

Simply Typed Lambda Calculus and the Curry-Howard Correspondence

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Submitted by: Ali Caglayan

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Abstract

The goal of this dissertation is to give an introduction to the formal study of lambda calculus and type theory. We begin by analysing the intuitive notion of *syntax*, highlighting the many subtleties associated with it. We discuss possible solutions to these issues, but ultimately remark that it is very difficult to be certain of correctness. We will however give a notion of syntax which is “correct enough” for our purposes.

The next section is to discuss the formality of *judgements*. This is a concept oft overlooked in the study of type theory. We will give a careful and detailed account of derivability and admissibility. We will also remark on inconsistencies of the treatment of certain concepts.

This will lead us into studying the *simply type lambda calculus* (STLC), in some ways one of the simplest (functional) programming languages. We will give syntax, judgements and rules governing its semantics. After which, we will prove meta properties about our type theory and discuss the notion of *type checking*.

We will then analyse the dynamics of the STLC. There is a long history of normalisation results we wish to briefly sketch. We will set up some machinery to prove some of these results. Finally we will discuss notions of canonicity and what these results mean for the design of programming languages.

Next there will be several examples of terms to be type checked. This will show the intricacies that go into designing a type checker. We will see that typing makes lambda calculus much weaker, in that many terms from the untyped lambda calculus cannot be typed. It is precisely these terms which gave the computational power of the untyped lambda calculus to begin with.

We will sketch some modifications to the simply typed lambda calculus that will give us certain desired features. We will show how these can be designed and discuss their normalisation results too.

Finally we will give a detailed account of the ideas that went in to, what is now known as the *Curry-Howard* correspondence. This is a very deep package of ideas with far reaching consequences, of which we will try to make account of.

Our closing remarks will be about future directions in type theory, questions that need to be answered and future of programming language design.

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1 Introduction

The goal of this dissertation is to give an introduction to the formal study of lambda calculus and type theory. We begin by analysing the intuitive notion of *syntax*, highlighting the many subtleties associated with it. We discuss possible solutions to these issues, but ultimately remark that it is very difficult to be certain of correctness. We will however give a notion of syntax which is “correct enough” for our purposes.

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This will lead us into studying the *simply type lambda calculus* (STLC), in some ways one of the simplest (functional) programming languages. We will give syntax, judgements and rules governing its semantics. After which, we will prove meta properties about our type theory and discuss the notion of *type checking*.

We will then analyse the dynamics of the STLC. There is a long history of normalisation results we wish to briefly sketch. We will set up some machinery to prove some of these results. Finally we will discuss notions of canonicity and what these results mean for the design of programming languages.

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Our closing remarks will be about future directions in type theory, questions that need to be answered and future of programming language design.

2 Syntax

2.1 Introduction

Syntax is a difficult and subtle concept to get right. There is usually a difficult tradeoff between simplicity, readability and correctness. It is very rare that an approach to syntax can give room to all three. We follow an approach to syntax outlined by Harper in [24].

2.2 Abstract binding trees

Definition 2.2.1 (Sorts). Let \mathcal{S} be a finite set of elements called *sorts*.

Definition 2.2.2 (Arity). An *arity* (or *signature*) consists of the following data:

1. A sort $s \in \mathcal{S}$.
2. A natural number n called the *argument arity*.
3. A natural number m called the *binding arity*.
4. A function $\text{soa} : [n] \rightarrow \mathcal{S}$ called the *sort of argument* function.
5. A function $\text{sov} : [m] \rightarrow \mathcal{S}$ called the *sort of variable* function.
6. A relation $\triangleleft \subseteq [n] \times [m]$ called *scoping*.

We denote the set of arities by \mathbf{A} .

Remark 2.2.3. Let $1 \leq k \leq n$ and $1 \leq l \leq m$. We say that the sort of argument k is $\text{soa}(k)$ and the sort of variable l is $\text{sov}(l)$. If $k \triangleleft l$ then we would say that the k th argument is in scope of the l th variable.

Remark 2.2.4. This is a modification to the definition given in [24]. In which each argument has a set of variables. For our purposes we want all arguments to use the same variables. This is achieved with a scoping relation. Details of this idea can be found in [42].

Definition 2.2.5. Let \mathcal{O} be a set of elements called *operators*, and let $\text{ArityOf} : \mathcal{O} \rightarrow \mathbf{A}$ be the function picking the *arity of an operator*. The arity of an operator $o \in \mathcal{O}$ is $\text{ArityOf}(o)$.

Remark 2.2.6. To specify an operator, it suffices to give the following data:

- A list of variables of various sort.
- A list of arguments of various sort.
- Binding relations between the two.
- The sort of the operator.

Definition 2.2.7. A set of *variables* is simply a set \mathcal{X} and a function $\text{SortOf} : \mathcal{X} \rightarrow \mathcal{S}$ choosing the sort of the variable. We write \mathcal{X}_s for all the variables $x \in \mathcal{X}$ with $\text{SortOf}(x) = s \in \mathcal{S}$. Observe that \mathcal{S} is the inverse image of SortOf over s .

Remark 2.2.8. Typically a set of variables is endowed with some sort of order. They are also typically countable. We could say that every set of variables should necessarily be equipped with an injection into the natural numbers.

Definition 2.2.9. We say a set of variables \mathcal{V} is *fresh* for a set of variables \mathcal{X} if $\mathcal{V} \cap \mathcal{X} = \emptyset$. We can then take the *union* of sets of variables $\mathcal{V} \cup \mathcal{U}$ with the obvious well-defined definition of SortOf .

Definition 2.2.10. The set of *abstract binding trees* (abts) of sort $s \in \mathcal{S}$ on a set of variables \mathcal{X} , is the least set $\mathcal{B}[\mathcal{X}]_s$ satisfying the following conditions:

1. If $x \in \mathcal{X}_s$ then $x \in \mathcal{B}[\mathcal{X}]_s$.
2. Let \mathbf{G} be an operator of sort s , argument arity n , binding arity m . Let $\mathcal{V} := \{v_1, \dots, v_m\}$ be a finite set of m variables fresh for \mathcal{X} . For $1 \leq j \leq n$, let $\mathcal{Y}_j := \{v_k \in \mathcal{V} \mid j \triangleleft k\}$ be the set of variables that the j th argument is in scope of. Now suppose for each $1 \leq j \leq n$, there are $M_j \in \mathcal{B}[\mathcal{X} \cup \mathcal{Y}_j]_{\text{soa}(j)}$. Then $\mathbf{G}(\mathcal{V}; M_1, \dots, M_n) \in \mathcal{B}[\mathcal{X}]_s$.

Remark 2.2.11. Harper's notion of *abstract binding tree* is a generalisation of the more common *abstract syntax tree*. The difference is that abts keep track of how their variables are bound. We will later demonstrate this by showing how variable capture is avoided. The above definition may seem complicated but it is simply a tree where branches are operators and nodes are variables. All these trees do not live in the same set however since the bound and free variables are being kept track of.

Definition 2.2.12 (α -equivalence). Let \mathcal{X} and \mathcal{X}' be bijective sets of variables, and let $\rho : \mathcal{X} \rightarrow \mathcal{X}'$ be a bijection. Define the following relation $\sim_\rho \subseteq \mathcal{B}[\mathcal{X}]_s \times \mathcal{B}[\mathcal{X}']_s$ by induction on both abts:

- If $x \in \mathcal{X}$ and $y \in \mathcal{X}'$ then $x \sim_\rho y$ if and only if $\rho(x) = y$.
- For bijective sets of variables \mathcal{V} and \mathcal{V}' of size n , free for \mathcal{X} and \mathcal{X}' respectively. By Remark 2.2.8 we give them orders. Let $\xi : \mathcal{V} \rightarrow \mathcal{V}'$ be the *unique* order-preserving bijection between them. For $1 \leq j \leq n$, let $\mathcal{Y}_j := \{v_k \in \mathcal{V} \mid j \triangleleft k\}$ and $\mathcal{Y}'_j := \{v'_k \in \mathcal{V}' \mid j \triangleleft k\}$ be the sets of variables the j th argument is in scope of in \mathcal{V} and \mathcal{V}' respectively. Observe that the restriction $\xi_j : \mathcal{Y}_j \rightarrow \mathcal{Y}'_j$ is also a bijection. Then $\mathbf{G}(\mathcal{V}; m_1, \dots, m_n) \sim_\rho \mathbf{G}(\mathcal{V}'; m'_1, \dots, m'_n)$ if and only if $m_j \sim_{\rho \cup \xi_j} M'_j$ for all $1 \leq j \leq n$.
- In all other cases the relation is false.

We say that an abt $a \in \mathcal{B}[\mathcal{X}]_s$ is α -equivalent to an abt $b \in \mathcal{B}[\mathcal{X}']_s$, written $a \simeq_\alpha b$, if there exists a bijection $\rho : \mathcal{X} \rightarrow \mathcal{X}'$ such that $a \sim_\rho b$.

We quickly sketch some routine proofs showing α -equivalence is in fact an equivalence relation.

Lemma 2.2.13 (Reflexivity). α -equivalence is reflexive.

Proof. Observe that for any $m \in \mathcal{B}[\mathcal{X}]_s$ we have $m \sim_{\text{id}} m$. \square

Lemma 2.2.14 (Symmetry). α -equivalence is symmetric.

Proof. Suppose $a \simeq_\alpha b$ then $a \sim_\rho b$ for some bijection ρ . The inverse ρ^{-1} is also a bijection, and observe that $b \sim_{\rho^{-1}} a$. \square

Lemma 2.2.15. α -equivalence is transitive.

Proof. Suppose $a \simeq_\alpha b$ and $b \simeq_\alpha c$ then $a \sim_\rho b$ and $b \sim_{\rho'} c$ for some bijections ρ and ρ' . Observe that the composite $\rho' \cdot \rho$ is also a bijection, and that as a result $a \sim_{\rho' \cdot \rho} c$. It can then easily be checked that $a \simeq_\alpha c$. \square

Corollary 2.2.16. α -equivalence is an equivalence relation.

Definition 2.2.17. Given $\sigma : \mathcal{X} \rightarrow \mathcal{Y}$ such that σ preserves sorts, i.e. $\text{SortOf} \cdot \sigma = \text{SortOf}$, we define a function $\mathcal{B}[\mathcal{X}]_s \rightarrow \mathcal{B}[\mathcal{Y}]_s$ denoted $a \mapsto a[\sigma]$ by induction on a :

- If $a = x \in \mathcal{X}$, then $x[\sigma] = \sigma(x)$.
- If $a = \mathbf{G}(\mathcal{V}; m_1, \dots, m_n)$ we would like to define $a[\sigma]$ as

$$\mathbf{G}(\mathcal{V}, m_1[\sigma], \dots, m_n[\sigma])$$

but this is not possible since \mathcal{V} may not be disjoint from \mathcal{Y} . Therefore we observe that we can accommodate for this by first freshening up our variables in \mathcal{V} with respect to \mathcal{Y} by finding another \mathcal{V}' whose elements are all fresh in \mathcal{Y} and $\mathcal{V} \simeq_\alpha \mathcal{V}'$. We will call such an operation $\mathcal{V}^{[\mathcal{Y}]}$ and then define $\mathbf{G}(\mathcal{V}; m_1, \dots, m_n)[\sigma] := \mathbf{G}(\mathcal{V}^{[\mathcal{Y}]}; m_1[\sigma], \dots, m_n[\sigma])$.

If σ is an inclusion, then the operation is *weakening* (at the level of syntax). If σ is a permutation (a self-bijection) then this is known as *exchange* (at the level of syntax). If σ is a surjection, then the operation is *contraction* (at the level of syntax).

Remark 2.2.18. We must be weary not to get confused later on with the *structural rules* with the same names. These operations are intrinsic to syntax, and are not directly related with rules we will look at later.

Remark 2.2.19. It can be seen that α -equivalence between a and b can be stated as the existence of a bijection ρ such that $a[\rho] = b$.

Lemma 2.2.20. Given functions σ and σ' , we have $a[\sigma][\sigma'] = a[\sigma' \cdot \sigma]$.

Proof. Expanding the definition of $a[\sigma]$ and $a[\sigma][\sigma']$ this can be observed. \square

Lemma 2.2.21. If ρ, ρ' are bijections, then $a \sim_\rho b$ implies $a[\sigma] \sim_{\rho'} b[\rho' \cdot \sigma \cdot \rho^{-1}]$. Hence the operation $-[\sigma]$ respects α -equivalence.

Proof. By Remark 2.2.19 and Lemma 2.2.20, we have $a \sim_\rho b \iff a[\rho] = b \iff a = b[\rho^{-1}]$. So $a[\sigma] = b[\rho^{-1}][\sigma] = b[\sigma \cdot \rho^{-1}]$ and hence $a[\sigma][\rho'] = b[\rho' \cdot \sigma \cdot \rho^{-1}] \iff a[\sigma] \sim_{\rho'} b[\rho' \cdot \sigma \cdot \rho^{-1}]$. \square

Definition 2.2.22. We override our definition of abstract binding tree by defining the set of all abts of sort s over a set of variables \mathcal{X} as $\mathcal{B}[\mathcal{X}]_s / \simeq_\alpha$.

Remark 2.2.23. Whenever we refer to an abt we typically write it as some representing element of the equivalence class.

Remark 2.2.24. Due to Lemma 2.2.21, Definition 2.2.17 makes sense for equivalence classes too. Thus we do not need to change the meaning of $-\lceil\sigma\rceil$, by simply noting that it acts on representatives of the equivalence class in a well-defined way.

Definition 2.2.25. We call the disjoint union $\sqcup_{s \in \mathcal{S}} \mathcal{B}[\mathcal{X}]_s$ of abts over \mathcal{X} with sort s the set of all abts over \mathcal{X} . We could have defined this first and then defined $\mathcal{B}[\mathcal{X}]_s$ as the inverse image of some sort choosing function over a sort s like in Definition 2.2.7. When we talk about the sort of an abt $a \in \mathcal{B}[\mathcal{X}]$ we refer to the s which corresponds to the set in which a lives.

2.3 Substitution

Definition 2.3.1. Let $M \in \mathcal{B}[\mathcal{X} \cup \{x\}]$ and $N \in \mathcal{B}[\mathcal{X}]_{\text{SortOf}(x)}$. Then $M[N/x]$, read as the substitution of x for N in M , is defined by induction on M as follows:

- Suppose $M = x$ then $M[N/x] := N$.
- Suppose $M = y \in \mathcal{X}_{\text{SortOf}(x)}$ then $M[N/x] := M$.
- Suppose $M = \mathbf{G}(V; m_1, \dots, m_n)$ then

$$M[N/x] := \mathbf{G}(V; m_1[N/x], \dots, m_n[N/x])$$

Remark 2.3.2. The reason we set up abstract binding trees is that it avoids “*variable capture*”. Take for example the following: $(\lambda x.xy)[M/x]$, this statement makes sense in most formulations of syntax, therefore a complicated exceptions need to be taken into consideration for the definition of substitution. The way we have set up syntax we see that this sentence is complete nonsense. $(\lambda x.xy)$ lives in some set $\mathcal{B}[\mathcal{X}]$ which definitely doesn’t have $x \in \mathcal{X}$ or else the operator λ would not be able to introduce x as a variable fresh for \mathcal{X} .

Remark 2.3.3. It should be noted that although badly formed sentences are avoided, it doesn’t stop one from writing it down erroneously. To the human eye, it may even look valid. This is a situation in which using a *proof assistant* would be a huge benefit. In this way writing down sentences that don’t make sense simply wouldn’t be a valid statement, and would be rejected by the program.

2.4 Reasoning behind approach to syntax

It is common for many (especially popular) type theory papers to start with an almost apology about syntax. Stating how to date, there is no clear solution. It is almost equally common for solutions to be presented, only to later have flaws discovered, or that the entire system is just too overly convoluted.

A common approach is to sacrifice readability, and instead focus on correctness and simplicity, *de Bruijn indices* [17] fit these criteria. Bound variables are written as elements of an infinite set, enumerated by the syntactic depth of the variables occurrence. When forming new syntax care has to be taken to shift the enumeration along correctly. The disadvantages of this approach is the fact that it is almost impossible to read with the human eye. Considering only practical implementations however, de Bruijn indices provide a workable background mechanism for syntax, used internally for the representation of syntax in languages. Variable names can then be seen as syntactic sugar that can be preprocessed.

