

High Reliability Series Serial EEPROMs

SPI BUS BR25□□□□family



BR25S□□□ Series

No.10001EBT08

Description

BR25S \(\subseteq \subseteq \sete \) series is a serial EEPROM of SPI BUS interface method.

Features

- 1) High speed clock action up to 20MHz (Max.)
- 2) Wait function by HOLDB terminal
- 3) Part or whole of memory arrays settable as read only memory area by program
- 4) 1.7~5.5V single power source action most suitable for battery use
- 5) Page write mode useful for initial value write at factory shipment
- 6) Highly reliable connection by Au pad and Au wire
- 7) For SPI bus interface (CPOL, CPHA) = (0, 0), (1, 1)
- 8) Auto erase and auto end function at data rewrite
- 9) Low current consumption

At write action (5V) : 1.5mA (Typ.) At read action (5V) : 1.0mA (Typ.) At standby action (5V) : 0.1µA (Typ.)

- 10) Address auto increment function at read action
- 11) Write mistake prevention function

Write prohibition at power on

Write prohibition by command code (WRDI)

Write prohibition by WPB pin

Write prohibition block setting by status registers (BP1, BP0)

Write mistake prevention function at low voltage

- 12) SOP8/SOP-J8/SSOP-B8/TSSOP-B8/MSOP8/TSSOP-B8J/VSON008X2030 Package
- 13) Data at shipment Memory array: FFh, status register WPEN, BP1, BP0:0
- 14) Data kept for 40 years
- 15) Data rewrite up to 1,000,000 times

●Page Write

Page	32Byte	64Byte
Part Number	BR25S320-W BR25S640-W	BR25S128-W BR25S256-W

●BR25S□□□ series

_	DIVZJOLL									
	Capacity	Bit format	Power source voltage	SOP8	SOP-J8	SSOP-B8	TSSOP-B8	MSOP8	TSSOP-B8J	VSON008 X2030
	32Kbit	4K×8	1.7V~5.5V	•	•	•	•	•	•	•
	64Kbit	8K×8	1.7V~5.5V	•	•	•	•	•	•	
	128Kbit	16K×8	1.7V~5.5V	•	•	•	•			
	256Kbit	32K×8	1.7V~5.5V	•	•					



● Absolute maximum ratings (Ta=25°C)

Parameter	Symbol	Limits		Unit
Impressed voltage	Vcc	-0.3~+6.5		V
		450(SOP8)	*1	
		450(SOP-J8)	*2	
		300(SSOP-B8)	*3	
Permissible dissipation	Pd	330(TSSOP-B8)	*4	mW
uissipation		310(MSOP8) *5		
		310(TSSOP-B8J) *6		
		300(VSON008X2030)	*7	
Storage temperature range	Tstg	-65~+125		°C
Operating temperature range	Topr	-40~+85		°C
Terminal voltage	_	-0.3~Vcc+0.3		٧

^{*} When using at Ta=25°C or higher, 4.5mW(*1, *2), 3.0mW(*3, *7),3.3mW(*4), 3.1mW(*5, *6) to be reduced per 1°C

●Memory cell characteristics (Ta=25°C , Vcc=1.7V~5.5V)

Parameter		Limits						
Farameter	Min.	Min.	Min.	Unit				
Number of data rewrite times *1	1,000,000	_	_	Time				
Data hold years *1	40	ı	-	Year				

^{*1} Not 100% TESTED

Recommended action conditions

Parameter	Symbol	Limits	Unit
Power source voltage	V _{CC}	1.7~5.5	\
Input voltage	V _{IN}	0~Vcc	V

●Input / output capacity (Ta=25°C, frequency=5MHz)

Parameter	Symbol	Conditions	Min.	Max.	Unit
Input capacity *1	C_{IN}	V_{IN} =GND	-	8	5_
Output capacity *1	C _{OUT}	V _{OUT} =GND	1	8	pF

^{*1} Not 100% TESTED.

● Electrical characteristics (Unless otherwise specified, Ta=-40~+85°C, Vcc=1.7~5.5V)

