CSE4203: Computer Graphics Lecture – 5 (part - A) Viewing

#### Outline

- Image-order and object-render rendering
- Viewing transformation
- Viewport transformation
- Orthographic projection transformation

### Rendering Techniques (1/2)

- One of the basic tasks of computer graphics is rendering 3D objects:
  - taking a scene, or model, composed of many geometric objects arranged in 3D space
  - producing a 2D image that shows the objects as viewed
  - from a particular viewpoint.

### Rendering Techniques (2/2)

- 1. <u>Image-order rendering:</u> iterate over the pixels in the image to be produced, rather than the elements in the scene to be rendered.
- 2. <u>object-order rendering:</u> that iterate over the elements in the scene to be rendered, rather than the pixels in the image to be produced.

## Image-order Rendering (1/2)

- Image-order rendering:
  - Ray-tracing:

For each pixel is considered in turn,

- All the objects that influence it are found
- and the pixel value is computed.

### Object-order Rendering (1/2)

- Object-order rendering:
  - Viewing Transformation:

For each object is considered in turn,

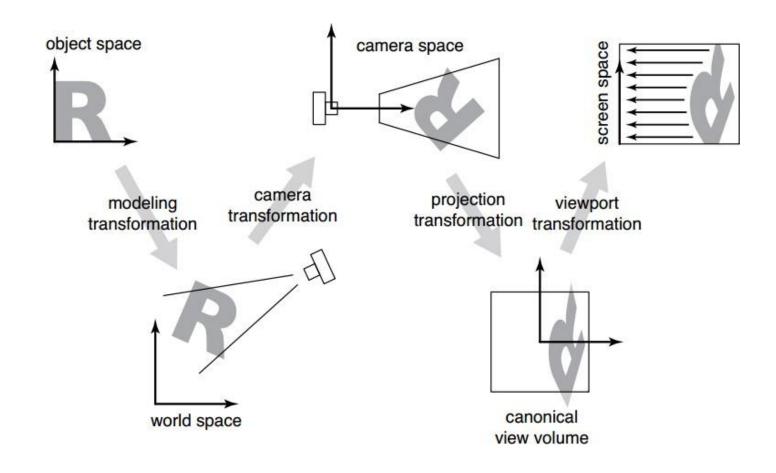
All the pixels that it influences are found and updated

### Object-order Rendering (2/2)

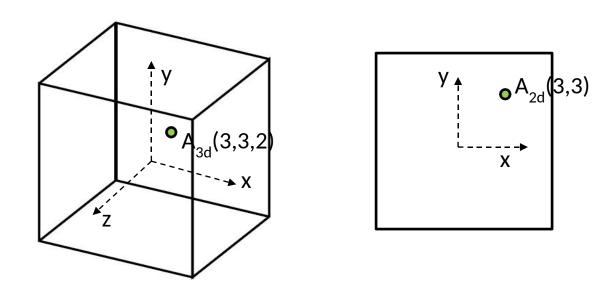
#### Viewing Transformation:

- How to use matrix transformations to express any parallel or perspective view.
- These transformations:
  - Project 3D points in the scene (world space) to 2D points in the image (image space)

#### Viewing Transformation Sequences (1/1)



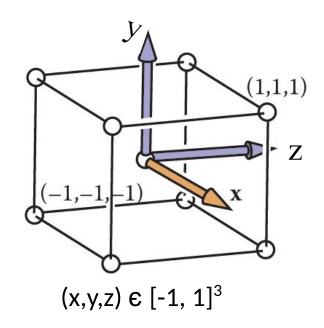
## Viewport Transformation (1/19)