Authors such as Barendregt have written hoardes of material on the working of lambda calculus, but to our knowledge do this under the assumption that “there ought to be a way to do syntax correctly, as long as we are cautious, we can do this naively without problem”. For example in Barendregt et. al. [1] we have notions of substitution left to the reader under the assumption that they can be fixed. In Barendregt’s older book [2], there are models of the syntax of (untyped) lambda calculus. This has the classic approach of “be aware of variable-capture and substitution”. This is unfortunately not an easy idea to convey to a computer.

In Crole’s book [10], syntax is derived from an *algebraic signature* which comes directly from categorical semantics. We want to give an independent view of type theory. The syntax only has types as well, meaning that only terms can be posed in this syntax. Operations on types themselves would have to be handled separately. This will also make it difficult to work with *bound variables*. Not only that but issues of α -equivalence predate type theory. In fact, Church’s combinatory logic [4] was an early attempt to avoid the use of variables in classical logic. Precisely because of these issues. We will see later that these two avoidances are much the same, under the lens of the Curry-Howard correspondence.

In Lambek and Scott’s book [36], very little attention is given to syntax and categorical semantics and deriving type theory from categories for study is in the forefront of their focus. This is fine but still begs the question, “If everybody thinks syntax is somehow fixable, why hasn’t anybody fixed it?”.

In Jacob’s book [27], we again have much reliance on categorical machinery. A variant of algebraic signature called a *many-typed signature* is given, which has its roots in mathematical logic. Here it is discussed that classically in logic the idea of a sort and a type were synonymous, and they go onto preferring to call them types. This still has the problems identified before as terms and types being treated separately, when it comes to syntax.

In Sørensen and Urzyczyn’s book [46] a more classical unstructured approach to syntax is taken. This is very similar to the approaches that Church, Curry and de Bruijn gave early on. The difficulty with this approach is that it is very hard to prove things about the syntax. There are many exceptional cases to be weary of (for example if a variable is bound etc.). It can also mean that the syntax is vulnerable to mistakes. We acknowledge it’s correctness in this case, however we prefer to use a safer approach.

We will finally look at one more point of view, that of mathematical logic. We look at Troelstra and Schwichtenberg's book [51] which studies proof theory. This is essentially the previous style but done to a greater extent, for they use that kind of handling of syntax to argue about more general logics. As before, we do not choose this approach.

We have seen books from either end of the spectrum, on one hand Barendregt's type theoretic camp, and on the other, the more categorical logically oriented camp. We have argued that the categorical logically oriented texts do not do a good job of explaining and defining syntax, their only interest is in their categories. The type theoretic texts also seem to be on mathematically shaky ground, sometimes much is left to the reader and finer details are overlooked.

Harper's seems more sturdy and correct in our opinion. We do note however that it isn't perfect. Our approach to α -equivalence is to simply take equivalence classes and pretend everything works. For the standard of mathematical rigor, this is not an acceptable state of affairs.

3 Judgements

3.1 Introduction

We will now develop the basic formal tools to describe how our programming languages work. We will first describe judgements and how to specify a type system. Our leading example will be the simply typed lambda calculus. We use the ideas developed in [24] as a basic guide line.

Definition 3.1.1. The notion of a *judgement* or *assertion* is a logical statement about an abt. The property or relation itself is called a *judgement form*. The judgement that an object or objects have that property or stand in relation is said to be an *instance* of that judgement form. A judgement form has also historically been called a *predicate* and its instances called *subjects*.

Remark 3.1.2. Typically a judgement is denoted J . We can write $a \ J$, $J \ a$ to denote the judgement asserting that the judgement form J holds for the abt a . For more abts this can also be written prefix, infix, etc. This will be done for readability. Typically for an unspecified judgement, that is an instance of some judgement form, we will write J .

Definition 3.1.3. An *inductive definition* of a judgement form consists of a collection of rules of the form

$$\frac{J_1 \quad \cdots \quad J_k}{J}$$

in which J and J_1, \dots, J_k are all judgements of the form being defined. The judgements above the horizontal line are called the *premises* of the rules, and the

judgement below the line is called its *conclusion*. A rule with no premises is called an *axiom*.

3.2 Inference rules

Remark 3.2.1. An inference rule is read as starting that the premises are *sufficient* for the conclusion: to show J , it is enough to show each of J_1, \dots, J_k . Axioms hold unconditionally. If the conclusion of a rule holds it is not necessarily the case that the premises held, in that the conclusion could have been derived by another rule.

Example 3.2.2. Consider the following judgement from -- nat , where $a \text{ nat}$ is read as “ a is a natural number”. The following rules form an inductive definition of the judgement form -- nat :

$$\frac{}{\text{zero nat}} \qquad \frac{a \text{ nat}}{\text{succ}(a) \text{ nat}}$$

We can see that an abt a is zero or is of the form $\text{succ}(a)$. We see this by induction on the abt, the set of such abts has an operator succ . Taking these rules to be exhaustive, it follows that $\text{succ}(a)$ is a natural number if and only if a is.

Remark 3.2.3. We used the word *exhaustive* without really defining it. By this we mean necessary and sufficient. Which we will define now.

Definition 3.2.4. A collection of rules is considered to define the *strongest* judgement form that *closed under* (or *respects*) those rules. To be closed under the rules means that the rules are *sufficient* to show the validity of a judgement: J holds if there is a way to obtain it using the given rules. To be the *strongest* judgement form closed under the rules means that the rules are also *necessary*: J holds *only if* there is a way to obtain it by applying the rules.

Let’s add some more rules to our example, to get a richer structure.

Example 3.2.5. The judgement form $a = b$ expresses the equality of two abts a and b . We define it inductively on our abts as we did for nat .

$$\frac{}{\text{zero} = \text{zero}} \qquad \frac{a = b}{\text{succ}(a) = \text{succ}(b)}$$

Our first rule is an axiom declaring that zero is equal to itself, and our second rule shows that abts of the form succ are equal only if their arguments are. Observe that these are exhaustive rules in that they are necessary and sufficient for the formation of $=$.

3.3 Derivations

To show that an inductively defined judgement holds, we need to exhibit a *derivation* of it.

Definition 3.3.1. A *derivation* of a judgement is a finite composition of rules, starting with axioms and ending with the judgement. It is a tree in which each node is a rule and whose children are derivations of its premises. We sometimes say that a derivation of J is evidence for the validity of an inductively defined judgement J .

Suppose we have a judgement J and

$$\frac{J_1 \quad \cdots \quad J_k}{J}$$

is an inference rule. Suppose $\nabla_1, \dots, \nabla_k$ are derivations of its premises, then

$$\frac{\nabla_1 \quad \cdots \quad \nabla_k}{J}$$

is a derivation of its conclusion. Notice that if $k = 0$ then the node has no children.

Writing derivations as trees can be very enlightening to how the rules compose. Going back to our example with `nat` we can give an example of a derivation.

Example 3.3.2. Here is a derivation of `succ(succ(succ(zero))) nat`:

$$\frac{\frac{\frac{\text{zero nat}}{\text{succ(zero) nat}}}{\text{succ(succ(zero)) nat}}}{\text{succ(succ(succ(zero))) nat}}$$

Remark 3.3.3. To show that a judgement is *derivable* we need only give a derivation for it. There are two main methods for finding derivations:

- *Forward chaining* or *bottom-up construction*
- *Backward chaining* or *top-down construction*

Forward chaining starts with the axioms and works forward towards the desired conclusion. Backward chaining starts with the desired conclusion and works backwards towards the axioms.

It is easy to observe the *algorithmic* nature of these two processes. In fact this is an important point to think about, since it may become relevant in the future.

Lemma 3.3.4. Given a derivable judgement J , there is an algorithm giving a derivation for J by forward chaining.

Proof. This is not a difficult algorithm to describe. We start with a set of rules $\mathcal{R} := \emptyset$ which we initially set to be empty. Now we consider all the rules that have premises in \mathcal{R} , initially this will be all the axioms. We add these rules to \mathcal{R} and repeat this process until J appears as a conclusion of one of the rules in \mathcal{R} . It is not difficult to see that this will necessarily give all derivations of all derivable judgements and since J is derivable, it will eventually give a derivation for J . \square

Remark 3.3.5. Notice how we had to specify that our judgement is derivable. Since if we were not, then our process would not terminate, hence would not be an algorithm. It is also worth noting that this algorithm is very inefficient since the size of \mathcal{R} will grow rapidly, especially when we have more rules available. This is sort of a brute force approach. What we will need is more clever picking of the rules we wish to add. Mathematically this is an algorithm, but not in any practical sense.

Forward chaining does not take into account any of the information given by the judgement J . The algorithm is in a sense blind.

Lemma 3.3.6. Given a derivable judgement J , we can give a derivation for J by backward chaining.

Proof. Backward chaining maintains a queue of goals, judgements whose derivations are to be sought. Initially this consists of the sole judgement we want to derive. At each step, we pick a goal, then we pick a rule whose conclusion is our picked goal and add the premises of the rule to our list of goals. Since J is derivable there must be a derivation that can be chosen. \square

Remark 3.3.7. We could as before consider all possible goals generated by all possible rules which would technically give us an algorithm like in the case for forward chaining. But it would also be as useless as that algorithm. What backward chaining allows us to do however is better pick to rules at each stage. This is the structure that type checkers will take later on and even proof assistants, programs that assist a user in proving a statement formally. Due to each stage giving us information about the kind of rule we ought to pick, backward chaining is more suitable for algorithmic ally proving something. In face if we set up our rules in such a way that for each goal there is only one such rule to pick, we have an algorithm!

3.4 Rule induction

Conveniently our notion of inductive definition of a judgement form is actually an inductive definition. In that the set of derivable judgements forms a well-founded tree as defined earlier. This means we can apply our more general notion of well-founded induction when proving properties of a judgement.

Definition 3.4.1. We say that a property \mathcal{P} is *closed under* or *respects* the rules defining a judgement form J . A property \mathcal{P} respects the rule

$$\frac{a_1 J \quad \cdots \quad a_k J}{a J}$$

if $\mathcal{P}(a)$ holds whenever $\mathcal{P}(a_1), \dots, \mathcal{P}(a_k)$ do.

Remark 3.4.2. This is nothing more than a rephrasing of well-founded trees which is classically more common. This style of inductive definition fits more closely with what is actually going on, and we would argue is easier to work with.

We will now give some examples detailing how rule induction can be used.

Example 3.4.3. Continuing our `nat` example, if we want to show $\mathcal{P}(a)$ for some a `nat` it is enough to show the following:

- $\mathcal{P}(\text{zero})$.
- for all a , if $\mathcal{P}(a)$, then $\mathcal{P}(\text{succ}(a))$.

This is the familiar notion of mathematical induction on the natural numbers.

Now for another example where we combine all the things we have just discussed.

Example 3.4.4. Consider the judgement form `tree` defined inductively by the following rules:

$$\frac{}{\text{empty tree}} \quad \frac{a_1 \text{ tree} \quad a_2 \text{ tree}}{\text{node}(a_1; a_2) \text{ tree}}$$

Here is a derivation of the judgement `node(empty; node(empty; empty)) tree`:

$$\frac{\frac{}{\text{empty tree}} \quad \frac{\frac{}{\text{empty tree}} \quad \frac{}{\text{empty tree}}}{\text{node}(\text{empty}; \text{empty}) \text{ tree}}}{\text{node}(\text{empty}; \text{node}(\text{empty}; \text{empty})) \text{ tree}}$$

Now rule induction for the judgement form `tree` states that, to show $\mathcal{P}(a)$ it is enough to show the following:

- $\mathcal{P}(\text{empty})$.
- for all a_1 and a_2 , if both $\mathcal{P}(a_1)$ and $\mathcal{P}(a_2)$ then, $\mathcal{P}(\text{node}(a_1; a_2))$.

This is the familiar notion of tree induction.

Now that we have induction on our inductive definitions we can prove some results about our examples.

Lemma 3.4.5. If `succ(a)` `nat`, then a `nat`.

Proof. By induction on `succ(a)`, when `succ(a)` is `zero` this is vacuously true. Otherwise when `succ(a)` is `succ(b)`, what we want to prove is `succ(b)` `nat` $\implies b$ `nat` but this is exactly our induction hypothesis. \square

Lemma 3.4.6 (Reflexivity of `=`). If a `nat`, then $a = a$.

Proof. By induction on a we have two cases which are exactly the two rules about `=` to begin with. \square

Lemma 3.4.7 (Injectivity of `succ`). If `succ(a1) = succ(a2)`, then $a_1 = a_2$.

Proof. We perform induction on `succ(a1)` and `succ(a2)`. Note that if any of the two are of the form `zero` then the statement is true vacuously. When `succ(a1)` is of the form `succ(b1)` and `succ(a2)` is of the form `succ(b2)` our statement that we want to prove is exactly what we get from the induction hypothesis. \square

Lemma 3.4.8 (Symmetry of $=$). If $a = b$, then $b = a$.

Proof. Begin with induction on a and b :

- Suppose a is of the form **zero** and b is of the form **zero** then we have **zero** = **zero** as desired.
- Suppose a is of the form **zero** and b is of the form **succ**(b') then our statement is vacuously true. The same happens for when b is **zero** and a is of the form **succ**(a').
- Finally when a is of the form **succ**(a') and b is of the form **succ**(b') we have **succ**(a') = **succ**(b'). By 3.4.7 we have $a' = b'$ and by our induction hypothesis we have $b' = a'$ as desired.

□

Lemma 3.4.9 (Transitivity of $=$). If $a = b$ and $b = c$ then $a = c$.

Proof. By induction on a , b and c we see that we have eight cases. Clearly six of these are vacuously true, so we will prove the other two:

- When a , b and c are of the form **zero** our statement holds trivially.
- When a , b and c are of the form **succ**(a'), **succ**(b') and **succ**(c') respectively, we can apply 3.4.7 on **succ**(a') = **succ**(b') and **succ**(b') = **succ**(c') to get $a' = b'$ and $b' = c'$. Then applying our induction hypothesis we have $a' = c'$, finally applying the second rule for $=$ we have **succ**(a') = **succ**(c').

□

Finally we can say our four rules correspond to Peano arithmetic!

Remark 3.4.10. Classical presentations of Peano arithmetic contain many more axioms to formulate. We can already see how this inductive approach is cleaner and more compact than classical sporadic presentations [22].

Remark 3.4.11. The statements that we have proven about Peano arithmetic is technically considered a *meta statement*, since the truth value of a judgement such as $a = b$ occurs in the logic we set everything up in. When we consider richer systems of judgements, we may be able to prove meta statements, internally.

3.5 Hypothetical judgements

A *hypothetical judgement* expresses an entailment between one or more hypothesis and a conclusion. There are two main notions of entailment in logic: *derivability* and *admissibility*. We first begin by defining derivability.

Definition 3.5.1. Given a set \mathcal{R} of rules, define the *derivability* judgement, $J_1, \dots, J_k \vdash_{\mathcal{R}} K$ where each J_i and K are basic judgements, to mean that we may derive K from the *expansion* $\mathcal{R} \cup \{J_1, \dots, J_k\}$ of the rules \mathcal{R} with the axioms

$$\frac{}{J_1} \quad \dots \quad \frac{}{J_k}$$

We treat the *hypotheses* J_1, \dots, J_k of the judgement $J_1, \dots, J_k \vdash_{\mathcal{R}} K$ as axioms and derive the *conclusion*, by composing rules in \mathcal{R} . Thus $J_1, \dots, J_k \vdash_{\mathcal{R}} K$ means the judgement K is derivable from the expanded rules $\mathcal{R} \cup \{J_1, \dots, J_k\}$.

Remark 3.5.2. We will typically denote a list of basic judgements by a capital Greek letter such as Γ or Δ . The expansion $\mathcal{R} \cup \{J_1, \dots, J_k\}$ may also be written as $\mathcal{R} \cup \Gamma$ where $\Gamma := J_1, \text{dots}, J_k$. The judgement $\Gamma \vdash_{\mathcal{R}} K$ means K is derivable from the rules $\mathcal{R} \cup \Gamma$, and the judgement $\vdash_{\mathcal{R}} \Gamma$ means that $\vdash_{\mathcal{R}} J$ for each J in Γ . We may also extend lists of basic judgements like this: Γ, J , which would correspond to the list of basic judgements J_1, \dots, J_k, J , similarly for J, Γ . We can then concatenate two lists of basic judgements in the obvious way, through list concatenation written Γ, Δ .

Remark 3.5.3. Alternative names for *hypothesis* and *conclusion* include *antecedent* and *consequent* respectively.