Parameter	Symbol	•	Limits	·	Unit	Conditions
Farameter	Symbol	Min.	Тур.	Max.	UTIIL	Conditions
"H" Input Voltage1	VIH1	0.7xVcc	_	Vcc+0.3	V	1.7≦Vcc≦5.5V
"L" Input Voltage1	VIL1	-0.3	_	0.3xVcc	V	1.7≦Vcc≦5.5V
"L" Output Voltage1	VOL1	0	_	0.4	V	IOL=2.1mA, 2.5≦Vcc<5.5V
"L" Output Voltage2	VOL2	0	_	0.2	V	IOL=1.0mA, 1.7≦Vcc<2.5V
"H" Output Voltage1	VOH1	Vcc-0.2	_	Vcc	V	IOH=-0.4mA, 2.5V≦Vcc<5.5V
"H" Output Voltage2	VOH2	Vcc-0.2	_	Vcc	V	IOH=-100μA, 1.7≦Vcc<2.5V
Input Leakage Current	ILI	-1	_	1	μΑ	V _{IN} =0~Vcc
Output Leakage Current	ILO	-1	_	1	μΑ	V _{OUT} =0~Vcc, CSB=Vcc
	ICC1	_	_	0.5 ^{*1}	mA	Vcc=1.8V, fSCK=5MHz, tE/W=5ms Byte Write, Page Write, Write Status register
Operating Current Write	ICC2	_	_	1.5 *2	mA	Vcc=2.5V, fSCK=10MHz, tE/W=5ms Byte Write, Page Write, Write Status register
	ICC3	_	1	2 *1 3 *2	mA	Vcc=5.5V, fSCK=20MHz, tE/W=5ms Byte Write, Page Write, Write Status register
	ICC4	_	_	1	mA	Vcc=1.8V, fSCK=5MHz, SO=OPEN Read, Read Status Register
	ICC5	_	_	1	mA	Vcc=2.5V, fSCK=2MHz, SO=OPEN Read, Read Status Register
	ICC6	_	ı	1.5	mA	Vcc=2.5V, fSCK=5MHz, SO=OPEN Read, Read Status Register
Operating Current Read	ICC7	_	_	2	mA	Vcc=2.5V, fSCK=10MHz, SO=OPEN Read, Read Status Register
	ICC8	_	-	2	mA	Vcc=5.5V, fSCK=5MHz, SO=OPEN Read, Read Status Register
	ICC9	_	_	4	mA	Vcc=5.5V, fSCK=10MHz, SO=OPEN Read, Read Status Register
	ICC10	_	_	8	mA	Vcc=5.5V, fSCK=20MHz, SO=OPEN Read, Read Status Register
Standby Current	ISB	_	_	2	μA	Vcc=5.5V, SO=OPEN CSB=HOLDB=WPB=Vcc, SCK=SI=Vcc or GND

^{*1} BR25S320/640-W

^{*2} BR25S128/256-W

O Radiation resistance design is not made

Block diagram

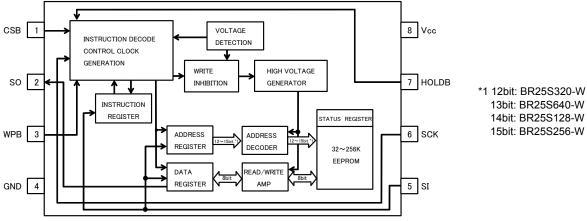


Fig.1 Block diagram

●Operating timing characteristics (Ta=-40~+85°C, unless otherwise specified, load capacity C_L=30pF)

			€Vcc<		•	≤Vcc<		•	.y O <u>L</u> − ≦Vcc<		4.5≦Vcc<5.5V			
Parameter	Symbol	Min.	Тур.	Max.	Min.	Тур.	Max.	Min.	Тур.	Max.	Min.	Тур.	Max.	Unit
SCK frequency	fsck	-	-	3	-	-	5	-	-	10	-	-	20	MHz
SCK high time	tsckwh	125	-	-	80	-	-	40	-	-	20	-	-	ns
SCK low time	tsckwl	125	-	-	80	-	-	40	-	-	20	-	-	ns
CSB high time	tcs	250	-	-	90	-	-	40	-	-	20	-	-	ns
CSB setup time	tcss	100	-	-	60	-	-	30	-	-	15	-	-	ns
CSB hold time	tcsH	100	-	-	60	-	-	30	-	-	15	-	-	ns
SCK setup time	tscks	100	-	-	50	-	-	20	-	-	15	-	-	ns
SCK hold time	tsckh	100	-	-	50	-	-	20	-	-	15	-	-	ns
SI setup time	tois	30	-	-	20	-	-	10	-	-	5	-	-	ns
SI hold time	tDIH	50	-	-	20	-	-	10	-	-	5	-	-	ns
Data output delay time	tpD	-	-	125	-	-	80	-	-	40	-	-	20	ns
Output hold time	tон	0	-	-	0	-	-	0	-	-	0	-	-	ns
Output disable time	toz	-	-	200	-	-	80	-	-	40	-	-	20	ns
HOLDB setting setup time	tHFS	100	-	-	0	-	-	0	-	-	0	-	-	ns
HOLDB setting hold time	tHFH	100	-	-	20	-	-	10	-	-	5	-	-	ns
HOLDB release setup time	tHRS	100	-	-	0	-	-	0	-	-	0	-	-	ns
HOLDB release hold time	thrh	100	-	-	20	-	-	10	-	-	5	-	-	ns
Time from HOLDB to output High-Z	tHOZ	-	-	100	-	-	80	-	-	40	-	-	20	ns
Time from HOLDB to output change	tHPD	-	-	100	-	-	80	-	-	40	-	-	20	ns
SCK rise time	trc	-	-	1	-	-	1	-	-	1	-	-	1	μs
SCK fall time	tFC	-	-	1	-	-	1	-	-	1	-	-	1	μs
OUTPUT rise time *1	tro	-	-	100	-	-	50	-	-	40	-	-	20	ns
OUTPUT fall time *1	tFO	-	-	100	-	-	50	-	-	40	-	-	20	ns
Write time	tE/W	-	-	5	-	-	5	-	-	5	-	-	5	ms

^{*1} NOT 100% TESTED

Pin assignment and description

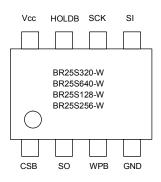


Fig.2 Pin assignment diagram

Terminal name	Input /Output	Function
Vcc	-	Power source to be connected
GND	-	All input / output reference voltage, 0V
CSB	Input	Chip select input
SCK	Input	Serial clock input
SI	Input	Start bit, ope code, address, and serial data input
SO	Output	Serial data output
HOLDB	Input	Hold input Command communications may be suspended temporarily (HOLD status)
WPB	Input	Write protect input Write command is prohibited Write status register command is prohibited

Sync data input / output timing

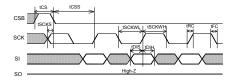


Fig.3 Input timing

 ${\rm SI}$ is taken into IC inside in sync with data rise edge of SCK. Input address and data from the most significant bit ${\rm MSB}$

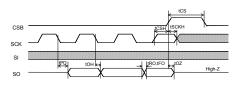


Fig.4 Input / Output timing

SO is output in sync with data fall edge of SCK. Data is output from the most significant bit MSB.