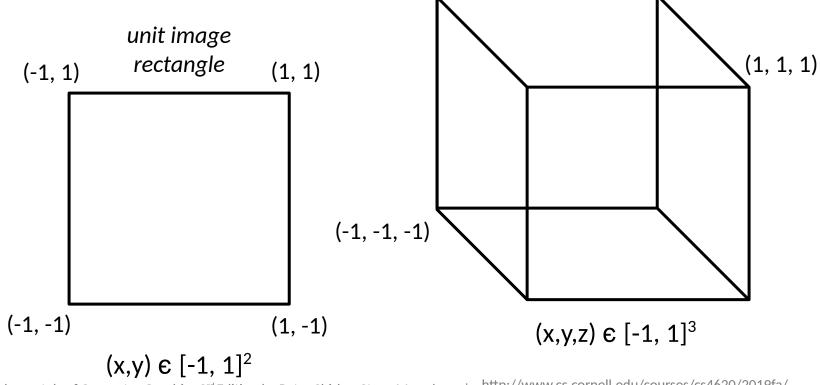
• Projection: Ignoring the z-coordinate

### Viewport Transformation (2/19)

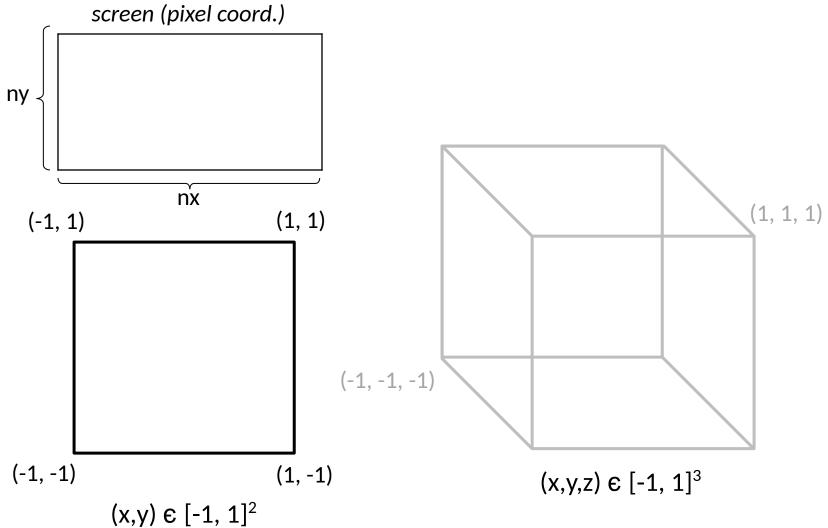
- Canonical View Volume:  $(x,y,z) \in [-1, 1]^3$ 
  - We will assume that the model to be drawn are completely inside the canonical view vol.



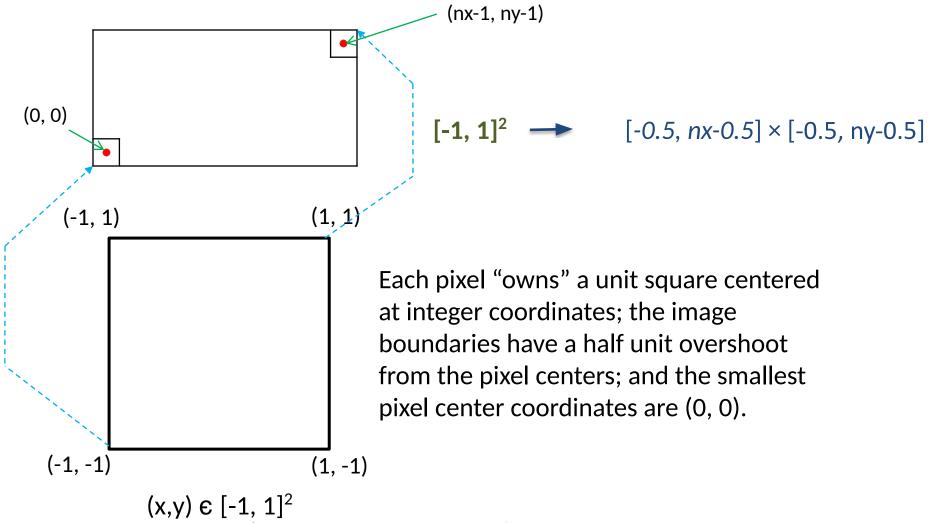
## Viewport Transformation (4/19)



