

Before you turn this problem in, make sure everything runs as expected. First, **restart the kernel** (in the menubar, select Kernel  $\rightarrow$  Restart) and then **run all cells** (in the menubar, select Cell  $\rightarrow$  Run All).

Make sure you fill in any place that says YOUR CODE HERE or "YOUR ANSWER HERE", as well as your name and collaborators below:

```
In [1]: NAME = "Aung Zar Lin"
        ID = "121956"
```

## Lab 05: Optimization Using Newton's Method

In this lab, we'll explore an alternative to gradient descent for nonlinear optimization problems: Newton's method.

### Newton's method in one dimension

Consider the problem of finding the *roots*  $\textbf{x}$  of a nonlinear function  $f: \mathbb{R}^N \rightarrow \mathbb{R}$ . A root of  $f$  is a point  $\textbf{x}$  that satisfies  $f(\textbf{x}) = 0$ .

In one dimension, Newton's method for finding zeroes works as follows:

1. Pick an initial guess  $x_0$
2. Let  $x_{i+1} = x_i + \frac{f(x_i)}{f'(x_i)}$
3. If not converged, go to #2.

Convergence occurs when  $|f(x_i)| < \epsilon_1$  or when  $|f(x_{i+1}) - f(x_i)| < \epsilon_2$ .

Let's see how this works in practice.

### Example 1: Root finding for a cubic polynomial

Let's begin by using Newton's method to find roots of a simple cubic polynomial  $f(x) = x^3 + x^2$ .

```
In [2]: import matplotlib.pyplot as plt
import numpy as np
from mpl_toolkits.mplot3d import Axes3D
import pandas as pd
```

Here's a function to evaluate a polynomial created with Numpy's `poly1d` function at a particular point  $x$ :

```
In [3]: def fx(x, p):
        f_x = np.polyval(p, x)
```

```
return f_x
```

And here's some code to create the polynomial  $x^3 + x^2$ , get its derivative, and evaluate the derivative at 200 points along the  $x$  axis;

```
In [4]: # Create the polynomial f(x) = x^3 + x^2
p = np.poly1d([1, 1, 0, 0]) # [1 * x^3, 1 * x^2, 0 * x^1, 0 * 1]

# Get f'(x) (the derivative of f(x) in polynomial form)
# We know it's 2x^2 + 2x, which is [3, 2, 0] in poly1d form
p_d = np.polyder(p)

print('f(x):')
print('-----')
print(p)
print('-----')
print("f'(x):")
print('-----')
print(p_d)
print('-----')

# Get 200 points along the x axis between -3 and 3
n = 200
x = np.linspace(-3, 3, n)

# Get values for f(x) and f'(x) in order to graph them Later
y = fx(x, p)
y_d = fx(x, p_d)
```

```
f(x):
-----
      3      2
1 x + 1 x
-----
f'(x):
-----
      2
3 x + 2 x
-----
```

Next, let's try three possible guesses for  $x_0$ : -3, 1, and 3, and in each case, run Newton's root finding method from that initial guess.

```
In [5]: # Initial guesses
x0_arr = [-3.0, 1.0, 3.0]

# Parameters for Newton: number of iterations,
# threshold for identifying a point as a zero
max_iters = 30
threshold = 0.0001

# Set up plot
fig1 = plt.figure(figsize=(8,8))
ax = plt.axes()
plt.plot(x, y, 'g-', label='f(x)')
plt.plot(x, y_d, 'b--', label="f'(x)")

roots = []
```

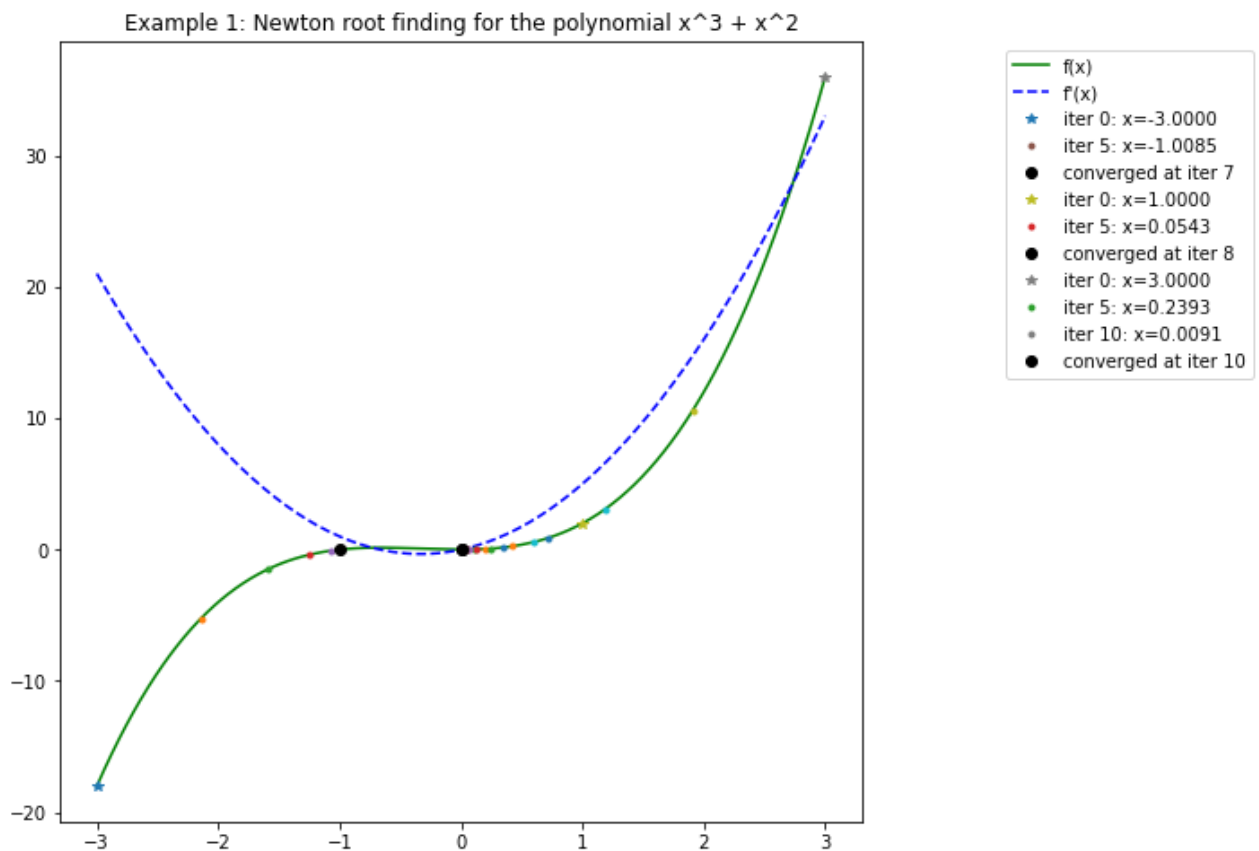
```

for x0 in x0_arr:
    i = 0
    xi = x0
    fxi = fx(xi, p)
    # Plot initial data point
    plt.plot(xi, fxi, '*', label=("iter 0: x=%.4f" % x0))
    while i < max_iters:
        #  $x_{i+1} = x_i - f(x_i)/f'(x_i)$ 
        xi = xi - fx(xi, p) / fx(xi, p_d)
        fxi = fx(xi, p)
        # Plot (xi, fxi) and add a Legend entry every 5 iterations
        if (i+1) % 5 == 0:
            plt.plot(xi, fxi, '.', label=("iter %d: x=%.4f" % (i+1, xi)))
        else:
            plt.plot(xi, fxi, '.')
        # Check if  $|f(x)| < \text{threshold}$ 
        if np.abs(fxi) < threshold:
            roots.append(xi)
            break
        i = i + 1
    plt.plot(xi, fx(xi, p), 'ko', label=("converged at iter %d" % (i+1)))

plt.legend(bbox_to_anchor=(1.5, 1.0), loc='upper right')
plt.title('Example 1: Newton root finding for the polynomial  $x^3 + x^2$ ')

plt.show()

```



## Example 2: Root finding for the sine function

Next, consider the function  $f(x) = \sin(x)$ :

```
In [6]: def fx_sin(x):
        return np.sin(x)

        def fx_dsine(x):
            return np.cos(x)
```

Let's get 200 points in the range  $[-\pi, \pi]$  for plotting:

```
In [7]: # Get f(x)=sin(x) and f'(x) at 200 points for plotting
n = 200
x = np.linspace(-np.pi, np.pi, n)
y = fx_sin(x)
y_d = fx_dsine(x)
```

```
In [8]: # Initial guesses
x0_arr = [2.0, 1.0, -2.0]

# Parameters for Newton: number of iterations,
# threshold for identifying a point as a zero
max_iters = 30
threshold = 0.0001

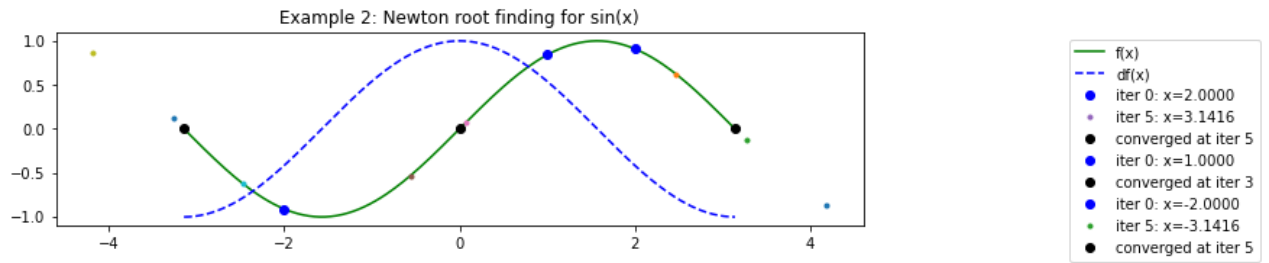
# Set up plot
fig1 = plt.figure(figsize=(10,10))
ax = plt.axes()
ax.set_aspect(aspect='equal', adjustable='box')
plt.plot(x, y, 'g-', label='f(x)')
plt.plot(x, y_d, 'b--', label='df(x)')

roots = []
for x0 in x0_arr:
    i = 0;
    xi = x0
    fxi = fx_sin(xi)
    # Plot initial data point
    plt.plot(xi, fxi, 'bo', label=("iter 0: x=%.4f" % x0))
    while i < max_iters:
        # x_{i+1} = x_i - f(x_i)/f'(x_i)
        xi = xi - fx_sin(xi) / fx_dsine(xi)
        fxi = fx_sin(xi)
        # Plot (xi, fxi) and add a Legend entry every 5 iterations
        if (i+1) % 5 == 0:
            plt.plot(xi, fxi, '.', label=("iter %d: x=%.4f" % (i+1, xi)))
        else:
            plt.plot(xi, fxi, '.')
        # Check if |f(x)| < threshold
        if np.abs(fxi) < threshold:
            roots.append(xi)
            break
        i = i + 1
    plt.plot(xi, fx_sin(xi), 'ko', label=("converged at iter %d" % (i+1)))

plt.legend(bbox_to_anchor=(1.5, 1.0), loc='upper right')
plt.title('Example 2: Newton root finding for sin(x)')

plt.show()

print('Roots: %f, %f, %f' % (roots[0], roots[1], roots[2]))
```



Roots: 3.141593, -0.000096, -3.141593

Notice that we get some extreme values of  $x$  for some cases. For example, when  $x_0 = -2$ , where the slope is pretty close to 0, the next iteration gives a value less than -4.

## Newton's method for optimization

Now, consider the problem of minimizing a scalar function  $J : \mathbb{R}^n \mapsto \mathbb{R}$ . We would like to find  $\theta^* = \text{argmin}_{\theta} J(\theta)$ . We already know gradient descent:  $\theta^{(i+1)} \leftarrow \theta^{(i)} - \alpha \nabla J(\theta^{(i)})$ . But Newton's method gives us a potentially faster way to find  $\theta^*$  as a zero of the system of equations  $\nabla J(\theta^*) = \mathbf{0}$ .

In one dimension, to find the zero of  $f'(x)$ , obviously, we would apply Newton's method to  $f'(x)$ , obtaining the iteration  $x_{i+1} = x_i - f'(x_i) / f''(x_i)$ . The multivariate extension of Newton's optimization method is  $\mathbf{x}_{i+1} = \mathbf{x}_i - \mathbf{H}^{-1}_f(\mathbf{x}_i) \nabla f(\mathbf{x}_i)$ , where  $\mathbf{H}_f(\mathbf{x})$  is the *Hessian* of  $f$  evaluated at  $\mathbf{x}$ :  $\mathbf{H}_f(\mathbf{x}) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \dots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \dots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \dots & \frac{\partial^2 f}{\partial x_n^2} \end{bmatrix}$

This means, for the minimization of  $J(\theta)$ , we would obtain the update rule  $\theta^{(i+1)} \leftarrow \theta^{(i)} - \mathbf{H}^{-1}_J(\theta^{(i)}) \nabla J(\theta^{(i)})$ .

