

Prob :-

Lec # 17

$$\frac{d^2 y(t)}{dt^2} + 4 \frac{dy(t)}{dt} + 3y(t) = 2 \frac{dx(t)}{dt} + 4x(t)$$

Compute

- A. Transfer function $H(s)$
- B. Find all possible impulse responses $h(t)$
- C. Find impulse response $h(t)$ for each of the following cases
 - (i) Causal
 - (ii) Stable
 - (iii) Neither Causal nor Stable
 - (iv) Both causal and stable

Solution :- $\frac{d^2 y(t)}{dt^2} + 4 \frac{dy(t)}{dt} + 3y(t) = 2 \frac{dx(t)}{dt} + 4x(t)$

A. Transfer function :-

Apply property on differential equation

$$s^2 Y(s) + 4sY(s) + 3Y(s) = 2sX(s) + 4X(s)$$

$$(s^2 + 4s + 3)Y(s) = (2s + 4)X(s)$$

$$\frac{Y(s)}{X(s)} = \frac{2s + 4}{s^2 + 4s + 3}$$

$$\therefore H(s) = \frac{2s + 4}{s^2 + 4s + 3}$$

Apply partial fraction

(7)

$$\frac{2s+4}{(s+3)(s+1)} = \frac{A}{s+3} + \frac{B}{s+1}$$

Solve it, you will get

$$A = 1, \quad B = 1$$

$$\therefore H(s) = \frac{1}{s+3} + \frac{1}{s+1}$$

B. All possible combinations of impulse responses $h(t)$.

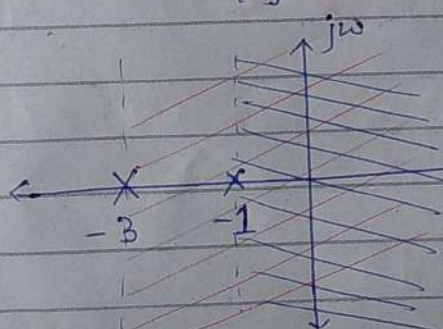
(i) When both sequences are right sided

$$H(s) = \frac{1}{s+3} + \frac{1}{s+1}$$

RSS RSS

pole : -3 -1

ROC : $\text{Re}\{s\} > -3$ $\text{Re}\{s\} > -1$



$$\begin{aligned} \frac{1}{s+3} &\xrightarrow{\text{RSS}} e^{-3t} u(t) \\ \frac{1}{s+1} &\xrightarrow{\text{RSS}} e^{-t} u(t) \end{aligned}$$

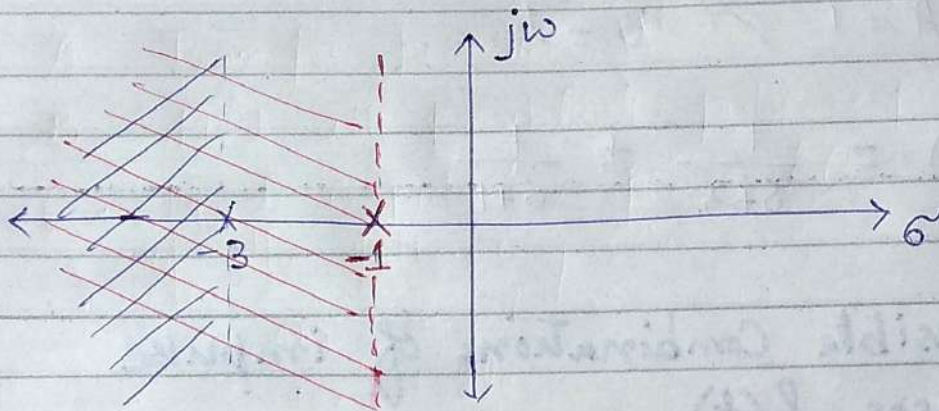
\therefore ROC of $H(s)$: $\text{Re}\{s\} > -1$

$$h(t) = e^{-3t} u(t) + e^{-t} u(t)$$

(ii) When both sequences are left sided. (8)