Example 3.5.4. Let Peano be the set of four rules for our nat example. Consider the following derivability judgement:

$$a \text{ nat} \vdash_{\text{Peano}} \text{succ}(\text{succ}(a)) \text{ nat}$$

This can be shown to be true by exhibiting the following derivation:

$$\frac{\frac{a \text{ nat}}{\text{succ}(a) \text{ nat}}}{\text{succ}(\text{succ}(a)) \text{ nat}}$$

We now show that derivability doesn't get affected by expansion.

Lemma 3.5.5 (Stability). If $\Gamma \vdash_{\mathcal{R}} J$, then $\Gamma \vdash_{\mathcal{R} \cup \mathcal{R}'} J$.

Proof. Any derivation of J from $\mathcal{R} \cup \Gamma$ is also a derivation from $(\mathcal{R} \cup \mathcal{R}') \cup \Gamma$ since $\mathcal{R} \subseteq \mathcal{R} \cup \mathcal{R}'$. \square

There are a number of structural properties that derivability satisfies:

Lemma 3.5.6 (Reflexivity). Every judgement is a consequence of itself:

$$\Gamma, J \vdash_{\mathcal{R}} J$$

Proof. Since J becomes an axiom, the proof is trivial. \square

Lemma 3.5.7 (Weakening). If $\Gamma \vdash_{\mathcal{R}} J$, then $\Gamma, K \vdash_{\mathcal{R}} J$. Entailment is not influenced by unused premises.

Proof. The proof is trivial. \square

Lemma 3.5.8 (Transitivity). If $\Gamma, K \vdash_{\mathcal{R}} J$ and $\Gamma \vdash_{\mathcal{R}} K$, then $\Gamma \vdash_{\mathcal{R}} J$. If we replace an axiom by a derivation of it, the result is a derivation of the consequent without the hypothesis.

Proof. It is clear that if there is a derivation for J from $\Gamma, K \cup \mathcal{R}$ and a derivation for K from $\Gamma \cup \mathcal{R}$, then there is clearly a derivation for J from $\Gamma \cup \mathcal{R}$. For the first case it is clear how to compose two derivations to give the desired derivation. \square

Definition 3.5.9. Another form of entailment, *admissibility*, written $\Gamma \models_{\mathcal{R}} J$, is a weaker form of hypothetical judgement stating that $\vdash_{\mathcal{R}} \Gamma$ implies $\vdash_{\mathcal{R}} J$. That is, the conclusion J is derivable from the rules \mathcal{R} when the assumptions are all derivable from the rules \mathcal{R} .

Remark 3.5.10. In particular, if any of the hypotheses are *not* derivable relative to \mathcal{R} , then the judgement is *vacuously* true.

The admissibility judgement is *not* stable under expansion of the rules.

Lemma 3.5.11. If $\Gamma \vdash_{\mathcal{R}} J$, then $\Gamma \models_{\mathcal{R}} J$.

Proof. By definition of admissibility we need to show that $\vdash_{\mathcal{R}} \Gamma$ implies $\vdash_{\mathcal{R}} J$. It can be seen that repeated application of transitivity allows us to form a similar statement for when K is a list of basic judgements in reference to 3.5.8. This repeated transitivity gives us the desired result. \square

We will now give an example of some inadmissible rules.

Example 3.5.12. Consider the collection of rules **Parity** consisting of the rules in **Peano** and the following:

$$\frac{}{\text{zero even}} \quad \frac{b \text{ odd}}{\text{succ}(b) \text{ even}} \quad \frac{a \text{ even}}{\text{succ}(a) \text{ odd}}$$

This is a simultaneous inductive definition. Clearly we have the following admissibility judgement

$$\text{succ}(a) \text{ even} \models_{\text{Parity}} a \text{ odd}$$

But by adding the following rule to **Parity**, and calling it **Parity'**

$$\frac{}{\text{succ}(\text{zero}) \text{ even}}$$

we see that the following is no longer true:

$$\text{succ}(a) \text{ even} \models_{\text{Parity}'} a \text{ odd}$$

since there is no composition of rules deriving **zero odd**. Hence admissibility is not stable under expansion.

Remark 3.5.13. Admissibility is a useful property of a rule. It essentially checks whether we can get rid of a rules, knowing that we can derive it anyway. Hence by identifying inadmissible rules we can streamline our rule set.

3.6 Hypothetical inductive definitions

Our inductive definitions give us a rich and expressive way to define and use rules. We wish to enrich it further by introducing rules whose premises and conclusions are derivability judgements.

Definition 3.6.1. A *hypothetical inductive definition* consists of a set of *hypothetical rules* of the following form:

$$\frac{\Gamma, \Gamma_1 \vdash J_1 \quad \cdots \quad \Gamma, \Gamma_n \vdash J_n}{\Gamma \vdash J}$$

We call the hypotheses Γ , the *global hypotheses* of the rule, and Γ_i are called the local hypotheses of the i th premise of the rule. We will require that all rules in a hypothetical inductive definition be *uniform* in the following sense.

Definition 3.6.2. A hypothetical rule is said to be *uniform* if it holds for *all* global contexts.

Remark 3.6.3. When we have uniformity, we can present the rule in an *implicit* or *local* form:

$$\frac{\Gamma_1 \vdash J_1 \quad \cdots \quad \Gamma_n \vdash J_n}{J}$$

with the understanding that the rule applies for any choice of global hypotheses.

Remark 3.6.4. A hypothetical inductive definition can be regarded as an ordinary inductive definition of a *formal derivability judgement* $\Gamma \vdash J$ consisting of a list of basic judgements Γ and a basic judgement J .

Definition 3.6.5. A *formal derivability judgement* $\Gamma \vdash J$ is closed under a set of hypothetical rules \mathcal{R} and the judgement is *structural* is that it is closed under the following rules

$$\frac{}{\Gamma, J \vdash J} \quad \frac{\Gamma \vdash J}{\Gamma, K \vdash J} \quad \frac{\Gamma \vdash K \quad \Gamma, K \vdash J}{\Gamma \vdash J}$$

These rules ensure that formal derivability behaves like a hypothetical judgement. We write $\Gamma \vdash_{\mathcal{R}} J$ to denote that $\Gamma \vdash J$ is derivable from rules \mathcal{R} .

Remark 3.6.6. This definition is perhaps quite confusing, this is because we have two layers of derivability. What a formal derivability judgement shows is that the judgement of being derivable is itself derivable. This also means that we do not have to define what hypothetical induction on a hypothetical inductive definition is, since the formal derivability judgement is itself a judgement. So the principle of *hypothetical rule induction* is just the principle of rule induction applied to the formal hypothetical rule induction.

Remark 3.6.7. In the context of type theory, basic judgements are typically assertions that a term a has a type A , written $a : A$. In this case Γ becomes known as a *typing context*. In this case, the first structural rule in Definition 3.6.5 is typically known as the *variable*. The second rule is known as *weakening*, this states that “having knowledge of an extra variable does not effect what you know”. Finally the third would correspond to “being able to forget an assumption, if you know you can derive it”. In the case of the simply typed lambda calculus, which will study later, we will see that such structural rules are admissible.

The idea of logical judgements builds on the work of Per Martin-Löf [38, 39].

4 Simply typed lambda calculus

First develop the features needed. Discuss the arbitrary nature of such features, then use Curry-Howard as motivation for “the language that ought to be”. Develop STLC, discuss in detail the implications, give categorical semantics. Discuss briefly the dynamics of simply typed lambda calculus. A big disadvantage of STLC over the untyped version (which we ought to discuss since we have the tools to) is that there is no recursion. There are many ways to fix this, see Gödel for example. In order to fix this we will introduce dependent types.

We begin by discussing the syntax of our type theory. We will start by specifying the sorts \mathcal{S} of our type theory.

Definition 4.0.1. The sorts of simply typed lambda calculus are terms and types $\mathcal{S} := \{\text{tm}, \text{ty}\}$.

We now specify the operators that we defined in definition 2.2.5. In remark 2.2.6 we discussed the data needed to give an operator, therefore we will present all our operators in the following table.

Definition 4.0.2. The operators in the syntax of simply typed lambda calculus are given by the following table:

Op	Sort	Vars	Type args	Term args	Scoping	Syntax
\rightarrow	ty	—	A, B	—	—	$A \rightarrow B$
\times	ty	—	A, B	—	—	$A \times B$
$(-, -)$	tm	—	—	x, y	—	(x, y)
λ	tm	x	A, B	—	M	$\lambda(x : A).M$
App	tm	—	A, B	—	M, N	MN

Remark 4.0.3. Note that some of the syntax loses information that was put in. The application is the main example of this. In practice if we know the type of M and N we can deduce the type of MN just from the rules we will define later. The syntax is sugared or *syntactic sugar* so we do not have to write so much. If done incorrectly it could be considered an abuse of notation. It should be possible to *desugar* the syntax by adding an *annotated* version of an operator. For example for application instead of MN we could write $\text{App}_{A,B}(M; N)$. Having this information in the syntax will be useful when we want to induct over syntax, for example when proving an initiality theorem. But in practice we will save ourselves from having to write it out.

Definition 4.0.4. We can now construct our raw terms and types as the collection

of abts (see definition 2.2.10) over the previously defined data $\text{Term} := \mathcal{B}[\emptyset]_{\text{tm}}$ and $\text{Type} := \mathcal{B}[\emptyset]_{\text{ty}}$.

Remark 4.0.5. Note that we have no variables. This is because if we set the definition of abt up correctly we don't need any, but terms can have sub-terms (sub-trees of the abt) which have variables. The sets Term and Type become *all* the types and terms we ought to be able to write down from scratch.

We now need to define judgements about our syntax and write down the rules to write them down.

4.1 Judgements

We begin with our basic judgements.

Definition 4.1.1. Firstly we have a judgement form

$$A \text{ type}$$

asserting that an abt A is a type. It may seem like a strange that we haven't mentioned the definition of a type yet, this is because a type is anything that satisfies this judgement. This is in some sense the definition of a type. Next we have the judgement form

$$a \Leftarrow A$$

which states that the term a can be checked to have type A . Whenever we wish to check what type a term has, we are in fact attempting to derive this judgement. Next we have

$$a \Rightarrow A$$

stating that the term a synthesises the type A . This is used to represent the “creation of a term”. We will later see why we have two judgements when typically in type theory there is a single one, written $a : A$. This is due to our adoption of *bidirectional type checking*, which we will discuss later. We now have two forms of *judgemental (or definitional) equality*. Firstly judgemental equality of types

$$A \equiv B \text{ type}$$

which states that types A and B are judgmentally equal. And finally we have the judgemental equality of terms of some types

$$a \equiv b : A$$

which states that the terms a and b of type A are judgmentally equal.

Remark 4.1.2. Since these are *basic judgements* we would typically never write them on their own like this. Typically we are interested in the derivability judgement $\Gamma \vdash \mathcal{J}$.

Definition 4.1.3. A context is a list of variables, with an associated type. Elements of the list are written $x : A$ where x is a variable, and A is its type. Typically a context is denoted by a capital greek letter Γ , Δ , etc.

We can now list the five derivability judgements that we have:

- $\Gamma \vdash A \text{ type}$ - “ A is a type in context Γ ”.
- $\Gamma \vdash T \Leftarrow A$ - “ T can be checked to have type A in context Γ ”.
- $\Gamma \vdash T \Rightarrow A$ - “ T synthesises the type A in context Γ ”.
- $\Gamma \vdash A \equiv B \text{ type}$ - “ A and B are judgmentally equal types in context Γ ”.
- $\Gamma \vdash S \equiv T : A$ - “ S and T are judgmentally equal terms of type A in context Γ ”.

4.2 Structural rules

Structural rules will dictate how our judgements interact with each other, how different contexts can be formed and how substitution works. This is all roughly what a “type theory” ought to provide.

Definition 4.2.1. We begin with the *variable* rule, this says that if a term x appears with a type A as an element in a context Γ then x synthesises a type A in context Γ . Or written more succinctly as:

$$\frac{(x : A) \in \Gamma}{\Gamma \vdash x \Rightarrow A} \text{ (var)}$$

We now state what it means to perform a substitution in the type theory. Later we will see that this rule is admissible. This says if I can derive that a has type A in context Γ and that in context of Γ and some variable x with type A I have a judgement \mathcal{J} , then I can derive that $\mathcal{J}[a/x]$ in context Γ .

$$\frac{\Gamma \vdash a \Leftarrow A \quad \Gamma, x : A \vdash \mathcal{J}}{\Gamma \vdash \mathcal{J}[a/x]} \text{ (subst)}$$

$$\frac{\Gamma \vdash A \text{ type} \quad \Gamma \vdash \mathcal{J}}{\Gamma, x : A \vdash \mathcal{J}} \text{ (wkg)}$$

$$\frac{\Gamma, x : A, y : B \vdash \mathcal{J}}{\Gamma, y : B, x : A \vdash \mathcal{J}} \text{ (exg)}$$

Remark 4.2.2. We noted these rules would appear in Remark 3.6.7. We also noted that these rules are admissible. Or at least we expect them to be.

Lemma 4.2.3. The rules (subst), (wkg) and (exg) are all admissible.

Proof. Though we didn't really specify it that way, the judgement forms can be thought of as operators. That was we can think of a derivability judgement $\Gamma \vdash \mathcal{J}$ as an abt itself. We didn't do it this way since it would be confusing which abt we are talking about. However we will note that in an implementation of a type theory on a computer, having a data structure such as an abt will be indispensable for designing and reasoning about type theories. In that light, a judgement form ought to be part of the syntax. On top of this, substitution is admissible simply because it is a property of the syntax (Definition 2.3.1). We could not finish the rest of the proof, but we can refer readers to [46] and [24]. \square

Definition 4.2.4. One of the features of bidirectional type checking is that we can switch the mode we are in. This is expressed as the mode switching rule:

$$\frac{\Gamma \vdash t \Rightarrow A \quad \Gamma \vdash A \equiv B \text{ type}}{\Gamma \vdash t \Leftarrow B} \text{ (switch)}$$

Remark 4.2.5. This rule has been specially set up in that it will be the *only way* to derive $\Gamma \vdash T \Leftarrow B$. These are the kinds of properties we would like our syntax to have. A careful analysis will be done under the guise of the *inversion lemma* (Lemma 4.5.1).

In a unidirectional type system, the judgements $\Gamma \vdash T \Rightarrow A$ and $\Gamma \vdash T \Leftarrow B$ are collapsed into one judgement: $\Gamma \vdash T : A$. And now the mode-switching rule may have a more familiar form:

$$\frac{\Gamma \vdash t : A \quad \Gamma \vdash A \equiv B \text{ type}}{\Gamma \vdash t : B}$$

Which shows that it is actually a rule about substituting along a judgemental equality! But this is a problem since a type checking algorithm will have to decide when to stop doing this. This is one of the big advantages that bidirectional type checking has over unidirectional type checking. The type checking algorithm will be simpler! [9] We sketch a type checking algorithm later in Theorem 4.6.3.

Remark 4.2.6. Occasionally, we will simply mode-switch using reflexivity $\Gamma \vdash A \equiv A \text{ type}$, in which case we will abbreviate the rule as follows:

$$\frac{\Gamma \vdash t \Rightarrow A}{\Gamma \vdash t \Leftarrow A} \text{ (cswitch)}$$

4.3 Equality rules

Finally we have some structural rules for our two judgemental equality judgements. We wish for these to be an equivalence relation and that they are compatible with each other.

First we begin with the structural rules for the judgement form $- \equiv - \text{ type}$:

Definition 4.3.1. We wish for our judgemental equality of types to be reflexive:

$$\frac{\Gamma \vdash A \text{ type}}{\Gamma \vdash A \equiv A \text{ type}} \text{ (}\equiv_{\text{type}}\text{-reflexivity)}$$

We want our judgemental equality of types to be symmetric:

$$\frac{\Gamma \vdash A \equiv B \text{ type}}{\Gamma \vdash B \equiv A \text{ type}} (\equiv_{\text{type-symmetry})$$

and our judgemental equality of types to be transitive:

$$\frac{\Gamma \vdash B \text{ type} \quad \Gamma \vdash A \equiv B \text{ type} \quad \Gamma \vdash B \equiv C \text{ type}}{\Gamma \vdash A \equiv C \text{ type}} (\equiv_{\text{type-transitivity})$$

Notice how the previous rule also checks that B is a type. This is because if we did not do this, we could insert any symbol in. This is clearly undesirable. It also demonstrates how subtly sensitive rules are.