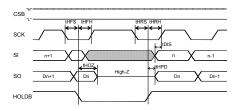
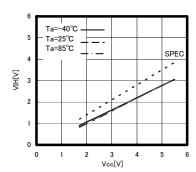


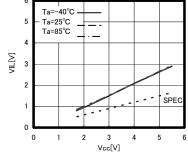
Fig.5 HOLD timing

AC timing characteristics conditions

Dorometer	Cumbal		Unit			
Parameter	Symbol	Min.	Min. Typ.		Offic	
Load capacity	C _L	-	-	30	pF	
Input rise time	-	-	-	50	ns	
Input fall time	-	-	-	50	ns	
Input voltage	-	0.3	2Vcc/0.8\	/cc	V	
Input / Output judgment voltage	-	0.3	3Vcc/0.7\	/cc	V	

● Characteristic data (The following characteristic data are Typ. Values.)





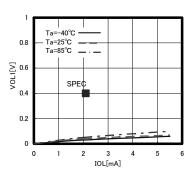
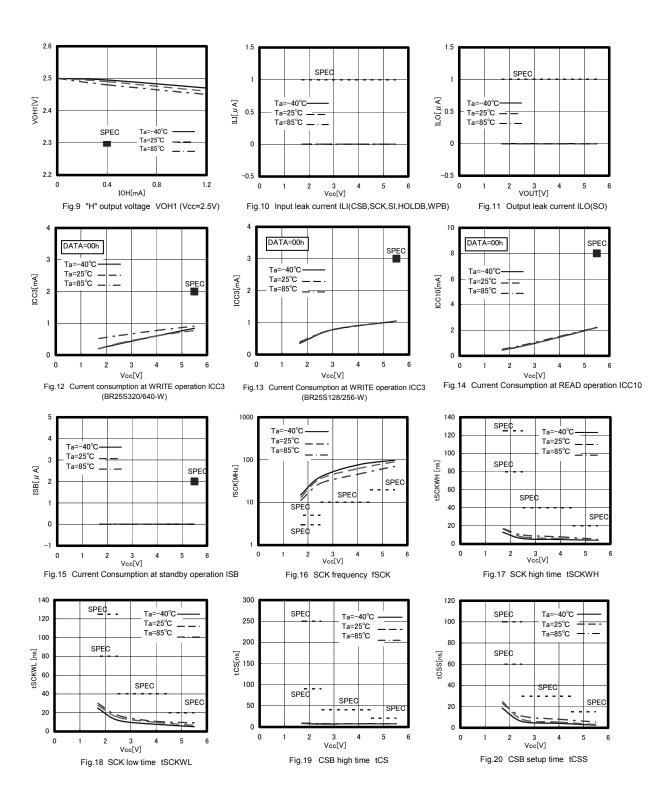


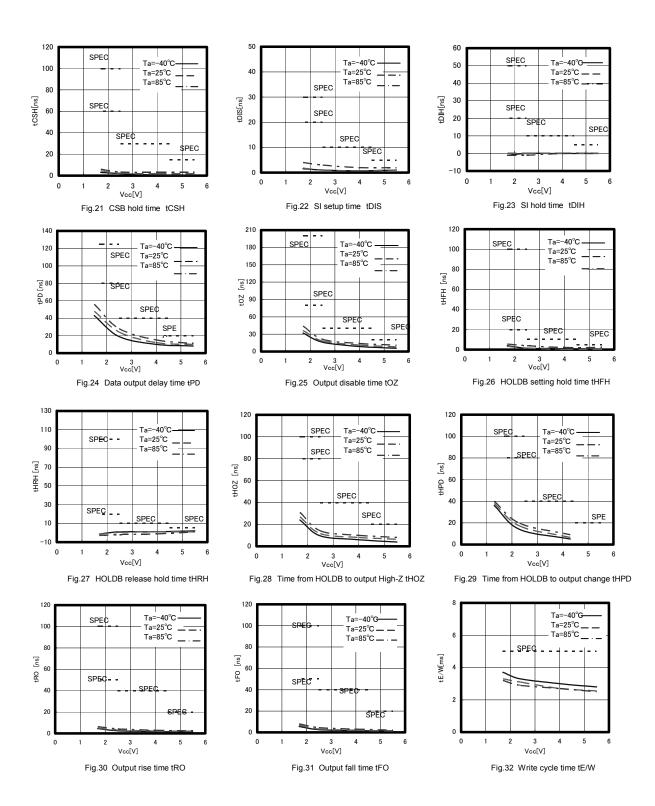
Fig.6 "H" input voltage VIH(CSB,SCK,SI,HOLDB,WPB) Fig.7 "L" input voltage VIL(CSB,SCK,SI,HOLDB,WPB)

Fig.8 "L" output voltage VOL1 (Vcc=2.5V)

● Characteristic data (The following characteristic data are Typ. Values.)



