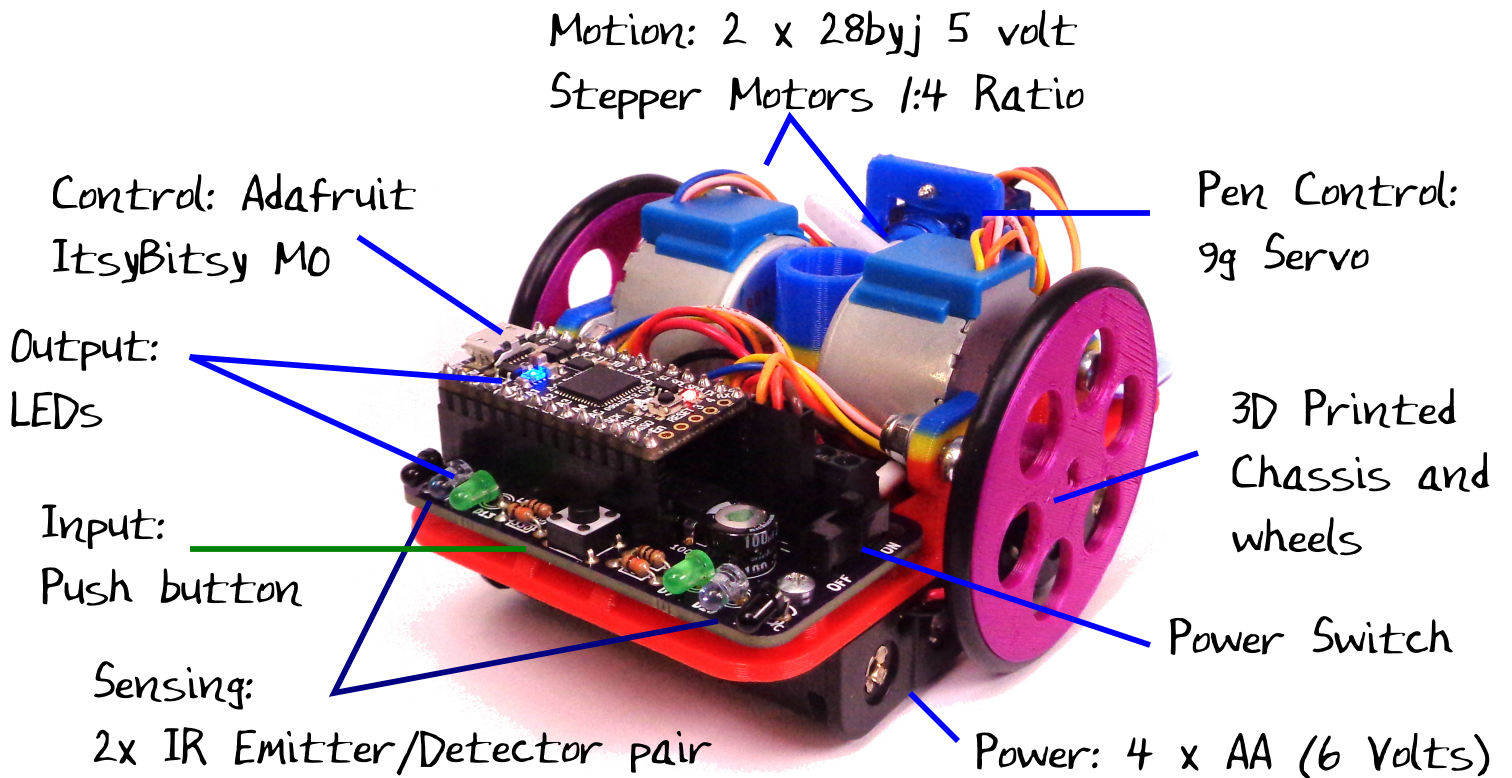


ChickTECH Turtle Robot Datasheet

Robot Name: _____

Builder's Name: _____



Programming (via USB):

- Python
- Arduino C



Calibration Parameters:

wheel_dia (mm): _____

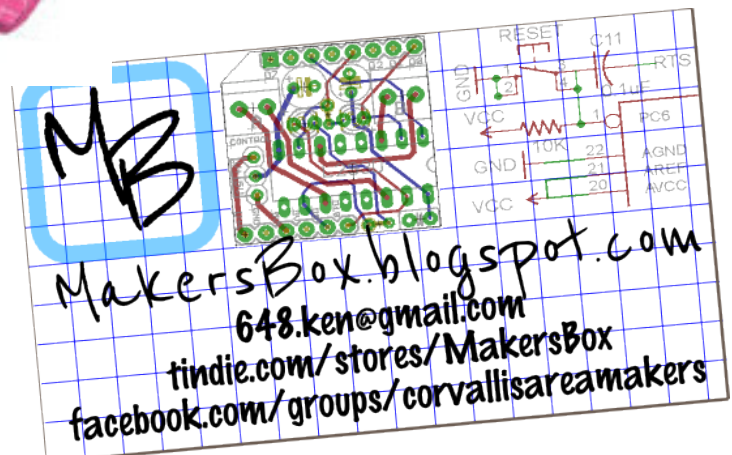
wheel_base (mm): _____

PEN_UP (angle): _____

PEN_Down (angle): _____

Turtle Commands:

```
left(degrees)
right(degrees)
forward(distance) mm
backwards(distance) mm
penup()
pendown()
goto(x, y)
```



Full details at <http://bit.ly/OSTurtle>