$$H(s) = \frac{1}{s+3} + \frac{1}{s+1}$$

pole : -3 -1
ROC : $\text{Re}\{s\} < -3$ $\text{Re}\{s\} < -1$



ROC of $H(s)$: $\text{Re}\{s\} < -3$

$$\frac{1}{s+3} \xrightarrow{\text{LSS}} -e^{-3t} u(-t)$$

$$\frac{1}{s+1} \xrightarrow{\text{LSS}} -e^{-t} u(-t)$$

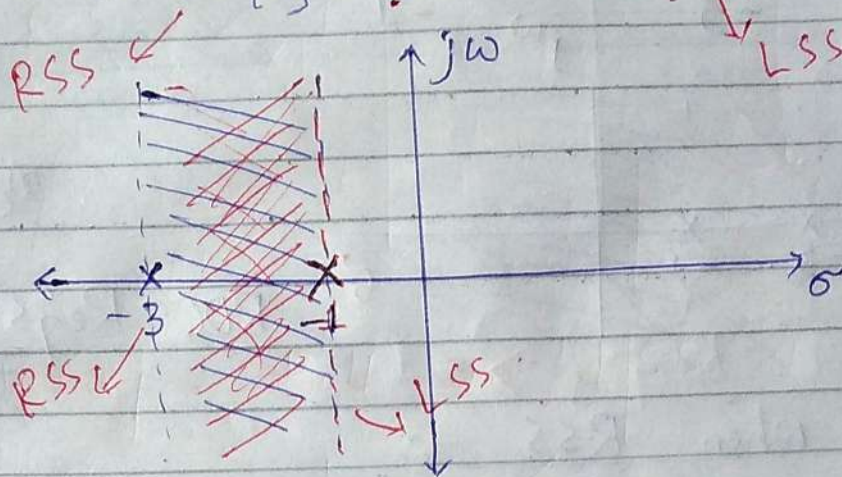
$$h(t) = [-e^{-3t} u(-t)] + [-e^{-t} u(-t)]$$

(iii) When ROC is in the form of strip (9)

$$H(s) = \frac{1}{s+3} + \frac{1}{s+1}$$

poles : -3 -1

ROC : $\text{Re}\{s\} > -3$ $\text{Re}\{s\} < -1$



ROC of $H(s)$: $-3 < \text{Re}\{s\} < -1$

$$\frac{1}{s+3} \xrightarrow{\text{RSS}} e^{-3t} u(t)$$

$$\frac{1}{s+1} \xrightarrow{\text{LSS}} -e^{-t} u(-t)$$

$$\therefore h(t) = [e^{-3t} u(t)] + [-e^{-t} u(-t)]$$

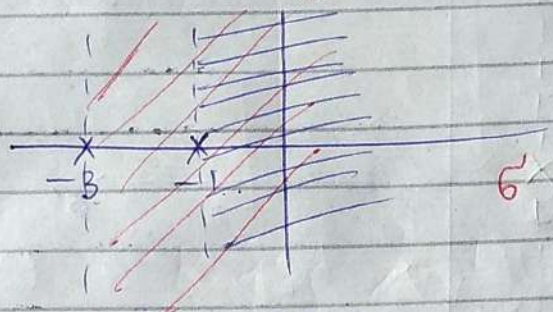
C. find $h(t)$ when system is ;

(3)