## Application to logistic regression

Let's create some difficult sample data as follows:

**Class 1:** Two features  $x_1$  and  $x_2$  jointly distributed as a two-dimensional spherical Gaussian with parameters

$$\mu = \begin{bmatrix} x_{1c} \\ x_{2c} \end{bmatrix}, \Sigma = \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_1^2 \end{bmatrix}$$

**Class 2:** Two features  $x_1$  and  $x_2$  in which the data are generated by first sampling an angle  $\theta$  according to a uniform distribution, sampling a distance  $d$  according to a one-dimensional Gaussian with a mean of  $(3\sigma_1)^2$  and a variance of  $(\frac{1}{2}\sigma_1)^2$ ,

then outputting the point  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = d \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}$ .

Generate 100 samples for each of the classes, guided by the following exercises.

## Exercise 1.1 (5 points)

Generate data for class 1 with 100 samples:

$\mu = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ ,  $\Sigma = \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_1^2 \end{bmatrix}$ .

### ► Hint:

In [9]:

```
mu_1 = np.array([1.0, 2.0])
sigma_1 = 1
num_sample = 100

cov_mat = np.array([[sigma_1, 0], [0, sigma_1]])
X1 = np.random.multivariate_normal(mu_1, cov_mat, num_sample)

# YOUR CODE HERE
#raise NotImplementedError()
```

In [10]:

```
print(X1[:5])

# Test function: Do not remove
assert X1.shape == (100, 2), 'Size of X1 is incorrect'
assert cov_mat.shape == (2, 2), 'Size of x_test is incorrect'
count = 0
for i in range(2):
    for j in range(2):
        if i==j and cov_mat[i,j] != 0:
            if cov_mat[i,j] == sigma_1:
                count += 1
        else:
            if cov_mat[i,j] == 0:
                count += 1
assert count == 4, 'cov_mat data is incorrect'

print("success!")
# End Test function
```

```
[[0.05972066 2.02507983]
 [0.22351787 1.35675528]
 [0.51964659 5.5349679 ]
 [1.18262603 3.3564972 ]
 [0.89393368 2.9793407 ]]
success!
```

**Expected result (or something similar):**  $\begin{bmatrix} -0.48508229 & 2.65415886 \\ 1.17230227 & 1.61743589 \\ -0.61932146 & 3.53986541 \\ 0.70583088 & 1.45944356 \\ -0.93561505 & 0.2042285 \end{bmatrix}$

## Exercise 1.2 (5 points)

Generate data for class 2 with 100 samples:

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \cos(\theta) \\ \sin(\theta) \end{bmatrix} d$$

where  $\theta$  is sampled uniformly from  $[0, 2\pi]$  and  $d$  is sampled from a one-dimensional Gaussian with a mean of  $(3\sigma_1)^2$  and a variance of  $\frac{1}{2}\sigma_1^2$ .

► **Hint:**

In [11]:

```
# 1. Create sample angle from 0 to 2pi with 100 samples
angle = np.random.uniform(low=0, high=2*np.pi, size = num_sample)
# 2. Create sample with normal distribution of d with mean and variance
d = np.random.normal(np.square(3*sigma_1), np.square(sigma_1*.5), size =num_sample)
# 3 Create X2
X2 = np.array([X1[:,0] + d*np.cos(angle), X1[:,1] + d*np.sin(angle)]).T

# YOUR CODE HERE
#raise NotImplementedError()
```

In [12]:

```
print('angle:',angle[:5])
print('d:', d[:5])
print('X2:', X2[:5])

# Test function: Do not remove
assert angle.shape == (100,) or angle.shape == (100,1) or angle.shape == 100, 'Size of
assert d.shape == (100,) or d.shape == (100,1) or d.shape == 100, 'Size of d is incorre
assert X2.shape == (100,2), 'Size of X2 is incorrect'
assert angle.min() >= 0 and angle.max() <= 2*np.pi, 'angle generate incorrect'
assert d.min() >= 8 and d.max() <= 10, 'd generate incorrect'
assert X2[:,0].min() >= -13 and X2[:,0].max() <= 13, 'X2 generate incorrect'
assert X2[:,1].min() >= -10 and X2[:,1].max() <= 13.5, 'X2 generate incorrect'

print("success!")
# End Test function
```

```
angle: [1.97074405 1.598663 4.14390958 2.78534555 1.95595168]
d: [8.66434792 8.86771789 9.20158249 8.87126579 8.79867849]
X2: [[-3.31391817 10.0056491 ]
      [-0.02356393 10.22103027]
      [-4.43403666 -2.2193949 ]
      [-7.13163319 6.45043489]
      [-2.41175725 11.13342866]]
success!
```

**Expected result (or something similar):** angle: [4.77258271 3.19733552 0.71226709 2.11244845 6.06280915] d: [9.13908279 8.84218552 9.24427852 8.74831667 8.85727588] X2: [[ 0.064701 -6.46837219] [-7.65614929 1.12480234] [ 6.37750805 9.58147629] [-3.80438416 8.95550952] [ 7.70745021 -1.73194274]]

## Exercise 1.3 (5 points)

Combine X1 and X2 into single dataset

In [13]:

```
# 1. concatenate X1, X2 together
X = np.concatenate([X1, X2], axis=0)
# 2. Create y with class 1 as 0 and class 2 as 1
y1 = np.zeros((num_sample,1))
y2 = np.ones((num_sample,1))
```

```
y = np.concatenate([y1, y2], axis=0)
# YOUR CODE HERE
#raise NotImplementedError()
```

In [14]:

```
print("shape of X:", X.shape)
print("shape of y:", y.shape)

# Test function: Do not remove
assert X.shape == (200, 2), 'Size of X is incorrect'
assert y.shape == (200,) or y.shape == (200,1) or y.shape == 200, 'Size of y is incorrect'
assert y.min() == 0 and y.max() == 1, 'class type setup is incorrect'

print("success!")
# End Test function
```

```
shape of X: (200, 2)
shape of y: (200, 1)
success!
```

**Expect result (or looked alike):** \ shape of X: (200, 2) \ shape of y: (200, 1)

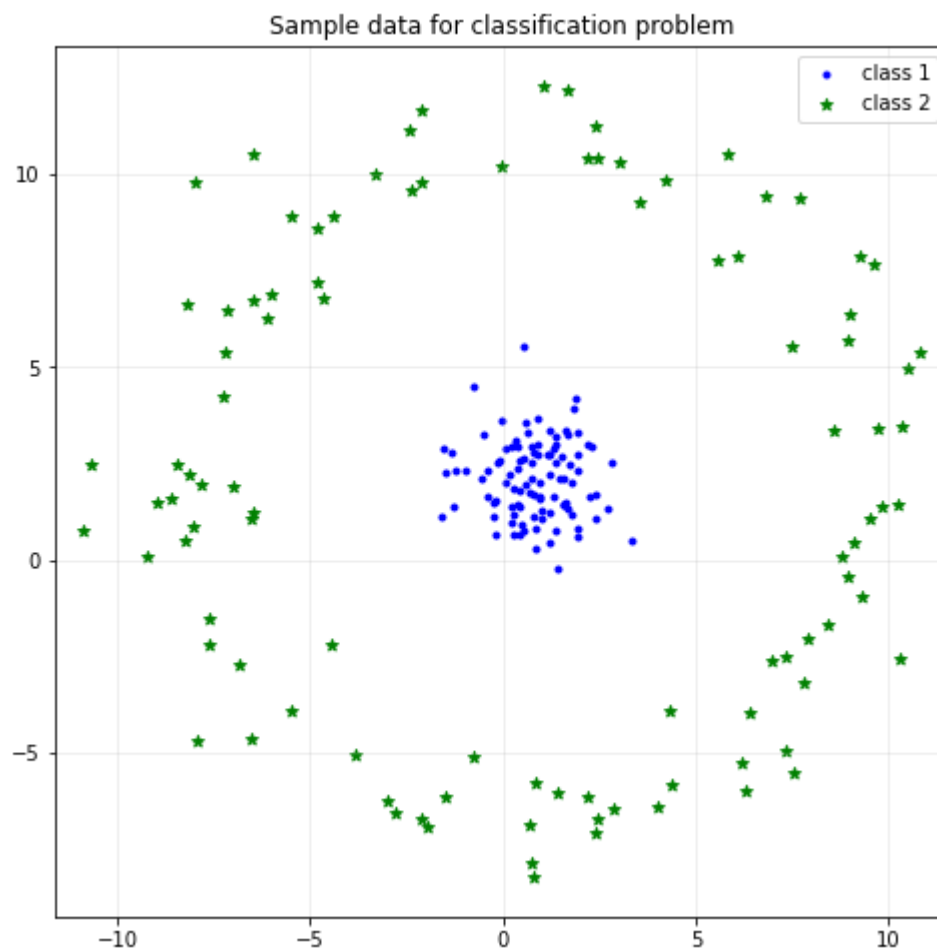
## Exercise 1.4 (5 points)

Plot the graph between class1 and class2 with **difference color and point style**.

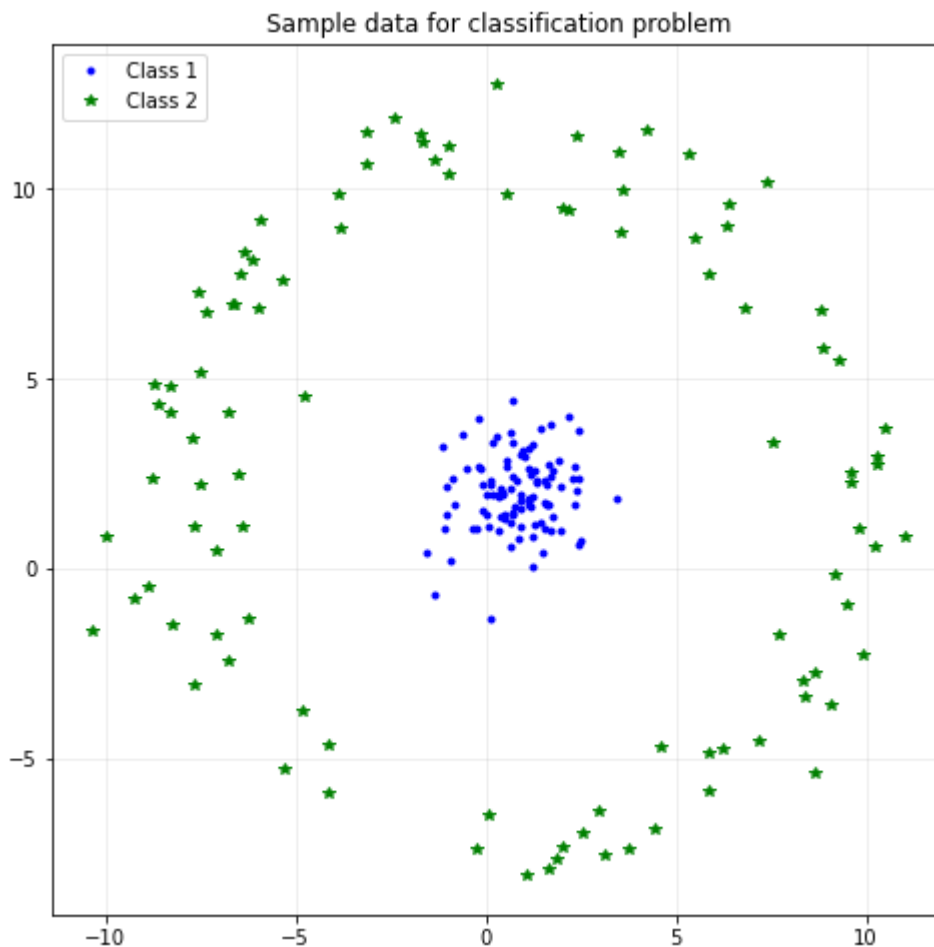
In [15]:

```
fig1 = plt.figure(figsize=(8,8))
ax = plt.axes()
plt.title('Sample data for classification problem')
plt.grid(axis='both', alpha=.25)
# plot graph here
# YOUR CODE HERE
plt.scatter(X1[:,0], X1[:,1], c='b', marker='.', label='class 1')
plt.scatter(X2[:,0], X2[:,1], c='g', marker='*', label='class 2')
plt.legend()
#raise NotImplementedError()
# end plot graph
plt.axis('equal')
plt.show()
```





**Expect result (or looked alike):**



## Exercise 1.5 (5 points)

Split data into training and test datasets with 80% of training set and 20% of test set

```
In [16]: train_size = 0.8

m, n = X.shape
idx = np.arange(m)
np.random.shuffle(idx)

train_m = int(m * train_size)

idx_train = idx[:train_m]
idx_test = idx[train_m:]

X_train = X[idx_train]
X_test = X[idx_test]
y_train = y[idx_train]
y_test = y[idx_test]

# YOUR CODE HERE
#raise NotImplementedError()
```

```
In [17]: print('idx_train:', idx_train[:10])
print("train size, X:", X_train.shape, ", y:", y_train.shape)
print("test size, X:", X_test.shape, ", y:", y_test.shape)
```

```
# Test function: Do not remove
assert X_train.shape == (160, 2), 'Size of X_train is incorrect'
assert y_train.shape == (160,) or y_train.shape == (160,1) or y.shape == 160, 'Size of
assert X_test.shape == (40, 2), 'Size of X_test is incorrect'
assert y_test.shape == (40,) or y_test.shape == (40,1) or y.shape == 40, 'Size of y_tes

print("success!")
# End Test function
```

```
idx_train: [119  45  14  57  47 145 158 136 159  33]
train size, X: (160, 2) , y: (160, 1)
test size, X: (40, 2) , y: (40, 1)
success!
```

**Expected reult (or something similar):** \ idx\_train: [ 78 61 28 166 80 143 6 76 98 133] \ train size, X: (160, 2) , y: (160, 1) \ test size, X: (40, 2) , y: (40, 1)

## Exercise 1.6 (5 points)

Write a function to normalize your  $X$  data

### Practice yourself (No grade, but has extra score 3 points)

Try to use Jupyter notebook's LaTeX equation capabilities to write the normalization equations for your dataset.

