Therefore,



FIGURE

$$\vec{\mathbf{B}} = -20.9 \; \hat{\mathbf{j}} \; \text{mT}$$



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•A proton moving at 4.00×10^6 m/s through a magnetic field of 1.70 T experiences a magnetic force of magnitude 8.20×10^{-13} N. What is the angle between the protons velocity and the field?

•An electron is accelerated from rest by a potential difference of 350~V. It then enters a uniform magnetic field of magnitude 200~mT, its velocity being at right angles to this field. Calculate (a) the speed of the electron and (b) the radius of its path in the magnetic field.

Hall Effect

- In 1879, Edwin H. Hall, a 24-year-old graduate student at the Johns Hopkins University, showed that the drifting conduction electrons in a copper wire can also be deflected by a magnetic field.
- This Hall effect allows to find out whether the charge carriers in a conductor are positively or negatively charged.
- The number of such carriers per unit volume of the conductor can also be measured.
- Fig.1.a shows a copper strip of width d, carrying a current i whose conventional direction is from the top of the figure to the bottom.
- The charge carriers are electrons and, as we know they drift (with drift speed v_D) in the opposite direction, from bottom to top.



Fig.1.a

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<u> Hall Effect</u>

- At the instant shown in Fig.1.a, an external magnetic field B, pointing into the plane of the figure, has just been turned on.
 - From Eq. (\$\vec{F_B}\$ = q(\$\vec{v}\$ \times \$\vec{B}\$) we see that a magnetic deflecting force \$\vec{F_B}\$ will act on each drifting electron, pushing it toward the right edge of the strip.
 - As time goes on, electrons move to the right, mostly piling up on the right edge of the strip, leaving uncompensated positive charges in fixed positions at the left edge.
 - The separation of positive and negative charges produces an electric field E within the strip, pointing from left to right in Fig.1.b.
 - This field exerts an electric force $\overline{F_E}$ on each electron, tending to push it to the left.

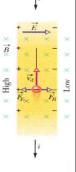
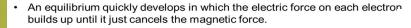


Fig.1.b

Hall Effect





- When this happens, as Fig.1.b shows, the force due to B and the force due t
 B are in balance.
- The drifting electrons then move along the strip toward the top of the page at velocity $\overrightarrow{v_p}$, with no further collection of electrons on the right edge of the strip and thus no further increase in the electric field \overrightarrow{E} .



- A Hall potential difference V is associated with the electric field across strip width d.
- From Eq. $(E = -\Delta V/\Delta s)$, the magnitude of that potential difference is

$$V = Ed$$

Fig.1.b

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Hall Effect

When the electric and magnetic forces are in balance, then

$$F_E = F_B$$

$$eE = ev_D B$$
 ... (2)

As the drift speed v_D is

$$v_D = \frac{J}{ne} = \frac{i}{neA} \qquad \dots (3)$$

in which J (= I/A) is the current density in the strip, A is the cross-sectional area of the strip, and n is the number density of charge carriers (their number per unit volume). In Eq.2, substituting for E with Eq.1 and substituting for v_D with Eq.3, we obtain

$$n = \frac{Bi}{Vle} \qquad ... (4)$$

in which I = A/a) is the thickness of the strip. With this equation we can find n from measurable quantities.