Now we list the rules making the judgement form $- \equiv - : A$ into an equivalence relation:

We wish for our judgemental equality of terms to be reflexive:

$$\frac{\Gamma \vdash t \Leftarrow A}{\Gamma \vdash t \equiv t : A} (\equiv_{\text{term-reflexivity})$$

We want our judgemental equality of terms to be symmetric:

$$\frac{\Gamma \vdash s \equiv t : A}{\Gamma \vdash t \equiv s : A} (\equiv_{\text{term-symmetry})$$

and our judgemental equality of terms to be transitive:

$$\frac{\Gamma \vdash t \Leftarrow A \quad \Gamma \vdash s \equiv t : A \quad \Gamma \vdash t \equiv r : A}{\Gamma \vdash s \equiv r : A} (\equiv_{\text{term-transitivity})$$

as we stated before for transitivity judgemental equality of types we need to also check that the middle term T is actually a term.

Finally we need a rule that will make that judgemental equality of types and judgemental equality of terms interact the way we expect them to:

$$\frac{\Gamma \vdash A \text{ type} \quad \Gamma \vdash s \equiv t : A \quad \Gamma \vdash A \equiv B \text{ type}}{\Gamma \vdash s \equiv t : B} (\equiv_{\text{term-}\equiv_{\text{type}}\text{-compat})$$

4.4 Type formers

What we have constructed thus far is essentially an “empty type theory”. What we have included which other authors typically gloss over is a clean way of constructing a type checking algorithm: bidirectional type checking and an account of judgemental equality. We now study what are known as type formers, typically when we wish to add a new type to a type theory we need to think about a collection of rules. These can roughly be sorted into 5 kinds of rules:

- Formation rules - How can I construct my type?
- Introduction rules - Which terms synthesise this type?
- Elimination rules - How can terms of this type be used?

- Computation (or equality) rules - How do terms of this type compute? (Normalise, etc.)
- Congruence rules - How do all the previous rules interact with judgemental equality

We make a note that although we will be providing all the rules, the congruence rules can be typically derived from the others. Although we do not know exactly how to do this so we will provide them explicitly. We also note that not every type need computation rules.

Building on top of our “empty type theory” we introduce \rightarrow the function type former:

Definition 4.4.1. Our formation rules tell us how to construct arrow types from other types:

$$\frac{\Gamma \vdash A \text{ type} \quad \Gamma \vdash B \text{ type}}{\Gamma \vdash A \rightarrow B \text{ type}} (\rightarrow\text{-form})$$

We note that \rightarrow is right-associative, in that $A \rightarrow B \rightarrow C = A \rightarrow (B \rightarrow C)$.

Our introduction rule tells us how to construct terms of our type. This is also known as λ -abstraction:

$$\frac{\Gamma, x : A \vdash M \Leftarrow B}{\Gamma \vdash \lambda x.M \Rightarrow A \rightarrow B} (\rightarrow\text{-intro})$$

Our elimination rule tells us how to use terms of this type. For function types this corresponds to application:

$$\frac{\Gamma \vdash M \Leftarrow A \rightarrow B \quad \Gamma \vdash N \Leftarrow A}{\Gamma \vdash MN \Rightarrow B} (\rightarrow\text{-elim})$$

We note that application is left-associative, in that $ABC = (AB)C$.

Finally we have computation rules which tell us how to compute our terms. We will later prove results about normalisation of the lambda calculus. We start with β -reduction which tells us how applied functions compute:

$$\frac{\Gamma, x : A \vdash y \Leftarrow B \quad \Gamma \vdash t \Leftarrow A}{\Gamma \vdash (\lambda x.y)t \equiv y[t/x] : B} (\rightarrow\text{-}\beta)$$

Then we introduce η -conversion which tells us if two functions applied to the same term and are judgmentally equal then the functions are judgmentally equal. This is “function extensionality” for judgemental equality.

$$\frac{\Gamma, y : A \vdash My \equiv M'y : B}{\Gamma \vdash M \equiv M' : A \rightarrow B} (\rightarrow\text{-}\eta)$$

Finally we have to make sure all our rules respect judgemental equality. This means showing that \rightarrow respects judgemental equality of types and that λ -terms and applications respect judgemental equality of terms.

$$\begin{array}{c}
\frac{\Gamma \vdash A \equiv A' \text{ type} \quad \Gamma \vdash B \equiv B' \text{ type}}{\Gamma \vdash A \rightarrow B \equiv A' \rightarrow B' \text{ type}} (\rightarrow \equiv_{\text{type}}\text{-cong}) \\
\\
\frac{\Gamma, x : A \vdash M \equiv M' : B}{\Gamma \vdash \lambda x. M \equiv \lambda x. M' : A \rightarrow B} (\rightarrow \equiv_{\text{term}}\text{-cong}) \\
\\
\frac{\Gamma \vdash M \equiv M' : A \rightarrow B \quad \Gamma \vdash N \equiv N' : A}{\Gamma \vdash MN \equiv M'N' : A \rightarrow B} (\rightarrow\text{-elim-cong})
\end{array}$$

Remark 4.4.2. Notice that we don't ensure that types compute the same way. This is because the computation rules will not be used in the type checking process and are therefore irrelevant to the inversion lemmas. Later we will prove that “fully reduced” computations are in fact equal. This is known as the Church-Rosser theorem (Theorem 5.8.15).

We define the product type as follows.

Definition 4.4.3. Given two types, we have their product type:

$$\frac{\Gamma \vdash A \text{ type} \quad \Gamma \vdash B \text{ type}}{\Gamma \vdash A \times B \text{ type}} (\times\text{-form})$$

We define *ordered pairs* as taking a term of each type:

$$\frac{\Gamma \vdash a \Leftarrow A \quad \Gamma \vdash b \Leftarrow B}{\Gamma \vdash (a, b) \Rightarrow A \times B} (\times\text{-intro})$$

We give two eliminators for pairs, the *first and second elements*:

$$\frac{\Gamma \vdash t \Leftarrow A \times B}{\Gamma \vdash \text{fst}(t) \Rightarrow A} (\times\text{-elim}_1) \quad \frac{\Gamma \vdash t \Leftarrow A \times B}{\Gamma \vdash \text{snd}(t) \Rightarrow B} (\times\text{-elim}_2)$$

And we finally need to dictate how this is computed:

$$\frac{\Gamma \vdash x \Leftarrow A \quad \Gamma \vdash y \Leftarrow B}{\Gamma \vdash \text{fst}(x, y) \equiv x : A} (\times\text{-}\beta_1) \quad \frac{\Gamma \vdash x \Leftarrow A \quad \Gamma \vdash y \Leftarrow B}{\Gamma \vdash \text{snd}(x, y) \equiv y : B} (\times\text{-}\beta_2)$$

However we need to be careful since there is a nontrivial equality we must also add as a rule:

$$\frac{\Gamma \vdash \text{fst}(t) \equiv \text{fst}(t') : A \quad \Gamma \vdash \text{snd}(t) \equiv \text{snd}(t') : B}{\Gamma \vdash t \equiv t' : A \times B} (\times\text{-}\eta)$$

Remark 4.4.4. There are many other ways to present product types, the eliminators are in a sense not unique. Typically in presentations of type theory [39] an inductive principle is given. This is simply just a way to build functions out of the type, the elimination principle is stated like that. What we note is that rule is in fact admissible in the presence of our fst and snd eliminators. We also argue that the fst and snd approach more closely matches what a programmer will do with the type theory.

Remark 4.4.5. Our presentation of η -reduction is unconventional. The traditional η :

$$\frac{\Gamma \vdash t \Leftarrow A \times B}{\Gamma \vdash (\text{fst}(t), \text{snd}(t)) \equiv t}$$

It is in fact admissible by observing the following proof tree in Appendix C.1.

We choose our presentation because it more clearly display what η really means and why it is there.

We will also need to add a unit type. This will be the simplest type, with only one term.

Definition 4.4.6. We begin with the formation rules, essentially saying that the unit type exists.

$$\frac{}{\mathbf{1} \text{ type}} \text{ (1-form)}$$

We then say that the unit type has a term:

$$\frac{}{\Gamma \vdash * \Rightarrow \mathbf{1}} \text{ (1-intro)}$$

Remark 4.4.7. We don't need to give any more rules since the unit type has all the properties we need. Our rules for \rightarrow allow us to build constant functions anyway. And we note that all functions $\mathbf{1} \rightarrow A$ are constant functions!

4.5 Inversion lemmas

Having listed all these rules, we need *Inversion lemmas* detailing how different judgements can *only* come from a set of given judgements. This is a crucial analysis if we wish to construct a type checking algorithm. An inversion lemma for a type theory is typically very difficult to state, and extremely tedious to prove. But nonetheless is essential if we want to induct over terms. These are also known as *Generation lemmas* [46, 24].

Luckily we set up syntax in such a way that we only need induct over the syntax. So we pick a syntactic form and the inversion lemma will tell us exactly how we can arrive at that conclusion. Let us list all term syntax we can create in STLC. We will write them in Backus-Naur form (BNF) [40] which is a common and clear way to write inductive generators:

$$\text{Term} ::= x \mid \lambda x. a \mid (a, b) \mid ab \mid c$$

Where x is a variable, a, b are terms and c is a constant, in this case any of $*$, fst , snd . We may also list the types that we have:

$$\text{Type} ::= A \mid A \times B \mid A \rightarrow B \mid \mathbf{1}$$

Where A, B are types.

Lemma 4.5.1 (Inversion lemmas). In the STLC the following judgement forms can only be derived in a specific way: If $\Gamma \vdash t \Leftarrow T$ then by induction on the syntax of t , one of the following must occur:

- (a) If $t = x$, then $(x : T) \in \Gamma$.
- (b) If $t = \lambda x.y$, then $\Gamma, x : A \vdash y : B$ and $\Gamma \vdash T \equiv A \rightarrow B$ type.
- (c) If $t = (a, b)$, then $\Gamma \vdash a \Leftarrow A$, $\Gamma \vdash b \Leftarrow B$ and $\Gamma \vdash T \equiv A \times B$ type.
- (d) If $t = ab$, then $\Gamma \vdash a \Leftarrow A \rightarrow T$ and $\Gamma \vdash b \Leftarrow A$ for some type A .
- (e) If $t = *$, then $\Gamma \vdash T \equiv \mathbf{1}$ type.
- (f) If $t = \text{fst}$, then $\Gamma \vdash T \equiv A \times B \rightarrow A$ for some types A and B .
- (g) If $t = \text{snd}$, then $\Gamma \vdash T \equiv A \times B \rightarrow B$ for some types A and B .

Proof. We argue for each case:

- (a) Observe that there is only one rule, namely (switch), which has the conclusion $\Gamma \vdash x \Leftarrow T$, hence it must be the case that $\Gamma \vdash x \Rightarrow T$. Next observe that there is one rule, namely (var), whose conclusion has a variable. This leads to the necessary assumption of $(x : T) \in \Gamma$. We note that it could be the case that $(x : T') \in \Gamma$ for some other type T' , in which case whilst switching we need further assume that $\Gamma \vdash T \equiv T'$ type.
- (b) As before we must (switch), whilst doing so we notice that $\Gamma \vdash \lambda x.y \Rightarrow T'$ only occurs in the conclusion of (\rightarrow -intro) which tells us that $T' = A \rightarrow B$ for some types A and B . Thus whilst switching we must also assume $\Gamma \vdash T \equiv A \rightarrow B$ type. And of course, we must assume the hypothesis of (\rightarrow -intro) which is $\Gamma, x : A \vdash y \Leftarrow B$.
- (c) Similarly (a, b) only occurs in (\times -intro) hence we must switch with the hypothesis that $\Gamma \vdash T \equiv A \times B$ for some types A and B . Then the hypothesis of (\times -intro) says it must be the case that both $\Gamma \vdash a \Leftarrow A$ and $\Gamma \vdash b \Leftarrow B$ hold.
- (d) To derive $\Gamma \vdash ab \Leftarrow T$ we switch with reflexivity (cswitch) to get $\Gamma \vdash ab \Rightarrow T$ and noticing that applications appear only in (\rightarrow -elim), (\times -elim₁) or (\times -elim₂). For the first notice that we would need to assume the existence of a type A such that $\Gamma \vdash a \Leftarrow A \rightarrow T$ and $\Gamma \vdash b \Leftarrow A$. For the later two, notice that the same occurs but for some type $A \times T$ or $T \times A$ for some type A instead.
- (e) The only way to derive $\Gamma \vdash * \Leftarrow T$ is by (switch) under the assumption that $\Gamma \vdash T \equiv \mathbf{1}$ type. This can be observed since ($\mathbf{1}$ -intro) is the only rule to mention $*$ in the conclusion.
- (f) Consider the rule (\times -elim₁), notice if we start by assuming the conclusion $\Gamma \vdash \text{fst}(t) \Rightarrow A$ we could also derive it through (\rightarrow -elim), leading to $\Gamma \text{fst} \Leftarrow A \times B \rightarrow A$ and $\Gamma \vdash t \Leftarrow A \times B$. For this to be consistent with (\times -elim₁) we see that it must always therefore be the case that $\Gamma \text{fst} \Leftarrow A \times B \rightarrow A$ for some A and B .
- (g) Same argument as before but adapted to snd.

□

Remark 4.5.2. Note that we only considered *inadmissible* rules.

4.6 Type checking

There are several natural problems that occur in a typed system [1]:

Firstly there are the problems of checking whether a given judgement is true:

Definition 4.6.1. Type checking is the problem of determining the truth of a statement $\Gamma \vdash a \Leftarrow A$.

Remark 4.6.2. We do not consider $\Gamma \vdash a \Rightarrow A$ since this will always be given by a (switch).

We would ideally wish for there to be an algorithm that will determine the truth of such a statement. Such an algorithm would render the problem of type checking in the STLC *decidable*.

Theorem 4.6.3. There is an algorithm that can decide the truth of the statement $\Gamma \vdash a \Leftarrow A$ in STLC.

Proof. We will not prove the full statement since this will require us to induct over syntax. We instead note some observations and sketch how such an algorithm may function. For demonstrations see Examples 6.10.1, 6.7.1, 6.8.1. We notice that the inversion lemmas 4.5.1 give us strong conditions on what a derivation tree ought to look like. In fact if we can contradict the inversion lemmas we will be able to decide that $\Gamma \vdash a \Leftarrow A$ is false. The only typing hypotheses we would have are those that arise from elimination rules such as (\rightarrow -elim), (\times -elim₁) and (\times -elim₂). Everything else is exactly how the inversion lemmas state. If the inversion lemma says that $\Gamma \vdash T \equiv A \times B$ then this would need to hold by reflexivity. □

Perhaps a more common, and practical problem is that of *type inference*. Given a desired statement $\Gamma \vdash a \vdash \boxed{?}$, how can we *infer* the missing type? This is a more difficult problem than type checking since we not only have to type check, but we have to constantly build up our type that we are checking against. In order to do this, we need a solid understanding of judgemental equality of types and which statements are not allowed.

Theorem 4.6.4. There is an algorithm that can deduce a type for the statement $\Gamma \vdash a \Leftarrow \boxed{?}$ to hold, or deduce that the term is untypable.

Proof. As before, we give only a sketch. For demonstrations see Examples 6.1.1, 6.2.1, 6.3.1, 6.4.1. Instead of using (cswitch) we will use (switch). This means we will have to provide it with some sort of judgemental equality of types. We make an educated guess for this by looking at the syntax of the term. If it is a lambda term, then it is only possible to choose a function type, if it is a pair, then a product type etc. Finally we will eventually accumulate many assumptions about types. The trick now is to see if these

equations are trivial. If we instead get a non-trivial typing equation such as $A \equiv A \rightarrow B$, we say that the term cannot be typed. Otherwise, we can substitute back through and get the type we started with. The reason we disallow $A \equiv A \rightarrow B$ is that there is no way to get such an equality at the level of syntax. In that sense it is non-trivial. \square

And finally the problem of determining a judgement such as $\Gamma \vdash a \equiv b : A$. We can use a property of our type theory called *canonicity*, this says that any term of a type, when reduced into $\beta\eta$ -normal form (see Definition 5.8.1), will only be constructed from constructors associated to that type. We cannot invest too much attention on this detail, as it is a very subtle property, not to mention, very essential for any programming language.

If for example, a term was found to have type \mathbb{N} (see Definition 7.2.1). We would expect it to be of the form 0 or $s(n)$ of some $n : \mathbb{N}$. This is not obvious, especially when terms that don't compute are included. For examples of terms that don't compute simply pick a type, and drop the computation rules. Observe that reduction will get stuck on these terms.

