Multi-Weighted Reachability Games

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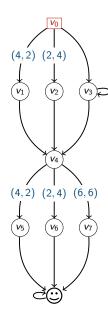
1. UMONS – Université de Mons, Belgium. 2. F.R.S.-FNRS & UMONS – Université de Mons, Belgium.

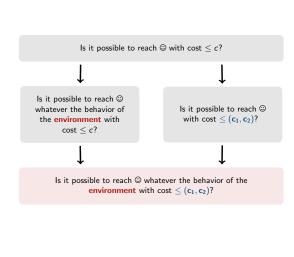
Highlights'23

2 Studied problems

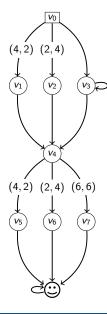
3 Conclusion

Reachability Games









- Turn-based;
- Two players: Player \bigcirc and Player \square ;
- A *d*-weighted graph $G = (V, E, (w_i)_{1 \le i \le d})$

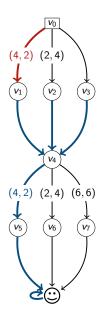
Quantitative reachability objective

Given a target set $\mathsf{F} \subseteq V$, for all **plays** (infinite paths in G) $\rho = \rho_0 \rho_1 \ldots$:

$$\mathsf{Cost}_i(
ho) = egin{cases} \sum_{n=0}^{k-1} w_i(
ho_n,
ho_{n+1}) & \mathsf{if} \ k \ \mathsf{is} \ \mathsf{the} \ \mathsf{least} \\ & \mathsf{index} \ \mathsf{st.}
ho_k \in \mathsf{F} \\ +\infty & \mathsf{otherwise} \end{cases}$$

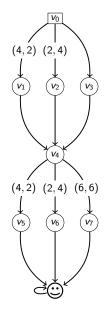
Rem: same target set for all dimensions. Ex:

- $Cost(v_0v_3^{\omega}) = (Cost_1(v_0v_3^{\omega}), Cost_2(v_0v_3^{\omega})) = (+\infty, +\infty)$
- \blacksquare Cost $(v_0v_1v_4v_5(\textcircled{@})^{\omega})=(10,6)$



- A strategy for Player \bigcirc : $\sigma_{\bigcirc}: V^*V_{\bigcirc} \longrightarrow V$.
- Given a **strategy profile** $(\sigma_{\bigcirc}, \sigma_{\square})$ and an initial vertex $v_0 \leadsto$ only one consistent play $\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_{v_0}$ called the **outcome**.

 $\underline{\mathsf{Ex}}: \langle \sigma_{\bigcirc}, \underline{\sigma_{\square}} \rangle_{v_0} = v_0 v_1 v_4 v_5 (\textcircled{@})^{\omega}.$

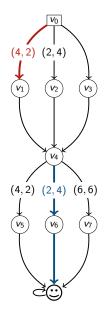


Player \bigcirc can **ensure** a cost profile $\mathbf{c} = (c_1, \ldots, c_d)$ from v if **there exists** a strategy σ_{\bigcirc} such that **for all strategies** σ_{\square} of Player \square :

$$\mathsf{Cost}(\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_{\nu}) \leq_{\mathsf{C}} \mathbf{c} = (c_1, \ldots, c_d)$$

Ex:

 \blacksquare (8,8) \rightsquigarrow Yes. (with memory!)



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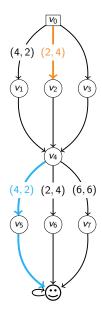
$$Cost(\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_{\nu}) \leq_{\mathsf{C}} \mathbf{c} = (c_1, \ldots, c_d)$$

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$$\longmapsto \qquad (8,8)$$

Player \bigcirc can adapt his strategy in function of the choice of Player $\square \leadsto$ finite-memory strategy!



