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# 4.7 Homogeneous Systems

The procedure for finding a basis for the solution space of a homogeneous system  $A\mathbf{x} = \mathbf{0}$ , or the null space of A, where A is  $m \times n$ , is as follows:

- **Step 1.** Solve the given homogeneous system by Gauss–Jordan reduction. If the solution contains no arbitrary constants, then the solution space is  $\{0\}$ , which has no basis; the dimension of the solution space is zero.
- **Step 2.** If the solution **x** contains arbitrary constants, write **x** as a linear combination of vectors  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_p$  with  $s_1, s_2, \dots, s_p$  as coefficients:

$$\mathbf{x} = s_1 \mathbf{x}_1 + s_2 \mathbf{x}_2 + \dots + s_p \mathbf{x}_p.$$

**Step 3.** The set of vectors  $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_p\}$  is a basis for the solution space of  $A\mathbf{x} = \mathbf{0}$ ; the dimension of the solution space is p.

If A is an  $m \times n$  matrix, we refer to the dimension of the null space of A as the **nullity** of A, denoted by nullity A.

### Example 1:-

Find a basis for and the dimension of the solution space W of the homogeneous system

$$\begin{bmatrix} 1 & 1 & 4 & 1 & 2 \\ 0 & 1 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 & 2 \\ 1 & -1 & 0 & 0 & 2 \\ 2 & 1 & 6 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}.$$

# Solution

**Step 1.** To solve the given system by the Gauss–Jordan reduction method, we transform the augmented matrix to reduced row echelon form, obtaining (verify)

$$x_4 + 2x_5 = 0 - - - (1)$$

$$x_2 + 2x_3 - x_5 = 0 - - - (2)$$

$$x_1 + 2x_3 + x_5 = 0 - - - (3)$$

Say  $x_5 = s \in R$  be an arbitrary variable.

From equation (1)  $x_4 = -2s$ 

Say  $x_3 = t \in R$  be an arbitrary variable.

From equation (2)  $x_2 = -2t + s$ 

From equation (3)  $x_1 = -2t - s$ 

Step 2:- 
$$X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -2t - s \\ -2t + s \\ t + 0s \\ 0t - 2s \\ 0t + s \end{bmatrix} = s \begin{bmatrix} -1 \\ 1 \\ 0 \\ -2 \\ 1 \end{bmatrix} + t \begin{bmatrix} -2 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

Step 3:- Basis of Null space (W) or solution space (W) is = 
$$\begin{bmatrix} -1 \\ 1 \\ 0 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

### Nullity=dimension of W=2

Question 10: (Exercise 4.7):- In exercise 3 through 1, find basis for and dimension of the solution space (Null Space) of the given homogeneous system.

$$\mathbf{10.} \begin{bmatrix} 1 & 2 & -3 & -2 & 1 & 3 \\ 1 & 2 & -4 & 3 & 3 & 4 \\ -2 & -4 & 6 & 4 & -3 & 2 \\ 0 & 0 & -1 & 5 & 1 & 9 \\ 1 & 2 & -3 & -2 & 0 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Solution: 
$$[A|O] = \begin{bmatrix} 1 & 2 & -3 & -2 & 1 & 3 & 0 \\ 1 & 2 & -4 & 3 & 3 & 4 & 0 \\ -2 & -4 & 6 & 4 & -3 & 2 & 0 \\ 0 & 0 & -1 & 5 & 1 & 9 & 0 \\ 1 & 2 & -3 & -2 & 0 & 7 & 0 \end{bmatrix}$$

I got Reduced Row Echelon Form using linear algebra toolkit (Do yourself: important and it is practice of row operations)

$$\sim
\begin{bmatrix}
1 & 2 & 0 & -17 & 0 & 0 & | & 0 \\
0 & 0 & 1 & -5 & 0 & 0 & | & 0 \\
0 & 0 & 0 & 0 & 1 & 0 & | & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & | & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & | & 0
\end{bmatrix}$$