YOUR ANSWER HERE

$$Z = \frac{X - \mu}{\sigma}$$

where  $\mu$  = mean and  $\sigma$  = standard deviation

In [18]:

```
def normalization(X):
    """
    Take in numpy array of X values and return normalize X values,
    the mean and standard deviation of each feature
    """
    means = np.mean(X, axis=0)
    stds = np.std(X, axis=0)
    X_norm = (X - means) / stds
    # YOUR CODE HERE
    #raise NotImplementedError()

    return X_norm
```

In [19]:

```
XX = normalization(X)

X_train_norm = XX[idx_train]
X_test_norm = XX[idx_test]

# Add 1 at the first column of training dataset (for bias) and use it when training
X_design_train = np.insert(X_train_norm,0,1,axis=1)
X_design_test = np.insert(X_test_norm,0,1,axis=1)

m,n = X_design_train.shape

print(X_train_norm.shape)
```

```

print(X_design_train.shape)
print(X_test_norm.shape)
print(X_design_test.shape)

# Test function: Do not remove
assert XX[:,0].min() >= -2.5 and XX[:,0].max() <= 2.5, 'Does the XX is normalized?'
assert XX[:,1].min() >= -2.5 and XX[:,1].max() <= 2.5, 'Does the XX is normalized?'

print("success!")
# End Test function

```

```
(160, 2)
```

```
(160, 3)
```

```
(40, 2)
```

```
(40, 3)
```

```
success!
```

## Exercise 1.7 (10 points)

define class for logistic regression: batch gradient descent

The class includes:

- **Sigmoid** function  $\text{sigmoid}(z) = \frac{1}{1+e^{-z}}$
- **Softmax** function  $\text{softmax}(z) = \frac{e^{z_i}}{\sum_n e^{z_i}}$
- **Hyperthesis (h)** function  $\hat{y} = h(X; \theta) = \text{softmax}(\theta \cdot X)$
- **Gradient (Negative likelihood)** function  $\text{gradient} = -X \cdot \frac{y - \hat{y}}{n}$
- **Cost** function  $\text{cost} = \frac{\sum \{(-y) \log(\hat{y}) - ((1-y) \log(1 - \hat{y}))\}}{n}$
- **Gradient ascent** function
- **Prediction** function
- **Get accuracy** function

In [20]:

```

class Logistic_BGD:
    def __init__(self):
        pass

    def sigmoid(self, z):
        s = 1 / (1 + np.exp(-z))
        # YOUR CODE HERE
        #raise NotImplementedError()
        return s

    def softmax(self, z):
        sm = np.exp(z)/np.sum(np.exp(z))
        # YOUR CODE HERE
        #raise NotImplementedError()
        return sm

    def h(self, X, theta):
        hf = self.sigmoid(X @ theta)
        # YOUR CODE HERE
        #raise NotImplementedError()
        return hf

    def gradient(self, X, y, y_pred):
        grad = X.T.dot(y_pred - y) / X.shape[0]

```

```

# YOUR CODE HERE
#raise NotImplementedError()
return grad

def costFunc(self, theta, X, y):
    y_pred = self.h(X, theta)
    error = (y * np.log(y_pred)) + ((1 - y) * np.log(1 - y_pred))
    cost = -sum(error) / X.shape[0]
    grad = self.gradient(X, y, y_pred)
    # YOUR CODE HERE
    #raise NotImplementedError()
    return cost, grad

def gradientAscent(self, X, y, theta, alpha, num_iters):
    m = len(y)
    J_history = []
    theta_history = []
    for i in range(num_iters):
        # 1. calculate cost, grad function
        cost, grad = self.costFunc(theta, X, y)
        # 2. update new theta
        #theta = None
        theta = theta - alpha * grad
        # YOUR CODE HERE
        #raise NotImplementedError()

        J_history.append(cost)
        theta_history.append(theta)
    J_min_index = np.argmin(J_history)
    print("Minimum at iteration:", J_min_index)
    return theta_history[J_min_index], J_history

def predict(self, X, theta):
    labels = []
    # 1. take y_predict from hypothesis function
    y_pred = self.h(X, theta)
    # 2. classify y_predict that what it should be class1 or class2
    for i in range(len(y_pred)):
        if y_pred[i] >= 0.5:
            labels.append(1)
        else:
            labels.append(0)
    # 3. append the output from prediction
    # YOUR CODE HERE
    #raise NotImplementedError()

    labels = np.asarray(labels)
    return labels

def getAccuracy(self, X, y, theta):
    y_pred = self.predict(X, theta)
    y_pred = y_pred.reshape(y.shape)
    percent_correct = 100 * np.sum(y == y_pred).astype(int) / y.shape[0]
    # YOUR CODE HERE
    #raise NotImplementedError()
    return percent_correct

```

In [21]: # Test function: Do not remove

```

lbgd = Logistic_BGD()
test_x = np.array([[1,2,3,4,5]]).T
out_x1 = lbgd.sigmoid(test_x)
out_x2 = lbgd.sigmoid(test_x.T)
print('out_x1', out_x1.T)
assert np.array_equal(np.round(out_x1.T, 5), np.round([[0.73105858, 0.88079708, 0.95257413, 0.98201379, 0.99330715]], 5))
assert np.array_equal(np.round(out_x2, 5), np.round([[0.73105858, 0.88079708, 0.95257413, 0.98201379, 0.99330715]], 5))
out_x1 = lbgd.softmax(out_x1)
out_x2 = lbgd.softmax(out_x2)
print('out_x1', out_x1.T)
assert np.array_equal(np.round(out_x1.T, 5), np.round([[0.16681682, 0.19376282, 0.20818183, 0.21440174, 0.21683678]], 5))
assert np.array_equal(np.round(out_x2, 5), np.round([[0.16681682, 0.19376282, 0.20818183, 0.21440174, 0.21683678]], 5))
test_t = np.array([[0.3, 0.2]]).T
test_x = np.array([[1,2,3,4,5, 6], [2, 9, 4, 3, 1, 0]]).T
test_y = np.array([[0,1,0,1,0,1]]).T
test_y_p = lbgd.h(test_x, test_t)
print('test_y_p', test_y_p.T)
assert np.array_equal(np.round(test_y_p.T, 5), np.round([[0.66818777, 0.9168273, 0.84553473, 0.85814894, 0.84553473, 0.85814894]], 5))
test_g = lbgd.gradient(test_x, test_y, test_y_p)
print('test_g', test_g.T)
assert np.array_equal(np.round(test_g.T, 5), np.round([[0.9746016, 0.73165696]], 5)), "
test_c, test_g = lbgd.costFunc(test_t, test_x, test_y)
print('test_c', test_c.T)
assert np.round(test_c, 5) == np.round(0.87192491, 5), "costFunc function is incorrect"
test_t_out, test_j = lbgd.gradientAscent(test_x, test_y, test_t, 0.001, 3)
print('test_t_out', test_t_out.T)
print('test_j', test_j)
assert np.array_equal(np.round(test_t_out.T, 5), np.round([[0.29708373, 0.19781153]], 5))
assert np.round(test_j[2], 5) == np.round(0.86896665, 5), "gradientAscent function is incorrect"
test_l = lbgd.predict(test_x, test_t)
print('test_l', test_l)
assert np.array_equal(np.round(test_l, 1), np.round([1,1,1,1,1,1], 1)), "gradientAscent function is incorrect"
test_a = lbgd.getAccuracy(test_x, test_y, test_t)
print('test_a', test_a)
assert np.round(test_a, 1) == 50.0, "getAccuracy function is incorrect"

print("success!")
# End Test function

```

```

out_x1 [[0.73105858 0.88079708 0.95257413 0.98201379 0.99330715]]
out_x1 [[0.16681682 0.19376282 0.20818183 0.21440174 0.21683678]]
test_y_p [[0.66818777 0.9168273 0.84553473 0.85814894 0.84553473 0.85814894]]
test_g [[0.9746016 0.73165696]]
test_c [0.87192491]
Minimum at iteration: 2
test_t_out [[0.29708373 0.19781153]]
test_j [array([0.87192491]), array([0.87044176]), array([0.86896665])]
test_l [1 1 1 1 1 1]
test_a 50.0
success!

```

**Expected result:** \ out\_x1 [[0.73105858 0.88079708 0.95257413 0.98201379 0.99330715]] \ out\_x1 [[0.16681682 0.19376282 0.20818183 0.21440174 0.21683678]] \ test\_y\_p [[0.66818777 0.9168273 0.84553473 0.85814894 0.84553473 0.85814894]] \ test\_g [[0.9746016 0.73165696]] \ test\_c [0.87192491] \ Minimum at iteration: 2 \ test\_t\_out [[0.29708373 0.19781153]] \ test\_j [array([0.87192491]), array([0.87044176]), array([0.86896665])] \ test\_l [1 1 1 1 1 1] \ test\_a 50.0

## Exercise 1.8 (5 points)

Training the data using Logistic\_BGD class.

- Input: X\_design\_train
- Output: y\_train
- Use 50,000 iterations

Find the initial\_theta yourself

```
In [22]: alpha = 0.001
iterations = 50000

BGD_model = Logistic_BGD()

initial_theta = np.ones((X_design_train.shape[1],1))
bgd_theta, bgd_cost = BGD_model.gradientAscent(X_design_train, y_train, initial_theta,

# YOUR CODE HERE
#raise NotImplementedError()
```

Minimum at iteration: 49999

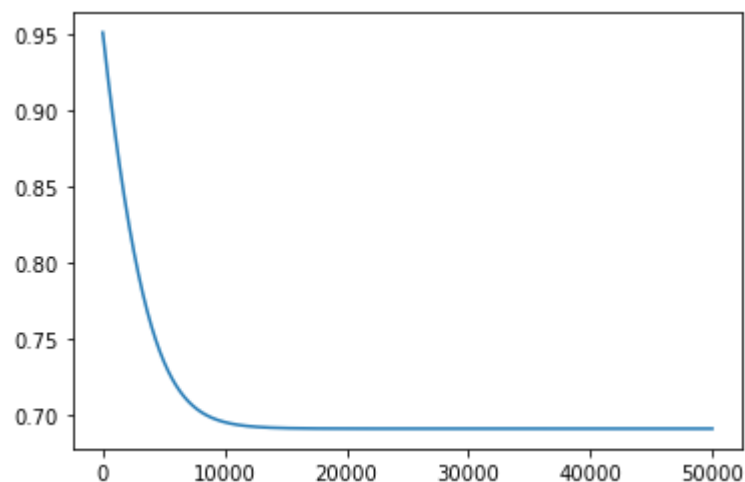
```
In [23]: print(bgd_theta)
print(len(bgd_cost))

print(bgd_cost[0])
plt.plot(bgd_cost)
plt.show()

# Test function: Do not remove
assert bgd_theta.shape == (X_train.shape[1] + 1,1) or bgd_theta.shape == (X_train.shape
assert len(bgd_cost) == iterations, "cost data size is incorrect"

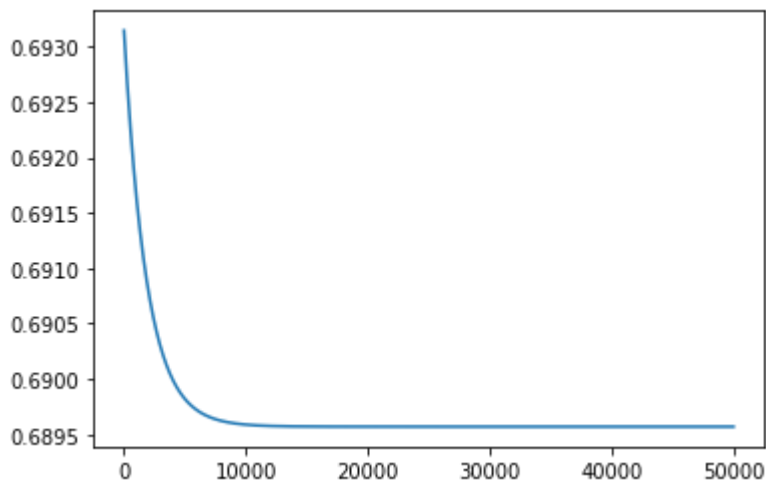
print("success!")
# End Test function
```

```
[[0.0961404 ]
 [0.04787377]
 [0.03641186]]
50000
[0.95098098]
```



success!

**Expected result (or look alike):** \ [[-0.07328673] \ [-0.13632896] \ [ 0.05430939]] \ 50000



## In lab exercises

1. Verify that the gradient descent solution is correct. Plot the optimal decision boundary you obtain.
2. Write a new class that uses Newton's method for the optimization rather than simple gradient descent.
3. Verify that you obtain a similar solution with Newton's method. Plot the optimal decision boundary you obtain.
4. Compare the number of iterations required for gradient descent vs. Newton's method. Do you observe other issues with Newton's method such as a singular or nearly singular Hessian matrix?

