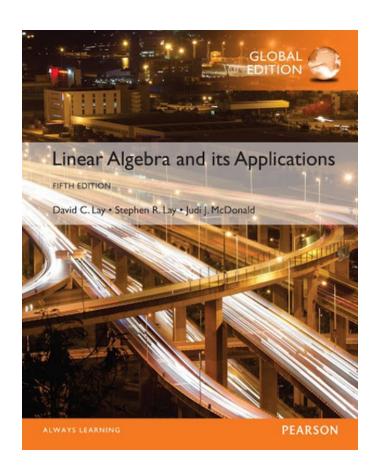
# Vector Spaces

# **VECTOR SPACES AND SUBSPACES**



- **Definition:** A **vector space** is a nonempty set *V* of objects, called *vectors*, on which are defined two operations, called *addition and multiplication by scalars* (real numbers), subject to the ten axioms (or rules) listed below. The axioms must hold for all vectors **u**, **v**, and **w** in *V* and for all scalars *c* and *d*.
  - 1. The sum of  $\mathbf{u}$  and  $\mathbf{v}$ , denoted by  $\mathbf{u} + \mathbf{v}$ , is in V.
  - 2. u + v = v + u.
  - 3. (u + v) + w = u + (v + w).
  - 4. There is a zero vector 0 in V such that

$$u + 0 = u$$
.

- 5. For each **u** in V, there is a vector  $-\mathbf{u}$  in V such that  $\mathbf{u} + (-\mathbf{u}) = 0$ .
- 6. The scalar multiple of **u** by c, denoted by c**u**, is in V.
- 7. c(u + v) = cu + cv.
- 8. (c+d)u = cu + du.
- 9.  $c(d\mathbf{u}) = (cd)\mathbf{u}$ .
- 10.1u = u.
- Using these axioms, we can show that the zero vector in Axiom 4 is unique, and the vector—u, called the **negative** of u, in Axiom 5 is unique for each u in V.

• For each **u** in V and scalar c,

$$0u = 0$$
 (1)  
 $c0 = 0$  (2)  
 $-u = (-1)u$  (3)

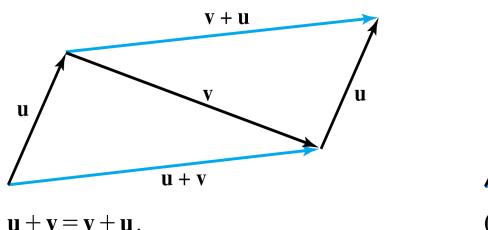
**Example 2:** Let V be the set of all arrows (directed line segments) in three-dimensional space, with two arrows regarded as equal if they have the same length and point in the same direction. Define addition by the parallelogram rule, and for each  $\mathbf{v}$  in V, define  $c\mathbf{v}$  to be the arrow whose length is |c| times the length of  $\mathbf{v}$ , pointing in the same direction as  $\mathbf{v}$  if  $c \ge 0$  and otherwise pointing in the opposite direction.

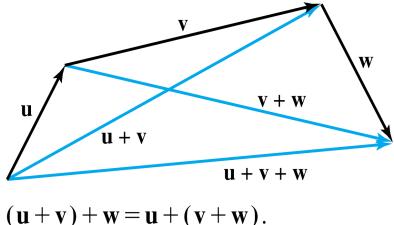
See the following figure below. Show that V is a vector space.

• **Solution:** The definition of *V* is geometric, using concepts of length and direction.

- No *x y z*-coordinate system is involved.
- An arrow of zero length is a single point and represents the zero vector.
- The negative of  $\mathbf{v}$  is  $(-1)\mathbf{v}$ .
- So Axioms 1, 4, 5, 6, and 10 are evident. See the figures on the next slide.

# **SUBSPACES**





- **Definition:** A **subspace** of a vector space V is a subset H of V that has three properties:
  - a. The zero vector of V is in H.
  - b. H is closed under vector addition. That is, for each **u** and **v** in H, the sum **u** + **v** is in H.

## SUBSPACES

- c. H is closed under multiplication by scalars. That is, for each  $\mathbf{u}$  in H and each scalar c, the vector  $c\mathbf{u}$  is in H.
- Properties (a), (b), and (c) guarantee that a subspace H of V is itself a vector space, under the vector space operations already defined in V.
- Every subspace is a vector space.
- Conversely, every vector space is a subspace (of itself and possibly of other larger spaces).

- The set consisting of only the zero vector in a vector space V is a subspace of V, called the **zero subspace** and written as  $\{0\}$ .
- As the term **linear combination** refers to any sum of scalar multiples of vectors, and Span  $\{\mathbf{v}_1,...,\mathbf{v}_p\}$  denotes the set of all vectors that can be written as linear combinations of  $\mathbf{v}_1,...,\mathbf{v}_p$ .

- Example 10: Given  $\mathbf{v}_1$  and  $\mathbf{v}_2$  in a vector space V, let  $H = \operatorname{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$ . Show that H is a subspace of V.
- Solution: The zero vector is in H, since  $0 = 0v_1 + 0v_2$ .
- To show that *H* is closed under vector addition, take two arbitrary vectors in *H*, say,

$$u = s_1 v_1 + s_2 v_2$$
 and  $w = t_1 v_1 + t_2 v_2$ .

• By Axioms 2, 3, and 8 for the vector space V,

$$u + w = (s_1 v_1 + s_2 v_2) + (t_1 v_1 + t_2 v_2)$$
$$= (s_1 + t_1) v_1 + (s_2 + t_2) v_2$$

• So u + w is in H.

Furthermore, if c is any scalar, then by Axioms 7 and 9,  $c\mathbf{u} = c(s_1\mathbf{v}_1 + s_2\mathbf{v}_2) = (cs_1)\mathbf{v}_1 + (cs_2)\mathbf{v}_2$ which shows that curis in H and H is closed under scalar

which shows that  $c\mathbf{u}$  is in H and H is closed under scalar multiplication.

• Thus H is a subspace of V.

- Theorem 1: If  $\mathbf{v}_1, ..., \mathbf{v}_p$  are in a vector space V, then Span  $\{\mathbf{v}_1, ..., \mathbf{v}_p\}$  is a subspace of V.
- We call Span  $\{\mathbf{v}_1,...,\mathbf{v}_p\}$  the subspace spanned (or generated) by  $\{\mathbf{v}_1,...,\mathbf{v}_p\}$ .
- Give any subspace H of V, a **spanning** (or **generating**) set for H is a set  $\{v_1,...,v_p\}$  in H such that

$$H = \operatorname{Span}\{\mathbf{v}_1, ... \mathbf{v}_p\}.$$