Computer Vision

Assignment 4

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1

1.1

Because if we traverse a vertical line in the picture, The color will change in a periodic manner. But if we traverse a horizontal line the color won't change across the path, It's either black or white.

1.2

The colors will change in $\frac{1}{2}$ × of the original frequency so the white dots will be farther apart.

1.3

The colors will change in 2× of the original frequency so the white dots will be closer.

2

2.1

In (0,0),
$$e^{-j2\pi(\frac{ux}{M} + \frac{vy}{N})} = 1 \Rightarrow F(0,0) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x,y) = 64 \times 20 = 1280$$

2.2

Fourier transform of an image can be computed using the below formula:

$$F(u,v) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x,y) e^{-j2\pi(\frac{ux}{M} + \frac{vy}{N})}$$

M, N = 2 so the above formula will change to:

$$F(u,v) = \sum_{x=0}^{1} \sum_{y=0}^{1} f(x,y)e^{-j2\pi(\frac{ux}{2} + \frac{vy}{2})}$$

$$\begin{array}{|c|c|}\hline 1 & 2 \\\hline 2 & 1 \\\hline \end{array} \Rightarrow F(u,v) = \begin{cases} F(0,0) = 6 \\ F(0,1) = 1 + 2 + 3e^{-j\pi} = 0 \\ F(1,0) = 1 + 2 + 3e^{-j\pi} = 0 \\ F(1,1) = 1 + 4e^{-j\pi} + e^{-j2\pi} = -2 \\ \end{cases}$$

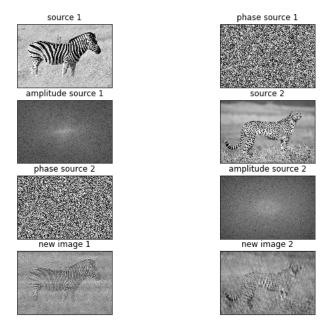
3 Implementations

3.1 Phase and Domain

I used numpy's fft2 to compute fourier transform o image (As said in the class) and fftshift to bring the corners to the center (As said in the class). I computed *log* of amplitude for visualization (As said in the class). Source

For the second part I used element-wise matrix exponentiation and element-wise multiplication $|f1| * e^{\angle f2}$ and vice versa. Source

The conclusion is that most of the info is in the phase.

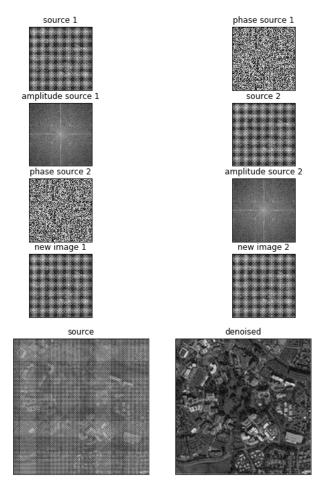


```
def draw_phase_amplitude(image):
2
         Returns the phase image and the amplitude image from the input image.
3
4
         Parameters:
             image (numpy.ndarray): The input image.
6
         Returns:
             tuple of numpy.ndarray: The tuple of the phase image and the amplitude image.
9
10
11
        phase = image.copy()
12
         amp = image.copy()
13
14
         #Writer your code here
15
        f = np.fft.fft2(phase)
16
        fshift1 = np.fft.fftshift(f)
17
        phase = np.angle(fshift1)
18
         amp = 20*np.log(np.abs(fshift1))
19
```

```
20
         return phase, amp
21
22
     def change_phase_domain(image1, image2):
23
24
         Substitutes the phase of image1 by the phase of image2 and returns two new images.
25
26
         Parameters:
27
             image1 (numpy.ndarray): The input image1.
28
             image2 (numpy.ndarray): The input image2.
29
30
31
             tuple of numpy.ndarray: The tuple of result images.
32
33
34
         img1 = image1.copy()
35
         img2 = image2.copy()
36
37
         #Write your code here
38
         f1 = np.fft.fft2(img1)
39
         f2 = np.fft.fft2(img2)
40
41
         combined1 = np.multiply(np.abs(f2), np.exp(1j*np.angle(f1)))
42
         combined2 = np.multiply(np.abs(f1), np.exp(1j*np.angle(f2)))
43
         img1 = np.real(np.fft.ifft2(combined1))
         img2 = np.real(np.fft.ifft2(combined2))
45
46
47
         return img1, img2
```

3.2 Noise Removal

As we can see in the image, we have some vertical and horizontal noises in the image. Which can be seen in the amplitude as 4 dots and 2 vertical and horizontal lines. So if we remove these the noise will be gone.



```
def denoise_image(image):
1
2
         Denoises the input image.
3
4
         Parameters:
5
             image (numpy.ndarray): The input image.
         Returns:
             numpy.ndarray: The result denoised image.
10
11
         denoised = image.copy()
12
13
         #Write your code here
14
         f = np.fft.fft2(denoised)
15
```

```
fshift = np.fft.fftshift(f)
16
17
18
        for i in range(fshift.shape[0]):
            for j in range(fshift.shape[1]):
19
                 if not (i >= 195 and i <= 317 and j >= 195 and j <= 317):
20
                     fshift[i][j] = 0
21
22
         ifshift = np.fft.ifftshift(fshift)
23
         f = np.real(np.fft.ifft2(ifshift))
24
         denoised = f
25
         return denoised
26
```

3.3 Image Enhancement

I used Gaussian High Pass filter here. I used a threshold D0 to specify the length of the filter (radius of the circle in the middle of the filter which determines what are the high frequencies that can pass the filter). Then I multiplied the filter with the fourier transform of the image and computed the invert fourier transform of the result. At last I added the filtered image to the original image. Source





```
def distance(point1,point2):
         return np.sqrt((point1[0]-point2[0])**2 + (point1[1]-point2[1])**2)
 2
 3
     def gaussianHP(D0,imgShape):
 4
         base = np.zeros(imgShape[:2],dtype=np.float64)
 5
         rows, cols = imgShape[:2]
         center = (rows/2,cols/2)
         for x in range(cols):
             for y in range(rows):
                 base[y,x] = 1 - np.exp(((-distance((y,x),center)**2)/(2*(D0**2))))
10
11
         return base
12
     def enhance_image(image):
13
14
         Enhances the input image by applying a filter in the frequency domain.
15
16
         Parameters:
17
             image (numpy.ndarray): The input image.
18
19
         Returns:
20
             numpy.ndarray: The result enhanced image.
21
22
23
         enhanced = image.copy()
24
         r,c = image.shape
25
         #Write your code here
26
27
         kernel = gaussianHP(50,image.shape)
28
```

```
29
        f = np.fft.fft2(enhanced)
30
         fshift = np.fft.fftshift(f)
31
32
         fshift = fshift * kernel
33
34
35
         ifshift = np.fft.ifftshift(fshift)
        f = np.real(np.fft.ifft2(ifshift))
36
37
         enhanced = np.array(enhanced,np.float64) + f
38
39
         return enhanced
40
```