● Characteristic data (The following characteristic data are Typ. Values.)





Features

OStatus registers

This IC has status register. The status register expresses the following parameters of 8 bits.

BP0 and BP1 can be set by write status register command. These 2 bits are memorized into the EEPROM, therefore are valid even when power source is turned off.

Rewrite characteristics and data hold time are same as characteristics of the EEPROM.

WEN can be set by write enable command and write disable command. WEN becomes write disable status when power source is turned off. R/B is for write confirmation, therefore cannot be set externally.

The value of status register can be read by read status register command.

1. Contexture of status register

Product number	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
BR25S320-W								
BR25S640-W					554	555		
BR25S128-W	WPEN	0	0	0	BP1	BP0	WEN	R/B
BR25S256-W								

bit	Memory location	Function
WPEN	EEPROM	WPB pin enable / disable designation bit WPEN=0=invalid WPEN=1=valid
BP1 BP0	EEPROM	EEPROM write disable block designation bit
WEN	registers	Write and write status register write enable / disable status confirmation bit WEN=0=prohibited WEN=1=permitted
Ē/B	registers	Write cycle status (READY / BUSY) status confirmation bit $R/B=0=READY$ $R/B=1=BUSY$

2. Write disable block setting

. Write disable block setting		d .			
BP1	BP0	Write disable block			
		BR25S320-W	BR25S640-W	BR25S128-W	BR25S256-W
0	0	None	None	None	None
0	1	C00h-FFFh	1800h-1FFFh	3000h-3FFFh	6000h-7FFFh
1	0	800h-FFFh	1000h-1FFFh	2000h-3FFFh	4000h-7FFFh
1	1	000h-FFFh	0000h-1FFFh	0000h-3FFFh	0000h-7FFFh

OWPB pin

By setting WPB=LOW, write command is prohibited. And the write command to be disabled at this moment is WRSR. However, when write cycle is in execution, no interruption can be made.

and the second s					
Product number	WRSR	WRITE			
BR25S320-W					
BR25S640-W	Prohibition possible	Prohibition			
BR25S128-W	but WPEN bit "1"	impossible			
BR25S256-W					

OHOLDB pin

By HOLDB pin, data transfer can be interrupted. When SCK="0", by making HOLDB from "1" into"0", data transfer to EEPROM is interrupted. When SCK = "0", by making HOLDB from "0" into "1", data transfer is restarted.

Command mode

Command	Contents	Ope code	
WREN	Write enable command	0000	0110
WRDI	Write disable command	0000	0100
READ	Read command	0000	0011
WRITE	Write command	0000	0010
RDSR	Read status register command	0000	0101
WRSR	Write status register command	0000	0001

Timing chart

1. Write enable (WREN) / disable (WRDI) command

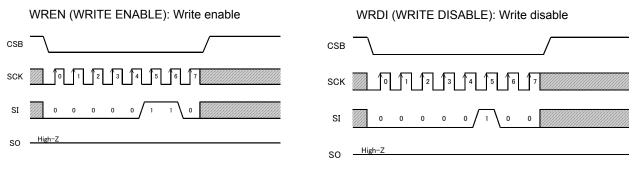


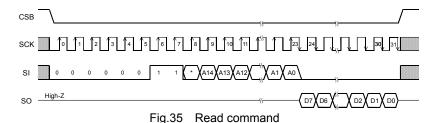
Fig.33 Write enable command

Fig.34 Write disable command

This IC has write enable status and write disable status. It is set to write enable status by write enable command, and it is set to write disable status by write disable command. As for these commands, set CSB LOW, and then input the respective ope codes. The respective commands are accepted at the 7-th clock rise. Even with input over 7 clocks, command becomes valid.

When to carry out write command, it is necessary to set write enable status by the write enable command. If write command is input in the write disable status, the command is cancelled. And even in the write enable status, once write command is executed, it gets in the write disable status. After power on, this IC is in write disable status.

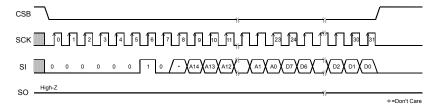
2. Read command (READ)



Product	Address	
number	length	
BR25S320-W	A11-A0	
BR25S640-W	A12-A0	
BR25S128-W	A13-A0	
BR25S256-W	A14-A0	

By read command, data of EEPROM can be read. As for this command, set CSB LOW, then input address after read ope code. EEPROM starts data output of the designated address. Data output is started from SCK fall of 23-th clock, and from D7 to D0 sequentially. This IC has increment read function. After output of data for 1 byte (8bits), by continuing input of SCK, data of the next address can be read. Increment read can read all the addresses of EEPROM. After reading data of the most significant address, by continuing increment read, data of the most insignificant address is read.