Reading from echelon form  $x_6 = 0$ ;  $x_5 = 0$ 

$$x_3 - 5x_4 = 0 \implies x_3 = 5x_4 \ Take \ x_4 = s \in R \implies x_3 = 5s$$

$$x_1 + 2x_2 - 17x_4 = 0 \implies x_1 = -2x_2 + 17x_4 \ Take \ x_2 = t \in R \implies x_1 = -2t + 17s$$

$$X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} -2t + 17s \\ t \\ 5s \\ s \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -2t + 17s \\ t + 0s \\ 0t + 5s \\ 0t + s \\ 0t + 0s \\ 0t + 0s \end{bmatrix} = t \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} 17 \\ 0 \\ 5 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

Basis of Null space (W) or solution space (W) is =basis of W= 
$$\left\{ \begin{bmatrix} 17 \\ 0 \\ 5 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right\}$$

Nullity of W=dimension of W=2.

# ■ Relationship between Nonhomogeneous Linear Systems and Homogeneous Systems

Consider the linear system

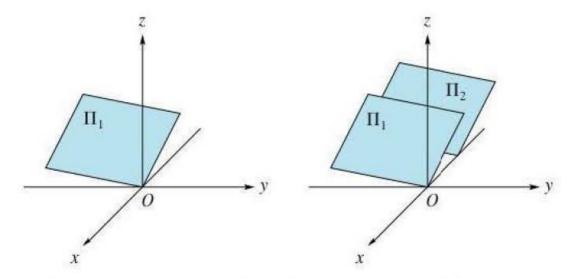
$$\begin{bmatrix} 1 & 2 & -3 \\ 2 & 4 & -6 \\ 3 & 6 & -9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ 6 \end{bmatrix}.$$

The set of all solutions to this linear system consists of all vectors of the form

$$\mathbf{x} = \begin{bmatrix} 2 - 2r + 3s \\ r \\ s \end{bmatrix}$$

(verify), which can be written as

$$\mathbf{x} = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} + r \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + s \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}.$$



 $\Pi_1$  is the solution space to  $A\mathbf{x} = \mathbf{0}$ .  $\Pi_2$  is the set of all solutions to  $A\mathbf{x} = \mathbf{b}$ .

$$\mathbf{x}_p = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}$$
 and  $\mathbf{x}_h = r \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + s \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}$ 

# 4.9

## Rank of a Matrix

In this section we obtain another effective method for finding a basis for a vector space V spanned by a given set of vectors  $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ . In Section 4.6 we developed a technique for choosing a basis for V that is a subset of S (Theorem 4.9). The method to be developed in this section produces a basis for V that is not guaranteed to be a subset of S. We shall also attach a unique number to a matrix A that we later show gives us information about the dimension of the solution space of a homogeneous system with coefficient matrix A.

Let

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

be an  $m \times n$  matrix. The rows of A, considered as vectors in  $R_n$ , span a subspace of  $R_n$  called the **row space** of A. Similarly, the columns of A, considered as vectors in  $R^m$ , span a subspace of  $R^m$  called the **column space** of A.

#### **EXAMPLE 1**

Find a basis for the subspace V of  $R_5$  that is spanned by  $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$ , where

$$\mathbf{v}_1 = \begin{bmatrix} 1 & -2 & 0 & 3 & -4 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 3 & 2 & 8 & 1 & 4 \end{bmatrix},$$
  
 $\mathbf{v}_3 = \begin{bmatrix} 2 & 3 & 7 & 2 & 3 \end{bmatrix}, \quad \text{and} \quad \mathbf{v}_4 = \begin{bmatrix} -1 & 2 & 0 & 4 & -3 \end{bmatrix}.$ 

#### Solution

Note that V is the row space of the matrix A whose rows are the given vectors.

$$A = \begin{bmatrix} 1 & -2 & 0 & 3 & -4 \\ 3 & 2 & 8 & 1 & 4 \\ 2 & 3 & 7 & 2 & 3 \\ -1 & 2 & 0 & 4 & -3 \end{bmatrix}.$$