## Exercise 1.9 (5 points)

Plot the optimal decision boundary of gradient ascent

```
In [24]: def boundary_points(X, theta):

    v_orthogonal = np.array([[theta[1,0]], [theta[2,0]]])
    v_ortho_length = np.sqrt(v_orthogonal.T @ v_orthogonal)
    dist_ortho = theta[0,0] / v_ortho_length
    v_orthogonal = v_orthogonal / v_ortho_length
    v_parallel = np.array([-v_orthogonal[1,0]], [v_orthogonal[0,0]])
    projections = X @ v_parallel
    proj_1 = min(projections)
    proj_2 = max(projections)
    point_1 = proj_1 * v_parallel - dist_ortho * v_orthogonal
    point_2 = proj_2 * v_parallel - dist_ortho * v_orthogonal
    return point_1, point_2
```

```
In [25]: fig1 = plt.figure(figsize=(5,5))
```

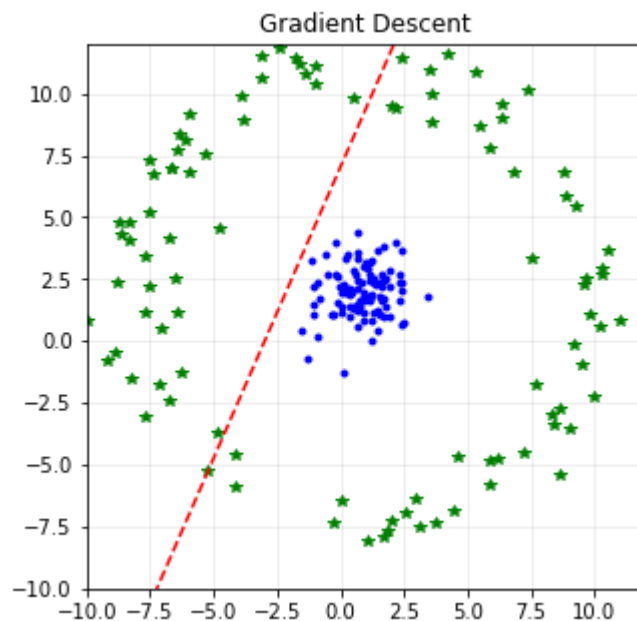
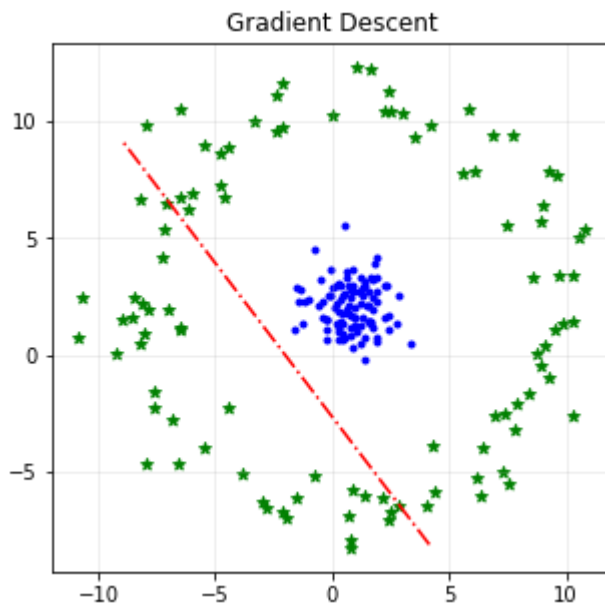


```

ax = plt.axes()
ax.set_aspect(aspect = 'equal', adjustable = 'box')
plt.title('Gradient Descent')
plt.grid(axis='both', alpha=.25)
plt.scatter(X1[:,0], X1[:,1], c='b', marker='.', label='class 1')
plt.scatter(X2[:,0], X2[:,1], c='g', marker='*', label='class 2')

point_1, point_2 = boundary_points(X, bgd_theta)
plt.plot([point_1[0,0], point_2[0,0]], [point_1[1,0], point_2[1,0]], 'r-.')
plt.show()

```



**Expected result (or look alike):\**

In [26]:

```
print("Accuracy =",BGD_model.getAccuracy(X_design_test,y_test,bgd_theta))
```

Accuracy = 22.5

## Exercise 2.1 (10 points)

Write Newton's method class

In [27]:

```

class Logistic_NM: #logistic regression for newton's method

    def __init__(self):
        pass

    def sigmoid(self,z):
        #s = None
        # YOUR CODE HERE
        s = 1 / (1 + np.exp(-1*z))
        #raise NotImplementedError()
        return s

    def h(self,X, theta):
        #hf = None
        # YOUR CODE HERE
        hf = self.sigmoid(X @ theta)
        #raise NotImplementedError()
        return hf

    def gradient(self, X, y, y_pred):
        #grad = None
        # YOUR CODE HERE
        m = len(y)
        grad = 1/m * np.dot(X.T,(y_pred - y))
        #raise NotImplementedError()
        return grad

    def hessian(self, X, y, theta):
        #hess_mat = None
        # YOUR CODE HERE
        y_hat = self.h(X, theta)
        X2 = X.T @ X
        Y2 = y_hat.T @ (1 - y_hat)
        value = Y2[0,0]
        hess_mat = X2 * value / X.shape[0]
        #raise NotImplementedError()
        return hess_mat

    def costFunc(self, theta, X, y):
        #cost, grad = None, None
        # YOUR CODE HERE
        m = len(y)
        y_pred = self.h(X, theta)
        error = (y * np.log(y_pred)) + ((1-y)*np.log(1-y_pred))
        cost = -1/m * np.sum(error)
        grad = self.gradient(X, y, y_pred)
        return cost, grad

    def newtonsMethod(self, X, y, theta, num_iters):
        m = len(y)
        J_history = []
        theta_history = []
        for i in range(num_iters):
            hessian_mat = np.zeros((X.shape[1], X.shape[1]))

            hmat_xi = self.hessian(X,y, theta)
            hessian_mat += hmat_xi
            cost, grad = self.costFunc(theta, X,y)
            theta = theta - np.linalg.pinv(hessian_mat) @ grad

```

```

        J_history.append(cost)
        theta_history.append(theta)
    J_min_index = np.argmin(J_history)
    return theta_history[J_min_index] , J_history

def predict(self,X, theta):
    labels=[]
    y_pred = self.h(X, theta)
    for i in range(len(y_pred)):
        if y_pred[i] >= 0.5:
            labels.append(1)
        else:
            labels.append(0)
    # YOUR CODE HERE
    #raise NotImplementedError()

    labels=np.asarray(labels)
    return labels

def getAccuracy(self,X,y,theta):
    #percent_correct = None
    # YOUR CODE HERE
    y_pred = self.predict(X, theta)
    y_pred = y_pred.reshape(y.shape)
    percent_correct = 100*np.sum(y == y_pred).astype(int) / y.shape[0]
    #raise NotImplementedError()
    return percent_correct

```

In [28]:

```

# Test function: Do not remove
lbgd = Logistic_NM()
test_x = np.array([[1,2,3,4,5]]).T
out_x1 = lbgd.sigmoid(test_x)
out_x2 = lbgd.sigmoid(test_x.T)
print('out_x1', out_x1.T)
assert np.array_equal(np.round(out_x1.T, 5), np.round([[0.73105858, 0.88079708, 0.95257
assert np.array_equal(np.round(out_x2, 5), np.round([[0.73105858, 0.88079708, 0.9525741
test_t = np.array([[0.3, 0.2]]).T
test_x = np.array([[1,2,3,4,5, 6], [2, 9, 4, 3, 1, 0]]).T
test_y = np.array([[0,1,0,1,0,1]]).T
test_y_p = lbgd.h(test_x, test_t)
print('test_y_p', test_y_p.T)
assert np.array_equal(np.round(test_y_p.T, 5), np.round([[0.66818777, 0.9168273, 0.8455
test_g = lbgd.gradient(test_x, test_y, test_y_p)
print('test_g', test_g.T)
assert np.array_equal(np.round(test_g.T, 5), np.round([[0.9746016, 0.73165696]], 5)), "
test_h = lbgd.hessian(test_x, test_y, test_t)
print('test_h', test_h)
assert test_h.shape == (2, 2), "hessian matrix function is incorrect"
assert np.array_equal(np.round(test_h.T, 5), np.round([[12.17334371, 6.55487738],[ 6.55
test_c, test_g = lbgd.costFunc(test_t, test_x, test_y)
print('test_c', test_c.T)
assert np.round(test_c, 5) == np.round(0.87192491, 5), "costFunc function is incorrect"
test_t_out , test_j = lbgd.newtonsMethod(test_x, test_y, test_t, 3)
print('test_t_out', test_t_out.T)
print('test_j', test_j)
assert np.array_equal(np.round(test_t_out.T, 5), np.round([[0.14765747, 0.15607017]], 5
assert np.round(test_j[2], 5) == np.round(0.7534506190845247, 5), "newtonsMethod functi

```

```

test_l = lbgd.predict(test_x, test_t)
print('test_l', test_l)
assert np.array_equal(np.round(test_l, 1), np.round([1,1,1,1,1,1], 1)), "gradientAscent
test_a = lbgd.getAccuracy(test_x, test_y, test_t)
print('test_a', test_a)
assert np.round(test_a, 1) == 50.0, "getAccuracy function is incorrect"

print("success!")
# End Test function

```

```

out_x1 [[0.73105858 0.88079708 0.95257413 0.98201379 0.99330715]]
test_y_p [[0.66818777 0.9168273 0.84553473 0.85814894 0.84553473 0.85814894]]
test_g [[0.9746016 0.73165696]]
test_h [[12.17334371 6.55487738]
 [ 6.55487738 14.84880387]]
test_c 0.8719249134773479
test_t_out [[0.14765747 0.15607017]]
test_j [0.8719249134773479, 0.7967484437157274, 0.7534506190845246]
test_l [1 1 1 1 1 1]
test_a 50.0
success!

```

**Expect result:** out\_x1 [[0.73105858 0.88079708 0.95257413 0.98201379 0.99330715]]\ test\_y\_p [[0.66818777 0.9168273 0.84553473 0.85814894 0.84553473 0.85814894]]\ test\_g [[0.9746016 0.73165696]]\ test\_h [[12.17334371 6.55487738]\ [ 6.55487738 14.84880387]]\ test\_c 0.8719249134773479\ Minimum at iteration: 2\ test\_t\_out [[0.14765747 0.15607017]]\ test\_j [0.8719249134773479, 0.7967484437157274, 0.7534506190845247]\ test\_l [1 1 1 1 1 1]\ test\_a 50.0

In [29]:

```

NM_model = Logistic_NM()

iterations = 1000

nm_theta, nm_cost = NM_model.newtonsMethod(X_design_train, y_train, initial_theta, iter
print("theta:", nm_theta)

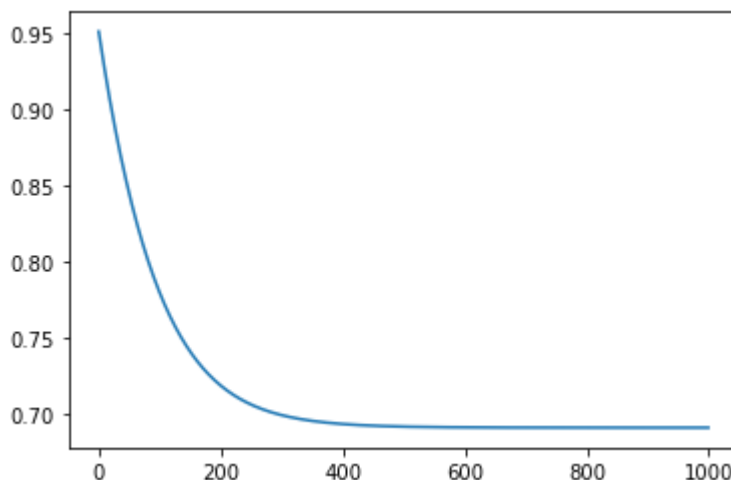
print(nm_cost[0])
plt.plot(nm_cost)
plt.show()

```

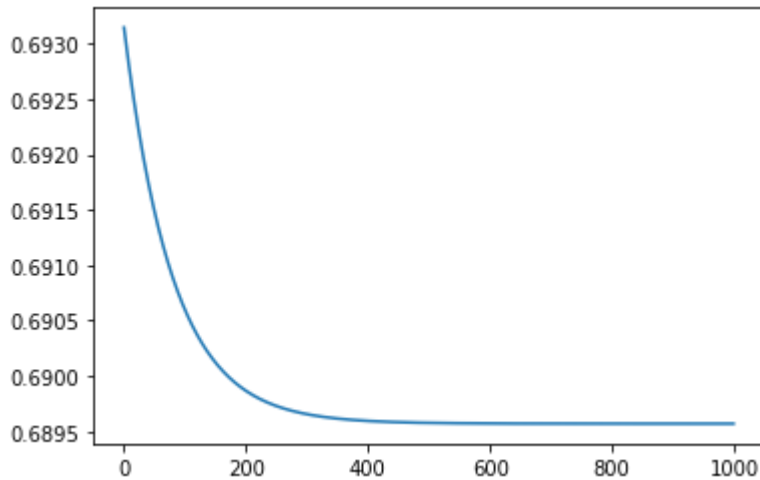
```

theta: [[0.09785403]
 [0.04983972]
 [0.03835179]]
0.9509809835169094

```



**Expected result (or look alike):** \ Minimum at iteration: 999 \ theta:  $\begin{bmatrix} -0.07313861 \\ -0.13605172 \end{bmatrix}$   $\begin{bmatrix} 0.05419746 \\ 0.6931471805599453 \end{bmatrix}$

