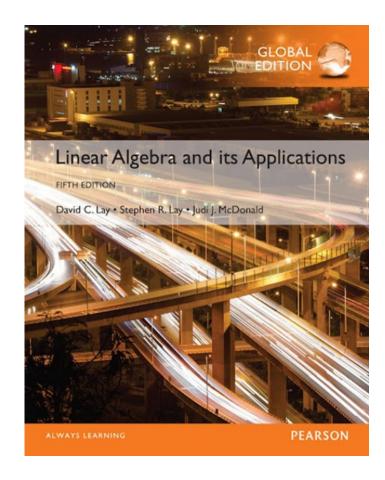
Matrix Algebra

2.3

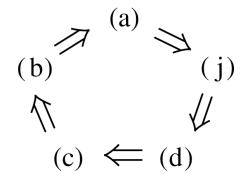
# CHARACTERIZATIONS OF INVERTIBLE MATRICES



- **Theorem 8:** Let A be a square  $n \times n$  matrix. Then the following statements are equivalent. That is, for a given A, the statements are either all true or all false.
  - a. A is an invertible matrix.
  - b. A is row equivalent to the  $n \times n$  identity matrix.
  - c. A has n pivot positions.
  - d. The equation Ax = 0 has only the trivial solution.
  - e. The columns of A form a linearly independent set.

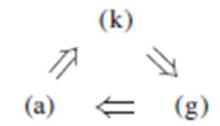
- f. The linear transformation  $x \mapsto Ax$  is one-to-one.
- g. The equation Ax = bhas at least one solution for each b in  $\mathbb{R}^n$ .
- h. The columns of A span  $\mathbb{R}^n$ .
- i. The linear transformation  $x \mapsto Ax$  maps  $\mathbb{R}^n$  onto  $\mathbb{R}^n$ .
- j. There is an  $n \times n$  matrix C such that CA = I.
- k. There is an  $n \times n$  matrix D such that AD = I.
- *l.*  $A^T$  is an invertible matrix.

- First, we need some notation.
- If the truth of statement (a) always implies that statement (j) is true, we say that (a) *implies* (j) and write (a)  $\Rightarrow$  (j).
- The proof will establish the "circle" of implications as shown in the following figure.



• If any one of these five statements is true, then so are the others.

- Finally, the proof will link the remaining statements of the theorem to the statements in this circle.
- **Proof:** If statement (a) is true, then  $A^{-1}$  works for C in (j), so (a)  $\Rightarrow$  (j).
- Next,  $(j) \Rightarrow (d)$ .
- Also,  $(d) \Rightarrow (c)$ .
- If A is square and has n pivot positions, then the pivots must lie on the main diagonal, in which case the reduced echelon form of A is  $I_n$ .
- Thus  $(c) \Rightarrow (b)$ .
- Also,  $(b) \Rightarrow (a)$ .



$$(g) \Leftrightarrow (h) \Leftrightarrow (i)$$

$$(d) \Leftrightarrow (e) \Leftrightarrow (f)$$

- This completes the circle in the previous figure.
- Next,(a)  $\Rightarrow$  (k) because  $A^{-1}$  works for D.
- Also, $(k) \Rightarrow (g)$  and  $(g) \Rightarrow (a)$ .
- So (k) and (g) are linked to the circle.
- Further, (g), (h), and (i) are equivalent for any matrix.
- Thus, (h) and (i) are linked through (g) to the circle.
- Since (d) is linked to the circle, so are (e) and (f), because (d), (e), and (f) are all equivalent for any matrix A.
- Finally,  $(a) \Rightarrow (1)$  and  $(1) \Rightarrow (a)$ .
- This completes the proof.

- Theorem 8 could also be written as "The equation Ax = b has a *unique* solution for each **b** in  $\mathbb{R}^n$ ."
- This statement implies (b) and hence implies that A is invertible.
- The following fact follows from Theorem 8. Let A and B be square matrices. If AB = I, then A and B are both invertible, with  $B = A^{-1}$  and  $A = B^{-1}$ .
- The Invertible Matrix Theorem divides the set of all  $n \times n$  matrices into two disjoint classes: the invertible (nonsingular) matrices, and the noninvertible (singular) matrices.

