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Robot Name:			
Builder's Name:			

Power: 4 x AA (6 Volts)

Motion: 2 x 28byj Stepper Motors 5V 1/64 Ratio

Control: Adafruit Trinket Pro 3V

MCU: Atmel 328p 8-bit, 12 MHz, 32 Kbyte RAM

Design Parameters:

wheel_dia (mm): _____ wheel_base (mm): _____ steps rev: PEN_UP (angle): _____ PEN DOwn (angle):

Input / Output Pins:

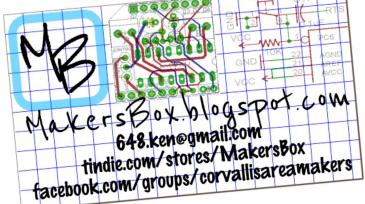
leftSensor = leftLight = rightSensor = ____ rightLight =

Programming: https://learn.adafruit.com/introducing-pro-trinket

Example Programs: https://goo.gl/ho7PZH

Turtle Commands:

left(degrees) right(degrees) forward(distance) mm backwards(distance) mm pendown()



What is a Robot?

"A robot is a machine—especially one programmable by a computer capable of carrying out a complex series of actions automatically. " - Wikipedia