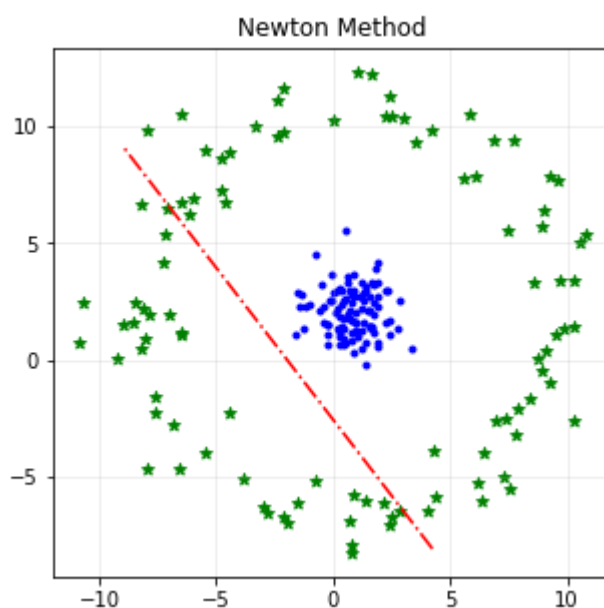


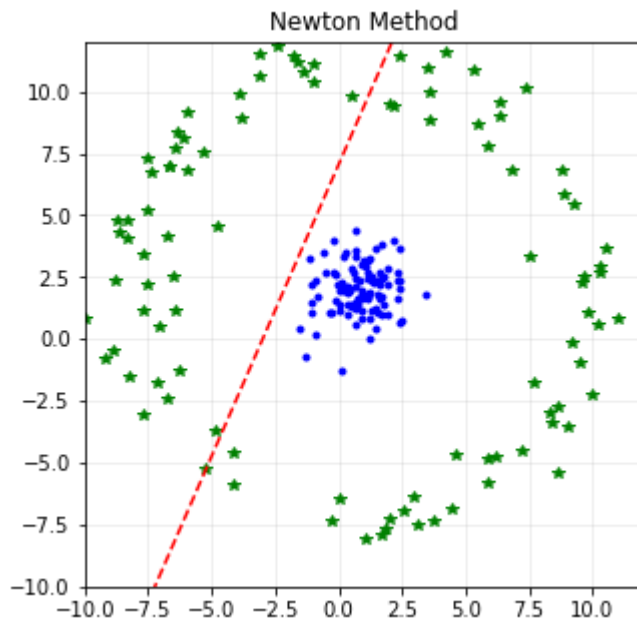
## Exercise 2.2 (5 points)

Plot the optimal decision boundary of Newton method

```
In [30]: # YOUR CODE HERE
fig1 = plt.figure(figsize=(5,5))
ax = plt.axes()
ax.set_aspect(aspect = 'equal', adjustable = 'box')
plt.title('Newton Method')
plt.grid(axis='both', alpha=.25)
plt.scatter(X1[:,0], X1[:,1], c='b', marker='.', label='class 1')
plt.scatter(X2[:,0], X2[:,1], c='g', marker='*', label='class 2')

point_1, point_2 = boundary_points(X, nm_theta)
plt.plot([point_1[0,0], point_2[0,0]], [point_1[1,0], point_2[1,0]], 'r-.')
plt.show()
#raise NotImplementedError()
```



**Expected result (or look alike):**

```
In [31]: print("Accuracy =", NM_model.getAccuracy(X_design_test, y_test, nm_theta))
```

Accuracy = 22.5

**Exercise 2.3 (5 points)**

Compare the number of iterations required for gradient descent vs. Newton's method. Do you observe other issues with Newton's method such as a singular or nearly singular Hessian matrix?

YOUR ANSWER HERE

**Take-home exercises**

1. Perform a *polar transformation* on the data above to obtain a linearly separable dataset. (5 points)
2. Verify that you obtain good classification accuracy for logistic regression with GD or Newton's method after the polar transformation (10 points)
3. Apply Newton's method to the dataset you used for the take home exercises in Lab 03. (20 points)

polar coordinates is a mapping from a point  $(r, \theta)$  in the polar coordinate plane to the corresponding point  $(x, y)$  in the Cartesian coordinate plane

$$r^2 = x^2 + y^2 \quad x = r \cos \theta \quad y = r \sin \theta$$

```
In [32]: df = pd.DataFrame(X, columns=['X0', 'X1'])
df['angles'] = np.arctan(df.X1 / df.X0)
df['radius'] = np.sqrt(df.X0 ** 2 + df.X1 ** 2)
df['y'] = y
```

```

newX = df[['angles', 'radius']].values
newX = np.insert(newX, 0, 1, axis=1)
X_train = newX[idx_train]
X_test = newX[idx_test]
y_train = y[idx_train]
y_test = y[idx_test]

```

In [33]:

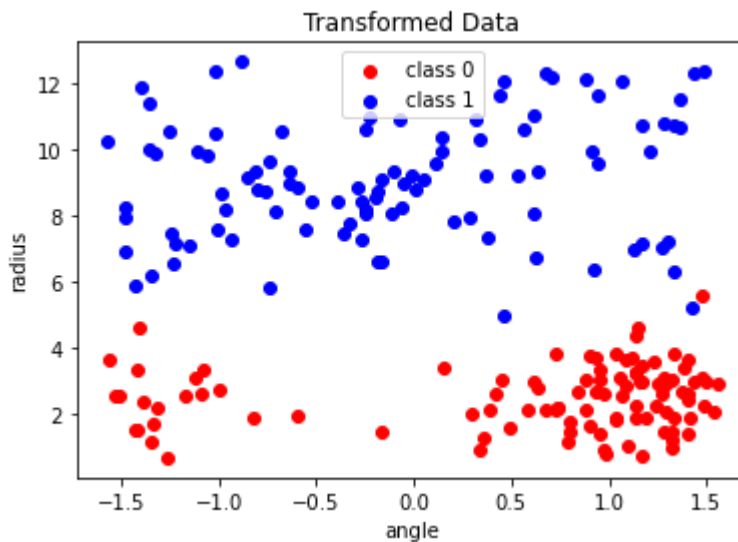
```

y0_df = df[df.y == 0]
y1_df = df[df.y == 1]

plt.title('Transformed Data')
plt.scatter(y0_df.angles, y0_df.radius, c='r', label='class 0')
plt.scatter(y1_df.angles, y1_df.radius, c='b', label='class 1')
plt.legend()
plt.xlabel('angle')
plt.ylabel('radius')

```

Out[33]: Text(0, 0.5, 'radius')



In [34]:

```

alpha = 0.001
iterations = 50000

BGD_model = Logistic_BGD()

initial_theta = np.ones((X_train.shape[1],1))
bgd_theta_polar, bgd_cost = BGD_model.gradientAscent(X_train, y_train, initial_theta, alpha)
print('theta: ', bgd_theta_polar)

```

```

Minimum at iteration: 49999
theta: [[-3.61385119]
        [-0.6266392 ]
        [ 0.77783254]]

```

In [35]:

```

NM_model = Logistic_NM()

iterations = 1000

nm_theta_polar, nm_cost = NM_model.newtonsMethod(X_train, y_train, initial_theta, iterations)
print("theta:", nm_theta_polar)

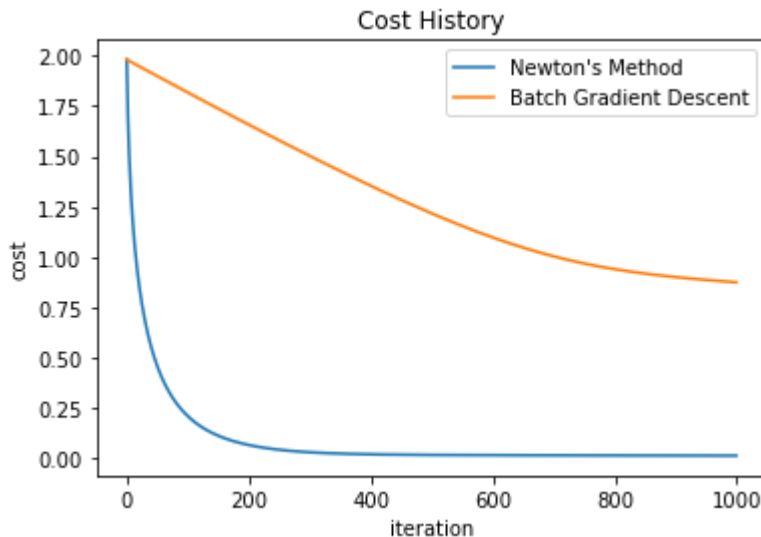
```

```
theta: [[-12.18409525]
 [ -0.12961706]
 [ 2.36698771]]
```

In [36]:

```
plt.plot(nm_cost, label='Newton\'s Method')
plt.plot(bgd_cost[:iterations], label='Batch Gradient Descent')
plt.title('Cost History')
plt.xlabel('iteration')
plt.ylabel('cost')
plt.legend()
plt.show()

print('Minimum Cost for each method from polar transformation')
print('Gradient Descent:', np.min(bgd_cost))
print('Newton\'s Method :', np.min(nm_cost))
```



Minimum Cost for each method from polar transformation

Gradient Descent: 0.11419681571541887

Newton's Method : 0.015572427864877987

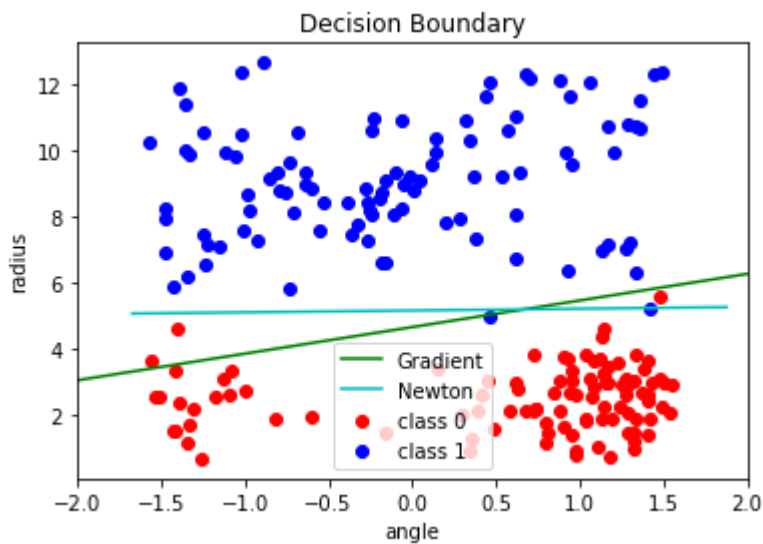
In [37]:

```
y0_df = df[df.y == 0]
y1_df = df[df.y == 1]

point_1, point_2 = boundary_points(newX[:,1:], bgd_theta_polar)
point_1n, point_2n = boundary_points(newX[:,1:], nm_theta_polar)

plt.title('Decision Boundary')
plt.scatter(y0_df.angles, y0_df.radius, c='r', label='class 0')
plt.scatter(y1_df.angles, y1_df.radius, c='b', label='class 1')
plt.legend()
plt.xlabel('angle')
plt.ylabel('radius')
plt.plot([point_1[0,0], point_2[0,0]], [point_1[1,0], point_2[1,0]], 'g-', label='Gradie')
plt.plot([point_1n[0,0], point_2n[0,0]], [point_1n[1,0], point_2n[1,0]], 'c-', label='Ne')
plt.legend(loc='best')
plt.xlim(-2,2)
plt.show()
```





```
In [38]: g_acc = BGD_model.getAccuracy(X_train, y_train, bgd_theta_polar)
n_acc = NM_model.getAccuracy(X_train, y_train, nm_theta_polar)

print("Train accuracy for polar transformation")
print('Gradient Accuracy : ', g_acc)
print('Newton Accuracy : ', n_acc)

g_acc = BGD_model.getAccuracy(X_test, y_test, bgd_theta_polar)
n_acc = NM_model.getAccuracy(X_test, y_test, nm_theta_polar)

print("Test accuracy for polar transformation")
print('Gradient Accuracy : ', g_acc)
print('Newton Accuracy : ', n_acc)
```

```
Train accuracy for polar transformation
Gradient Accuracy : 98.125
Newton Accuracy : 99.375
Test accuracy for polar transformation
Gradient Accuracy : 97.5
Newton Accuracy : 95.0
```

## The report

Write a brief report covering your experiments (both in lab and take home) and submit the Jupyter notebook via JupyterHub at <https://puffer.cs.ait.ac.th> before the next lab.