• Each statement in the theorem describes a property of every  $n \times n$  invertible matrix.

- The *negation* of a statement in the theorem describes a property of every  $n \times n$  singular matrix.
- For instance, an  $n \times n$  singular matrix is *not* row equivalent to  $I_n$ , does *not* have n pivot position, and has linearly *dependent* columns.

**Example 1:** Use the Invertible Matrix Theorem to decide if *A* is invertible:

$$A = \begin{bmatrix} 1 & 0 & -2 \\ 3 & 1 & -2 \\ -5 & -1 & 9 \end{bmatrix}$$

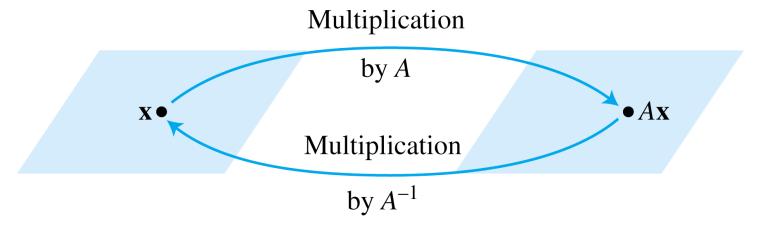
Solution:

$$A \sim \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 4 \\ 0 & -1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 4 \\ 0 & 0 & 3 \end{bmatrix}$$

- So A has three pivot positions and hence is invertible, by the Invertible Matrix Theorem, statement (c).
- The Invertible Matrix Theorem *applies only to square matrices*.
- For example, if the columns of a  $4\times3$  matrix are linearly independent, we cannot use the Invertible Matrix Theorem to conclude anything about the existence or nonexistence of solutions of equation of the form Ax = b.

# INVERTIBLE LINEAR TRANSFORMATIONS

- Matrix multiplication corresponds to composition of linear transformations.
- When a matrix A is invertible, the equation  $A^{-1}Ax = x$  can be viewed as a statement about linear transformations. See the following figure.



 $A^{-1}$  transforms A**x** back to **x**.

#### INVERTIBLE LINEAR TRANSFORMATIONS

• A linear transformation  $T: \mathbb{R}^n \to \mathbb{R}^n$  is said to be **invertible** if there exists a function  $S: \mathbb{R}^n \to \mathbb{R}^n$  such that

$$S(T(\mathbf{x})) = \mathbf{x} \quad \text{for all } \mathbf{x} \text{ in } \mathbb{R}^n \tag{1}$$

$$T(S(\mathbf{x})) = \mathbf{x} \text{ for all } \mathbf{x} \text{ in } \mathbb{R}^n$$
 (2)

**Theorem 9:** Let  $T: \mathbb{R}^n \to \mathbb{R}^n$  be a linear transformation and let A be the standard matrix for T. Then T is invertible if and only if A is an invertible matrix. In that case, the linear transformation S given by  $S(\mathbf{x}) = A^{-1}\mathbf{x}$  is the unique function satisfying equation (1) and (2).

## INVERTIBLE LINEAR TRANSFORMATIONS

- **Proof:** Suppose that *T* is invertible.
- Then (2) shows that T is onto  $\mathbb{R}^n$ , for if  $\mathbf{b}$  is in  $\mathbb{R}^n$  and  $\mathbf{x} = S(\mathbf{b})$ , then  $T(\mathbf{x}) = T(S(\mathbf{b})) = \mathbf{b}$ , so each  $\mathbf{b}$  is in the range of T.
- Thus A is invertible, by the Invertible Matrix Theorem, statement (i).
- Conversely, suppose that A is invertible, and let  $S(\mathbf{x}) = A^{-1}\mathbf{x}$ . Then, S is a linear transformation, and S satisfies (1) and (2).
- For instance,  $S(T(x)) = S(Ax) = A^{-1}(Ax) = x$ .
- Thus, T is invertible.