

RoboCup Competition



Weight Collection

The purpose of this robot was to outperform other robots in collecting weights throughout an arena



3rd Place

This robot came 3rd place out of a pool of 39 teams



Fully Autonomous

Programmed in Arduino to perform without human input



Success

The robot successfully picked up 96% of weights detected via time-of-flight sensors (attached to green parts on upper CAD model)

Specific Skills

Iterative Hardware Testing

Team Leadership

Digital and Analogue embedded system peripheral control

Project Budgeting

Project Management Software (ClickUp)

CAD Software (Solidworks)

Github Repo: https://github.com/Alisternz/Robocup/blob/main/RobocupReport3.pdf

Guitar Pedal



Wah Wah Pedal

Created and ordered a PCB, soldered on components using a manual pick and place machine



The Electronics

A wah wah pedal is an application of a band-pass filter, by adjusting the value of the potentiometer (X1), this band moves through the frequency spectrum



Signal Processing Modification

The output of this circuit was scaled and passed into an Arduino analogue input. The frequency spectrum of the signals were measured and plotted through an OLED display

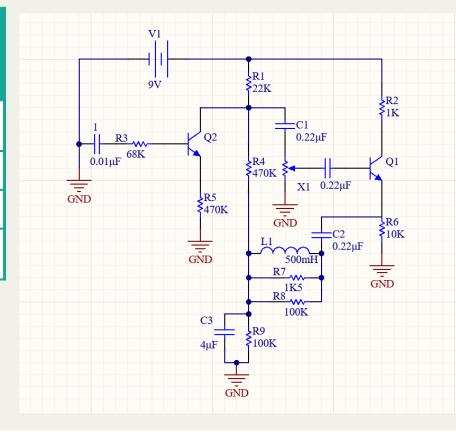
Specific Skills

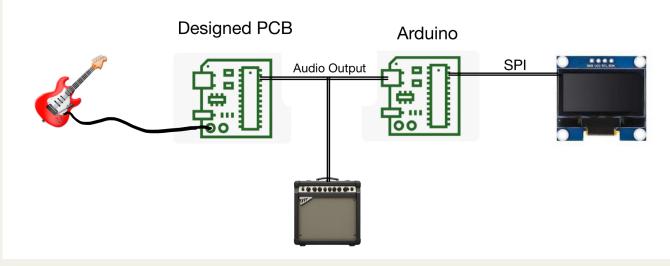
Schematic and PCB layout (Altium)

Component Selection

Signal Processing

CAD (Solidworks)





The Garden Gnome



The Rules

Over the last year, myself and a group of friends have been running a competition, where a prize goes to the house that holds the garden gnome for the longest cumulative time.



The Project

In response to the game, I engineering a weatherresistant module to detect when a Gnome Thief enters the property. The unit contains an IR sensor, internal battery and RF unit to alert the house when the back gate is opened.

Specific Skills

Water-Resistant Mechanical Design

CAD (Fusion 360)

RF Design

Electrical Component Selection

