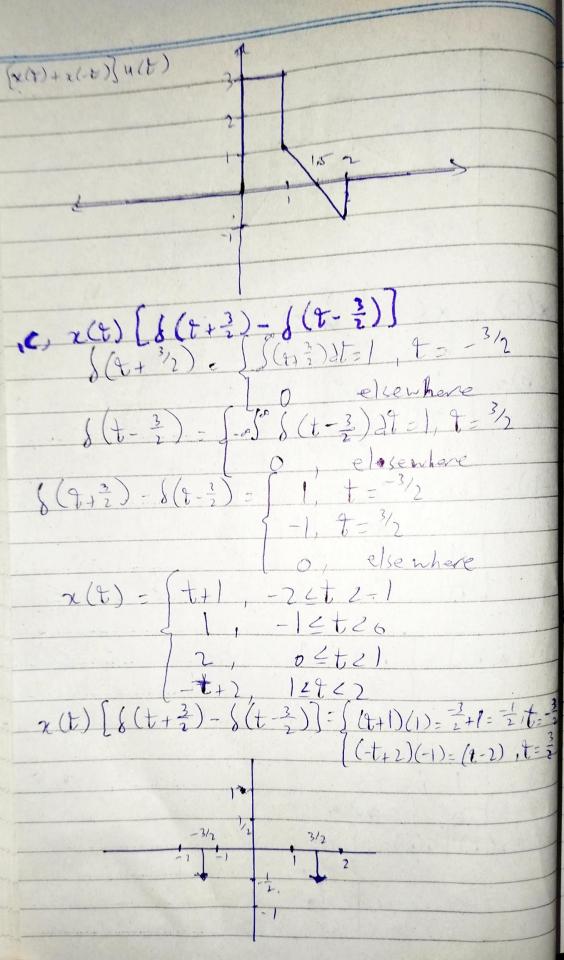
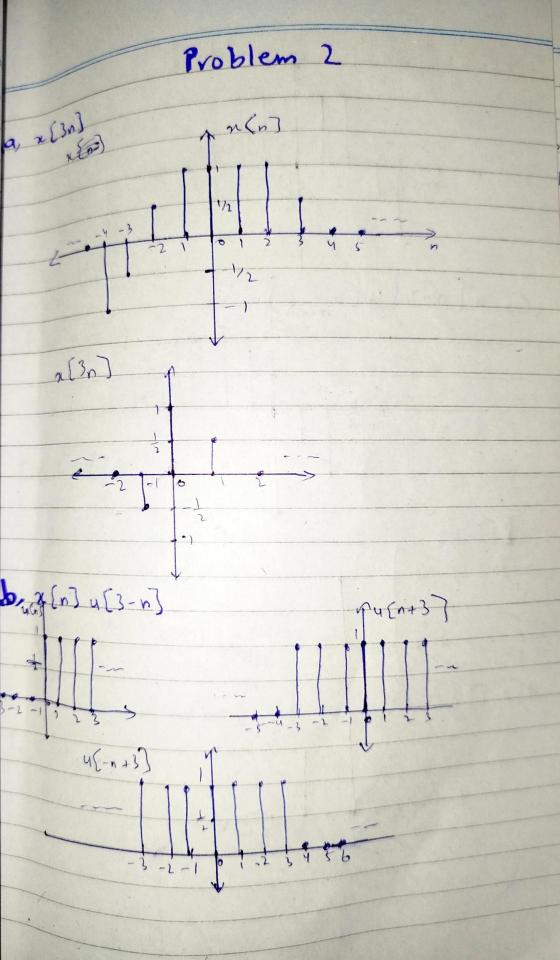