How this relates to equality of terms is as follows.

Theorem 4.6.5. There is an algorithm that can decide the truth of $\Gamma \vdash a \equiv b : A$.

Proof. By Canonicity, every term has a canonical form. Simply $\beta\eta$ -reducing both sides should yield to a reflexive derivation, if the two are equal. \square

Remark 4.6.6. See Examples 6.9.1 and 6.11.1 for a demonstration.

5 Normalisation of STLC

5.1 Introduction

We now wish to analyse the computational power of our type theory. When designing the type checking algorithm we made a point not to invoke any computational rules, since we want to be able to spot a correct program without running it. This is an issue later on where we see *untyped* terms may not *normalise*.

Computational rules, are our basic steps of computation. In the late 1930s, Alan Turing had a model of what it meant to be *effectively calculable*, now known as a Turing Machine [52]. Critically he included an appendix which outlined how Church's untyped lambda calculus was equivalent to his notion of effective calculability. We will discuss the historical nature of this further in chapter 8.2.

One important question in computer science is knowing whether or not a computation will halt, known as the *Halting problem*. It can in fact be shown that Turing machines, and by extension untyped lambda calculus, cannot decide their own halting problem. This stems from the fact that these gadgets are “*too good*” at computation. It is closely related to Gödel's analysis of the power of arithmetic [22, 23].

The main goal of this chapter will be to show that the STLC, defined in the previous chapter, has computations that *always* terminate. This is known as *strong normalisation*. This immediately highlights some of the weaknesses of the STLC, however we will later discuss what is missing and how this can be fixed. The technical term for this is that

STLC is *not* Turing-complete. \square We will also see that there are *untyped* lambda terms that cannot be *typed*.

It can be observed that there is not a unique way to compute something, i.e. run the program. What is important is that the result is unique. Such a property is known as the Church-Rosser property. We will show that Church-Rosser property holds for β -, η - and $\beta\eta$ -reductions.

Guiding references for this chapter are [46] and [1].

5.2 Well-founded relations

The notion of well-founded induction is a standard theorem of set theory. The classical proof of which usually uses the law of excluded middle [28, p. 62], [3, Ch. 7]. Its use in the formal semantics of programming languages is not much different either [53, Ch. 3]. There are however more constructive notions of well-foundedness [44, §8] with more careful use of excluded middle. We will follow [50], as this is the simplest to understand, and we won't be using this material much other than an initial justification for induction in classical mathematics.

Definition 5.2.1. Let X be a set and \prec a binary relation on X . A subset $Y \subseteq X$ is called **\prec -inductive** if

$$\forall x \in X, \quad (\forall y \prec x, y \in Y) \Rightarrow x \in Y.$$

Definition 5.2.2. The relation \prec is **well-founded** if the only \prec -inductive subset of X is X itself. A set X equipped with a well-founded relation is called a *well-founded set*.

Theorem 5.2.3 (Well-founded induction). Let X be a well-founded set and P a property of the elements of X (a proposition). Then

$$\forall x \in X, P(x) \quad \Longleftrightarrow \quad \forall x \in X, \quad (\forall y \prec x, P(y)) \Rightarrow P(x).$$

Proof. The forward direction is clearly true. For the converse, assume $\forall x \in X, ((\forall y \prec x, P(y)) \Rightarrow P(x))$. Note that $P(y) \Leftrightarrow x \in Y := \{x \in X \mid P(x)\}$ which means our assumption is equivalent to $\forall x \in X, (\forall y \prec x, y \in Y) \Rightarrow x \in Y$ which means Y is \prec -inductive by definition. Hence by 5.2.2 $Y = X$ giving us $\forall x \in X, P(x)$. \square

5.3 Properties of relations

First we define what we mean by a binary relation being *compatible* with the syntax of the STLC.

Definition 5.3.1. A binary relation \succ on Term, the set of all terms, is said to be *compatible with the syntax of STLC* (or just simply *compatible*) if the following conditions hold:

1. If $M \succ N$ then $\lambda x.M \succ \lambda x.N$.
2. If $M \succ N$ then $MZ \succ NZ$.
3. If $M \succ N$ then $ZM \succ ZN$.
4. If $M \succ N$ then $(Z, M) \succ (Z, N)$.
5. If $M \succ N$ then $(M, Z) \succ (N, Z)$.

Remark 5.3.2. The notion of compatibility allows us to make sure a relation also considers sub-terms. This is a tricky thing to get right but due to our focus on the correct structure of syntax we are fine.

Remark 5.3.3. The reader may ask what relations have to do with normalisation, but it is a formalism that we have chosen. This is definitely not the only way to prove properties like Church-Rosser. The main reason we have chosen this method is for its simplicity. In fact earlier we discussed the dynamics of languages, this is exactly that. There are many ways to go about dynamics including transition systems and equational dynamics. Our approach corresponds to the more classical and simple transition systems approach. It can be shown that this is equivalent to equational dynamics in that a reduction step will be justified by application of rules from STLC. Uses of relations like this are more generally known as *abstract rewriting systems* [2, 1].

We will demonstrate our last remark by considering the following relation:

Definition 5.3.4. Let \sim_{ty} denote the relation among terms of *having the same type*. Suppose $\Gamma \vdash s \Leftarrow S$ and $\Gamma \vdash t \Leftarrow T$, then:

$$s \sim_{\text{ty}} t \iff \Gamma \vdash S \equiv T \text{ type}$$

Lemma 5.3.5. The relation \sim_{ty} is a compatible relation.

Proof. Suppose $M \sim_{\text{ty}} N$, then we have $\Gamma \vdash M \Leftarrow S$, $\Gamma \vdash N \Leftarrow T$ and $\Gamma \vdash S \equiv T \text{ type}$. Observe that for (1) applications of (wkg) and (\equiv_{term} -refl), followed by ($\rightarrow \equiv_{\text{term}}$ -cong) gives the desired result. Conditions (2) and (3) are then simply (\rightarrow -elim-cong) by the same argument. And finally (4) and (5) are (\times -term-cong). Observe that all desired derivation trees can be constructed. \square

Definition 5.3.6. Given a relation \succ on a set X , we denote by \succ^+ the *transitive closure* of \succ . This is the smallest relation which coincides with \succ and is transitive. We also consider the *reflexive-transitive closure* \succ^* of \succ which is simply the relation $\Delta(X) \cup \succ^+$ where $\Delta(X)$ is the image of the diagonal function $x \mapsto (x, x)$. (We've simply added that $x \succ^* x$)

Remark 5.3.7. Transitive closures correspond to chains of the relation, and reflexive-transitive closures allow for chains of length 0. It should also be noted that we took the *union* of a relation. This is a well-defined notion and can easily be seen to be a relation.

Let \rightarrow be a binary relation on a set A , \rightarrow^+ be its transitive closure and \twoheadrightarrow be its reflexive-transitive closure.

5.4 Normalising relations

Now we define (very generally) what it means for an element of a set to be in *normal form* and *normalising* with respect to some relation.

Definition 5.4.1. An element $a \in A$ is said to be of *normal form* if $\forall b \in A, a \not\rightarrow b$.

Definition 5.4.2. An element $a \in A$ is said to be *normalising* (or *weakly normalising*) if there is a reduction sequence $a \rightarrow a_1 \rightarrow a_2 \rightarrow \cdots \rightarrow a_n$ where a_n is in normal form, for some n . We call a_n a *normal form* or *reduct* of a .

Remark 5.4.3. Note that not every reduction sequence is guaranteed to be finite. We also note that if \rightarrow a relation is Church-Rosser (to be defined below) then a_n is *the* normal form or reduct.

We discuss what it means for a relation to be Church-Rosser:

Definition 5.4.4. A relation \rightarrow has the *Church-Rosser* (CR) property if and only if for all $a, b, c \in A$ such that $a \rightarrow b$ and $a \rightarrow c$, there exists $d \in A$ with $b \twoheadrightarrow d$ and $c \twoheadrightarrow d$.

Remark 5.4.5. This says no matter what path we take along a relation, there will always be elements at which the paths cross.

We will also need a slightly weaker version called weak Church-Rosser, for reasons we will see later:

Definition 5.4.6. A relation \rightarrow has the *weak Church-Rosser* (WCR) property if and only if for all $a, b, c \in A$ such that $a \rightarrow b$ and $a \rightarrow c$, there exists $d \in A$ with $b \twoheadrightarrow d$ and $c \twoheadrightarrow d$.

We now state the obvious:

Corollary 5.4.7. If \rightarrow is CR then \rightarrow is WCR.

Proof. Observe that WCR is a special case of CR. □

The converse to this is in general *false* but it is true when another condition holds, namely that \rightarrow is *strongly normalising*.

Definition 5.4.8. A binary relation \rightarrow is *strongly normalising* (SN) if and only if there is no infinite sequence $a_0 \rightarrow a_1 \rightarrow a_2 \rightarrow \dots$.

Remark 5.4.9. In other words, a relation \rightarrow is strongly normalising if and only if *every* sequence $a_0 \rightarrow a_1 \rightarrow a_2 \rightarrow \dots$ terminates after a finite number of steps.

Remark 5.4.10. We typically also say an element is strongly normalising if the condition holds for that element. This allows us to state SN in a different (and perhaps more correct) way: A relation \rightarrow is strongly normalising if each element is strongly normalising with respect to \rightarrow . Then we can define an element to be strongly normalising if all of its reducts are strongly normalising. The nice thing about this definition is that we have seen it before, this is precisely what it means to be a *well-founded relation* from Definition 5.2.2. So \rightarrow is strongly normalising if and only if it is well-founded. This is good because we can induct over it!

Corollary 5.4.11. If a relation \rightarrow is strongly normalising then every element is normalising.

Proof. By induction on \rightarrow we see that either an element is in normal form, or it reduces to normal form. This is precisely what it means to be normalising. \square

5.5 Newman's lemma

We now state a lemma which will be very useful. It is a sufficient condition for the converse of Corollary 5.4.7 to hold.

Lemma 5.5.1 (Newman's Lemma). If \rightarrow is strongly normalising and WCR then it is CR.

Proof. Since \rightarrow is strongly normalising, any $a \in A$ has a normal form. Call an element *ambiguous* if a reduces to two distinct normal forms. Clearly \rightarrow is CR if there are no ambiguous elements of A . Assume, for contradiction, that there is an ambiguous a . We will show that there is another ambiguous a' where $a \rightarrow a'$. Suppose we have $a \rightarrow b_1$ and $a \rightarrow b_2$ where b_1 and b_2 are two different normal forms. Both reductions must make at least one step, thus both reductions can be written as $a \rightarrow a_1 \rightarrow b_1$ and $a \rightarrow a_2 \rightarrow b_2$. Suppose $a_1 = a_2$ then we can choose $a' = a_1 = a_2$. Now suppose $a_1 \neq a_2$, we know by WCR that $a_1 \rightarrow b_3$ and $a_2 \rightarrow b_3$ for some b_3 . We can assume that b_3 is a normal form. Since b_1 and b_2 are distinct, b_3 is different from b_1 or b_2 so we can choose $a' = a_1$ or $a' = a_2$. Since we can always choose an a' , we can repeat this process and get an infinite chain of ambiguous elements. It is clear that this contradicts strongly normalising, hence A has no ambiguous elements. \square

Remark 5.5.2. Newman's lemma dates from 1942. A special case of it was known to Thue as early as 1910 [47].

5.6 β -reduction

Now we define what we mean by β -reduction and β -normal form.

Definition 5.6.1. We define β -reduction to be the least compatible relation \rightarrow_β on Term satisfying the following conditions:

1. $(\lambda x.y)t \rightarrow_\beta y[t/x]$
2. $\text{fst}(x, y) \rightarrow_\beta x$
3. $\text{snd}(x, y) \rightarrow_\beta y$

A term on the left hand side of any of the above is called a β -redex (reducible expression) and the right hand sides are said to *arise by contracting the redex*.

Remark 5.6.2. Observe that these are very similar to our β rules, in fact they are exactly those. So the question may arise: why haven't we defined β -reduction using the rules that we already have? The answer is that we could but we would have a much harder time, the rules also take into account typing information but we are explicitly not worried about that since we will show later β -reduction doesn't change a typed terms type. It is somewhat simpler and clearer to focus purely on terms. We will later justify calling this β -reduction. Such dynamics falls under what is known as *equational dynamics*. This would require us to have a suitable way of dealing with judgemental equality, which we feel would obstruct the inner workings of the result.

Definition 5.6.3. A term M is said to be in β -normal form if it is in normal form with respect to \rightarrow_β .

Remark 5.6.4. That is to say a term is in β -normal form if there is no β -reduction to any other term. Or better yet, M does not contain a β -redex.

Definition 5.6.5. Let \twoheadrightarrow_β be the transitive, reflexive closure of \rightarrow_β called a *multi-step β -reduction*.

Remark 5.6.6. Not every term is normalising. Take for example the term $\Omega = (\lambda x.xx)(\lambda x.xx)$ which cannot be typed as we will see later. There is an infinite reduction sequence:

$$\Omega \rightarrow_\beta \Omega \rightarrow_\beta \Omega \rightarrow_\beta \Omega \rightarrow_\beta \dots$$

Since Ω cannot be given a type, it is deemed *ill-typed*.

This means we have to be careful which terms we are talking about. When talking about terms of the STLC we should add that we expect them to be well-typed (derivable). We will see later there are many syntactically valid terms that are ill-typed.

We want to now prove that every derivable term is β -normalising. In order to do this we need to keep track of available redexes and bound them. We will then show there is a reduction strategy that decreases this bound yielding our result.

This proof is usually attributed to an unpublished note of Turing but it has been rediscovered by various authors. We will follow the proof in Girard's book [21].

Definition 5.6.7. The *degree* $\partial(T)$ of a type T is defined by:

- $\partial(T) := 1$ if T is atomic.
- $\partial(U \times V), \partial(U \rightarrow V) := \max(\partial(U), \partial(V)) + 1$.

Definition 5.6.8. The (β) -degree $\partial_\beta(t)$ of a redex is defined by:

- $\partial_\beta(\text{fst}(u, v)), \partial_\beta(\text{snd}(u, v)) := \partial(U \times V)$ where $\Gamma \vdash (u, v) \Leftarrow U \times V$.
- $\partial_\beta((\lambda x.v)u) := \partial(U \rightarrow V)$ where $\Gamma \vdash \lambda x.v \Leftarrow U \rightarrow V$.

Definition 5.6.9. The (β) -degree $d_\beta(t)$ of a term is the maximum of the degrees of its redexes:

$$d_\beta(t) := \max\{\partial_\beta(s) \mid s \text{ is a redex in } t\}$$

Remark 5.6.10. A redex is associated to two degrees, one as a redex and another as a term. Since a redex r may contain other redexes we have that $\partial(r) \leq d(r)$. It should be noted we have defined degree to mean 3 different things here, but as long as we are careful we should not get confused.

Lemma 5.6.11. If r is a redex of type T then $\partial(T) < \partial_\beta(r)$.

Proof. Checking the cases for r :

- $\partial(T) < \partial_\beta(\text{fst}(t, u)) = \max(\partial(T), \partial(U)) + 1$.
- $\partial(T) < \partial_\beta(\text{snd}(u, t)) = \max(\partial(U), \partial(T)) + 1$.
- $\partial(T) < \partial_\beta((\lambda x.t)u) = \max(\partial(U), \partial(T)) + 1$.

□

Lemma 5.6.12. If $\Gamma, x : T \vdash t \Leftarrow U$ then $d_\beta(t[u/x]) \leq \max(d_\beta(t), d_\beta(u), \partial(T))$.

Proof. Analysing the redexes of $t[u/x]$ we find that they fall into the following cases:

- They are redexes of t (in which u has become x).
- They are redexes of u , proliferating due to each occurrence of x in t .
- They are formed when t is of the form $\text{fst}(x)$, $\text{snd}(x)$, or xv for u of the form (u', u'') , (u', u'') , or $\lambda y.u'$ respectively. These new redexes have degree $\partial(T)$.

□

Lemma 5.6.13. If $t \rightarrow_\beta u$ then $d_\beta(u) \leq d_\beta(t)$.