3. Write command (WRITE)



Product	Address	
number	length	
BR25S320-W	A11-A0	
BR25S640-W	A12-A0	
BR25S128-W	A13-A0	
BR25S256-W	A14-A0	

Fig.36 Write command

By write command, data of EEPROM can be written. As for this command, set CSB LOW, then input address and data after write ope code. Then, by making CSB HIGH, the EEPROM starts writing. The write time of EEPROM requires time of tE/W (Max 5ms). During tE/W, other than read status register command is not accepted. Set CSB HIGH between taking the last data (D0) and rising the next SCK clock. At the other timing, write command is not executed, and this write command is cancelled. This IC has page write function, and after input of data for 1 byte (8 bits), by continuing data input without setting CSB HIGH, 2byte or more data can be written for one tE/W. The maximum number of write bytes is specified per device of each capacity. Up to 64 arbitrary bytes can be written (in the case of BR25S128/256-W). In page write, the insignificant 5 bit of the designated address is incremented internally at every time when data of 1 byte is input and data is written to respective addresses. When data of the maximum bytes or higher is input, address rolls over, and previously input data is overwritten.

4. Write status register, Read status register command (WRSR/RDSR)

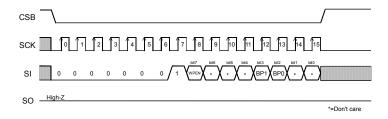


Fig.37 Write status register

Write status register command can write data of status register. The data can be written by this command are 3 bits, that is, WPEN(bit7), BP1 (bit3) and BP0 (bit2) among 8 bits of status register. By BP1 and BP0, write disable block of EEPROM can be set. As for this command, set CSB LOW, and input ope code of write status register, and input data. Then, by making CSB HIGH, EEPROM starts writing. Write time requires time of tE/W as same as write. As for CSB rise, set CSB HIGH between taking the last data bit (bit0) and the next SCK clock rising. At the other timing, command is cancelled. Write disable block is determined by BP1 BP0, and the block can be selected from 1/4 , 1/2, and entire of memory array (Refer to the write disable block setting table.). To the write disabled block, write cannot be made, and only read can be made.

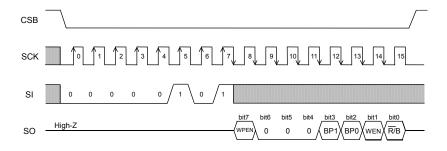


Fig.38 Read status register command

WPB cancel valid area

WPB is normally fixed to "H" or "L" for use, but when WPB is controlled so as to cancel write status register command, pay attention to the following WPB valid timing.

While write status register command is executed, by setting WPB = "L" in cancel valid area, command can be cancelled. The area from command ope code to CSB rise at internal automatic write start becomes the cancel valid area. However, once write is started, by any input write cycle cannot be cancelled. WPB input becomes Don't Care, and cancellation becomes invalid.

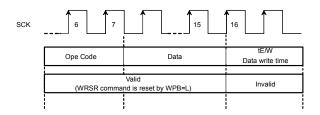


Fig.39 WPB valid timing (At inputting WRSR command)

●HOLDB pin

By HOLDB pin, command communication can be stopped temporarily (HOLD status). The command communications are carried out when the HOLDB pin is HIGH. To get in HOLD status, at command communication, when SCK=LOW, set the HOLDB pin LOW. At HOLD status, SCK and SI become Don't Care, and SO becomes high impedance (High-Z). To release the HOLD status, set the HOLDB pin HIGH when SCK=LOW. After that, communication can be restarted from the point before the HOLD status. For example, when HOLD status is made after A5 address input at read, after release of HOLD status, by starting A4 address input, read can be restarted. When in HOLD status, keep CSB LOW. When it is set CSB=HIGH in HOLD status, the IC is reset, therefore communication after that cannot be restarted.

Method to cancel each command

OREAD, RDSR

· Method to cancel: cancel by CSB = "H".

Ope code	Address	Data		
8 bits	16 bits	8 bits		
Cancel available in all areas of read mode				

Fig.40 READ cancel valid timing

OWRITE, PAGE WRITE

- a : Ope code or address input area Cancellation is available by CSB="H".
- b : Data input area (D7~D1 input area) Cancellation is available by CSB="H".
- c : Data input area (D0 area)
 In this area, cancellation is not available.
 When CSB is set HIGH, write starts.
- d: tE/W area

In the area c, by rising CSB, write starts. While writing, by any input, cancellation cannot be made.

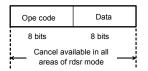


Fig.41 RDSR cancel valid timing

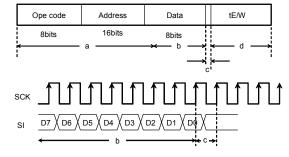


Fig.42 WRITE cancel valid timing

Note1) If Vcc is made OFF during write execution, designated address data is not guaranteed, therefore write it once again. Note2) If CSB is rised at the same timing as that of the SCK rise, write execution / cancel becomes unstable, therefore, it is recommended to rise in SCK = "L" area. As for SCK rise, assure timing of tCSS / tCSH or more.

OWRSR

- a : From ope code to 15-th clock rise Cancellation is available by CSB="H".
- b : From 15-th clock rise to 16-th clock rise (write enable area)
 In this area, cancellation is not available.
 When CSB is set HIGH, write starts.
- c: After 16-th clock rise.

Cancellation is available by CSB="H".

However, if write starts (CSB is rised)

in the area b, cancellation cannot be made by any means.

And, by inputting on SCK clock, cancellation cannot be made.