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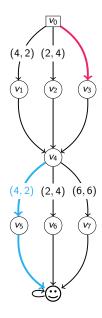
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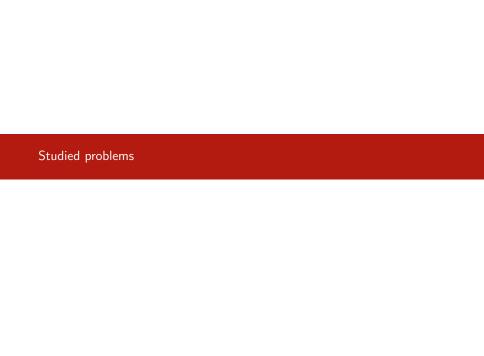
• $(8,8) \rightsquigarrow$ Yes. (with memory!)

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 $\mathsf{Ensure}(\mathsf{v}) = \{ \mathbf{c} \in \overline{\mathbb{N}}^d \mid \exists \sigma_\bigcirc \ \mathsf{st.} \ \forall \sigma_\square, \ \mathsf{Cost}(\langle \sigma_\bigcirc, \sigma_\square \rangle_\mathsf{v}) \leq_\mathsf{C} \mathbf{c} \}.$

 $minimal(Ensure(v)) = Pareto(v) \rightsquigarrow Pareto frontier from v.$

For $\mathbf{c} = (c_1, \dots, c_d) \in \mathsf{Pareto}(v)$, a strategy σ_{\bigcirc} is **c-Pareto-optimal** if σ_{\bigcirc} ensures \mathbf{c} from v.



Studied problems

- Compute the Pareto frontier and Pareto-optimal strategies.
- Decide the constrained existence problem.

Constrained existence problem (CEP)

Given a game, a vertex $v \in V$ and $\mathbf{c} \in \mathbb{N}^d$, does there exist a strategy σ_{\bigcirc} of Player \bigcirc such that for all strategies of Player \square , we have:

$$\mathsf{Cost}(\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_{\nu}) \leq_{\mathsf{C}} \mathbf{c}$$

Ensure^k(v) = {
$$\mathbf{c} \in \overline{\mathbb{N}}^d \mid \exists \sigma_{\bigcirc} \text{ st. } \forall \sigma_{\square},$$

 $\mathsf{Cost}(\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_v) \leq_{\mathsf{C}} \mathbf{c} \wedge |\langle \sigma_{\bigcirc}, \sigma_{\square} \rangle_v|_F \leq k$ }.

The algorithm computes, step by step, the sets $I^k(v)$ for all $v \in V$.

For all $k \in \mathbb{N}$ and all $v \in V$, $I^k(v) = minimal(Ensure^k(v))$

There exists $k^* \in \mathbb{N}$ such that for all $v \in V$ and for all $\ell \in \mathbb{N}$, $I^{k^*}(v) = I^{k^*+\ell}(v)$.

For all
$$v \in V$$
, $I^{k^*}(v) = Pareto(v)$.

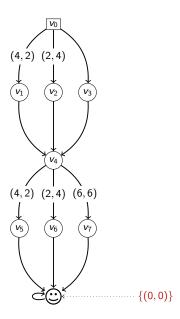
Theorem

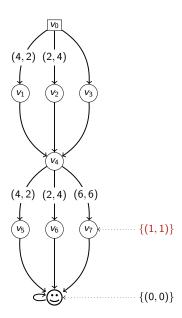
The fixpoint algorithm runs in time polynomial in W and |V| and is **exponential** in d.

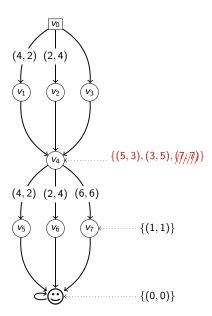
Where W is the maximal weight on an edge.