Proof. Consider the reduction where u is obtained from t by replacing the redex r in u by c . Now we consider all the redexes of u where we find:

- redexes which were originally in t , but not in r , and have been modified by the replacement of r by c . Observe that their degree does not change.
- redexes which were originally in c . But c is obtained by reducing r , or in other words a substitution in r . Notice $(\lambda x.s)s'$ becomes $s[s'/x]$ and Lemma 5.6.12 tells us that $d_\beta(c) \leq \max(d_\beta(s), d_\beta(s'), \partial(T))$, where T is the type of x . But by Lemma 5.6.11 we have $\partial(T) \leq \partial(r)$. Applying max gives us $\max(d(s), d(s'), \partial(T)) \leq \max(d_\beta(s), d_\beta(s'), \partial_\beta(r))$ and hence $d_\beta(c) \leq \max(d_\beta(s), d_\beta(s'), \partial(r)) = d(r)$.
- redexes which come from replacing r by c . These redexes have degree equal to $\partial(T)$ where T is the type of r . By Lemma 5.6.11 we have $\partial(T) \leq \partial(r)$.

□

Next we will prove a lemma bounding the number of redexes of a certain degree.

Lemma 5.6.14. Let r be a redex of maximal degree n in t , and suppose that all redexes strictly contained in r have degree less than n . If u is obtained from t by reducing r to c . Then u has strictly fewer redexes of degree n .

Proof. When the reduction happens we make the following observations:

- The redexes outside r in t remain u .
- The redexes strictly inside r are in general conserved but sometimes become more prolific. Take for example $(\lambda x.(x, x))s \rightarrow_\beta (s, s)$. The number of redexes in the reduct are double that of redex on the left. However the degree of the proliferated redexes must be strictly less than n .
- The redex r is destroyed and possibly replaced by redexes of strictly smaller degree.

□

Remark 5.6.15. Although not defined, we take the meaning of a *redex strictly inside* to be a redex that is not the whole redex.

We now have all the machinery needed to prove that typed terms in the STLC are strongly β -normalising.

Theorem 5.6.16. Every derivable term $\Gamma \vdash t \Leftarrow A$ in the STLC is strongly β -normalising.

Proof. Consider the function $\mu : \mathbf{Term} \rightarrow \mathbb{N} \times \mathbb{N}$ which takes $t \mapsto (n, m)$ where $n = d_\beta(t)$ and m is the number of redexes in t of degree n . By Lemma 5.6.14 it is possible to choose a redex r of t in such a way that, after reduction of r to c , the reduct t' satisfies $\mu(t') < \mu(t)$. Thus by double induction on n and m it is possible to see that $\mu(t)$ can always be decreased until t is normal. □

Remark 5.6.17. The ordering in $\mu(t') < \mu(t)$ on $\mathbb{N} \times \mathbb{N}$ is the lexicographic ordering. Meaning $(n', m') < (n, m)$ if and only if $n' < n$ or $n' = n$ and $m' < m$. (Think Alphabetical order).

Remark 5.6.18. Since we have decreasing sequences of natural numbers we must have a finite number of reductions in *any* reduction sequence. Of course we have weakly normalising too.

Lemma 5.6.19. Suppose $\Gamma \vdash M \Leftarrow T$ and $M \rightarrow_\beta N$, then $\Gamma \vdash M \equiv N : T$.

Proof. We will only sketch the proof here. It will require inducting over syntax and the definition of \rightarrow_β . The main part to notice is that as \rightarrow_β is a compatible relation, we can destruct the syntax down and isolate a redex. Then using $(\rightarrow\text{-}\beta)$, $(\times\text{-}\beta_1)$ and $(\times\text{-}\beta_2)$ we can combine their results with congruence rules to build the term back up. It will be a technically finicky proof. \square

Remark 5.6.20. Although we haven't checked Lemma 5.6.19, it would be extremely surprising if it were false. So we have a strong feeling that it ought to be true.

We now wish to prove that \rightarrow_β is weakly Church-Rosser. First we take some results from Takahashi [48, 49], who considers *parallel reductions*. This is a stronger relation than \rightarrow_β and weaker than \twoheadrightarrow_β . This might not seem like much but, parallel (β -)reduction, denoted \Rightarrow_β (not to be confused with our typing judgements), satisfies the diamond in Church-Rosser. And since \twoheadrightarrow_β is the transitive closure of \Rightarrow_β , it too satisfies the diamond in Church-Rosser hence \rightarrow_β has the Church-Rosser property. We will formalise this argument as follows and consider β , η and $\beta\eta$ reductions along the way.

Definition 5.6.21. *Parallel β -reduction*, \Rightarrow_β , is defined inductively on terms by the following rules:

1. $x \Rightarrow_\beta x$ for a variable or constant x .
2. $\lambda x.M \Rightarrow_\beta \lambda x.M'$ if $M \Rightarrow_\beta M'$.
3. $MN \Rightarrow_\beta M'N'$ if $M \Rightarrow_\beta M'$ and $N \Rightarrow_\beta N'$.
4. $(M, N) \Rightarrow_\beta (M', N')$ if $M \Rightarrow_\beta M'$ and $N \Rightarrow_\beta N'$.
5. $(\lambda x.M)N \Rightarrow_\beta M'[N'/x]$ if $M \Rightarrow_\beta M'$ and $N \Rightarrow_\beta N'$.
6. $\text{fst}(M, N) \Rightarrow_\beta M'$ if $M \Rightarrow_\beta M'$.
7. $\text{snd}(M, N) \Rightarrow_\beta N'$ if $N \Rightarrow_\beta N'$.

Remark 5.6.22. If we expand the definition of compatible in the definition of \rightarrow_β it may appear to be identical to the definition of \Rightarrow_β . The key difference is the direction in which we are building up the terms. In the above definition we are breaking down the syntax and making sure that *all* components also satisfy the relation. We will see later the relation with \rightarrow_β .

Remark 5.6.23. The name comes from the fact that parallel reduction can reduce many β -redexes at once, unlike usual reduction.

Corollary 5.6.24. The relation \Rightarrow_β is reflexive.

Proof. Observe that ignoring the last three rules in the definition of \Rightarrow_β we still cover all the syntax. \square

The following lemma shows the strengths of our notions of β -reduction. It will be very useful later on.

Lemma 5.6.25. We have the following implications:

$$M \rightarrow_\beta M' \implies M \Rightarrow_\beta M' \implies M \twoheadrightarrow_\beta M'$$

Proof. For the first implication, observe that a redex in M is being contracted to such that $M \rightarrow_\beta M'$. We can also contract the redex in the definition of $M \Rightarrow_\beta M'$ by choosing the correct rule. For the second implication, proceed by induction on M :

- If $M = x \Rightarrow_\beta M'$ then clearly $M' = x$ hence $x \twoheadrightarrow x$.
- If $M = \lambda x.N$ then $M' = \lambda x.N'$ where $N \Rightarrow_\beta N'$, which by the induction hypothesis gives us $N \twoheadrightarrow_\beta N'$, and since \twoheadrightarrow_β is the transitive, reflexive closure of a compatible relation, we have $M \twoheadrightarrow_\beta M'$.
- If $M = (a, b)$, then by induction hypothesis and \twoheadrightarrow_β being compatible we have $M \twoheadrightarrow_\beta M'$.
- Finally for the case that M is a β -redex, observe that \twoheadrightarrow_β can reduce this redex, and by the induction hypothesis and subredexes of that.

\square

Remark 5.6.26. The previous proof may be considered as a sketch since we didn't explicitly check every case. This can definitely be done but it is not so interesting.

We can now discuss *the complete (β -)development of a term*. This is a way of completely reducing down *all* β -redexes at once.

Definition 5.6.27. The *complete (β -)development* of a term $\Gamma \vdash t \Leftarrow A$, written t^* is defined by induction on syntax:

- For a variable or constant $x^* = x$.
- $(\lambda x.M)^* = \lambda x.M^*$.
- $(MN)^* = M^*N^*$ if MN is not a β -redex.
- $(a, b)^* = (a^*, b^*)$.
- $((\lambda x.M)N)^* = M^*[N^*/x]$.
- $(\text{fst}(a, b))^* = a^*$.
- $(\text{snd}(a, b))^* = b^*$.

Lemma 5.6.28. Given a term $\Gamma \vdash t \Leftarrow A$, t^* is in β -normal form.

Proof. Observe by induction that the complete development rids a term of *all* β -redexes. \square

Here is a technical lemma that is the driving force behind our proof of being Church-Rosser. It says that the complete development is always the most reduced form of a term.

Lemma 5.6.29. Suppose $M \Rightarrow_\beta N$ then $N \Rightarrow_\beta M^*$.

Proof. We proceed by induction on $M \Rightarrow_\beta N$:

- Suppose $M = x$ then $M = x \Rightarrow_\beta x = N$. Hence $N = x \Rightarrow_\beta x^* = M^*$.
- Suppose $M = \lambda x.t \Rightarrow_\beta \lambda x.t'$. Then $t \Rightarrow_\beta t'$ and $t' \Rightarrow_\beta t^*$ by the induction hypothesis, hence $N = \lambda x.t' \Rightarrow_\beta \lambda x.t^* = (\lambda x.t)^* = M^*$.
- Suppose $M = ab$ and M is not a β -redex, then $M = ab \Rightarrow_\beta a'b' = N$, with $a \Rightarrow_\beta a'$ and $b \Rightarrow_\beta b'$. Then by the induction hypotheses, we have $a' \Rightarrow_\beta a^*$ and $b' \Rightarrow_\beta b^*$, yielding $a'b' \Rightarrow_\beta a^*b^* = (ab)^* = M^*$, since M is not a β -redex.
- Suppose $M = (a, b) \Rightarrow_\beta (a', b')$ where $a \Rightarrow_\beta a'$ and $b \Rightarrow_\beta b'$. Then by the induction hypotheses we have $a' \Rightarrow_\beta a^*$ and $b' \Rightarrow_\beta b^*$. Hence $N = (a', b') \Rightarrow_\beta (a^*, b^*) = (a, b)^* = M^*$.
- Suppose $M = (\lambda x.y)t \Rightarrow_\beta y'[t'/x]$ with $y \Rightarrow_\beta y'$ and $t \Rightarrow_\beta t'$. By our induction hypotheses: $y' \Rightarrow_\beta y^*$ and $t' \Rightarrow_\beta t^*$. It can be shown by induction on the syntax of y' that $y'[t'/x] \Rightarrow_\beta y^*[t^*/x]$ however the proof would get too long. Assuming this we have $y'[t'/x] \Rightarrow_\beta y^*[t^*/x] = (y[t/x])^*$, again by induction on y and t , and again we omit since it would lengthen the proof substantially, finally giving us $N \Rightarrow_\beta M^*$.
- Finally suppose $M = \text{fst}(a, b) \Rightarrow_\beta a'$ where $a \Rightarrow_\beta a'$, by our induction hypothesis, $a' \Rightarrow_\beta a^*$ so $N = a' \Rightarrow_\beta a^* = (\text{fst}(a, b))^* = M^*$.
- The case for snd is very similar to the case for fst .

\square

Now we show that \Rightarrow_β satisfies a diamond property.

Corollary 5.6.30. Given $M \Rightarrow_\beta N_1$ and $M \Rightarrow_\beta N_2$ then $N_1 \Rightarrow_\beta M'$ and $N_2 \Rightarrow_\beta M'$ for some M' .

Proof. By Lemma 5.6.29 we observe that $M' = M^*$ gives us the desired result. \square

We now have all we need to prove our desired result.

Lemma 5.6.31. β -reduction is weakly Church-Rosser.

Proof. Given $a \rightarrow_\beta b$ and $a \rightarrow_\beta b'$ we see that by Lemma 5.6.25, we have $a \Rightarrow_\beta b$ and $a \Rightarrow_\beta b'$. Hence by the diamond property of \Rightarrow_β (Corollary 5.6.30), we have $b \Rightarrow_\beta a'$ and $b' \Rightarrow_\beta a'$ for some a' . Which by Lemma 5.6.25 again, gives us $b \rightarrow_\beta a'$ and $b' \rightarrow_\beta a'$. \square

Theorem 5.6.32. β -reduction is Church-Rosser (on well-typed terms).

Proof. β -reduction is strongly normalising by Lemma 5.6.16 and weakly Church-Rosser by Lemma 5.6.31. Hence by Newman's Lemma (5.5.1) we have that β -reduction is Church-Rosser. \square

Remark 5.6.33. In [49, 2] it is stated that the diamond property of \Rightarrow_β (Lemma 5.6.30) directly implies that \rightarrow_β is Church-Rosser. We could not understand how this implication has come about, so we instead use Newman's lemma.

5.7 η -reduction

The proof of Church-Rosser for η -reduction will be simpler than that of β -reduction. This is because reduced η -redexes have comparably tame behaviour and don't product any new redexes.

Definition 5.7.1. We define η -reduction to be the least compatible relation \rightarrow_η on Term satisfying the following conditions:

1. $\lambda x.f x \rightarrow_\eta f$
2. $(\text{fst}(t), \text{snd}(t)) \rightarrow_\eta t$

Just like for β -reduction we have the notions of η -redex and terms that arise by contracting the redex.

Definition 5.7.2. A term is said to be in η -normal form if it is in normal form with respect to \rightarrow_η .

Definition 5.7.3. Let \rightarrow_η be the transitive, reflexive closure of \rightarrow_η called a *multi-step η -reduction*.

We will now show that \rightarrow_η is strongly normalising.

Remark 5.7.4. Originally we had thought to modify the proof of β -normalisation, and make it work for η . However, this is where the difference between the two is key. β -normalisation has the power to create new β -redexes whereas η -normalisation never does. In fact η -normalisation is strongly normalising even in the untyped lambda calculus. This suggests that talking about degrees is not the correct approach and there ought to be some other metric for which can be used to bound η -reducible terms. Based off of work in [19], the authors of [46, Ex. 3.21] define a *depth* function for terms. We believe this to be the actual depth of the underlying tree of the abstract binding tree of the syntax of the term. But that is not a relevant result for now.

Definition 5.7.5. Given a term t we define the *depth* $\delta(t)$ of t by induction on terms:

- $\delta(x) := 0$ for x a variable or constant.
- $\delta(ab) := 1 + \max(\delta(a), \delta(b))$.
- $\delta(\lambda x.y) := 1 + \delta(y)$.
- $\delta((a, b)) := 1 + \max(\delta(a), \delta(b))$.

Lemma 5.7.6. If $t \rightarrow_\eta u$ then $\delta(u) < \delta(t)$.

Proof. Observe that since \rightarrow_η is a compatible relation, we need only prove the statement for a redex. We do this by cases:

- $$\begin{aligned} \delta((\text{fst}(s), \text{snd}(s))) &= 1 + \max(\delta(\text{fst}(s)), \delta(\text{snd}(s))) \\ &= 1 + \max(1 + \delta(s), 1 + \delta(s)) \\ &= \delta(s) + 2 \end{aligned}$$
- $$\begin{aligned} \delta(\lambda x.sx) &= 1 + \delta(sx) \\ &= 2 + \max(\delta(s), \delta(x)) \\ &= \delta(s) + 2 \end{aligned}$$

Observe that in both cases we have that the depth of a redex s is $\delta(s) = \delta(r) + 2$ where r is the reduct of s . However at the level of terms we cannot guarantee equality due to the nature of depth and compatibility. \square

Lemma 5.7.7. η -reduction is strongly normalising.

Proof. By Lemma 5.7.6 we have that the depth of any η -reduction sequence is strictly decreasing. Hence there may only be finitely many steps in any given η -reduction sequence. \square

Lemma 5.7.8. Suppose $\Gamma \vdash M \Leftarrow T$ and $M \rightarrow_\eta N$, then $\Gamma \vdash M \equiv N : T$.

Proof. The proof ought to be similar to the sketch outlined in Lemma 5.6.19. \square

Now we define a notion of *parallel*

Definition 5.7.9. *Parallel η -reduction*, \Rightarrow_η , is defined inductively on terms by the following rules:

1. $x \Rightarrow_\eta x$ for a variable or constant x .
2. $\lambda x.M \Rightarrow_\eta \lambda x.M'$ if $M \Rightarrow_\eta M'$.
3. $MN \Rightarrow_\eta M'N'$ if $M \Rightarrow_\eta M'$ and $N \Rightarrow_\eta N'$.

4. $(M, N) \Rightarrow_\eta (M', N')$ if $M \Rightarrow_\eta M'$ and $N \Rightarrow_\eta N'$.
5. $\lambda x.Mx \Rightarrow_\eta M'$ if $M \Rightarrow_\eta M'$ and $x \notin \text{FV}(M)$.
6. $(\text{fst}(t), \text{snd}(t)) \Rightarrow_\eta t'$ if $t \Rightarrow_\eta t'$.