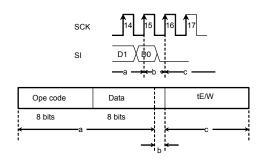


Fig.43 WRSR cancel valid timing

Note1) If Vcc is made OFF during write execution, designated address data is not guaranteed, therefore write it once again

Note2) If CSB is rised at the same timing as that of the SCK rise, write execution / cancel becomes unstable, therefore, it is recommended to rise in SCK = "L" area. As for SCK rise, assure timing of tCSS / tCSH or more.

OWREN/WRDI

- a: From ope code to 7-th clock rise, cancellation is available by CSB = "H".
- $b\,:\, Cancellation \,\, is \,\, not \,\, available \,\, 7\text{-th clock}.$

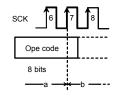


Fig.44 WREN/WRDI cancel valid timing

I/O peripheral circuits

In order to realize stable high speed operations, pay attention to the following input / output pin conditions.

Olnput pin pull up, pull down resistance

When to attach pull up, pull down resistance to EEPROM input pin, select an appropriate value for the microcontroller VOL, IOL with considering VIL characteristics of this IC.

1. Pull up resistance

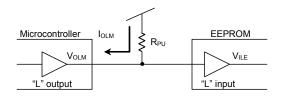


Fig.45 Pull up resistance

$$R_{PU} \ge \frac{V_{CC} - V_{OLM}}{I_{OLM}} \cdots \textcircled{1}$$

$$V_{OLM} \le V_{ULF} \cdots \textcircled{2}$$

Example) When Vcc=5V, V_{ILE} =1.5V, V_{OLM} =0.4V, I_{OLM} =2mA, from the equation ①,

$$R_{PU} \ge \frac{5 - 0.4}{2 \times 10^{-3}}$$

$$\therefore R_{PU} \ge 2.3[k\Omega]$$

With the value of Rpu to satisfy the above equation, V_{OLM} becomes 0.4V or lower, and with V_{ILE} (=1.5V), the equation ② is also satisfied.

- V_{ILE} :EEPROM V_{IL} specifications
- V_{OLM}: Microcontroller V_{OL} specifications
- I_{OLM} :Microcontroller I_{OL} specifications

And, in order to prevent malfunction or erroneous write at power ON/OFF, be sure to make CSB pull up.

2.Pull down resistance

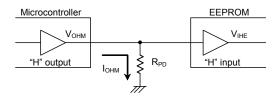


Fig.46 Pull down resistance

$$R_{PD} \ge \frac{V_{OHM}}{I_{OHM}} \cdots 3$$
 $V_{OHM} \ge V_{IHE} \cdots 4$

Example) When V_{CC} =5V, V_{OHM} = V_{CC} -0.5V, I_{OHM} =0.4mA, V_{IHE} = V_{CC} ×0.7V, from the equation③,

$$R_{PD} \ge \frac{5-0.5}{0.4 \times 10^{-3}}$$

Further, by amplitude VIHE, VILE of signal input to EEPROM, operation speed changes. By inputting Vcc/GND level amplitude of signal, more stable high speed operations can be realized. On the contrary, when amplitude of 0.8VCC / 0.2Vcc is input, operation speed becomes slow.*1

In order to realize more stable high speed operation, it is recommended to make the values of R_{PU} , R_{PD} as large as possible, and make the amplitude of signal input to EEPROM close to the amplitude of VCC / GND level. (1 In this case, guaranteed value of operating timing is guaranteed.)

OSO load capacity condition

Load capacity of SO output pin affects upon delay characteristic of SO output (Data output delay time, time from HOLDB to High-Z, Output rise time, Output fall time.). In order to make output delay characteristic into better, make SO load capacity small.

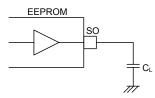


Fig.47 SO load capacity

OOther cautions

Make the each wire length from the microcontroller to EEPROM input pin same length, in order to prevent setup / hold violation to EEPROM, owing to difference of wire length of each input.

● Equivalent circuit Output circuit

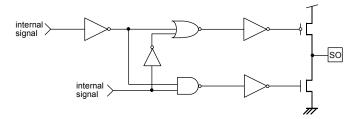


Fig.48 SO output equivalent circuit

Olnput circuit

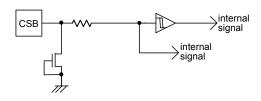
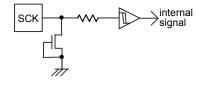


Fig.49 CSB input equivalent circuit



SI internal signal

Fig.50 SCK input equivalent circuit

HOLDB internal signal

Fig.52 HOLDB input equivalent circuit



Fig.51 SI input equivalent circuit

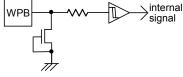


Fig.53 WPB input equivalent circuit

Notes on power ON/OFF

OAt standby

Set CSB "H", and be sure to set SCK, SI input "L" or "H". Do not input intermediate electric potantial.

OAt power ON/OFF

When Vcc rise or fall, set CSB="H" (=Vcc).

When CSB is "L", this IC gets in input accept status (active). If power is turned on in this status, noises and the likes may cause malfunction, erroneous write or so. To prevent these, at power ON, set CSB "H". (When CSB is in "H" status, all inputs are canceled.)

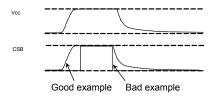


Fig.54 CSB timing at power ON/OFF

(Good example) CSB terminal is pulled up to Vcc.

At power OFF, take 10ms or more before supply. If power is turned on without observing this condition, the IC internal circuit may not be reset.

(Bad example) CSB terminal is "L" at power ON/OFF.