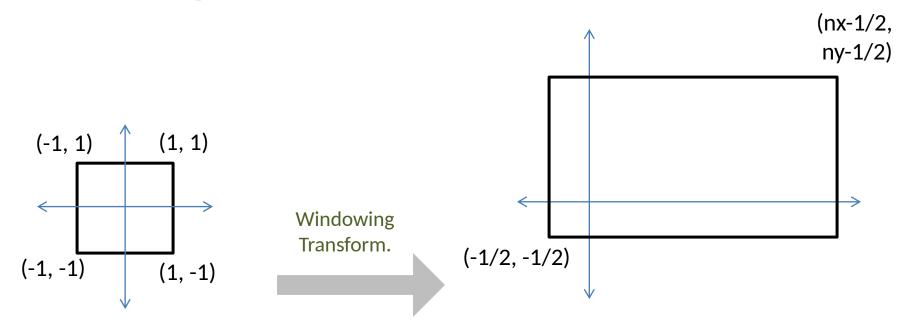
# Viewport Transformation (5/19)



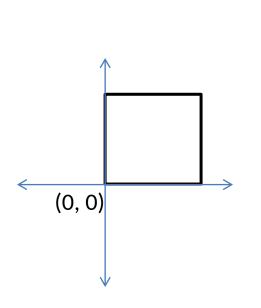
### Viewport Transformation (7/19)

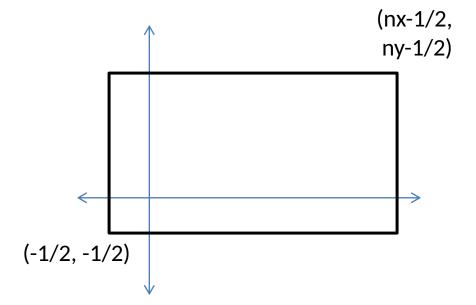


#### Viewport Transformation (8/19)



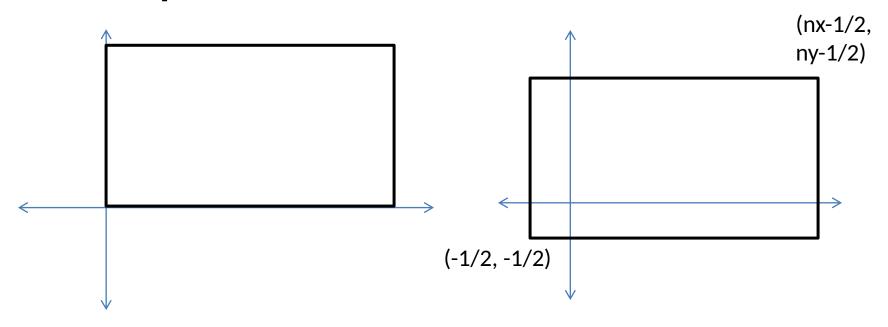
# Viewport Transformation (9/19)





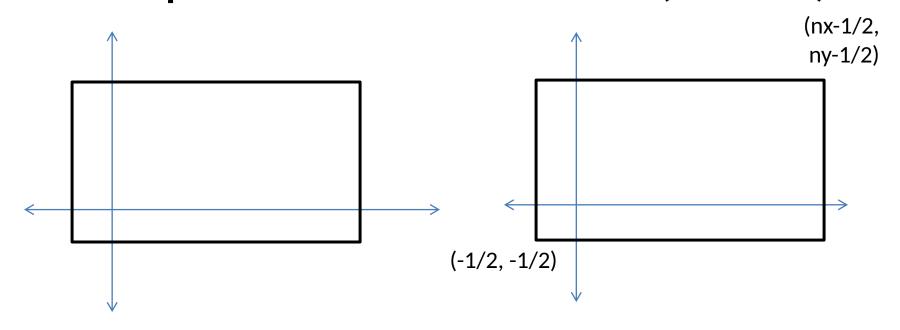
T(1, 1)

# Viewport Transformation (10/19)



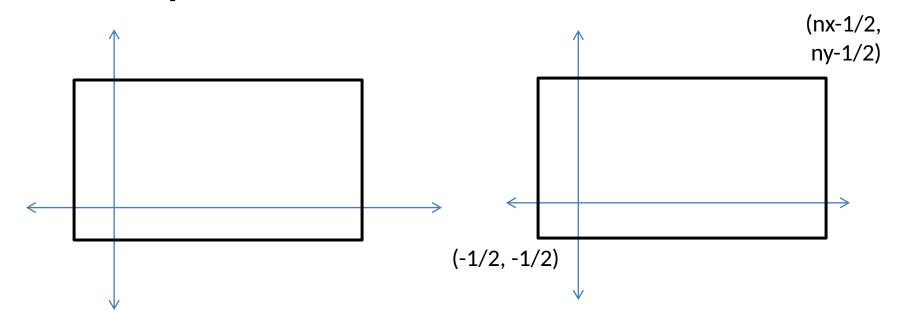
$$T(1, 1) \longrightarrow S(nx/2, ny/2)$$