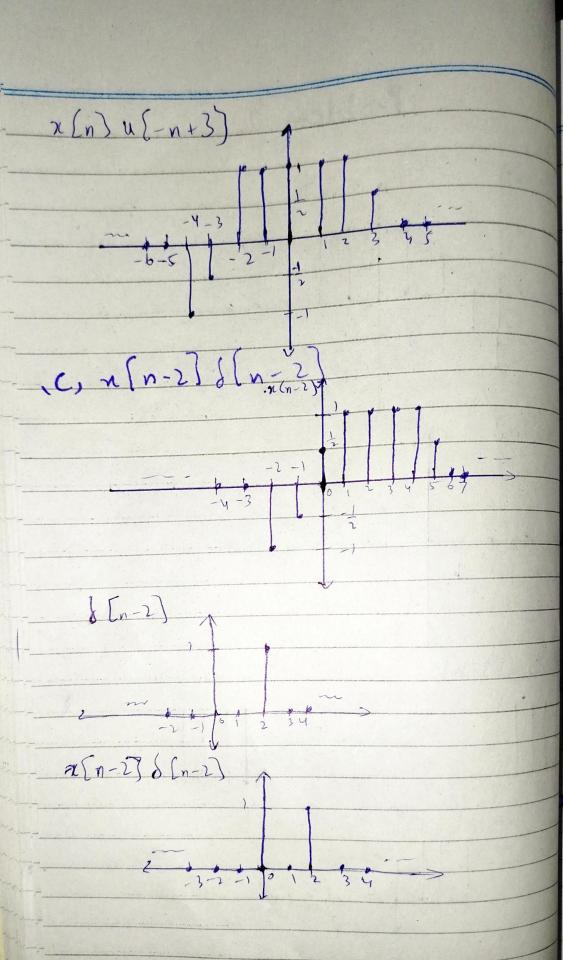
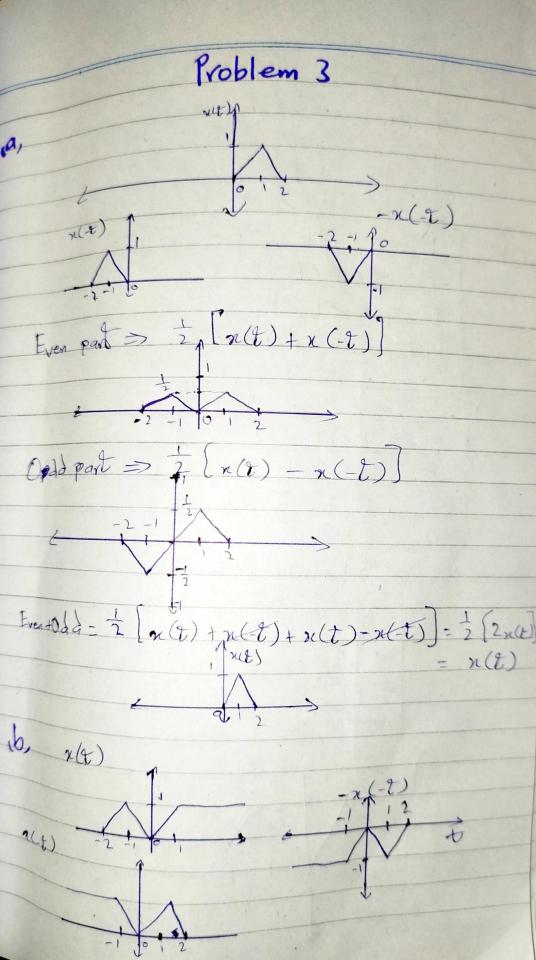