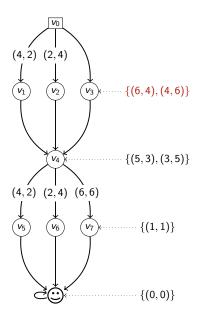
Computing Pareto(v) and Pareto-optimal strategies

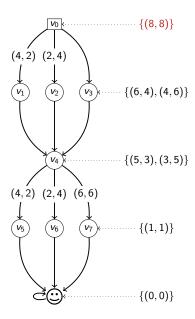
```
for v \in F do I^{0}(v) = \{0\}
for v \notin F do I^0(v) = {\infty}
repeat
     for v \in V do
           if v \in F then I^{k+1}(v) = \{0\}
                 else if v \in V_{\bigcirc} then
                  I^{k+1}(v) = \text{minimal} \left( \bigcup_{v' \in \text{supp}(v)} \uparrow I^k(v') + \mathbf{w}(v, v') \right)
                 else if v \in V_{\square} then
                 I^{k+1}(v) = \min \left( \bigcap_{v' \in \text{const}(v)} \uparrow I^k(v') + \mathbf{w}(v, v') \right)
until I^{k+1}(v) = I^k(v) for all v \in V
```











Pareto-optimal strategies

```
for v \in F do I^{0}(v) = \{0\}
for v \notin F do I^0(v) = {\infty}
repeat
       for v \in V do
               \overline{\mathbf{if} \ \ v \in} \ \mathsf{F} \ \mathbf{then} \ \mathsf{I}^{k+1}(v) = \{\mathbf{0}\}\
                        else if \underline{v} \in V_{\bigcirc} then
                              \mathsf{I}^{k+1}(v) = \mathsf{minimal}\left(\bigcup_{v' \in \mathsf{succ}(v)} \uparrow \mathsf{I}^k(v') + \mathbf{w}(v,v')\right)
                                        for x \in I^{k+1}(v) do
                                                \overrightarrow{\text{if } \mathbf{x} \in I^k(\mathbf{v})} then f_{\mathbf{v}}^{k+1}(\mathbf{x}) = f_{\mathbf{v}}^k(\mathbf{x})
                                             f_v^{k+1}(\mathbf{x}) = (v', \mathbf{x}') where v' and \mathbf{x}' are such that v' \in \text{succ}(v), \mathbf{x} = \mathbf{x}' + \mathbf{w}(v, v') and \mathbf{x}' \in I^k(v')
                        else if v \in V_{\square} then
                        I^{k+1}(v) = \min \left\{ \bigcap_{v' \in \mathsf{ence}(v)} \uparrow I^k(v') + \mathbf{w}(v, v') \right\}
until I^{k+1}(v) = I^k(v) for all v \in V
```

Computing Pareto-optimal strategies

Given $u \in V$ and $\mathbf{c} \in I^*(u) \setminus \{\infty\}$, we define a strategy σ_{\bigcirc}^* from u such that for all $hv \in \operatorname{Hist}_{\bigcirc}(u)$, let $\mathcal{C}(hv) = \{\mathbf{x}' \in I^*(v) \mid \mathbf{x}' \leq_{\mathsf{C}} \mathbf{c} - \operatorname{Cost}(hv) \land \mathbf{x}' \leq_{\mathsf{L}} \mathbf{c} - \operatorname{Cost}(hv)\}$,

$$\sigma_{\bigcirc}^*(\mathit{hv}) = \begin{cases} v' & \text{for some } v' \in \mathsf{succ}(v), \text{ if } \mathcal{C}(\mathit{hv}) = \emptyset \\ f_v^*(\mathbf{x})[1] & \text{where } \mathbf{x} = \min_{\leq \mathsf{L}} \mathcal{C}(\mathit{hv}), \text{ if } \mathcal{C}(\mathit{hv}) \neq \emptyset \end{cases}.$$

 σ_{\bigcirc}^* is a **c**-Pareto-optimal strategy from u.



Conclusion

	Componentwise order	Lexicographic order
minimal(Ensure(v))	in exponential time	in polynomial time
CEP	PSPACE-complete	in P

- uniform approach to compute minimal(Ensure(v)) both for the componentwise order and the lexicographic order → fixpoint algorithm;
- (Pareto)-optimal strategies can be synthesized thanks to the fixpoint algorithm;
- Pareto-optimal strategies may require memory.