## Viewport Transformation (11/19)



$$T(1, 1) \longrightarrow S(nx/2, ny/2) \longrightarrow T(-1/2, -1/2)$$

### Viewport Transformation (12/19)



$$T(1, 1) \longrightarrow S(nx/2, ny/2) \longrightarrow T(-1/2, -1/2)$$

$$M_{vp} = T(-1/2, -1/2) * S(nx/2, ny/2) * T(1,1)$$

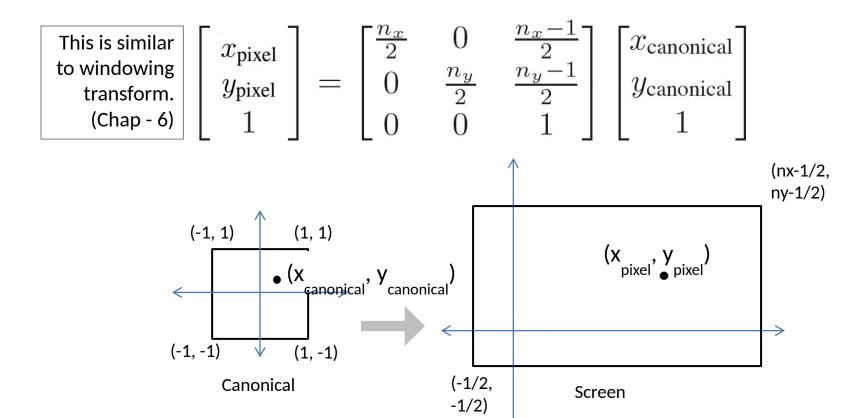
#### Viewport Transformation (15/19)

$$M_{vp} = T(-1/2, -1/2) * S(nx/2, ny/2) * T(1, 1)$$

$$\begin{bmatrix} \frac{n_x}{2} & 0 & \frac{n_x-1}{2} \\ 0 & \frac{n_y}{2} & \frac{n_y-1}{2} \\ 0 & 0 & 1 \end{bmatrix}$$
 Q: Do matrix multiplication and check

### Viewport Transformation (16/19)

$$M_{vp} = T(-1/2, -1/2) * S(nx/2, ny/2) * T(1, 1)$$



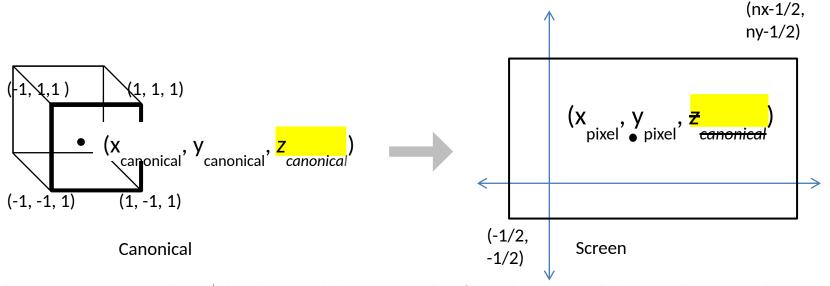
#### Viewport Transformation (18/19)

$$\begin{bmatrix} \frac{n_x}{2} & 0 & \frac{n_x - 1}{2} \\ 0 & \frac{n_y}{2} & \frac{n_y - 1}{2} \\ 0 & 0 & 1 \end{bmatrix}$$

$$M_{\text{vp}} = \begin{bmatrix} \frac{n_x}{2} & 0 & 0 & \frac{n_x - 1}{2} \\ 0 & \frac{n_y}{2} & 0 & \frac{n_y - 1}{2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