Remark 5.7.10. Notice the condition on $\lambda x.Mx$ we have to check that M is specifically not “in scope” of x . Since M on it’s own does not make sense otherwise.

Corollary 5.7.11. The relation \Rightarrow_η is reflexive.

Proof. Observe that ignoring the last two rules, still qualifies any term t to satisfy $t \Rightarrow_\eta t$. \square

Now we show the strength of \Rightarrow_η relative to the other two η -reduction relations.

Lemma 5.7.12. We have the following implications:

$$M \rightarrow_\eta M' \implies M \Rightarrow_\eta M' \implies M \twoheadrightarrow_\eta M'$$

Proof. This first implication is trivial. The second implication can be done by induction on M and the definition of $M \Rightarrow_\eta M'$. \square

Now we define a way of completely reducing all η -redexes of a term.

Definition 5.7.13. The *complete (η -)development* of a term t , written t^* is defined by induction on syntax:

- For a variable or constant $x^* = x$.
- $(\lambda x.M)^* = \lambda x.M^*$ if $\lambda x.M$ is not an η -redex.
- $(MN)^* = M^*N^*$.
- $(a, b)^* = (a^*, b^*)$ if (a, b) is not an η -redex.
- $(\lambda x.Mx)^* = M^*$ if $x \notin \text{FV}(M)$.
- $(\text{fst}(t), \text{snd}(t))^* = t^*$.

Remark 5.7.14. We have overloaded the notation t^* but since this section is only concerned with η -reduction this is fine.

Remark 5.7.15. Notice we have not mentioned any typing information about t . η -reduction is quite strong even without the presence of types.

Lemma 5.7.16. Given a term t , t^* is in η -normal form.

Proof. Observe by induction that the complete development rids a term of *all* η -redexes. \square

Now for the technical lemma that will give us Church-Rosser.

Lemma 5.7.17. Suppose $M \Rightarrow_\eta N$ then $N \Rightarrow_\eta M^*$.

Proof. Begin by induction on $M \Rightarrow_\eta N$:

- If $M = x$, then $x \Rightarrow_\eta N$ so $N = x \Rightarrow_\eta x = M^*$.
- If $M = \lambda x.t$ and M is not an η -redex, then $M \rightarrow_\eta \lambda x.t' = N$. By definition $t \Rightarrow_\eta t'$, and by the induction hypothesis $t' \Rightarrow_\eta t^*$. Hence $N = \lambda x.t' \Rightarrow_\eta \lambda x.t^* = (\lambda x.t)^*$ since $(\lambda x.t)$ is not an η -redex.
- If $M = ab \Rightarrow_\eta a'b' = N$. By definition $a \Rightarrow_\eta a'$ and $b \Rightarrow_\eta b'$. By the induction hypotheses $a' \Rightarrow_\eta a^*$ and $b' \Rightarrow_\eta b^*$. Hence $N = a'b' \Rightarrow_\eta a^*b^* = (ab)^* = M^*$.
- If $M = (a, b)$ and (a, b) is not an η -redex, then $M \rightarrow_\eta (a', b') = N$. By definition $a \Rightarrow_\eta a'$ and $b \Rightarrow_\eta b'$. By the induction hypotheses $a' \Rightarrow_\eta a^*$ and $b' \Rightarrow_\eta b^*$. Hence $N = (a', b') \Rightarrow_\eta (a^*, b^*) = (a, b)^* = M^*$ since (a, b) is not an η -redex.
- If $M = \lambda x.tx$ for $x \notin \text{FV}(t)$, then $M \rightarrow_\eta \lambda x.tx = N$. There are two cases for N :
 - If $N = t'$ for some $t \Rightarrow_\eta t'$ then $M^* = (t')^*$ and hence $N = t' \Rightarrow_\eta t^* = M^*$.
 - If $N = \lambda x.t'x$ for some $tx \Rightarrow_\eta t'x$ then our induction hypothesis gives $t'x \Rightarrow_\eta (tx)^* = t^*x$. Hence $t' \Rightarrow_\eta t^*$. Thus by definition we have $\lambda x.t'x \Rightarrow_\eta t^*$ since $t' \Rightarrow_\eta t^*$. The induction here is a bit tricky and would probably benefit with some clearer notation.
- Finally if $M = (\text{fst}(t), \text{snd}(t)) \Rightarrow_\eta N$ then we have two cases for N :
 - If $N = t'$ for some $t \Rightarrow_\eta t'$, then by the induction hypothesis $t' \Rightarrow_\eta t^* = (\text{fst}(t), \text{snd}(t))^* = M^*$.
 - If $N = ((\text{fst}(t'), \text{snd}(t')))$ for some $t \Rightarrow_\eta t'$, then by the induction hypothesis $t' \Rightarrow_\eta t^*$. Hence by definition we have $((\text{fst}(t'), \text{snd}(t'))) \Rightarrow_\eta t^*$ since $t' \Rightarrow_\eta t^*$.

□

Now we show that \Rightarrow_η satisfies a diamond property.

Corollary 5.7.18. Given $M \Rightarrow_\eta N_1$ and $M \Rightarrow_\eta N_2$ then $N_1 \Rightarrow_\eta M'$ and $N_2 \Rightarrow_\eta M'$ for some M' .

Proof. By Lemma 5.7.17 we observe that $M' = M^*$ gives us the desired result. □

We now have all we need to prove our desired result.

Lemma 5.7.19. η -reduction is weakly Church-Rosser.

Proof. Given $a \rightarrow_\eta b$ and $a \rightarrow_\eta b'$ we see that by Lemma 5.7.12, we have $a \Rightarrow_\eta b$ and $a \Rightarrow_\eta b'$. Hence by the diamond property of \Rightarrow_η (Corollary 5.7.18), we have $b \Rightarrow_\eta a'$ and $b' \Rightarrow_\eta a'$ for some a' . Which by Lemma 5.7.12 again, gives us $b \twoheadrightarrow_\eta a'$ and $b' \twoheadrightarrow_\eta a'$. □

Theorem 5.7.20. η -reduction is Church-Rosser.

Proof. η -reduction is strongly normalising by Lemma 5.7.7 and weakly Church-Rosser by Lemma 5.7.19. Hence by Newman's Lemma (5.5.1) we have that η -reduction is Church-Rosser. \square

Remark 5.7.21. Notice yet again how we at no point used the typing of terms for η .

Remark 5.7.22. η -reduction is typically seen as an easy case and it is not so common to see proofs written out explicitly for it. Lemma 5.7.17 for example is not such an easy proof to write or read. This is due to the iterated uses of induction. One way to make this easier to check is to use a proof assistant. This however would take some time to set up properly, and may risk diverging our attention.

5.8 $\beta\eta$ -reduction

We now begin the intricate business of mixing the two reductions, keeping note of how they interact, and finally showing that, used together, they satisfy Church-Rosser.

Definition 5.8.1. We define $\beta\eta$ -reduction, $\rightarrow_{\beta\eta}$ to be the union of the relations \rightarrow_{β} and \rightarrow_{η} .

Remark 5.8.2. Observe that $\rightarrow_{\beta\eta}$ is also a compatible relation.

Definition 5.8.3. We define $\twoheadrightarrow_{\beta\eta}$ as the transitive, reflexive closure of $\rightarrow_{\beta\eta}$.

Lemma 5.8.4. A term $\Gamma \vdash t \Leftarrow A$ has a β -normal form if and only if it has a $\beta\eta$ -normal form.

Proof. A similar proof can be found in [2, Corollary 15.1.5], this would of course have to be modified to accommodate for product types. The idea of the proof is to show that $M \twoheadrightarrow_{\beta\eta} N$ implies $M \twoheadrightarrow_{\beta} P \rightarrow_{\eta} N$ for some P . Then since η -reduction is strongly normalising, it must be the case that β -reduction is strongly normalising if and only if $\beta\eta$ -reduction is. \square

Corollary 5.8.5. $\beta\eta$ -reduction is strongly normalising on typed terms.

Proof. By Lemma 5.6.16 and Lemma 5.8.4. \square

Next we introduce parallel $\beta\eta$ -reduction.

Definition 5.8.6. Parallel $\beta\eta$ -reduction, $\Rightarrow_{\beta\eta}$, is defined inductively on terms by the following rules:

1. $x \Rightarrow_{\beta\eta} x$ for a variable or constant x .
2. $\lambda x.M \Rightarrow_{\beta\eta} \lambda x.M'$ if $M \Rightarrow_{\beta\eta} M'$.
3. $MN \Rightarrow_{\beta\eta} M'N'$ if $M \Rightarrow_{\beta\eta} M'$ and $N \Rightarrow_{\beta\eta} N'$.

4. $(M, N) \Rightarrow_{\beta\eta} (M', N')$ if $M \Rightarrow_{\beta\eta} M'$ and $N \Rightarrow_{\beta\eta} N'$.
5. $(\lambda x.M)N \Rightarrow_{\beta\eta} M'[N'/x]$ if $M \Rightarrow_{\beta\eta} M'$ and $N \Rightarrow_{\beta\eta} N'$.
6. $\text{fst}(M, N) \Rightarrow_{\beta\eta} M'$ if $M \Rightarrow_{\beta\eta} M'$.
7. $\text{snd}(M, N) \Rightarrow_{\beta\eta} N'$ if $N \Rightarrow_{\beta\eta} N'$.
8. $\lambda x.Mx \Rightarrow_{\beta\eta} M'$ if $M \Rightarrow_{\beta\eta} M'$ and $x \notin \text{FV}(M)$.
9. $(\text{fst}(t), \text{snd}(t)) \Rightarrow_{\beta\eta} t'$ if $t \Rightarrow_{\beta\eta} t'$.

Corollary 5.8.7. $\Rightarrow_{\beta\eta}$ is reflexive.

Proof. Observe that any term can be put through the definition of $\Rightarrow_{\beta\eta}$ even by ignoring the last five cases. \square

Next we give the technical lemma that will let us prove Church-Rosser.

Lemma 5.8.8. We have the following implications:

$$M \rightarrow_{\beta\eta} M' \implies M \Rightarrow_{\beta\eta} M' \implies M \twoheadrightarrow_{\beta\eta} M'$$

Proof. This first implication is trivial. The second implication can be done by induction on M and the definition of $M \Rightarrow_{\beta\eta} M'$. \square

Now we need a way of fully $\beta\eta$ -reducing a term.

Definition 5.8.9. The *complete $(\beta\eta)$ -development* of a term t , written t^* is defined by induction on syntax:

- For a variable or constant $x^* = x$.
- $(\lambda x.M)^* = \lambda x.M^*$ if $\lambda x.M$ is not an η -redex.
- $(MN)^* = M^*N^*$ if MN is not a β -redex.
- $(a, b)^* = (a^*, b^*)$ if (a, b) is not an η -redex.
- $((\lambda x.M)N)^* = M^*[N^*/x]$.
- $(\text{fst}(a, b))^* = a^*$.
- $(\text{snd}(a, b))^* = b^*$.
- $(\lambda x.Mx)^* = M^*$ if $x \notin \text{FV}(M)$.
- $(\text{fst}(t), \text{snd}(t))^* = t^*$.

Remark 5.8.10. We have yet again overridden the notation t^* . As before we keep the notion contained within the section to avoid any confusion.

Lemma 5.8.11. Given a term $\Gamma \vdash t \Leftarrow A$, t^* is in $\beta\eta$ -normal form.

Proof. Observe that any $\beta\eta$ -redexes will be reduced. This proof can be done by induction on syntax. The induction may have to go a bit deeper than just over term forms since we need to single out the cases for $\beta\eta$ -redexes. \square

Now we can prove our technical lemma that will give us Church-Rosser for $\beta\eta$.

Lemma 5.8.12. Suppose $M \Rightarrow_{\beta\eta} N$, then $N \Rightarrow_{\beta\eta} M^*$.

Proof. We begin by induction on $M \Rightarrow_{\beta\eta} N$:

- If $M = x \Rightarrow_{\beta\eta} x = N$, then $N = x \Rightarrow_{\beta\eta} x = x^* = M^*$.
- If $M = \lambda x.t$ is not an η -redex, then $M = \lambda x.t \Rightarrow_{\beta\eta} \lambda x.t'$ where $t \Rightarrow_{\beta\eta} t'$, then by the induction hypothesis, $t' \Rightarrow_{\beta\eta} t^*$, hence $\lambda x.t' \Rightarrow_{\beta\eta} \lambda x.t^* = (\lambda x.t)^* = M^*$ since t is not an η -redex.
- If $M = ab$ is not a β -redex, then $M = ab \Rightarrow_{\beta\eta} a'b'$ where $a \Rightarrow_{\beta\eta} a'$ and $b \Rightarrow_{\beta\eta} b'$. By our induction hypotheses we have $a' \Rightarrow_{\beta\eta} a^*$ and $b' \Rightarrow_{\beta\eta} b^*$, hence $a'b' \Rightarrow_{\beta\eta} a^*b^* = (ab)^* = M^*$ since ab is not a β -redex.
- If $M = (a, b)$ is not an η -redex, then $M = (a, b) \Rightarrow_{\beta\eta} (a', b')$ where $a \Rightarrow_{\beta\eta} a'$ and $b \Rightarrow_{\beta\eta} b'$. By our induction hypotheses we have $a' \Rightarrow_{\beta\eta} a^*$ and $b' \Rightarrow_{\beta\eta} b^*$, hence $(a', b') \Rightarrow_{\beta\eta} (a^*, b^*) = (a, b)^* = M^*$ since (a, b) is not an η -redex.
- If $M = (\lambda x.y)t \Rightarrow_{\beta\eta} N$, by induction on N :
 - If $N = y'[t'/x]$ where $y \Rightarrow_{\beta\eta} y'$ and $t \Rightarrow_{\beta\eta} t'$. By our induction hypotheses, we have $y' \Rightarrow_{\beta\eta} y^*$ and $t' \Rightarrow_{\beta\eta} t^*$. By induction on y' and t' it can be shown that $N = y'[t'/x] \Rightarrow_{\beta\eta} y^*[t^*/x] = ((\lambda x.y)t)^* = M^*$.
 - If $N = (\lambda x.y')t'$ where $y \Rightarrow_{\beta\eta} y'$ and $y \Rightarrow_{\beta\eta} t'$. By the our induction hypotheses, we have $y' \Rightarrow_{\beta\eta} y^*$ and $t' \Rightarrow_{\beta\eta} t^*$. Hence $N = (\lambda x.y')t' \Rightarrow_{\beta\eta} y^*[t^*/x] = ((\lambda x.M)t)^* = M^*$.
- If $M = \text{fst}(a, b) \Rightarrow_{\beta\eta} N$, by induction on N :
 - If $N = a'$ where $a \Rightarrow_{\beta\eta} a'$, then by our induction hypothesis, $a' \Rightarrow_{\beta\eta} a^*$, hence $N = a' \Rightarrow_{\beta\eta} a^* = (\text{fst}(a, b))^* = M^*$.
 - If $N = \text{fst}(a', b')$ where $a \Rightarrow_{\beta\eta} a'$ and $b \Rightarrow_{\beta\eta} b'$. Then $\text{fst}(a', b') \Rightarrow_{\beta\eta} a^* = (\text{fst}(a, b))^* = M^*$ since $a' \Rightarrow_{\beta\eta} a^*$ by our induction hypothesis.
- If $M = \text{snd}(a, b) \Rightarrow_{\beta\eta} N$, by induction on N :
 - If $N = b'$ where $b \Rightarrow_{\beta\eta} b'$, then by our induction hypothesis, $b' \Rightarrow_{\beta\eta} b^*$, hence $N = b' \Rightarrow_{\beta\eta} b^* = (\text{snd}(a, b))^* = M^*$.
 - If $N = \text{snd}(a', b')$ where $a \Rightarrow_{\beta\eta} a'$ and $b \Rightarrow_{\beta\eta} b'$. Then $N = \text{snd}(a', b') \Rightarrow_{\beta\eta} b^* = (\text{snd}(a, b))^* = M^*$ since $b' \Rightarrow_{\beta\eta} b^*$ by our induction hypothesis.
- If $M = \lambda x.tx$ where $x \notin \text{FV}(t)$ then $M \Rightarrow_{\beta\eta} N$. Induction over N :
 - If $N = t'$ where $t \Rightarrow_{\beta\eta} t'$, then by our induction hypothesis $t' \Rightarrow_{\beta\eta} t^* = (\lambda x.tx)^* = M^*$.