In your solution, be sure to follow instructions!

```
In [39]: # Import Pandas. You may need to run "pip3 install pandas" at the console if it's not a

import pandas as pd

# Import the data

data_train = pd.read_csv('train_LoanPrediction.csv')
data_test = pd.read_csv('test_LoanPrediction.csv')

# Start to explore the data
```

```
print('Training data shape', data_train.shape)
print('Test data shape', data_test.shape)

print('Training data:\n', data_train)
```

Training data shape (614, 13)

Test data shape (367, 12)

Training data:

	Loan_ID	Gender	Married	Dependents	Education	Self_Employed	\
0	LP001002	Male	No	0	Graduate	No	
1	LP001003	Male	Yes	1	Graduate	No	
2	LP001005	Male	Yes	0	Graduate	Yes	
3	LP001006	Male	Yes	0	Not Graduate	No	
4	LP001008	Male	No	0	Graduate	No	
..	...	...	...	...	...	...	
609	LP002978	Female	No	0	Graduate	No	
610	LP002979	Male	Yes	3+	Graduate	No	
611	LP002983	Male	Yes	1	Graduate	No	
612	LP002984	Male	Yes	2	Graduate	No	
613	LP002990	Female	No	0	Graduate	Yes	

	ApplicantIncome	CoapplicantIncome	LoanAmount	Loan_Amount_Term	\
0	5849	0.0	NaN	360.0	
1	4583	1508.0	128.0	360.0	
2	3000	0.0	66.0	360.0	
3	2583	2358.0	120.0	360.0	
4	6000	0.0	141.0	360.0	
..	...	...	...	...	
609	2900	0.0	71.0	360.0	
610	4106	0.0	40.0	180.0	
611	8072	240.0	253.0	360.0	
612	7583	0.0	187.0	360.0	
613	4583	0.0	133.0	360.0	

	Credit_History	Property_Area	Loan_Status
0	1.0	Urban	Y
1	1.0	Rural	N
2	1.0	Urban	Y
3	1.0	Urban	Y
4	1.0	Urban	Y
..	...	...	...
609	1.0	Rural	Y
610	1.0	Rural	Y
611	1.0	Urban	Y
612	1.0	Urban	Y
613	0.0	Semiurban	N

[614 rows x 13 columns]

In [40]:

```
# Check for missing values in the training and test data
```

```
print('Missing values for train data:\n-----\n', data_train.isnull())
print('Missing values for test data \n -----\n', data_test.isnull()).
```

Missing values for train data:

```
-----
Loan_ID          0
Gender           13
Married          3
Dependents       15
```

```

Education          0
Self_Employed      32
ApplicantIncome     0
CoapplicantIncome   0
LoanAmount          22
Loan_Amount_Term    14
Credit_History     50
Property_Area       0
Loan_Status         0
dtype: int64
Missing values for test data
-----
Loan_ID            0
Gender             11
Married            0
Dependents         10
Education          0
Self_Employed      23
ApplicantIncome     0
CoapplicantIncome   0
LoanAmount          5
Loan_Amount_Term    6
Credit_History     29
Property_Area       0
dtype: int64

```

In [41]:

```

# Compute ratio of each category value
# Divide the missing values based on ratio
# Fillin the missing values
# Print the values before and after filling the missing values for confirmation

print(data_train['Married'].value_counts())

married = data_train['Married'].value_counts()
print('Elements in Married variable', married.shape)
print('Married ratio ', married[0]/sum(married.values))

def fill_marital_status(data, yes_num_train, no_num_train):
    data['Married'].fillna('Yes', inplace = True, limit = yes_num_train)
    data['Married'].fillna('No', inplace = True, limit = no_num_train)

fill_marital_status(data_train, 2, 1)
print(data_train['Married'].value_counts())
print('Missing values for train data:\n-----\n', data_train.isnull())

```

```

Yes    398
No     213
Name: Married, dtype: int64
Elements in Married variable (2,)
Married ratio  0.6513911620294599
Yes    400
No     214
Name: Married, dtype: int64
Missing values for train data:
-----
Loan_ID            0
Gender             13
Married            0
Dependents         15
Education          0

```

```

Self_Employed      32
ApplicantIncome     0
CoapplicantIncome   0
LoanAmount          22
Loan_Amount_Term    14
Credit_History     50
Property_Area       0
Loan_Status         0
dtype: int64

```

In [42]:

```

print(data_train['Dependents'].value_counts())
dependent = data_train['Dependents'].value_counts()

print('Dependent ratio 1 ', dependent['0'] / sum(dependent.values))
print('Dependent ratio 2 ', dependent['1'] / sum(dependent.values))
print('Dependent ratio 3 ', dependent['2'] / sum(dependent.values))
print('Dependent ratio 3+ ', dependent['3+'] / sum(dependent.values))

def fill_dependent_status(num_0_train, num_1_train, num_2_train, num_3_train, num_0_test, num_1_test, num_2_test, num_3_test):
    data_train['Dependents'].fillna('0', inplace=True, limit = num_0_train)
    data_train['Dependents'].fillna('1', inplace=True, limit = num_1_train)
    data_train['Dependents'].fillna('2', inplace=True, limit = num_2_train)
    data_train['Dependents'].fillna('3+', inplace=True, limit = num_3_train)
    data_test['Dependents'].fillna('0', inplace=True, limit = num_0_test)
    data_test['Dependents'].fillna('1', inplace=True, limit = num_1_test)
    data_test['Dependents'].fillna('2', inplace=True, limit = num_2_test)
    data_test['Dependents'].fillna('3+', inplace=True, limit = num_3_test)

fill_dependent_status(9, 2, 2, 2, 5, 2, 2, 1)

print(data_train['Dependents'].value_counts())

# Convert category value "3+" to "4"

data_train['Dependents'].replace('3+', 4, inplace = True)
data_test['Dependents'].replace('3+', 4, inplace = True)

0      345
1      102
2      101
3+      51
Name: Dependents, dtype: int64
Dependent ratio 1  0.5759599332220368
Dependent ratio 2  0.17028380634390652
Dependent ratio 3  0.1686143572621035
Dependent ratio 3+ 0.08514190317195326
0      354
1      104
2      103
3+      53
Name: Dependents, dtype: int64

```

In [43]:

```

print(data_train['LoanAmount'].value_counts())

LoanAmt = data_train['LoanAmount'].value_counts()

print('mean loan amount ', np.mean(data_train["LoanAmount"]))

loan_amount_mean = np.mean(data_train["LoanAmount"])

```

```
data_train['LoanAmount'].fillna(loan_amount_mean, inplace=True, limit = 22)
data_test['LoanAmount'].fillna(loan_amount_mean, inplace=True, limit = 5)
```

```
120.0    20
110.0    17
100.0    15
187.0    12
160.0    12
..
570.0     1
300.0     1
376.0     1
117.0     1
311.0     1
Name: LoanAmount, Length: 203, dtype: int64
mean loan amount  146.41216216216216
```

In [44]:

```
print('Missing values for train data:\n-----\n', data_train.isnull())
print('Missing values for test data \n -----\n', data_test.isnull()).
```

Missing values for train data:

```
-----
Loan_ID          0
Gender           13
Married          0
Dependents       0
Education        0
Self_Employed   32
ApplicantIncome  0
CoapplicantIncome 0
LoanAmount       0
Loan_Amount_Term 14
Credit_History  50
Property_Area    0
Loan_Status      0
dtype: int64
```

Missing values for test data

```
-----
Loan_ID          0
Gender           11
Married          0
Dependents       0
Education        0
Self_Employed   23
ApplicantIncome  0
CoapplicantIncome 0
LoanAmount       0
Loan_Amount_Term 6
Credit_History  29
Property_Area    0
dtype: int64
```

In [45]:

```
print(data_train['Gender'].value_counts())
gender = data_train['Gender'].value_counts()
print('Elements in Gender variable', gender.shape)
Male_ratio = gender[0]/sum(gender.values)
Female_ratio = gender[1]/sum(gender.values)
print('Male ratio ', Male_ratio)
print('Female ratio ', Female_ratio)
```

```

def fill_gender_status(num_male_train, num_female_train, num_male_test, num_female_test,
    data_train['Gender'].fillna('Male', inplace = True, limit = num_male_train)
    data_train['Gender'].fillna('Female', inplace = True, limit = num_female_train)
    data_test['Gender'].fillna('Male', inplace = True, limit = num_male_test)
    data_test['Gender'].fillna('Female', inplace = True, limit = num_female_test)

num_male_train = round(Male_ratio * data_train['Gender'].isnull().sum())
num_female_train = round(Female_ratio * data_train['Gender'].isnull().sum())
num_male_test = round(Male_ratio * data_test['Gender'].isnull().sum())
num_female_test = round(Female_ratio * data_test['Gender'].isnull().sum())
fill_gender_status(num_male_train, num_female_train, num_male_test, num_female_test)

print(data_train['Gender'].value_counts())
print('Missing values for train data:\n-----\n', data_train.isnull())
print('Missing values for test data:\n-----\n', data_test.isnull()).s

```

```

Male      489
Female    112
Name: Gender, dtype: int64
Elements in Gender variable (2,)
Male ratio  0.8136439267886856
Female ratio  0.18635607321131448
Male      500
Female    114
Name: Gender, dtype: int64
Missing values for train data:

```

```

-----
Loan_ID      0
Gender       0
Married      0
Dependents   0
Education    0
Self_Employed 32
ApplicantIncome 0
CoapplicantIncome 0
LoanAmount   0
Loan_Amount_Term 14
Credit_History 50
Property_Area 0
Loan_Status  0
dtype: int64

```

Missing values for test data:

```

-----
Loan_ID      0
Gender       0
Married      0
Dependents   0
Education    0
Self_Employed 23
ApplicantIncome 0
CoapplicantIncome 0
LoanAmount   0
Loan_Amount_Term 6
Credit_History 29
Property_Area 0
dtype: int64

```

In [46]: `print(data_train['Self_Employed'].value_counts())`

```

S_E = data_train['Self_Employed'].value_counts()
no_ratio = S_E[0]/sum(S_E.values)
yes_ratio = S_E[1]/sum(S_E.values)
print("Elements in Self-Employed variable ", S_E.shape)
print("No ratio ", no_ratio)
print("yes ratio ", yes_ratio)

def fill_selfemployed_status(num_no_train, num_yes_train, num_no_test, num_yes_test):
    data_train['Self_Employed'].fillna('No', inplace = True, limit = num_no_train)
    data_train['Self_Employed'].fillna('Yes', inplace = True, limit = num_yes_train)
    data_test['Self_Employed'].fillna('No', inplace = True, limit = num_no_test)
    data_test['Self_Employed'].fillna('Yes', inplace = True, limit = num_yes_test)

num_no_train = round(no_ratio * data_train['Self_Employed'].isnull().sum())
num_yes_train = round(yes_ratio * data_train['Self_Employed'].isnull().sum())
num_no_test = round(no_ratio * data_test['Self_Employed'].isnull().sum())
num_yes_test = round(yes_ratio * data_test['Self_Employed'].isnull().sum())
fill_selfemployed_status(num_no_train, num_yes_train, num_no_test, num_yes_test)

print(data_train['Self_Employed'].value_counts())
print('Missing values for train data:\n-----\n', data_train.isnull())
print('Missing values for test data:\n-----\n', data_test.isnull()).s

```

```

No      500
Yes      82
Name: Self_Employed, dtype: int64
Elements in Self-Employed variable  (2,)
No ratio  0.8591065292096219
yes ratio  0.140893470790378
No      527
Yes      87
Name: Self_Employed, dtype: int64
Missing values for train data:
-----

```

Loan_ID	0
Gender	0
Married	0
Dependents	0
Education	0
Self_Employed	0
ApplicantIncome	0
CoapplicantIncome	0
LoanAmount	0
Loan_Amount_Term	14
Credit_History	50
Property_Area	0
Loan_Status	0

```

dtype: int64
Missing values for test data:
-----

```

Loan_ID	0
Gender	0
Married	0
Dependents	0
Education	0
Self_Employed	0
ApplicantIncome	0
CoapplicantIncome	0
LoanAmount	0
Loan_Amount_Term	6

```
Credit_History      29
Property_Area       0
dtype: int64
```

In [47]:

```
print(data_train['Loan_Amount_Term'].value_counts())

LoanAT = data_train['Loan_Amount_Term'].value_counts()

print('mean loan amount term ', np.mean(data_train['Loan_Amount_Term']))

LoanAT_mean = np.mean(data_train['Loan_Amount_Term'])

data_train['Loan_Amount_Term'].fillna(LoanAT_mean, inplace = True, limit = data_train['
data_test['Loan_Amount_Term'].fillna(LoanAT_mean, inplace = True, limit = data_test['Lo

print(data_train['Loan_Amount_Term'].value_counts())
print('Missing values for train data:\n-----\n', data_train.isnull())
print('Missing values for test data:\n-----\n', data_test.isnull()).s
```

```
360.0    512
180.0     44
480.0     15
300.0     13
84.0       4
240.0       4
120.0       3
36.0        2
60.0        2
12.0        1
```

Name: Loan\_Amount\_Term, dtype: int64

mean loan amount term 342.0

```
360.0    512
180.0     44
480.0     15
342.0     14
300.0     13
84.0       4
240.0       4
120.0       3
36.0        2
60.0        2
12.0        1
```

Name: Loan\_Amount\_Term, dtype: int64

Missing values for train data:

```
-----
Loan_ID      0
Gender       0
Married      0
Dependents   0
Education    0
Self_Employed 0
ApplicantIncome 0
CoapplicantIncome 0
LoanAmount   0
Loan_Amount_Term 0
Credit_History 50
Property_Area 0
Loan_Status  0
dtype: int64
```



Missing values for test data:

```
-----
Loan_ID          0
Gender           0
Married         0
Dependents      0
Education       0
Self_Employed   0
ApplicantIncome 0
CoapplicantIncome 0
LoanAmount      0
Loan_Amount_Term 0
Credit_History  29
Property_Area    0
dtype: int64
```