Using elementary row operations, we find that A is row equivalent to the matrix (verify)

$$B = \begin{bmatrix} 1 & 0 & 2 & 0 & 1 \\ 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix},$$

which is in reduced row echelon form. The row spaces of A and B are identical, and a basis for the row space of B consists of

$$\mathbf{w}_1 = \begin{bmatrix} 1 & 0 & 2 & 0 & 1 \end{bmatrix}, \quad \mathbf{w}_2 = \begin{bmatrix} 0 & 1 & 1 & 0 & 1 \end{bmatrix},$$
  
and  $\mathbf{w}_3 = \begin{bmatrix} 0 & 0 & 0 & 1 & -1 \end{bmatrix}.$ 

#### Example 2:

Find a basis for the row space of the matrix A defined in the solution of Example 1 that contains only row vectors from A. Also, compute the row rank of A.

#### Solution

Using the procedure in the alternative proof of Theorem 4.9, we form the equation

$$a_{1}\begin{bmatrix} 1 & -2 & 0 & 3 & -4 \end{bmatrix} + a_{2}\begin{bmatrix} 3 & 2 & 8 & 1 & 4 \end{bmatrix} + a_{3}\begin{bmatrix} 2 & 3 & 7 & 2 & 3 \end{bmatrix} + a_{4}\begin{bmatrix} -1 & 2 & 0 & 4 & -3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 & 2 & -1 & 0 & 0 & 0 & 0 & 0 \\ -2 & 2 & 3 & 2 & 0 & 0 & 0 & 0 \\ 0 & 8 & 7 & 0 & 0 & 0 & 0 & 0 \\ 3 & 1 & 2 & 4 & 0 & 0 & 0 \\ -4 & 4 & 3 & -3 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} A^{T} \mid \mathbf{0} \end{bmatrix}; \tag{1}$$

that is, the coefficient matrix is  $A^T$ . Transforming the augmented matrix  $\begin{bmatrix} A^T & \mathbf{0} \end{bmatrix}$  in (1) to reduced row echelon form, we obtain (verify)

Since the leading 1's in (2) occur in columns 1, 2, and 3, we conclude that the first three rows of A form a basis for the row space of A. That is,

$$\{[1 -2 0 3 -4], [3 2 8 1 4], [2 3 7 2 3]\}$$

is a basis for the row space of A. The row rank of A is 3.

Find a basis for the column space of the matrix A defined in the solution of Example 1, and compute the column rank of A.

#### Solution 1

Writing the columns of A as row vectors, we obtain the matrix  $A^T$ , which when transformed to reduced row echelon form is (as we saw in Example 4)

$$\begin{bmatrix} 1 & 0 & 0 & \frac{11}{24} \\ 0 & 1 & 0 & -\frac{49}{24} \\ 0 & 0 & 1 & \frac{7}{3} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Thus, the vectors  $\begin{bmatrix} 1 & 0 & 0 & \frac{11}{24} \end{bmatrix}$ ,  $\begin{bmatrix} 0 & 1 & 0 & -\frac{49}{24} \end{bmatrix}$ , and  $\begin{bmatrix} 0 & 0 & 1 & \frac{7}{3} \end{bmatrix}$  form a

basis for the row space of  $A^T$ . Hence the vectors

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ \frac{11}{24} \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ -\frac{49}{24} \end{bmatrix}, \text{ and } \begin{bmatrix} 0 \\ 0 \\ 1 \\ \frac{7}{3} \end{bmatrix}$$

form a basis for the column space of A, and we conclude that the column rank of A is 3.

#### Solution 2

If we want to find a basis for the column space of A that contains only the column vectors from A, we follow the procedure developed in the proof of Theorem 4.9, forming the equation

$$a_{1} \begin{bmatrix} 1\\3\\2\\-1 \end{bmatrix} + a_{2} \begin{bmatrix} -2\\2\\3\\2 \end{bmatrix} + a_{3} \begin{bmatrix} 0\\8\\7\\0 \end{bmatrix} + a_{4} \begin{bmatrix} 3\\1\\2\\4 \end{bmatrix} + a_{5} \begin{bmatrix} -4\\4\\3\\-3 \end{bmatrix} = \begin{bmatrix} 0\\0\\0\\0 \end{bmatrix}$$

whose augmented matrix is  $[A \mid \mathbf{0}]$ . Transforming this matrix to reduced row echelon form, we obtain (as in Example 1)

$$\begin{bmatrix} 1 & 0 & 2 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

