Adatosere táblázat egyedi kitöltéshez
A fehérnel jelölt szabad területeken adhatók át user adatok a PLC és a Robot között bit, word és double word formátumban: M_in, M_in16, M_in32, M_out, M_out16, M_out32 robot lögvényekkel.

A fehérre	el jelölt szabad t			t között bit, word és double	word formátumban: M_in, M_in16, M_i	n32, M_out, M_out16, M_out32 robot	fügvényekkel.			
ROBOT	D regiszter	Word cim	neneti adatterület Adatszón belüli bit	Robot bemeneti cím	PLC device TO robot	PLC device FROM robot	Robot kimeneti cím	Word cim	meneti adatterület Adatszón belüli bit	D regiszter
	v	word cim	U3E0\HG0.0	M_in(10000) BIT			M out(10000)	word cim	U3E1\HG0.0	D10000.0
	Ŷ		U3E0\HG0.1	M_in(10001) BIT			M_out(10001)		U3E1\HG0.1	D10000.1
Elso Rebot CPU	Ŷ	U3E0\HG0	0320(100.1					U3E1\HG0	0321(100.1	D10000.1
	x x x	U3E0\HG1	U3E0\HG0.F	M_in(10015) BIT	Dedikált I/O címtartomány (PLC küldi a robotnak)	Dedikált I/O címtartomány (Robot küldi PLC-nek)	M_out(10015)		U3E1\HG0.F	D10000.F
			.0F					U3E1\HG1	.0F	D10001
	×		.0F						.0F	
	×	U3E0\HG9	.0F					U3E1\HG9	.0F	D10009
		0320 (1103	U3E0\HG10.0	M in(10160)			M_out(10160)		U3E1\HG10.0	
			U3E0\HG10.1	10161			10161	U3E1/HG10	U3E1\HG10.1	D10010
			U3E0\HG10.2	10162			10162		U3E1\HG10.2	
			U3E0\HG10.3	10163			10163		U3E1\HG10.3	
			U3E0\HG10.4	10164			10164		U3E1\HG10.4	
			U3E0\HG10.5	10165			10165		U3E1\HG10.5	
	D10	U3E0\HG10	U3E0\HG10.6	10166		10167 U3E1 HG10 10168 10169 10170 10171 10172 10172 10173 10174 10174 10175 U3E1 HG10	10166		U3E1\HG10.6	
			U3E0\HG10.7	10167			10167		U3E1\HG10.7	
			U3E0\HG10.8	10168			10168		U3E1\HG10.8	
			U3E0\HG10.9	10169					U3E1\HG10.9	
			U3E0\HG10.A	10170					U3E1\HG10.A	
			U3E0\HG10.B	10171						
			U3E0\HG10.C	10172						
			U3E0\HG10.D	10173				4		
			U3E0\HG10.E	10174						
			U3E0\HG10.F	10175						
	D11 D12	U3E0\HG11	.0F	M_in16(10176) 10192			M_in16(10176)	U3E1\HG11	.0F	D10011 D10012
		U3E0\HG12	.0F				10192	U3E1\HG12	.0F	
	D13	U3E0\HG13	.0F	10208			10208	U3E1\HG13	.0F	D10013
	***		.0F						.0F	
	 D16	 U3E0\HG20	.0F	10320			10320	U3E1\HG20	.0F	D10020
	D17	U3E0\HG21	.0F	10336	1		10336	U3E1\HG21	.0F	D10021
	D18	U3E0\HG22	.0F	10352			10352	U3E1\HG22	.0F	D10022
	D19	U3E0\HG23	.0F	10368	1		10368	U3E1\HG23	.0F	D10023
	D20	U3E0\HG24	.0F	10384	1		10384	U3E1\HG24	.0F	D10024
	D21	U3E0\HG25	.0F	10400	1		10400	U3E1\HG25	.0F	D10025
	D22	U3E0\HG26	.0F	10416			10416	U3E1\HG26	.0F	D10026
	D23	U3E0\HG27	.0F	10432			10432	U3E1\HG27	.0F	D10027
	D24	U3E0\HG28	.0F	10448			10448	U3E1\HG28	.0F	D10028
	D25	U3E0\HG29	.0F	10464			10464	U3E1\HG29	.0F	D10029
	D26	U3E0\HG30	.0F	10480			10480	U3E1\HG30	.0F	D10030
	D27	U3E0\HG31	.0F	10496			10496	U3E1\HG31	.0F	D10031
	D28	U3E0\HG32	.0F	10512			10512	U3E1\HG32	.0F	D10032
ğ	D29	U3E0\HG33	.0F	10528			10528	U3E1\HG33	.0F	D10033