In [48]:

```
print(data_train['Credit_History'].value_counts())

CH = data_train['Credit_History'].value_counts()

ratio_1 = CH[0] / sum(CH.values)
ratio_0 = CH[1] / sum(CH.values)

print('Elements is Credit_History variable ', CH.shape)
print("ratio 1.0 : ", ratio_1)
print("ratio 0.0 : ", ratio_0)

def fill_creditH_status(num_1_train, num_0_train, num_1_test, num_0_test):
    data_train['Credit_History'].fillna(1.0, inplace = True, limit = num_1_train)
    data_train['Credit_History'].fillna(0.0, inplace = True, limit = num_0_train)
    data_test['Credit_History'].fillna(1.0, inplace = True, limit = num_1_test)
    data_test['Credit_History'].fillna(0.0, inplace = True, limit = num_0_test)

num_1_train = round(ratio_1 * data_train['Credit_History'].isnull().sum())
num_0_train = round(ratio_0 * data_train['Credit_History'].isnull().sum())
num_1_test = round(ratio_1 * data_test['Credit_History'].isnull().sum())
num_0_test = round(ratio_0 * data_test['Credit_History'].isnull().sum())

fill_creditH_status(num_1_train, num_0_train, num_1_test, num_0_test)

print(data_train['Credit_History'].value_counts())
print('Missing values for train data:\n-----\n', data_train.isnull())
print('Missing values for test data:\n-----\n', data_test.isnull().s
```

```
1.0    475
0.0     89
Name: Credit_History, dtype: int64
Elements is Credit_History variable (2,)
ratio 1.0 : 0.15780141843971632
ratio 0.0 : 0.8421985815602837
1.0    483
0.0    131
Name: Credit_History, dtype: int64
Missing values for train data:
-----
Loan_ID          0
Gender           0
Married         0
Dependents      0
```

```

Education          0
Self_Employed      0
ApplicantIncome    0
CoapplicantIncome  0
LoanAmount         0
Loan_Amount_Term   0
Credit_History     0
Property_Area      0
Loan_Status        0
dtype: int64
Missing values for test data:
-----
Loan_ID           0
Gender            0
Married           0
Dependents        0
Education         0
Self_Employed     0
ApplicantIncome   0
CoapplicantIncome 0
LoanAmount        0
Loan_Amount_Term  0
Credit_History    0
Property_Area     0
dtype: int64

```

```

In [49]: data_train.drop(columns=['Loan_ID'], inplace = True)
         data_test.drop(columns=['Loan_ID'], inplace = True)

```

```

In [50]: data_train['Dependents'] = data_train['Dependents'].astype(int)
         data_test['Dependents'] = data_test['Dependents'].astype(int)

```

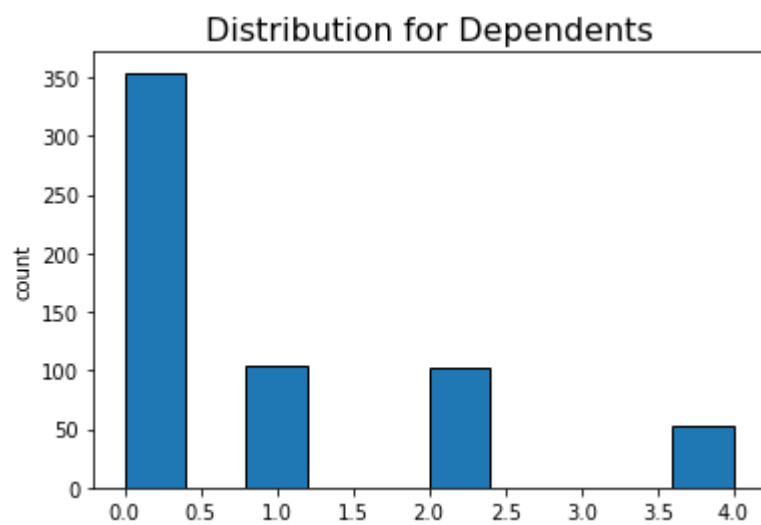
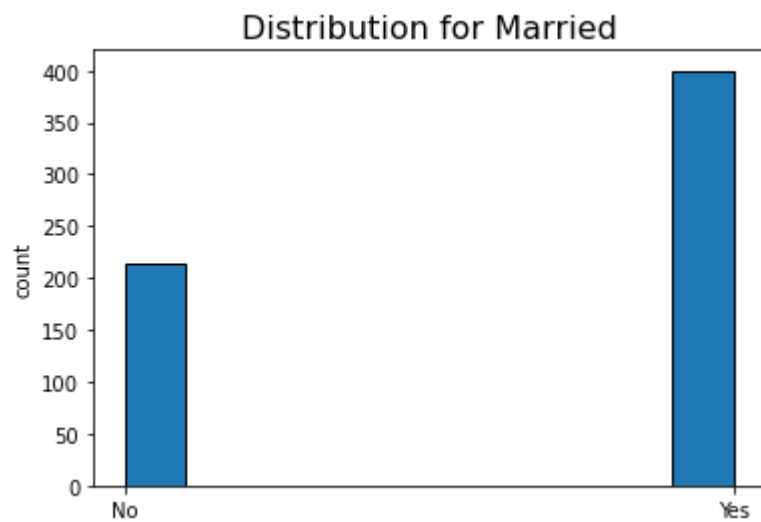
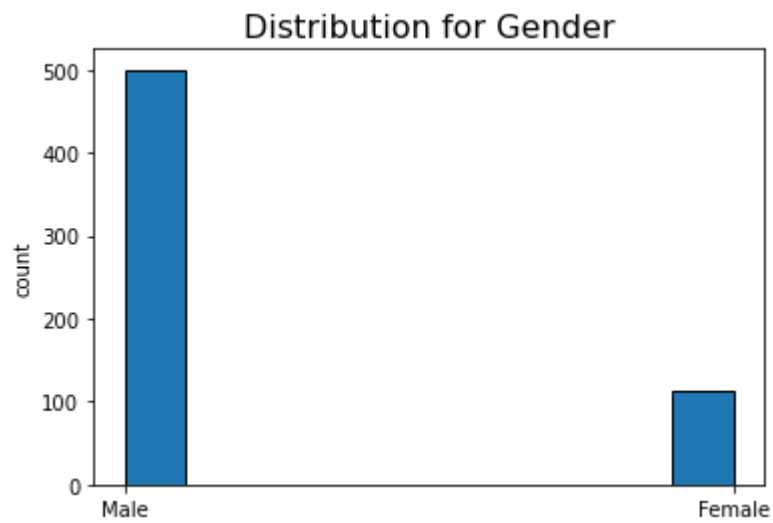
```

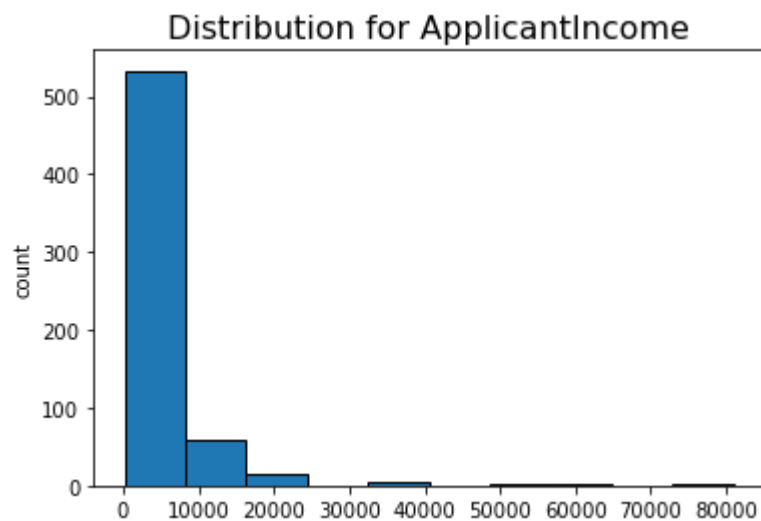
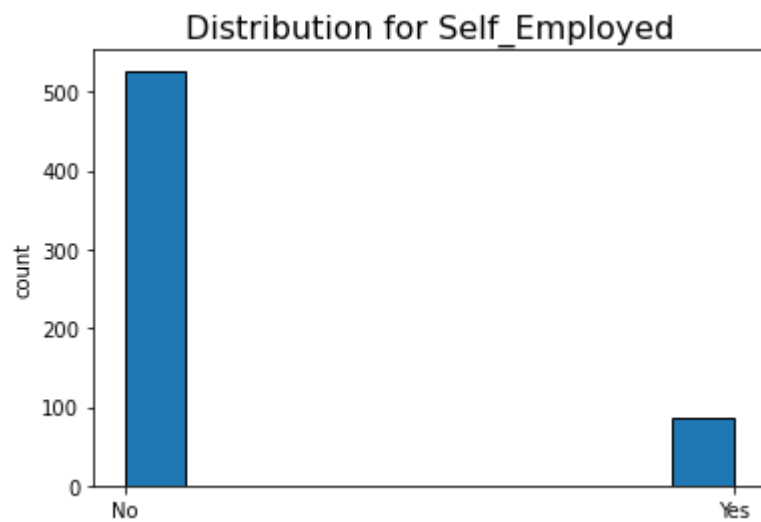
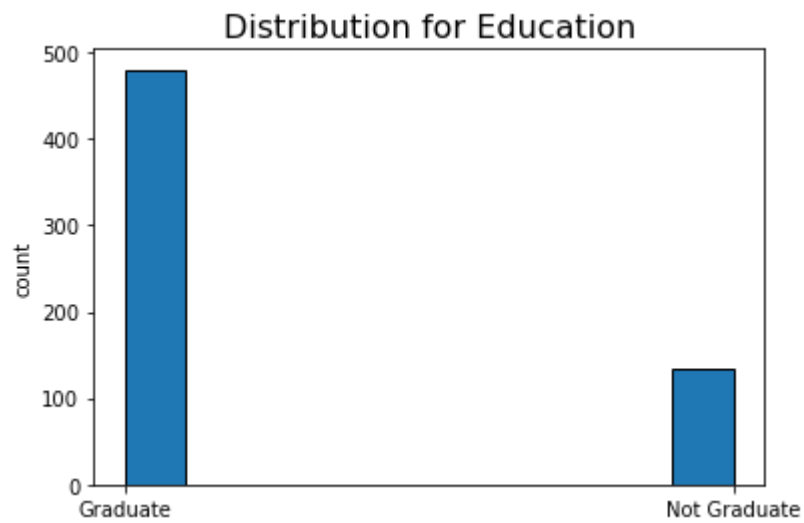
In [51]: column_names = list(data_train.columns)

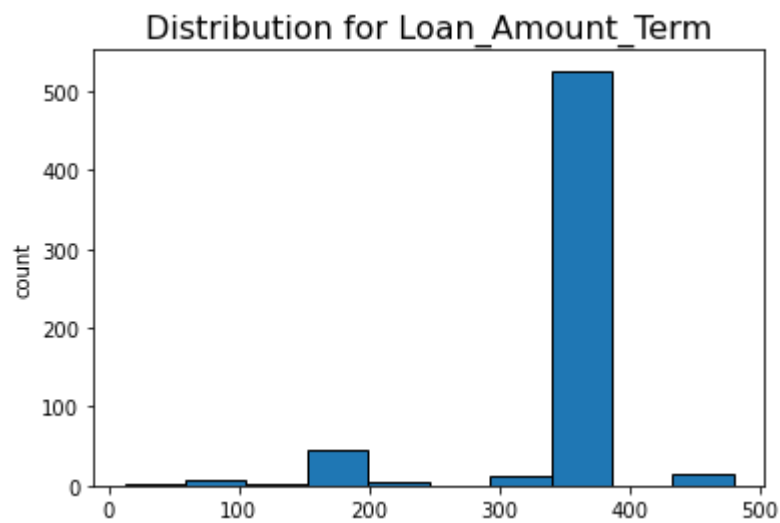
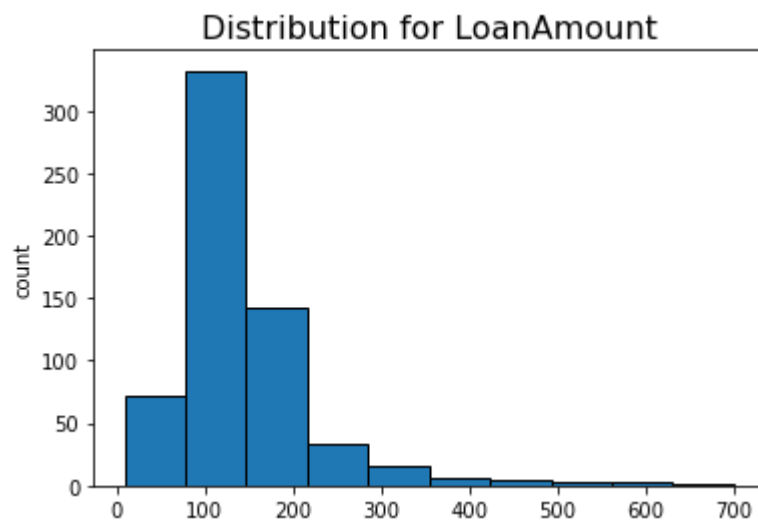
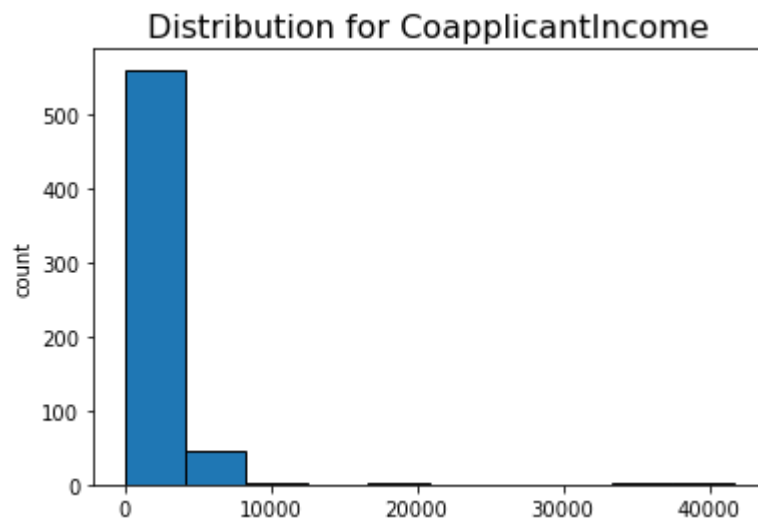
         def hisplot(data, name):
             plt.hist(data[name], edgecolor='black')
             plt.title(f"Distribution for {name}", size=16)
             plt.ylabel('count')
             plt.show()

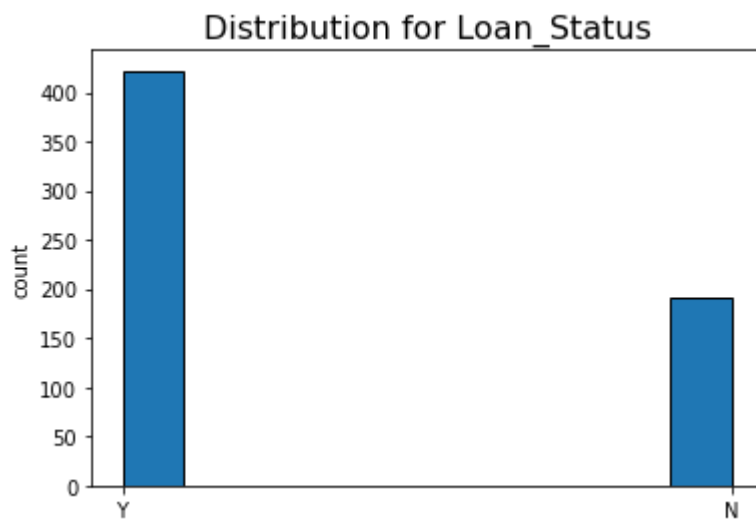
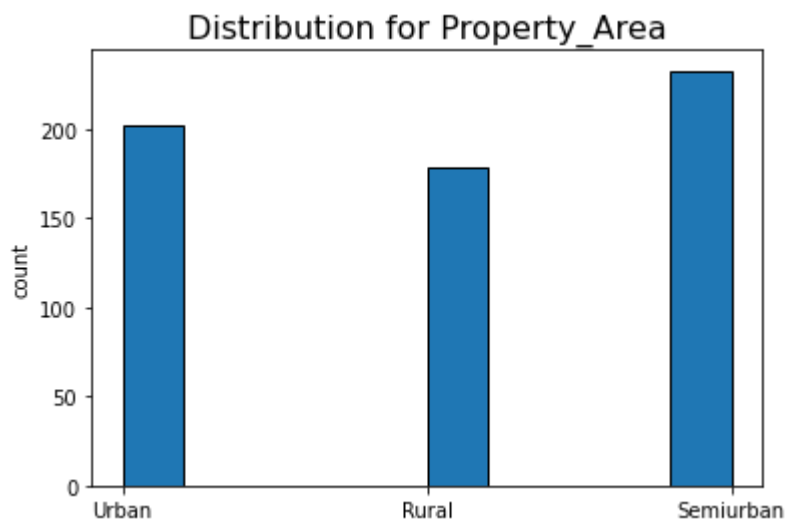
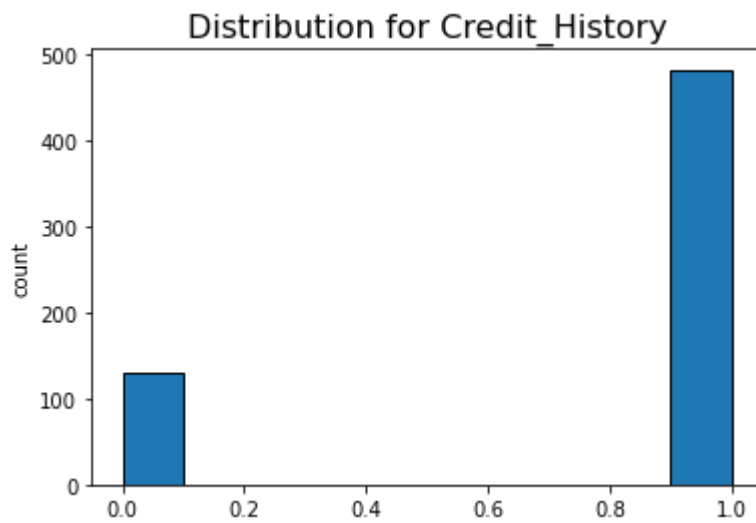
         for names in column_names:
             hisplot(data_train, names)