[x(t) + x(-t)] m(t) [t+1 for -2622-1 2 for 02t2 1-t+2 for 15t22 x(t)= (t+2 for -25t2-1 1 2 for -14t20 1 for 04t21 -til for 15t22 [x(t)+x(-t)]=[2t+3] for $-2 \le t \le -1$ 1 3 for -12t21 -2t+3 for 16t22 y(t) . [] , t = 0 [x(t)+x(-t)]y(t)= [0 220 105t21 -2t+3; 14t22 0.22 0



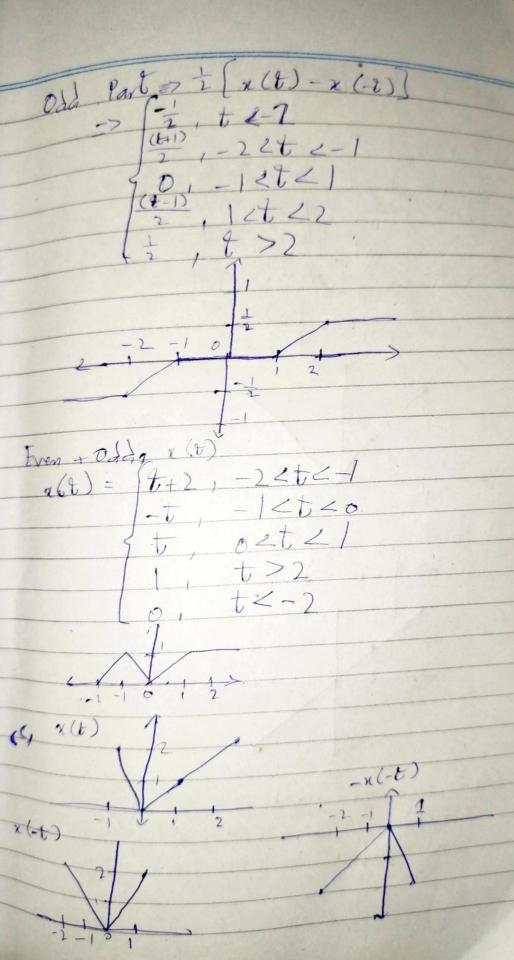


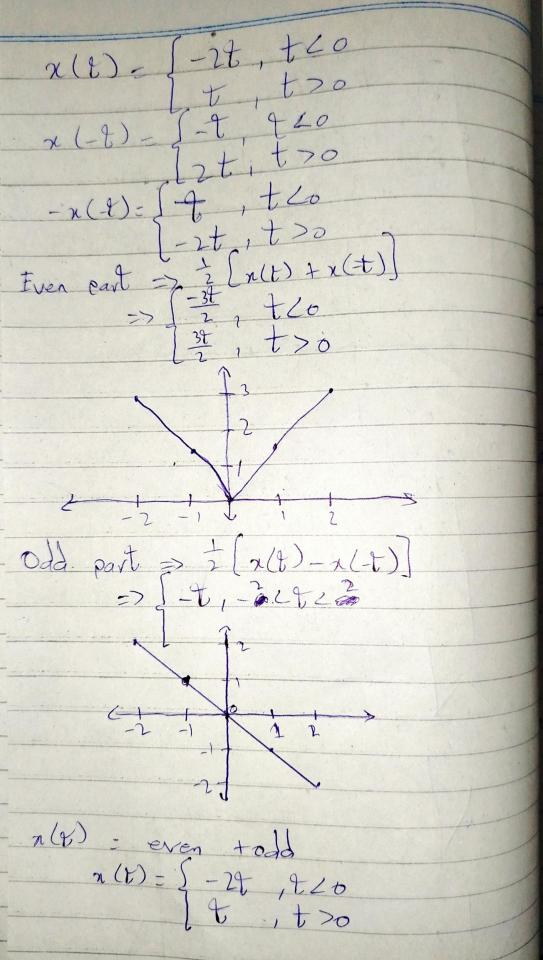




x(t): | t+2, -2.462-1 12620 t, 02t21 1 +>> 1, t<-1 -t ,-1ct 26 102521 1-t+2, 12t2 7-12726 10220 2,1222 6, 157 Ever Part => \frac{1}{2} \left[n(t) + n(-t) \right]

=> \frac{1}{2} \quad \frac{1}{2} \left[2 - 2 \right] -2t - 4 , -1 2=t 16421 (++3)





Problem 4 m(t)= (2, octo) & 1,12823 (-1,32224 0, elsewhere Now, x(t) in term of unit signal $\chi(2) = \begin{cases} 2y(2) - 2y(2-1), & 0 < 1 < 1 \\ y(2-1) - y(2-3), & 1 < 2 < 3 \end{cases}$ |- u(t-3)+ u(t-4), 3<t24 10, elsewhere otherwise Jaking derivative

d x(t) = [2](t-1) - 2((t-1)), 0(4)

dt = {((t-1) - 5(t-3), 12+23} 1-5(t-1)+5(t-4),32tc4 o , otherwise = x(t) = 2,5(t) -2((t-1)+5(t-1)-5(t-3) $= \frac{-5(t-3) + 5(t-4)}{25(t) - 5(t-1) - 25(t-3) + 5(t-4)}$ Craphically,

y(t) = x (tx10) + x2(t) R, H, => x(\(\frac{1}{2}\) + x2(\(\frac{1}{2}\)) we put delay in it = x(t-t,+10)+x2(t-t,) L. H.S => x(t) delay x(t-t,) = x(t-t,) systems x(t-t,+10) +x^2(t-t,) L. H. S = R. H. S. time invariant For Linearity y,(t) = x,(t+10) + x,(t) y, (t) = x, (t+10) + x, (t) y3(t) = a,y,(t) + azy,(t) yz(t) = a, x, (t+10)+a, x, (t) +92x, (t+10)+92x, (t) $= \frac{1}{4.5}$ $= \frac{1}{4.5}$ 92 ×2 (t) $= \frac{q_2 n_2(0)}{a_1 x_1(t+10) + a_2 x_2(t+10) + a_1 x_1^2(t) + a_2 x_2(t+10) + a_1 x_1^2(t)} + a_1 x_1^2(t) + a_2 x_1^2(t) + a_2 x_1^2(t) + a_1 x_1(t)) (a_1 x_1(t))$ 7 R. H.S. So, the system is non-linear