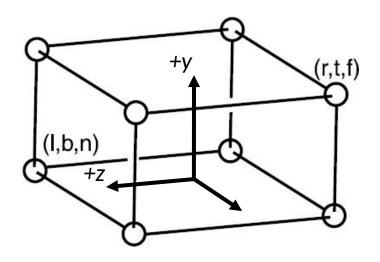
### Viewport Transformation (19/19)

 $\begin{bmatrix} \text{carry along the} \\ \textbf{z-coordinate} \\ \text{without} \\ \text{changing it} \end{bmatrix} = \begin{bmatrix} x_{\text{pixel}} \\ y_{\text{pixel}} \\ z_{\text{canonical}} \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{n_x}{2} & 0 & 0 & \frac{n_x-1}{2} \\ 0 & \frac{n_y}{2} & 0 & \frac{n_y-1}{2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_{\text{canonical}} \\ y_{\text{canonical}} \\ z_{\text{canonical}} \\ 1 \end{bmatrix}$ 



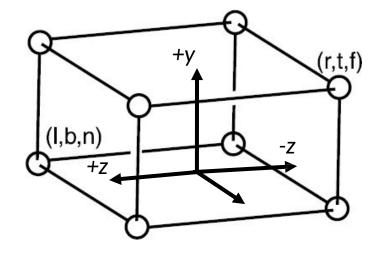
#### Orthographic Projection Transformation (1/1)

• What if we want to render geometry in some region other than canonical view vol.?



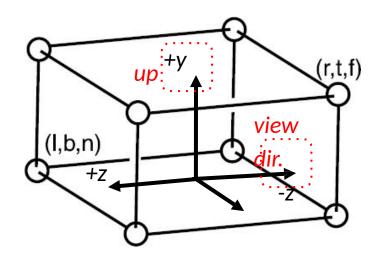
## Orthographic View Volume (1/3)

- We'll name the coordinates of its sides so that the view volume is [I, r] ×
   [b, t] × [f, n]
  - View direction: looking along -z
  - Orientation: +y up
    - $x = 1 \equiv left plane$ ,
    - $x = r \equiv right plane$ ,
    - $y = b \equiv bottom plane$ ,
    - y = t = top plane,
    - z = n = near plane,
    - $z = f \equiv far plane$ .



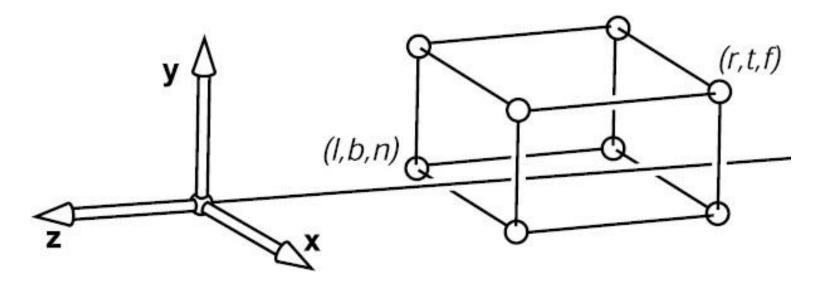
### Orthographic View Volume (2/3)

- Looking along the minus z-axis with his head pointing in the positive y-direction.
  - View direction: looking along -z
  - Orientation: +y up
- But, this is unintuitive!



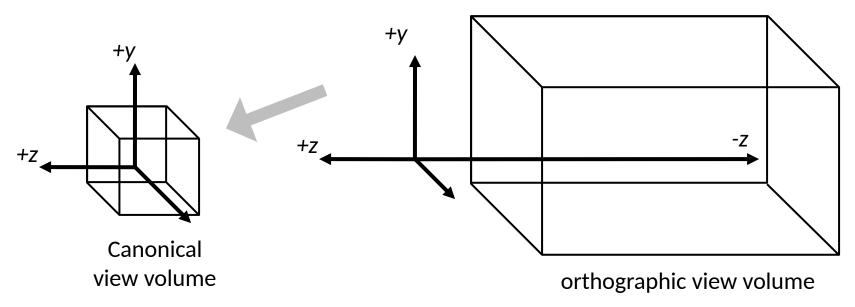
## Orthographic View Volume (3/3)