In this case, CSB always becomes "L" (active status), and EEPROM may have malfunction or erroneous write owing to noises and the likes.

Even when CSB input is High-Z, the status becomes like this case.

OOperating timing after power ON

As shown in Fig.55, at standby, when SCK is "H", even if CSB is fallen, SI status is not read at fall edge. SI status is read at SCK rise edge after fall of CSB. At standby and at power ON/OFF, set CSB "H" status.

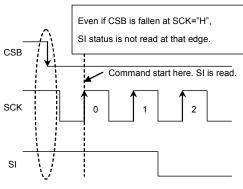
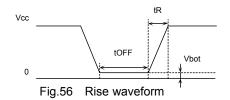


Fig.55 Operating timing

OAt power on malfunction preventing function

This IC has a POR (Power On Reset) circuit as mistake write countermeasure. After POR action, it gets in write disable status. The POR circuit is valid only when power is ON, and does not work when power is OFF. When power is ON, if the recommended conditions of the following tR, tOFF, and Vbot are not satisfied, it may become write enable status owing to noises and the likes.



Recommended conditions of t _R , t _{OFF} , Vbot				
tR toff Vbot				
10ms or belo	w 10ms	or higher	0.3V or below	
100ms or belo	DW 10ms	or higher	0.2V or below	

OLow voltage malfunction preventing function

LVCC (Vcc-Lockout) circuit prevents data rewrite action at low power, and prevents wrong write.

At LVCC voltage (Typ. =1.2V) or below, it prevent data rewrite.

Noise countermeasures

OVcc noise (bypass capacitor)

When noise or surge gets in the power source line, malfunction may occur, therefore, for removing these, it is recommended to attach a bypass capacitor $(0.1\mu F)$ between IC Vcc and GND. At that time, attach it as close to IC as possible.

And, it is also recommended to attach a bypass capacitor between board Vcc and GND.

OSCK noise

When the rise time of SCK (tRC) is long, and a certain degree or more of noise exists, malfunction may occur owing to clock bit displacement. To avoid this, a Schmitt trigger circuit is built in SCK input. The hysteresis width of this circuit is set about 0.2V, if noises exist at SCK input, set the noise amplitude 0.2Vp-p or below. And it is recommended to set the rise time of SCK (tRC) 100ns or below. In the case when the rise time is 100ns or higher, take sufficient noise countermeasures. Make the clock rise, fall time as small as possible.

OWPB noise

During execution of write status register command, if there exist noises on WPB pin, mistake in recognition may occur and forcible cancellation may result. To avoid this, a Schmitt trigger circuit is built in WPB input. In the same manner, a Schmitt trigger circuit is built in CSB input, SI input and HOLDB input too.

●Notes for use

- (1) Described numeric values and data are design representative values, and the values are not guaranteed.
- (2) We believe that application circuit examples are recommendable, however, in actual use, confirm characteristics further sufficiently. In the case of use by changing the fixed number of external parts, make your decision with sufficient margin in consideration of static characteristics and transition characteristics and fluctuations of external parts and our LSI.
- (3) Absolute maximum ratings

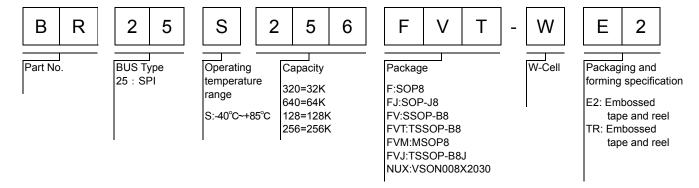
If the absolute maximum ratings such as impressed voltage and operating temperature range and so forth are exceeded, LSI may be destructed. Do not impress voltage and temperature exceeding the absolute maximum ratings. In the case of fear exceeding the absolute maximum ratings, take physical safety countermeasures such as fuses, and see to it that conditions exceeding the absolute maximum ratings should not be impressed to LSI.

- (4) GND electric potential
 - Set the voltage of GND terminal lowest at any action condition. Make sure that each terminal voltage is higher than that of GND terminal.
- (5) Heat design

In consideration of permissible dissipation in actual use condition, carry out heat design with sufficient margin.

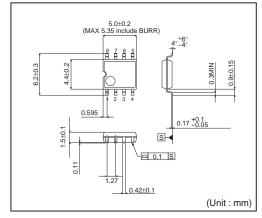
- (6) Terminal to terminal short circuit and wrong packaging
 - When to package LSI onto a board, pay sufficient attention to LSI direction and displacement. Wrong packaging may destruct LSI. And in the case of short circuit between LSI terminals and terminals and power source, terminal and GND owing to foreign matter, LSI may be destructed.
- (7) Use in a strong electromagnetic field may cause malfunction, therefore, evaluate design sufficiently.