(i) Causal

$$H(s) = \frac{1}{s+3} + \frac{1}{s+1}$$

-3 $j\omega$ -1



right most pole

6' ROC: $\text{Re}\{s\} > -1$

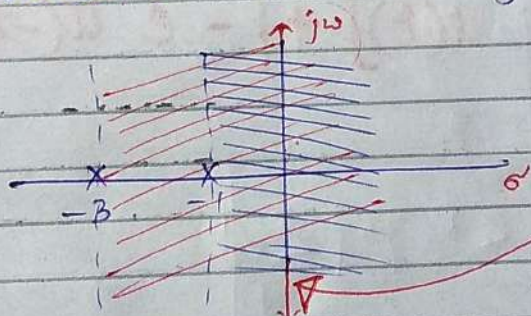
Causal when RSS \therefore

$$\frac{1}{s+3} \xrightarrow{\text{RSS}} e^{-3t} u(t)$$

$$\frac{1}{s+1} \xrightarrow{\text{RSS}} e^{-t} u(t)$$

$$h(t) = e^{-3t} u(t) + e^{-t} u(t)$$

(ii) Stable :- includes $j\omega$ -axis



$j\omega$ -axis is included in ROC

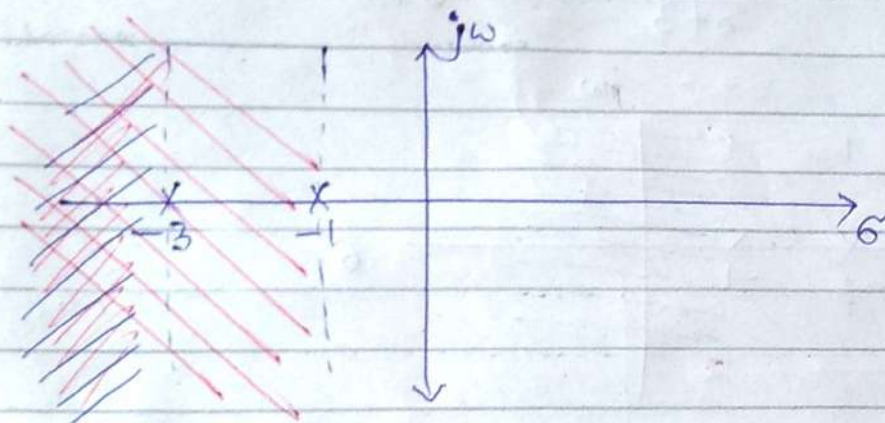
$$h(t) = e^{-3t} u(t) + e^{-t} u(t)$$

\downarrow RSS \downarrow RSS

(iii) Neither Causal Nor Stable :-

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$$H(s) = \frac{1}{s+3} + \frac{1}{s+1}$$

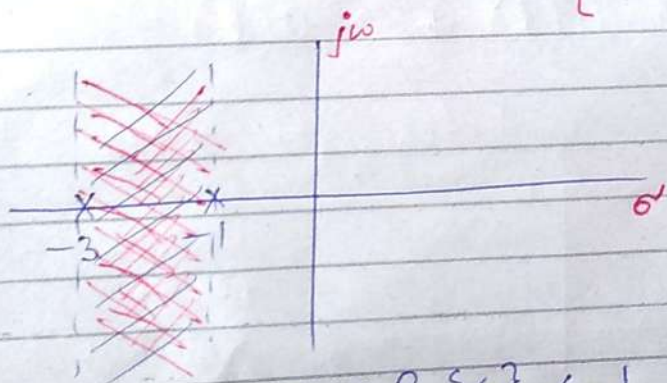


One way :- Both are LSS

$$\text{ROC: } \text{Re}\{s\} < -3$$

$$h(t) = [-e^{-3t}u(-t)] + [-e^{-t}u(-t)]$$

2nd way: ROC is strip $\begin{cases} \text{one is LSS} \\ \text{one is RSS} \end{cases}$



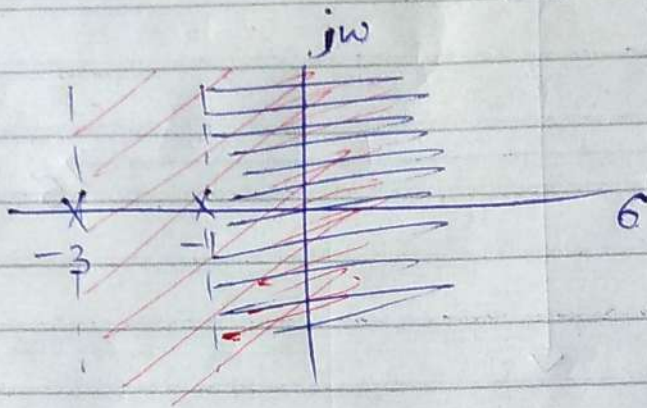
$$\text{ROC: } \underbrace{-3 < \text{Re}\{s\}}_{\text{RSS}} < \underbrace{-1}_{\text{LSS}}$$

$$h(t) = [e^{-3t}u(t)] + [-e^{-t}u(-t)]$$

(iv) Both Stable & Causal.

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$$H(s) = \frac{1}{s+3} + \frac{1}{s+1}$$



ROC: $\text{Re}\{s\} > -1$

$$h(t) = [e^{-3t} u(t)] + [e^{-t} u(t)]$$