

# Remote control heavy hammer car

#### Goal

In this lesson, we will learn to use the emakefun infrared remote control to control the Magic\_Car heavy hammer car

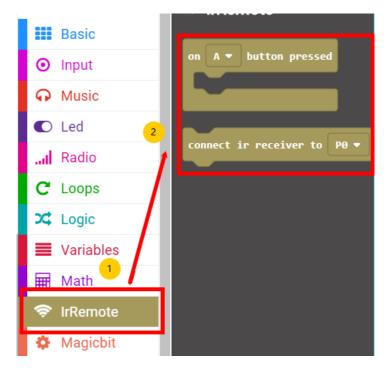
### Programming method

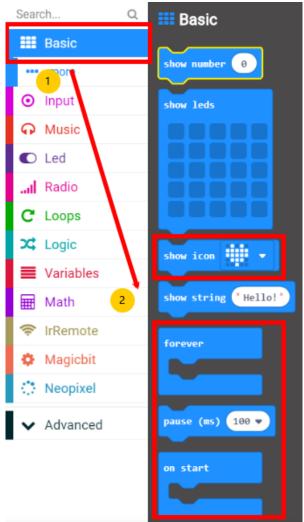
- (1) online programming: connect micro:bit with the computer through the USB cable, open my computer, find the MICROBIT memory and open it, double-click MICROBIT.HTM, and open the browser programming page. After creating a new project, click advanced, click expand, enter the extension package address<a href="https://github.com/emakefun/pxt-magicbit.git">https://github.com/emakefun/pxt-magicbit.git</a> enter enter or search, add the Microbit extension package, and you can start programming the car
- (2) offline programming: open the offline programming software, enter the programming interface, create a new project, click advanced, click expand, enter the address of the extension package <a href="https://github.com/emakefun/pxt-magicbit.git">https://github.com/emakefun/pxt-magicbit.git</a> and press enter or search, add the Microbit extension package, and then you can start programming and control the car.

## Block programming

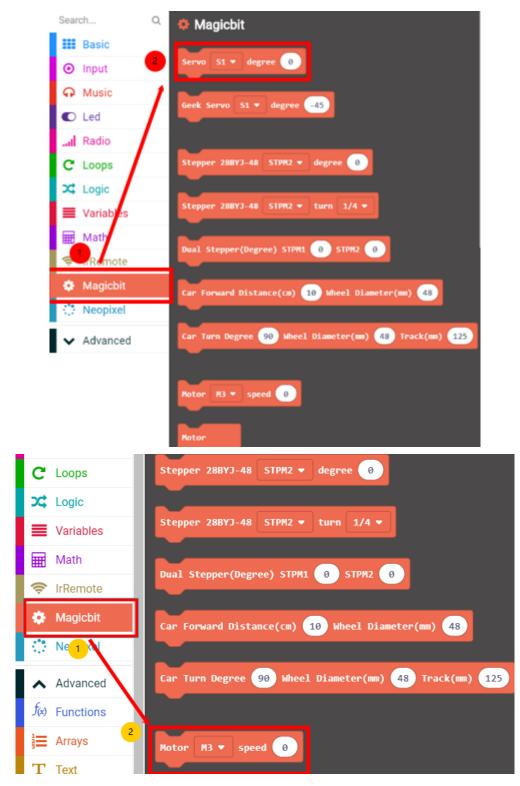
1. Location of building blocks required





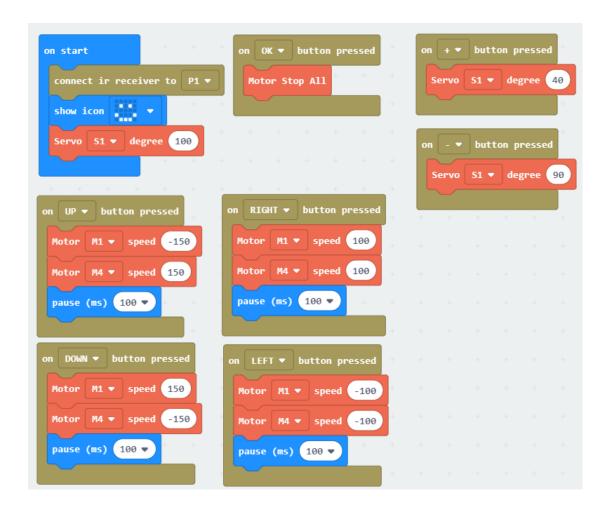






1、 Final program building block combination





### Wiring

#### 1. Connection of steering gear;

The car steering gear is connected to the S1 pin of the PWM steering gear of the expansion board, in which the yellow line of the steering gear is connected to the blue pin of the expansion board, the red line of the steering gear is connected to the red pin of the control board, and the brown line of the steering gear is connected to the black GND pin of the control board.

#### 2. Motor connection;

The motor to the left of the car is connected to the extension board M4 interface. The motor to the right of the car is connected to the expanded M1 interface.

- 3. Installation of jumper cap of infrared receiving head; The jumper cap between the infrared receiver of the control board and the buzzer should be inserted well, otherwise the infrared receiver cannot be used.
- 4.the other wire of the headlamp is connected to the blue pin of the expansion board P8



## The experimental results

After downloading the program to the microbit motherboard of Magic\_Car car, open the main switch of the expansion board, microbit displays a smiley face, when the button up of the remote control is pressed, the heavy hammer car will advance; When the DOWN button of the remote control is pressed, the heavy hammer truck will fall back. When the LEFT button of the remote control is pressed, the heavy hammer truck will turn LEFT; When the RIGHT button of the remote control is pressed, the heavy hammer will turn RIGHT; When the button A or B of the remote control is pressed, the hammer arm of the heavy hammer truck will rise or fall to the corresponding position. In actual operation, the Angle of the steering gear can be adjusted to adjust the height of the hammer arm.