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Setting up the environment

```
clear all;
close all;
warning('off', 'all'); % Turn back off after debugging

currentFile = matlab.desktop.editor.getActiveFilename;
Get the full path of the active file
runfilelocation = fileparts(currentFile);

% Dynamically get the parent folder
[projectRoot, ~, ~] = fileparts(runfilelocation);
```

Parse the excel file %% parseValues = excel_file_parser(projectRoot,'ExcelFile','ProblemDefinition'); % Extract excel values

Warning: Column headers from the file were modified to make them valid MATLAB identifiers before creating variable names for the table. The original column headers are saved in the VariableDescriptions property.

Set 'VariableNamingRule' to 'preserve' to use the original column headers as table variable names.

Problem selection %% selectedFunction = select_function(projectRoot);

```
The available list of functions are:

1. S0001_f_5d_Crash_Problem

2. S0002_f_BeamDisplacement_Problem

3. S0003_f_TestCrashProblem

4. S0004_f_TestCrash1

5. S0005_f_CrashDesignProblem

6. S0006_f_DemonstrationCrashProblem

7. S0008_f_cfk1d

8. S0009_f_cfk3d

9. S0010_f_cfkIter1

10. S0011_f_cfkIter2
```

```
11. S0012_f_cfkIter3
12. tutorial_01_euclidean_distance_3d
You have selected function: tutorial 01 euclidean distance 3d
```

Create data manager

```
dataManager = SolutionSpaceData(parseValues.DesignVariable,...
    parseValues.QuantatiesOfInterest,parseValues.DesignParameters,...
    parseValues.Labels, parseValues.PlotDesigns,...
    parseValues.ExtraOptions, selectedFunction);

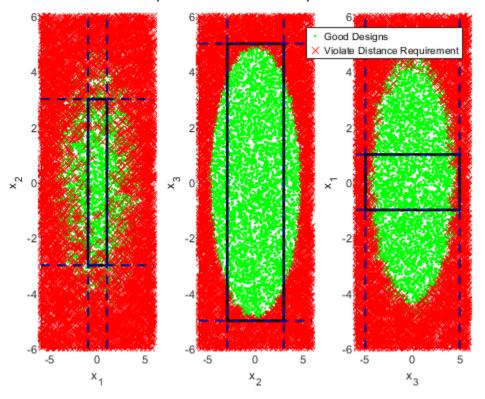
dataManager.selectedFunction = selectedFunction;
```

Create GUI

```
create_solution_space_GUI(dataManager);
Calculating performance measure...
Calculating performance measure...
Calculating performance measure...
Subplot 1: xVarIndex = 1, yVarIndex = 2
Subplot 2: xVarIndex = 2, yVarIndex = 3
Subplot 3: xVarIndex = 3, yVarIndex = 1
```



3D Sphere - Box Decomposition



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