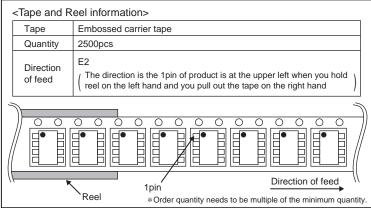
Ordering part number



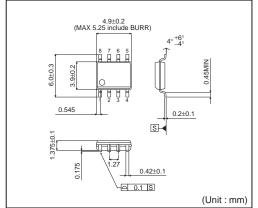
Package specifications

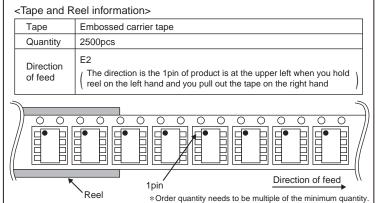
SOP8





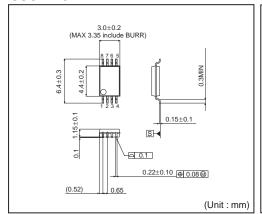
SOP-J8

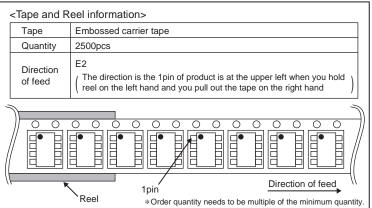




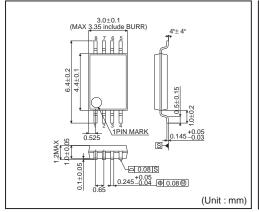
● Package specifications (Continue)

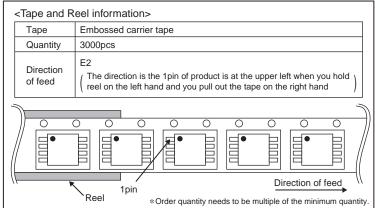
SSOP-B8



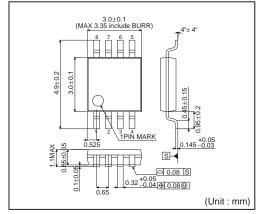


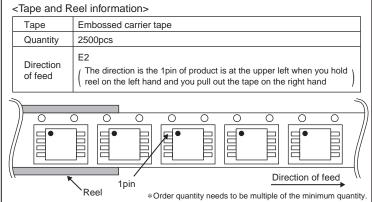
TSSOP-B8





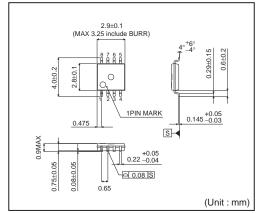
TSSOP-B8J

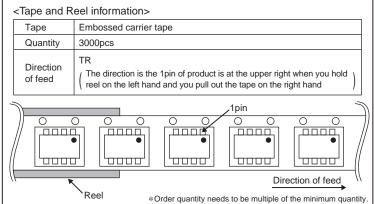




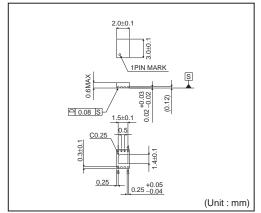
● Package specifications (Continue)

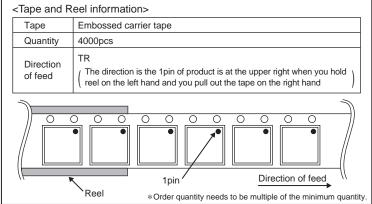
MSOP8





VSON008X2030





Notes

No copying or reproduction of this document, in part or in whole, is permitted without the consent of ROHM Co.,Ltd.

The content specified herein is subject to change for improvement without notice.

The content specified herein is for the purpose of introducing ROHM's products (hereinafter "Products"). If you wish to use any such Product, please be sure to refer to the specifications, which can be obtained from ROHM upon request.

Examples of application circuits, circuit constants and any other information contained herein illustrate the standard usage and operations of the Products. The peripheral conditions must be taken into account when designing circuits for mass production.

Great care was taken in ensuring the accuracy of the information specified in this document. However, should you incur any damage arising from any inaccuracy or misprint of such information, ROHM shall bear no responsibility for such damage.

The technical information specified herein is intended only to show the typical functions of and examples of application circuits for the Products. ROHM does not grant you, explicitly or implicitly, any license to use or exercise intellectual property or other rights held by ROHM and other parties. ROHM shall bear no responsibility whatsoever for any dispute arising from the use of such technical information.

The Products specified in this document are intended to be used with general-use electronic equipment or devices (such as audio visual equipment, office-automation equipment, communication devices, electronic appliances and amusement devices).

The Products specified in this document are not designed to be radiation tolerant.

While ROHM always makes efforts to enhance the quality and reliability of its Products, a Product may fail or malfunction for a variety of reasons.

Please be sure to implement in your equipment using the Products safety measures to guard against the possibility of physical injury, fire or any other damage caused in the event of the failure of any Product, such as derating, redundancy, fire control and fail-safe designs. ROHM shall bear no responsibility whatsoever for your use of any Product outside of the prescribed scope or not in accordance with the instruction manual.

The Products are not designed or manufactured to be used with any equipment, device or system which requires an extremely high level of reliability the failure or malfunction of which may result in a direct threat to human life or create a risk of human injury (such as a medical instrument, transportation equipment, aerospace machinery, nuclear-reactor controller, fuel-controller or other safety device). ROHM shall bear no responsibility in any way for use of any of the Products for the above special purposes. If a Product is intended to be used for any such special purpose, please contact a ROHM sales representative before purchasing.

If you intend to export or ship overseas any Product or technology specified herein that may be controlled under the Foreign Exchange and the Foreign Trade Law, you will be required to obtain a license or permit under the Law.



Thank you for your accessing to ROHM product informations. More detail product informations and catalogs are available, please contact us.

ROHM Customer Support System

http://www.rohm.com/contact/