20	D30	U3E0\HG34	.0F	10544			10544	U3E1\HG34	.0F	D10034
Elsd	D31	U3E0\HG35	.0F	10560			10560	U3E1\HG35	.0F	D10035
	D32	U3E0\HG36	.0F	10576			10576	U3E1\HG36	.0F	D10036
	D33	U3E0\HG37	.0F	10592			10592	U3E1\HG37	.0F	D10037
	D34	U3E0\HG38	.0F	10608			10608	U3E1\HG38	.0F	D10038
	D35	U3E0\HG39	.0F	10624			10624	U3E1\HG39	.0F	D10039
	D36	U3E0\HG40	.0F	10640			10640	U3E1\HG40	.0F	D10040
	D37 D38	U3E0\HG41 U3E0\HG42	.0F	10656 10672			10656 10672	U3E1\HG41 U3E1\HG42	.0F	D10041 D10042
			.0F						.0F	
	D39 D40	U3E0\HG43 U3E0\HG44	.0F	10688 10704			10688 10704	U3E1\HG43 U3E1\HG44	.0F	D10043 D10044
	D41	U3E0\HG45	.0F	10720			10720	U3E1\HG45	.0F	D10045
	D41	U3E0\HG45	.0F	10720			10720	U3E1\HG45	.0F	D10045
	D43	U3E0\HG47	.0F	10752			10752	U3E1\HG47	.0F	D10047
	D44	U3E0\HG48	.0F	10768			10768	U3E1\HG48	.0F	D10048
	D45	U3E0\HG49	.0F	10784			10784	U3E1\HG49	.0F	D10049
	D46	U3E0\HG50	.0F	10800			10800	U3E1\HG50	.0F	D10050
	D47	U3E0\HG51	.0F	10816			10816	U3E1\HG51	.0F	D10051
	D48	U3E0\HG52	.0F	10832			10832	U3E1\HG52	.0F	D10052
	D49	U3E0\HG53	.0F	10848			10848	U3E1\HG53	.0F	D10053
	D50	U3E0\HG54	.0F	10864			10864	U3E1\HG54	.0F	D10054
	D51	U3E0\HG55	.0F	10880			10880	U3E1\HG55	.0F	D10055
	D52	U3E0\HG56	.0F	10896			10896	U3E1\HG56	.0F	D10056
	D53	U3E0\HG57	.0F	10912			10912	U3E1\HG57	.0F	D10057
	D54	U3E0\HG58	.0F	10928			10928	U3E1\HG58	.0F	D10058
	D55 D56	U3E0\HG59 U3E0\HG60	.0F	10944 10960			10944 10960	U3E1\HG59 U3E1\HG60	.0F	D10059 D10060
	D56 D57	U3E0\HG60 U3E0\HG61	.0F	10960 10976	1		10960		.0F	D10060 D10061
	201	U3EU\HG61	.0F	103/0			109/0	U3E1\HG61	.0F	D10001
			.0F				-		.0F	
			.0F				—		.0F	
			.0F		İ				.0F	
			.0F						.0F	
			.0F		1				.0F	
			.0F		1				.0F	
			.0F						.0F	
			.0F						.0F	
			.0F						.0F	
	D511	U3E0\HG511	.0F	18176			18176	U3E1\G511	.0F	D10511
		U3E0\HG512	.0F	18192			18192	U3E1\G512	.0F	D10512
			.0F		Extended function area	Extended function area			.0F	
	D1023	U3E0\HG1023	.0F					U3E1\G1023	.0F	D11023
	х	U3E0\HG1024	U3E0\HG1024.0	M_in(10000) bit			M_out(10000) bit	U3E2\HG0	U3E2\HG0.0	D20000
	х		U3E0\HG1024.1 .2E	M_in(10001) bit			M_out(10001) bit		U3E2\HG0.1	
	×		.2E U3E0\HG1024.F	 M_in(10015) bit	Dedikált I/O címtartomány	Dedikált I/O címtartomány	 M_out(10015) bit		.2E U3E2\HG0.F	
		U3E0\HG1025	.0F	M_III(10012) DIT	(PLC küldi a robotnak)	(Robot küldi PLC-nek)	M_001(10015) Bil	U3E2\HG1	.0F	D20001
	× ×	0323(HQ1023	.0F					U3E2 \riG1	.0F	020001
J G	¥	 U3E0\HG1033	.0F					U3E2\HG9	.0F	D20009
Másodík Robot CPU	D1034	U3E0\HG1034	.0F	10160			10160	U3E2\HG10	.0F	D20010
			.0F						.0F	
			.0F		1				.0F	
Má			.0F		1				.0F	
			.0F		1				.0F	
		U3E0\HG1535	.0F	18176	1		18176	U3E2\HG511	.0F	
		U3E0\HG1536	.0F	18192			18192	U3E2\HG512	.0F	
			.0F		Extended function area	Extended function area			.0F	
	D2047	U3E0\G12047	.0F					U3E2\HG1023	.0F	D21023