- If entire orthographic view volume has negative z then n > f.
  - z = n plane is closer



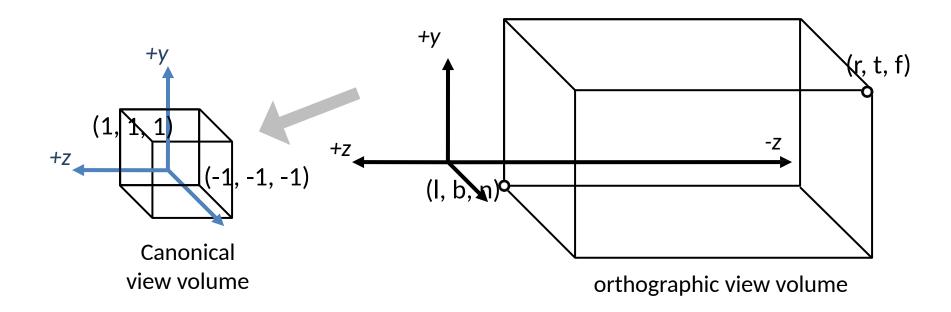
### Orthographic to Canonical View Volume (1/3)

- Transform from orthographic view volume to the canonical view volume
  - We need to apply windowing transformation (just like before!)



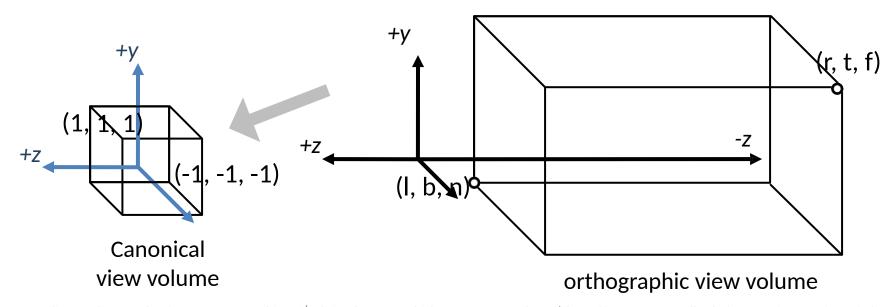
### Orthographic to Canonical View Volume (2/3)

$$\mathbf{M}_{\mathrm{orth}} = egin{bmatrix} rac{2}{r-l} & 0 & 0 & -rac{r+l}{r-l} \ 0 & rac{2}{t-b} & 0 & -rac{t+b}{t-b} \ 0 & 0 & rac{2}{n-f} & -rac{n+f}{n-f} \ 0 & 0 & 0 & 1 \end{bmatrix}$$

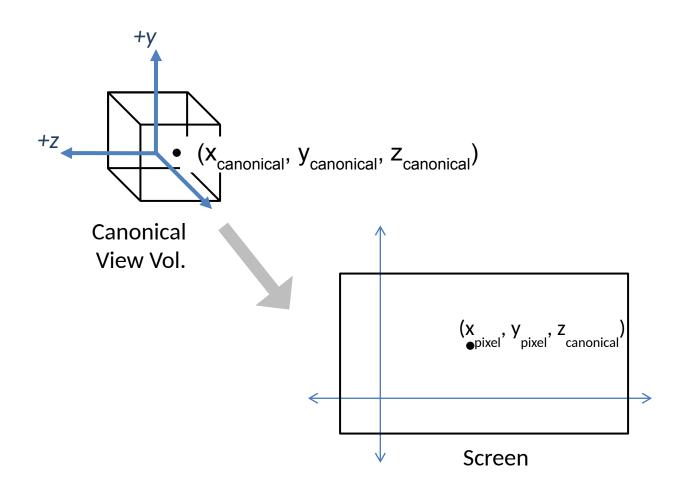


### Orthographic to Canonical View Volume (3/3)

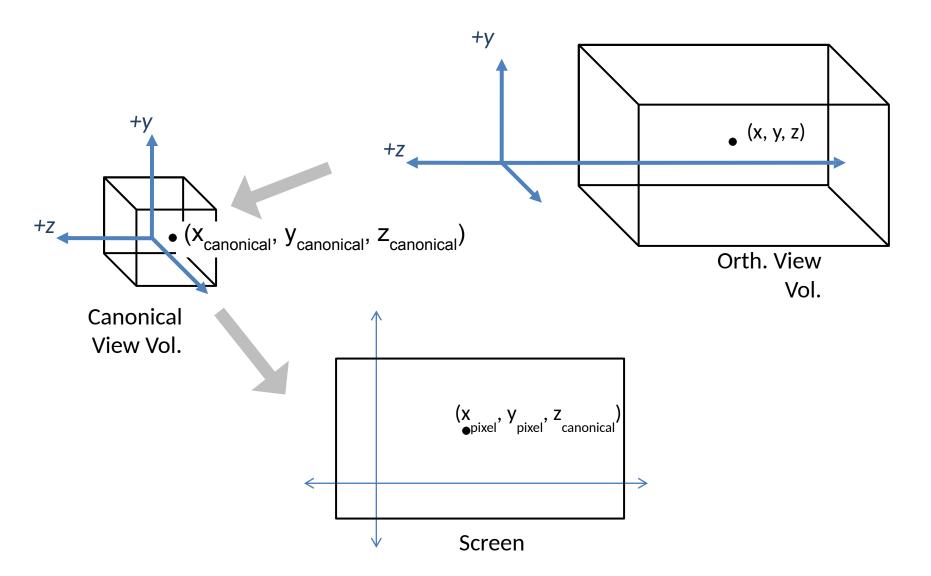
$$\mathbf{M}_{\mathrm{orth}} = \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\ 0 & 0 & \frac{2}{n-f} & -\frac{n+f}{n-f} \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \begin{array}{l} \text{Q: How can we get this} \\ \text{matrix?} \\ \text{Help: Chap 6 (Windowing} \\ \text{Transformation) and } \mathbf{M}_{\text{vp}} \\ \end{array}$$



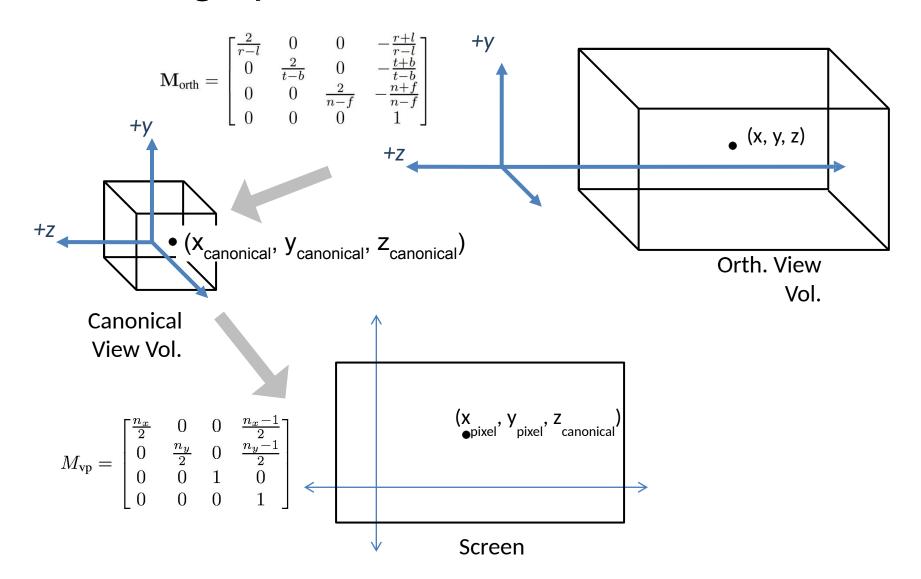
#### Orthographic → Canonical → Screen (1/5)



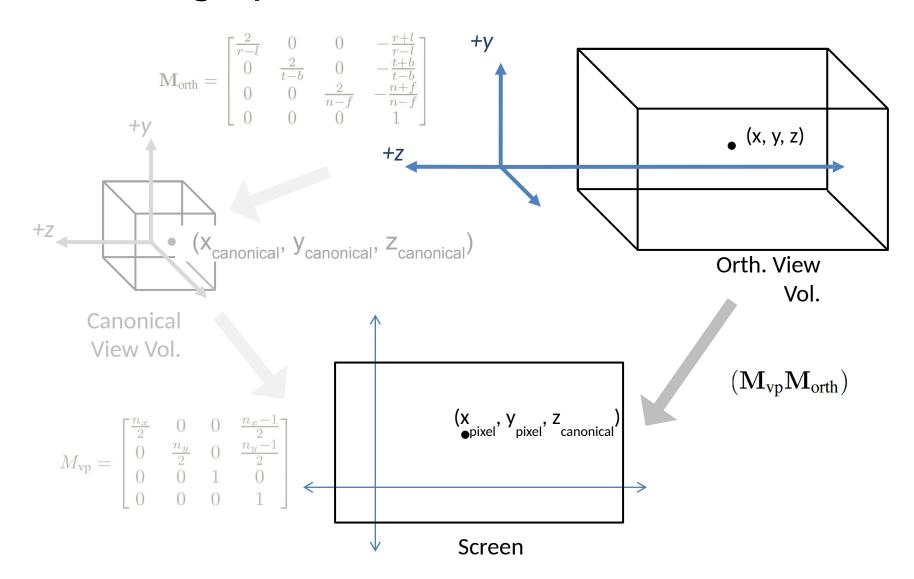
#### Orthographic → Canonical → Screen (2/5)



#### Orthographic → Canonical → Screen (3/5)



#### Orthographic → Canonical → Screen (4/5)



#### Orthographic → Canonical → Screen (5/5)

$$\begin{bmatrix} x_{\text{pixel}} \\ y_{\text{pixel}} \\ z_{\text{canonical}} \\ 1 \end{bmatrix} = (\mathbf{M}_{\text{vp}} \mathbf{M}_{\text{orth}}) \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$
Orth. View Vol.
$$(\mathbf{M}_{\text{vp}} \mathbf{M}_{\text{orth}})$$
Screen

#### Code: Orthographic to Screen (1/1)

#### Drawing many 3D lines with endpoints $a_i$ and $b_i$ :

```
Construct M_{vp}
Construct M_{orth}

M = M_{vp} * M_{vp orth}

for each line segment (a_i, b_i) do:

p = M*a_i

q = M*b_i

drawline (x_p, y_p, x_q, y_q)
```

#### Practice Problem - 1

Transform a 3D line AB from an *orthographic view volume* to a *viewport* of size 128 x 96. Vertices of the line are A(-1, -3, -5) and B(2, 4, -6). The orthographic view volume has the following setup:

$$I = -4$$
,  $r = 4$ ,  $b = -4$ ,  $t = 4$ ,  $n = -4$ ,  $f = -8$ 

You must -

- a. Determine the transformation matrix M.
- b. Multiply M with the vertices of the line and determine the position of vertices on viewport.

#### Practice Problem — 1 (Sol.)

$$M_{
m vp} = egin{bmatrix} rac{n_x}{2} & 0 & 0 & rac{n_x-1}{2} \ 0 & rac{n_y}{2} & 0 & rac{n_y-1}{2} \ 0 & 0 & 1 & 0 \ 0 & 0 & 0 & 1 \ \end{pmatrix} egin{bmatrix} {\sf nx = 128} \ {\sf ny = 96} \ \end{bmatrix}$$

$$\mathbf{M}_{\text{orth}} = \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\ 0 & 0 & \frac{2}{n-f} & -\frac{n+f}{n-f} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$
$$\begin{bmatrix} \mathsf{I} = -4, \, \mathsf{r} = 4, \\ \mathsf{b} = -4, \, \mathsf{t} = 4, \\ \mathsf{n} = -4, \, \mathsf{f} = -8 \end{bmatrix}$$

#### Practice Problem – 1 (Sol.)

$$M = M_{vp}^* M_{orth}$$

$$\mathbf{M} = \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\ 0 & 0 & \frac{2}{n-f} & -\frac{n+f}{n-f} \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{n_x}{2} & 0 & 0 & \frac{n_x-1}{2} \\ 0 & \frac{n_y}{2} & 0 & \frac{n_y-1}{2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$A' = MA$$
 $B' = MB$ 

### **Further Reading**

Fundamentals of Computer Graphics, 4th Edition - Chapter 7