

Dancing forklift

Goal

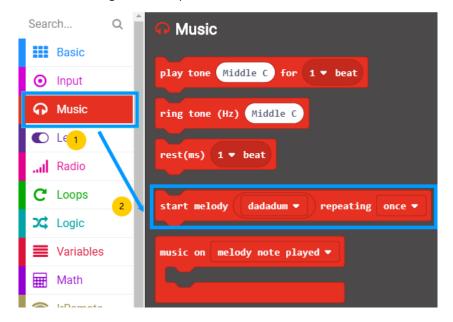
In this lesson, we will learn how to control the steering gear, motor and RGB lamp of the Magic_Car forklift to achieve the forklift dancing.

Programming method

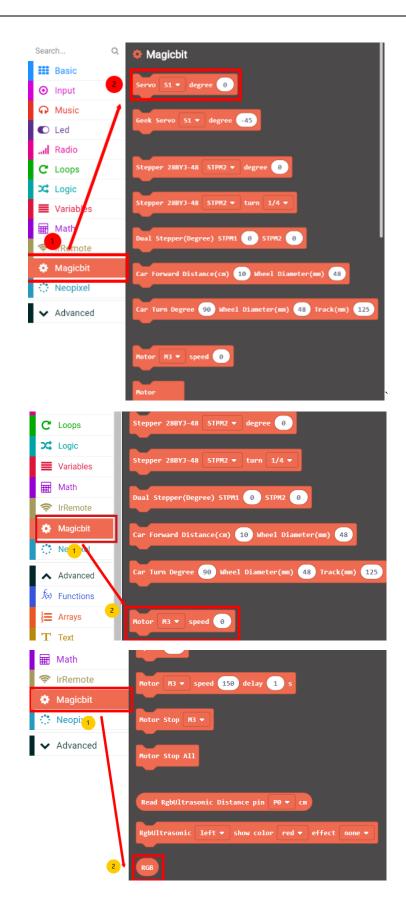
- (1) online programming: connect micro:bit with the computer through the USB cable, open my computer, find the MICROBIT memory disk and open it, double-click MICROBIT.HTM, and open the browser programming page. After creating a new project, click advanced, click expand, enter the extension package address https://github.com/emakefun/pxt-magicbit.git, enter enter or search, add the Microbit extension package, and you can start programming the car.
- (2) offline programming: open the offline programming software, enter the programming interface, create a new project, click advanced, click expand, enter the address of the extension package https://github.com/emakefun/pxt-magicbit.git, and press enter or search, add the Microbit extension package, and then you can start programming and control the car.

Block programming

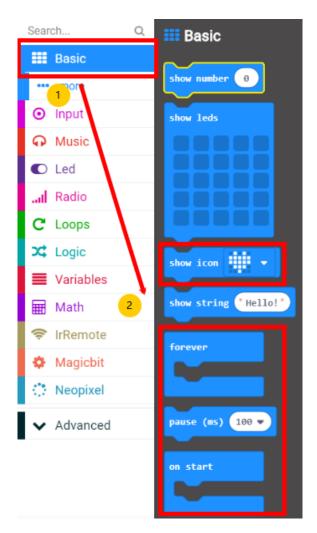
1. Location of building blocks required

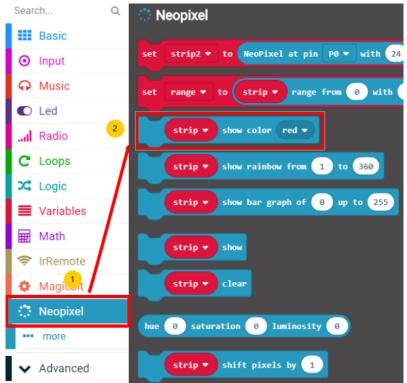






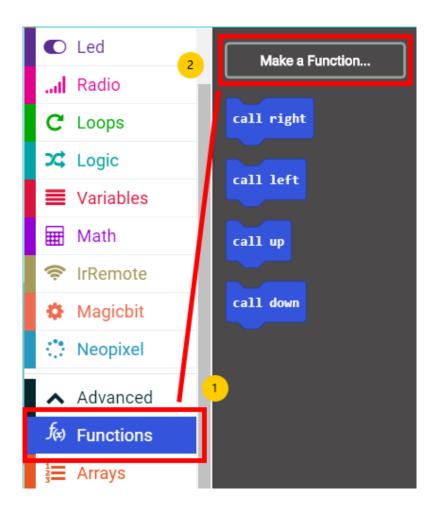


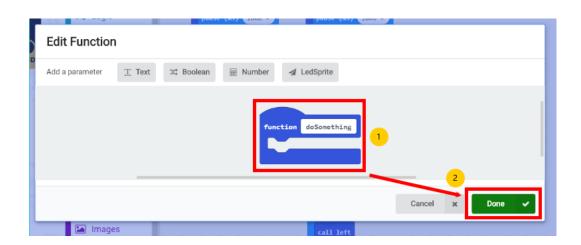






2. Create function blocks





3. Final program building block combination



```
函数 left
函数 right
                                                                          M1 ▼ speed (-150
       M1 ▼ speed 150
                                        M4 ▼ speed -150
                                                                          M4 ▼ speed 150
       M4 ▼ speed (150
                                       RGB show color indigo ▼
       RGB show color green ▼
                                                                         RGB show color red ▼
      S1 ▼ degree 10
                                        S1 ▼ degree 10
                                  pause (ms) 250 ▼
                                                                    pause (ms) 250 ▼
 pause (ms) 250 ▼
 pause (ms) 250 ▼
                                                                    pause (ms) 250 ▼
                                  pause (ms) 250 ▼
                       call up
                                                                                   ed -150
                        call dow
                                                                              show color purple ▼
                        call left
                                                                               degree 10
                       call right
                                                                     pause (ms) 250 ▼
                        call right
                        call left
                                                                    pause (ms) 250 ▼
```

Wiring

1. Connection of steering gear;

The car steering gear is connected to the S1 pin of the PWM steering gear of the expansion board, in which the yellow line of the steering gear is connected to the blue pin of the expansion board, the red line of the steering gear is connected to the red pin of the control board, and the brown line of the steering gear is connected to the black GND pin of the control board.

2. Motor connection:

The motor to the left of the car is connected to the extension board M4 interface. The motor to the right of the car is connected to the expanded M1 interface.

The experimental results

Download program to Magic_Car car microbit motherboard, open expansion board master switch, microbit show smiling face, buzzer will play a funk, and then Magic_Car forklift move, backward, turn left, turn right, turn right, turn left again, in the process of moving forklift RGB will change color, forklift front fork also move down, so cycle.