```









```
In [52]: import pandas as pd

train_gender = pd.Categorical(list(data_train['Gender']), categories=['Male', 'Female'])
test_gender = pd.Categorical(list(data_test['Gender']), categories=['Male', 'Female'])

train_codes, uniques = pd.factorize(train_gender, sort=True)
data_train['Gender'] = train_codes
```

```
test_codes, uniques = pd.factorize(test_gender, sort=True)
data_test['Gender'] = test_codes
```

```
In [53]: train_married = pd.Categorical(list(data_train['Married']), categories=['No', 'Yes'])
test_married = pd.Categorical(list(data_test['Married']), categories=['No', 'Yes'])

train_codes, uniques = pd.factorize(train_married, sort=True)
data_train['Married'] = train_codes

test_codes, uniques = pd.factorize(test_married, sort=True)
data_test['Married'] = test_codes
```

```
In [54]: train_edu = pd.Categorical(list(data_train['Education']), categories = data_train['Educ
test_edu = pd.Categorical(list(data_test['Education']), categories = data_test['Educati

train_codes, uniques = pd.factorize(train_edu, sort=True)
data_train['Education'] = train_codes

test_codes, uniques = pd.factorize(test_edu, sort=True)
data_test['Education'] = test_codes
```

```
In [55]: train_se = pd.Categorical(list(data_train['Self_Employed']), categories=data_train['Sel
test_se = pd.Categorical(list(data_test['Self_Employed']), categories=data_test['Self_E

train_codes, uniques = pd.factorize(train_se, sort=True)
data_train['Self_Employed'] = train_codes

test_codes, uniques = pd.factorize(test_se, sort=True)
data_test['Self_Employed'] = test_codes
```

```
In [56]: train_pa = pd.Categorical(list(data_train['Property_Area']), categories=data_train['Pro
test_pa = pd.Categorical(list(data_test['Property_Area']), categories=data_test['Proper

train_codes, uniques = pd.factorize(train_pa, sort=True)
data_train['Property_Area'] = train_codes

test_codes, uniques = pd.factorize(test_pa, sort=True)
data_test['Property_Area'] = test_codes
```

```
In [57]: train_ls = pd.Categorical(list(data_train['Loan_Status']), categories=data_train['Loan_

train_codes, uniques = pd.factorize(train_ls, sort=True)
data_train['Loan_Status'] = train_codes
```

```
In [58]: data_train.info()
```

```
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 614 entries, 0 to 613
Data columns (total 12 columns):
#   Column          Non-Null Count  Dtype
---  -
0   Gender          614 non-null   int64
```

```

1 Married          614 non-null    int64
2 Dependents       614 non-null    int64
3 Education         614 non-null    int64
4 Self_Employed    614 non-null    int64
5 ApplicantIncome  614 non-null    int64
6 CoapplicantIncome 614 non-null    float64
7 LoanAmount       614 non-null    float64
8 Loan_Amount_Term 614 non-null    float64
9 Credit_History   614 non-null    float64
10 Property_Area   614 non-null    int64
11 Loan_Status     614 non-null    int64
dtypes: float64(4), int64(8)
memory usage: 57.7 KB

```

In [59]:

```
data_test.info()
```

```

<class 'pandas.core.frame.DataFrame'>
RangeIndex: 367 entries, 0 to 366
Data columns (total 11 columns):
#   Column                Non-Null Count  Dtype
---  -
0   Gender                367 non-null    int64
1   Married               367 non-null    int64
2   Dependents            367 non-null    int64
3   Education              367 non-null    int64
4   Self_Employed         367 non-null    int64
5   ApplicantIncome       367 non-null    int64
6   CoapplicantIncome     367 non-null    int64
7   LoanAmount            367 non-null    float64
8   Loan_Amount_Term      367 non-null    float64
9   Credit_History        367 non-null    float64
10  Property_Area         367 non-null    int64
dtypes: float64(3), int64(8)
memory usage: 31.7 KB

```

In [60]:

```
print(data_train.shape)
print(data_test.shape)
```

```

(614, 12)
(367, 11)

```

In [61]:

```

def data_Norm(data):
    means = np.mean(data,axis=0)
    stds = np.std(data, axis=0)
    data_norm = (data - means) / stds
    return data_norm

```

In [62]:

```

y= data_train['Loan_Status']

X = data_train.drop(columns=['Loan_Status'], axis=1)

```

In [63]:

```

X = data_Norm(X)
X = np.array(X)
y = np.array([y]).T

```



```
print(X.shape)
print(y.shape)
```

```
(614, 11)
(614, 1)
```

```
In [64]: X = np.insert(X, 0, 1, axis=1)
         print(X.shape)
```

```
(614, 12)
```

```
In [65]: import random
         def train_test_split(X, y, percent_train, random_seed):
             idx = np.arange(0, X.shape[0])
             random.seed(random_seed)
             random.shuffle(idx)
             m = X.shape[0]
             m_train = int(m * percent_train)
             train_idx = idx[: m_train]
             test_idx = idx[m_train :]

             X_train = X[train_idx, :]
             X_test = X[test_idx, :]

             y_train = y[train_idx]
             y_test = y[test_idx]

             return X_train, X_test, y_train, y_test
```

```
In [66]: percent_train = 0.8
         X_train, X_test, y_train, y_test = train_test_split(X, y, percent_train = percent_train)
         print("X train shape: ", X_train.shape)
         print("X test shape: ", X_test.shape)
         print("Y train shape: ", y_train.shape)
         print("Y test shape: ", y_test.shape)
```

```
X train shape: (491, 12)
X test shape: (123, 12)
Y train shape: (491, 1)
Y test shape: (123, 1)
```

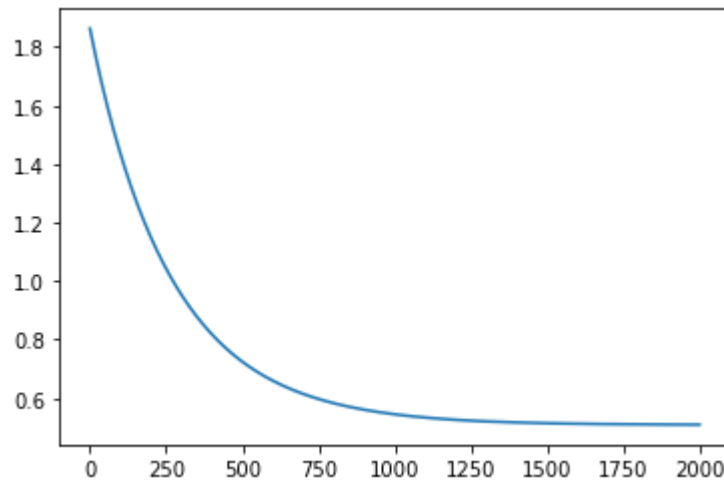
```
In [67]: NM_model = Logistic_NM()

         iterations = 2000
         initial_theta = np.ones((X_train.shape[1],1))
         nm_theta, nm_cost = NM_model.newtonsMethod(X_train, y_train, initial_theta, iterations)
         print("theta:", nm_theta)

         print(nm_cost[0])
         plt.plot(nm_cost)
         plt.show()
```

```
theta: [[-0.87974829]
        [ 0.01223725]
        [-0.21262895]
        [ 0.11319489]
        [ 0.17210148]
```

```
[ 0.06764779]
[ 0.04921505]
[ 0.22121309]
[ 0.05171198]
[ 0.07482697]
[-0.95384756]
[-0.19542552]]
1.8632054110519107
```



In [68]:

```
n_acc = NM_model.getAccuracy(X_train, y_train, nm_theta)
print('Newton Accuracy for training set : ', n_acc)

n_acc = NM_model.getAccuracy(X_test, y_test, nm_theta)
print('Newton Accuracy for test set : ', n_acc)
```

```
Newton Accuracy for training set : 78.61507128309572
Newton Accuracy for test set : 72.35772357723577
```

The test set accuracy is the same as lab 3.

## Summary

The training set accuracy for gradient method and newton methods are the same but the newton method required only 1000 iterations while the gradient method required 50000 iterations with 0.001 alpha.

In newton method, there is sometime occur that the Hessian matrix is singlar which means it does not have inverse matrix. So the `np.linalg.inv` cannot be used for that case but we can use `np.linalg.pinv` for the inverse.

After transforming to polar coordinate, we can the see that the accuracy is improved.

In [ ]: