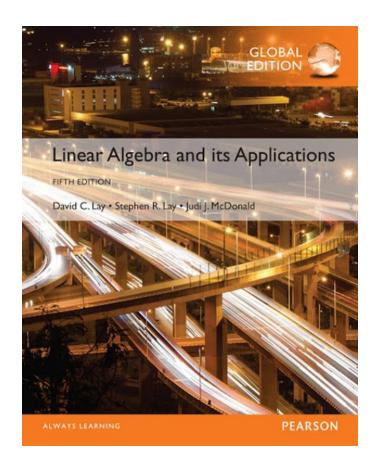
# Vector Spaces

# THE DIMENSION OF A **VECTOR SPACE**



- **Theorem 9:** If a vector space V has a basis
- B =  $\{b_1,...,b_n\}$  any set in V containing more than n vectors must be linearly dependent.
- **Proof:** Let  $\{\mathbf{u}_1, ..., \mathbf{u}_p\}$  be a set in V with more than n vectors.

The coordinate vectors  $[\mathbf{u}_1]_B$ , ...,  $[\mathbf{u}_p]_B$  form a linearly dependent set in  $\mathbb{R}^n$ , because there are more vectors (p) than entries (n) in each vector.

• So there exist scalars  $c_1, ..., c_p$ , not all zero, such that

$$c_{1} \left[ \mathbf{u}_{1} \right]_{\mathbf{B}} + \dots + c_{p} \left[ \mathbf{u}_{p} \right]_{\mathbf{B}} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$
 The zero vector in  $\mathbb{R}^{n}$ 

 Since the coordinate mapping is a linear transformation,

$$\left[c_{1}\mathbf{u}_{1} + \dots + c_{p}\mathbf{u}_{p}\right]_{\mathsf{B}} = \begin{vmatrix}0\\ \vdots\\0\end{vmatrix}$$

• The zero vector on the right displays the n weights needed to build the vector  $c_1 \mathbf{u}_1 + ... + c_p \mathbf{u}_p$  from the basis vectors in B.

- That is,  $c_1 \mathbf{u}_1 + ... + c_p \mathbf{u}_p = 0 \cdot \mathbf{b}_1 + ... + 0 \cdot \mathbf{b}_n = 0$ .
- Since the  $c_i$  are not all zero,  $\{\mathbf{u}_1, ..., \mathbf{u}_p\}$  is linearly dependent.
- Theorem 9 implies that if a vector space V has a basis  $B = \{b_1, ..., b_n\}$ , then each linearly independent set in V has no more than n vectors.

■ Theorem 10: If a vector space V has a basis of n vectors, then every basis of V must consist of exactly n vectors.

- **Proof:** Let  $B_1$  be a basis of n vectors and  $B_2$  be any other basis (of V).
- Since  $B_1$  is a basis and  $B_2$  is linearly independent,  $B_2$  has no more than n vectors, by Theorem 9.
- Also, since B<sub>2</sub> is a basis and B<sub>1</sub> is linearly independent,
  B<sub>2</sub> has at least n vectors.
- Thus  $B_2$  consists of exactly n vectors.

- **Definition:** If *V* is spanned by a finite set, then *V* is said to be **finite-dimensional**, and the **dimension** of *V*, written as dim *V*, is the number of vectors in a basis for *V*. The dimension of the zero vector space {**0**} is defined to be zero. If *V* is not spanned by a finite set, then *V* is said to be **infinite-dimensional**.
- **Example 3:** Find the dimension of the subspace

$$H = \begin{cases} \begin{bmatrix} a - 3b + 6c \\ 5a + 4d \\ b - 2c - d \\ 5d \end{bmatrix} : a, b, c, d \text{ in } \mathbb{R} \end{cases}$$

• H is the set of all linear combinations of the vectors

$$\mathbf{v}_{1} = \begin{bmatrix} 1 \\ 5 \\ 0 \\ 0 \end{bmatrix}, \mathbf{v}_{2} = \begin{bmatrix} -3 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \mathbf{v}_{3} = \begin{bmatrix} 6 \\ 0 \\ -2 \\ 0 \end{bmatrix}, \mathbf{v}_{4} = \begin{bmatrix} 0 \\ 4 \\ -1 \\ 5 \end{bmatrix}$$

- Clearly,  $\mathbf{v}_1 \neq \mathbf{0}$ ,  $\mathbf{v}_2$  is not a multiple of  $\mathbf{v}_1$ , but  $\mathbf{v}_3$  is a multiple of  $\mathbf{v}_2$ .
- By the Spanning Set Theorem, we may discard  $v_3$  and still have a set that spans H.

#### SUBSPACES OF A FINITE-DIMENSIONAL SPACE

- Finally,  $v_4$  is not a linear combination of  $v_1$  and  $v_2$ .
- So  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_4\}$  is linearly independent and hence is a basis for H.
- Thus  $\dim H = 3$ .

■ Theorem 11: Let *H* be a subspace of a finite-dimensional vector space *V*. Any linearly independent set in *H* can be expanded, if necessary, to a basis for *H*. Also, *H* is finite-dimensional and

$$\dim H \leq \dim V$$

# SUBSPACES OF A FINITE-DIMENSIONAL SPACE

- **Proof:** If  $H = \{0\}$ , then certainly dim  $H = 0 \le \dim V$ .
- Otherwise, let  $S = \{\mathbf{u}_1, ..., \mathbf{u}_k\}$  be any linearly independent set in H.

- If S spans H, then S is a basis for H.
- Otherwise, there is some  $u_{k+1}$  in H that is not in Span S.

#### SUBSPACES OF A FINITE-DIMENSIONAL SPACE

- But then  $\{u_1, ..., u_k, u_{k+1}\}$  will be linearly independent, because no vector in the set can be a linear combination of vectors that precede it (by Theorem 4).
- So long as the new set does not span H, we can continue this process of expanding S to a larger linearly independent set in H.
- But the number of vectors in a linearly independent expansion of *S* can never exceed the dimension of *V*, by Theorem 9.

# THE BASIS THEOREM

• So eventually the expansion of S will span H and hence will be a basis for H, and  $\dim H \leq \dim V$ .

■ Theorem 12: Let V be a p-dimensional vector space,  $p \ge 1$ . Any linearly independent set of exactly p elements in V is automatically a basis for V. Any set of exactly p elements that spans V is automatically a basis for V.

• **Proof:** By Theorem 11, a linearly independent set *S* of *p* elements can be extended to a basis for *V*.

#### THE BASIS THEOREM

- But that basis must contain exactly p elements, since  $\dim V = p$ .
- So *S* must already be a basis for *V*.
- Now suppose that S has p elements and spans V.
- Since V is nonzero, the Spanning Set Theorem implies that a subset S' of S is a basis of V.
- Since  $\dim V = p$ , S'must contain p vectors.
- Hence S = S'.

#### THE DIMENSIONS OF NUL A AND COL A

Let A be an  $m \times n$  matrix, and suppose the equation Ax = 0 has k free variables.

• A spanning set for Nul A will produce exactly k linearly independent vectors—say,  $\mathbf{u}_1, \dots, \mathbf{u}_k$ —one for each free variable.

• So  $\{u_1,...,u_k\}$  is a basis for Nul A, and the number of free variables determines the size of the basis.

#### DIMENSIONS OF NUL A AND COL A

• Thus, the dimension of Nul A is the number of free variables in the equation Ax = 0, and the dimension of Col A is the number of pivot columns in A.

**Example 5:** Find the dimensions of the null space and the column space of

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix}$$

#### DIMENSIONS OF NUL A AND COL A

• **Solution:** Row reduce the augmented matrix  $\begin{bmatrix} A & 0 \end{bmatrix}$  to echelon form:

$$\begin{bmatrix} 1 & -2 & 2 & 3 & -1 & 0 \\ 0 & 0 & 1 & 2 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

- There are three free variable— $x_2$ ,  $x_4$  and  $x_5$ .
- Hence the dimension of Nul A is 3.
- Also dim Col A = 2 because A has two pivot columns.