Since the leading 1's occur in columns 1, 2, and 4, we conclude that the first, second, and fourth columns of A form a basis for the column space of A. That is,

$$\left\{ \begin{bmatrix} 1\\3\\2\\-1 \end{bmatrix}, \begin{bmatrix} -2\\2\\3\\2 \end{bmatrix}, \begin{bmatrix} 3\\1\\2\\4 \end{bmatrix} \right\}$$

is a basis for the column space of A. The column rank of A is 3.

**DEFINITION 4.15** The dimension of the row (column) space of A is called the **row** (**column**) rank of A.

**Theorem 4.18** The row rank and column rank of the  $m \times n$  matrix  $A = [a_{ij}]$  are equal.

**Theorem 4.19** If A is an  $m \times n$  matrix, then rank A + nullity A = n.

#### Question:- For given matrix, Find

- (a) Basis for row space that are not rows (vectors) of A
- (b) Basis for row space that are rows (vectors) of A
- (c) Basis for column space that are not columns (vectors) of A
- (d) Basis for column space that are columns (vectors) of A
- (e) Prove that rank A + nullity A = number of columns for following matrix.

(a) Answer (a) Basis for row space that are not rows (vectors) of A

$$w_1 = [1 \quad 0 \quad 2 \quad 0 \quad 1]; w_2 = [0 \quad 1 \quad 2 \quad 0 \quad -1]; w_3 = [0 \quad 0 \quad 0 \quad 1 \quad 2]$$

(d) Basis for column space that are columns (vectors) of A

$$v_{1} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \\ 2 \end{bmatrix}; v_{2} = \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \\ 1 \end{bmatrix}; v_{3} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

(b) Basis for row space that are rows (vectors) of A

$$w_1 = [1 \quad 1 \quad 4 \quad 1 \quad 2]; w_2 = [0 \quad 1 \quad 2 \quad 1 \quad 1]; w_3 = [0 \quad 0 \quad 0 \quad 1 \quad 2]$$

(c) Basis for column space that are not columns (vectors) of A

$$v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \\ 2 \end{bmatrix}; v_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ -2 \\ -1 \end{bmatrix}; v_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \\ -1 \end{bmatrix}$$

Row rank=number of non-zero rows of A in RREF=3

Column rank= number of leading ones=3

Rank of matrix A = Row rank = Column rank = 3

Now to find nullity (dimension of null or solution space) augment RREF with null vector. i.e.,

$$\begin{bmatrix} \mathbf{1} & 0 & 2 & 0 & 1 & | & 0 \\ 0 & \mathbf{1} & 2 & 0 & -1 & | & 0 \\ 0 & 0 & 0 & \mathbf{1} & 2 & | & 0 \\ 0 & 0 & 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & 0 & 0 & | & 0 \end{bmatrix}$$

$$x_4 + 2x_5 = 0$$
;  $x_2 + 2x_3 - x_5 = 0$ ;  $x_1 + 2x_3 + x_5 = 0$ 

$$x_4 = -2x_5$$
;  $x_2 = -2x_3 + x_5$ ;  $x_1 = -2x_3 - x_5$ 

Suppose  $x_5 = r$  then  $x_4 = -2r$ ;

Suppose  $x_3 = s$  then  $x_2 = -2s + r$ ;  $x_1 = -2s - r$ 

$$X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -2s - r \\ -2s + r \\ s \\ -2r \\ r \end{bmatrix} = r \begin{bmatrix} -1 \\ 1 \\ 0 \\ -2 \\ 1 \end{bmatrix} + s \begin{bmatrix} -2 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

Basis for null/solution space= 
$$\left\{ \begin{bmatrix} -1\\1\\0\\-2\\1 \end{bmatrix}, \begin{bmatrix} -2\\-2\\1\\0\\0 \end{bmatrix} \right\}$$

Nullity of A=2

$$rank A + nullity A = number of columns$$

$$3 + 2 = 5$$