- If $N = \lambda x.t'x$ where $t \Rightarrow_{\beta\eta} t'$ and $x \notin \text{FV}(t')$. By our induction hypothesis $t' \Rightarrow_{\beta\eta} t^*$, hence $N = \lambda x.t'x \Rightarrow_{\beta\eta} t^* = (\lambda x.tx)^* = M^*$.
- If $M = (\text{fst}(t), \text{snd}(t))$ and $M \Rightarrow_{\beta\eta} N$. By induction on N :
 - If $N = t'$ where $t \Rightarrow_{\beta\eta} t'$, then by our induction hypothesis $t' \Rightarrow_{\beta\eta} t^*$, hence $N = t' \Rightarrow_{\beta\eta} t^* = (\text{fst}(t), \text{snd}(t))^* = M^*$.
 - If $N = (\text{fst}(t'), \text{snd}(t'))$ where $t \Rightarrow_{\beta\eta} t'$ then by our induction hypothesis, $t' \Rightarrow_{\beta\eta} t^*$ hence $(\text{fst}(t'), \text{snd}(t')) \Rightarrow_{\beta\eta} t^* = (\text{fst}(t), \text{snd}(t))^* = M^*$.

□

Corollary 5.8.13. Given $M \Rightarrow_{\beta\eta} N_1$ and $M \Rightarrow_{\beta\eta} N_2$ then $N_1 \Rightarrow_{\beta\eta} M'$ and $N_2 \Rightarrow_{\beta\eta} M'$ for some M' .

Proof. By Lemma 5.8.12 we observe that $M' = M^*$ gives us the desired result. □

Now we can show that $\beta\eta$ -reduction is weakly Church-Rosser.

Lemma 5.8.14. $\beta\eta$ -reduction is weakly Church-Rosser.

Proof. Given $a \rightarrow_{\beta\eta} b$ and $a \rightarrow_{\beta\eta} b'$ we see that by Lemma 5.8.8, we have $a \Rightarrow_{\beta\eta} b$ and $a \Rightarrow_{\beta\eta} b'$. Hence by the diamond property of $\Rightarrow_{\beta\eta}$ (Corollary 5.8.13), we have $b \Rightarrow_{\beta\eta} a'$ and $b' \Rightarrow_{\beta\eta} a'$ for some a' . Which by Lemma 5.8.8 again, gives us $b \rightarrow_{\beta\eta} a'$ and $b' \rightarrow_{\beta\eta} a'$. □

Theorem 5.8.15. $\beta\eta$ -reduction is Church-Rosser (for typed terms).

Proof. $\beta\eta$ -reduction is strongly normalising by Lemma 5.8.5 and weakly Church-Rosser by Lemma 5.8.14. Hence by Newman's Lemma (5.5.1) we have that $\beta\eta$ -reduction is Church-Rosser for typed terms. □

The best reference for these arguments is [2]. There have been a few papers after which many of the arguments have been vastly simplified notably [48]. However to our knowledge there is no single account of many of these results.

6 STLC Examples

6.1 Identity function $\lambda x.x$

Example 6.1.1 (Identity function). Let's consider the following lambda term $\lambda x.x$. We wish to find a type T such that given some context Γ we have $\Gamma \vdash \lambda x.x \Leftarrow T$. The only rule that allows us to get to this judgement is the mode-switching rule (switch). We also have the opportunity to add some structure to the type, so we keep this in mind.

$$\frac{\Gamma \vdash \lambda x.x \Rightarrow \boxed{?} \quad \Gamma \vdash T \equiv \boxed{?} \text{ type}}{\Gamma \vdash \lambda x.x \Leftarrow T} \text{ (switch)}$$

A first guess on what $\boxed{?}$ is could be T . But this would be a baseless claim to make. Since our syntax has some structure, we can infer what the type ought to be. Checking the conclusions of our rules, we need to find something that will roughly match $\Gamma \vdash \lambda x.x \Rightarrow \boxed{?}$. We see that there is only one rule that fits: (\rightarrow -intro). We also see that $\boxed{?}$ will have to be $A \rightarrow B$ for some types A and B . So we *must* have the following hypothesis in order to progress:

$$\Gamma \vdash T \equiv A \rightarrow B \text{ type} \quad (*)$$

Hence we must have the following derivation:

$$\begin{array}{c} (\rightarrow\text{-intro}) \frac{\Gamma, x : A \vdash x \Leftarrow B}{\Gamma \vdash \lambda x.x \Rightarrow A \rightarrow B} \quad \Gamma \vdash T \equiv A \rightarrow B \text{ type} \\ \hline \Gamma \vdash \lambda x.x \Leftarrow T \quad (\text{switch}) \end{array}$$

We need to now resolve the hypothesis $\Gamma, x : A \vdash x \Leftarrow B$. Observing the conclusions of our rules we see that we must mode-switch. As before we have a chance to change our type, so we play the same game with the holes:

$$\begin{array}{c} \Gamma, x : A \vdash x \Rightarrow \boxed{?} \quad \Gamma, x : A \vdash B \equiv \boxed{?} \text{ type} \\ \hline (\rightarrow\text{-intro}) \frac{\Gamma, x : A \vdash x \Leftarrow B}{\Gamma \vdash \lambda x.x \Rightarrow A \rightarrow B} \quad \Gamma \vdash T \equiv A \rightarrow B \text{ type} \\ \hline \Gamma \vdash \lambda x.x \Leftarrow T \quad (\text{switch}) \end{array}$$

Now observe that there is precisely one rule, the variable rule (var), with a hypothesis in the form of $\Gamma, x : A \vdash x \Rightarrow \boxed{?}$, but for this to be correct we have to place A into $\boxed{?}$. This means we will have to assume:

$$\Gamma, x : A \vdash B \equiv A \text{ type} \quad (**)$$

But since the hypothesis of (var) is quite clearly true, namely that $(x : A) \in \Gamma, x : A$ we are done! Here is the full derivation tree:

$$\begin{array}{c} (\text{var}) \frac{(x : A) \in \Gamma, x : A}{\Gamma, x : A \vdash x \Rightarrow A} \quad \Gamma, x : A \vdash B \equiv A \text{ type} \\ \hline (\rightarrow\text{-intro}) \frac{\Gamma, x : A \vdash x \Leftarrow B}{\Gamma \vdash \lambda x.x \Rightarrow A \rightarrow B} \quad \Gamma \vdash T \equiv A \rightarrow B \text{ type} \\ \hline \Gamma \vdash \lambda x.x \Leftarrow T \quad (\text{switch}) \end{array}$$

However we are not quite done yet. We have two type equations (*) and (**) to resolve. It is clear that if we choose $B := A$ and $T := A \rightarrow A$ we can resolve all our equational hypotheses. So in actual fact a derivation tree would look like this:

$$\begin{array}{c} (x : A) \in \Gamma, x : A \\ \hline \Gamma, x : A \vdash x \Rightarrow A \quad (\text{var}) \\ \hline \Gamma, x : A \vdash x \Leftarrow A \quad (\text{cswitch}) \\ \hline \Gamma \vdash \lambda x.x \Rightarrow A \rightarrow A \quad (\rightarrow\text{-intro}) \\ \hline \Gamma \vdash \lambda x.x \Leftarrow A \rightarrow A \quad (\text{cswitch}) \end{array}$$

It is clear when using the compact mode-switching, the derivation tree is much easier to understand and read. But when searching for a type we necessarily have to use regular mode-switching.

6.2 Function application $\lambda x.\lambda y.xy$

Example 6.2.1 (Function application). Here is another example of a term that type checks. We want to find a type T such that $\Gamma \vdash \lambda x.\lambda y.xy \Leftarrow T$ is true. A derivation tree can be found in Appendix C.2. Here is a proof:

Proof. We begin with the judgement $\Gamma \vdash \lambda x.\lambda y.xy \Leftarrow T$, now the only way to arrive at this judgement is via the mode-switching rule. Whilst doing this we add type variables A and B which can easily be seen to form into $A \rightarrow B$ and let $T \equiv A \rightarrow B$. We can come back later and validate this judgement. The mode-switching should have given us $\Gamma \vdash \lambda x.\lambda y.xy \Rightarrow A \rightarrow B$ which we can only arrive at by applying the (\rightarrow -intro) rule. This gives us $\Gamma, x : A \vdash \lambda y.xy \Leftarrow B$. Which we have to mode-switch, and as before we take this chance to introduce type variables C and D in order to arrive at the judgement $\Gamma, x : A \vdash \lambda y.xy \Rightarrow C \rightarrow D$. This allows us to apply (\rightarrow -intro) giving us $\Gamma, x : A, y : C \vdash xy \Leftarrow D$. Now we apply the (\rightarrow -elim) rule since we have an application. For this we need $\Gamma, x : A, y : C \vdash y \Leftarrow C$, which is marked as (\dagger), and observe that a simple application of mode-switching and the variable rule allows us to derive this judgement. The other hypothesis we need is $\Gamma, x : A, y : C \vdash x \Leftarrow C \rightarrow D$. Again by mode-switching and setting $C \rightarrow D \equiv A$ we get $\Gamma, x : A, y : C \vdash x \Rightarrow A$ which is clearly derivable by the variable rule.

Now we have 3 type equations $(*)$, $(**)$ and $(***)$, substituting back in we get $\Gamma \vdash T \equiv (C \rightarrow D) \rightarrow C \rightarrow D$ for some types C and D . So $\Gamma \vdash \lambda x.\lambda y.xy \Leftarrow T$ if we have types C and D . \square

Remark 6.2.2. The density of information in the previous proof is one reason why it is sometimes clearer to draw a derivation tree. The crucial lesson is the choices we have to make at each step. We have set up our rules in such a manner that there is very often only *one* choice that can be made. When being ambiguous about the type we start with, we are in essence *inferring* typing information. Simply typed lambda calculus where the terms do not have typing information is typically referred to as Curry-style. Where as when terms are annotated with their types it is referred to as Church-style [46].

6.3 Mockingbird $\lambda x.xx$

In the untyped lambda calculus, λ -terms with no free variables can be called combinators. By combining combinators interesting expressions can be written in a readable way. This is related to the idea of combinatory logic which was mostly developed by Haskell Curry. Many combinators have been recorded and one of the best known references is [45], “*To Mock a Mockingbird*”. We will take a look at some other combinators later but we will start with the Mockingbird, also known as $\lambda x.xx$.

Example 6.3.1. We wish to find a type T such that $\Gamma \vdash \lambda x.xx \Leftarrow T$ for some context Γ . We begin, as with every beginning, with the (switch) rule. We take this time to assume that $\Gamma \vdash T \equiv A \rightarrow B$ type given that there is no other way for a λ -term, as discussed in previous examples. This gives us $\Gamma \vdash \lambda x.xx \Rightarrow A \rightarrow B$. Observing that we can only apply (\rightarrow -intro) we arrive at $\Gamma, x : A \vdash xx \Leftarrow B$. First performing a (cswitch) we get $\Gamma, x : A \vdash xx \Rightarrow B$ which then points us to (\rightarrow -elim). This gives us $\Gamma, x : A \vdash x \Leftarrow \boxed{?}$

and $\Gamma, x : A \vdash x \Leftarrow \boxed{?} \rightarrow B$. Now we need to resolve both of these, the first is easier. We can see that we will have to (cswitch) and then use the variable rule, since this is the only judgement that matches with our hole. This also allows us to deduce that $\boxed{?}$ can be filled with A , yielding $\Gamma, x : A \vdash x \Leftarrow A \rightarrow B$. This is where things become problematic. We can of course apply the switch rule. But the only way to do this is with the hypothesis $\Gamma, x : A \vdash A \equiv A \rightarrow B$ type. And we see that $\Gamma, x : A \vdash x \Rightarrow A$ resolves via (var). At this point it would seem we are done, but now we will show the importance of checking the type equations we hypothesised. We set up judgemental equality in such a way that if $\Gamma \vdash A \equiv B$ type then the abts A and B where equal as abts. Thus we have an equation $A = A \rightarrow B$, but this is impossible! This means that the term $\lambda x.xx$ cannot be typed! This is the first stark difference we have seen compared to the untyped lambda calculus. It is typical to assume that by adding typing information to lambda calculus we will break nothing. But as we can clearly see, this is not the case.

Remark 6.3.2. This also presents an opportunity to show why we can *only normalise typed terms*. Using the notion of β -reduction we define back in 5.6.1, it appears that $\lambda x.xx$ is in (β -)normal form. This is misleading since any application of this function to some other term will not be able to reach normal form:

$$(\lambda x.xx)(\lambda x.xx) \rightarrow_{\beta} yy[\lambda x.xx/y] = (\lambda x.xx)(\lambda x.xx) \rightarrow_{\beta} \dots$$

This is very similar to the example in Remark 5.6.6. Of course here, we have stayed fixed, but it is not too difficult to see how a term such as $\lambda x.xxx$ can get very much out of hand when attempting to normalise it. So it is not as if typing is a proof trick, which allows us to prove normalisation, but a property of computation in STLC. Only well-typed programs can run.

6.4 Aye-aye $(\lambda x.x)(\lambda x.x)$

It doesn't mean however any expression containing an ill-typed term is ill-typed. Take for instance $(\lambda x.x)(\lambda x.x)$ which may be written as $(\lambda x.xx)(\lambda x.x)$. As we saw in 6.3.1, $\lambda x.xx$ cannot be typed.

Example 6.4.1. Now suppose we want to show $\Gamma \vdash (\lambda x.x)(\lambda x.x) \Leftarrow T$ for some type T . We begin with (cswitch) noting that we will later use (\rightarrow -elim) so there is no reason to introduce an equality. From $\Gamma \vdash (\lambda x.x)(\lambda x.x) \Rightarrow T$ we use (\rightarrow -elim) to arrive with two hypotheses $\Gamma \vdash \lambda x.x \Leftarrow A \rightarrow T$ and $\Gamma \vdash \lambda x.x \Leftarrow A$ for some type A . Here we might be inclined to think something has gone wrong, since we have the same term being typed in two different ways! But this is not the case.

We noted in Definition 2.2.12 that variables were really just considered up to α -equivalence and that it is always sensible to change when things get confusing. We also noted that such intricacies are the source of many problems in theory and implementation of type theories. It's not hard to see that $\lambda x.x$ can have any type $A \rightarrow A$ we give it. This is because it is simply the identity function. Therefore we could have equally written the judgements as $\Gamma \vdash \lambda x.x \Leftarrow A \rightarrow T$ and $\Gamma \vdash \lambda y.y \Leftarrow A$ and this would not have been confusing.

Working on the first we see that after a (cswitch) we get $\Gamma \vdash \lambda x.x \Rightarrow A \rightarrow T$ which allows us to use (\rightarrow -intro) giving us $\Gamma, x : A \vdash x \Leftarrow T$. We see that switching with

$\Gamma, x : A \vdash T \equiv A$ **type** leads to $\Gamma, x : A \vdash x \Rightarrow A$ which is obviously true by (var). Applying the weakening rule on our type equation $\Gamma, x : A \vdash T \equiv A$ **type** gives us $\Gamma \vdash T \equiv A$ **type** hence going back to $\Gamma \vdash \lambda y.y \Leftarrow A$ we can switch with $\Gamma \vdash A \equiv C \rightarrow D$ in order to be able to progress with (\rightarrow -intro). Now applying (\rightarrow -intro) to $\Gamma \vdash \lambda y.y \Rightarrow C \rightarrow D$ we get $\Gamma, y : C \vdash y \Leftarrow D$. Mode switching with $\Gamma, y : C, \vdash D \equiv C$ **type** we get $\Gamma, y : C \vdash y \Rightarrow C$ which is true by (var). We finally see that $\Gamma \vdash T \equiv C \rightarrow C$ **type**, and that $\Gamma \vdash (\lambda x.x)(\lambda x.x) \Rightarrow A \rightarrow A$ for some type A . An important thing to note, is that even though we have two syntactically identical terms that look like $\lambda x.x$ the type information we gave them had to be different. In this case $(A \rightarrow A) \rightarrow (A \rightarrow A)$ for the first occurrence and $A \rightarrow A$ for the second.

$$\begin{array}{c}
\begin{array}{c}
\text{(var)} \frac{(x : A \rightarrow A) \in \Gamma, x : A \rightarrow A}{\Gamma, x : A \rightarrow A \vdash x \Rightarrow A \rightarrow A} \\
\text{(cswitch)} \frac{\Gamma, x : A \rightarrow A \vdash x \Rightarrow A \rightarrow A}{\Gamma, x : A \rightarrow A \vdash x \Leftarrow A \rightarrow A} \\
\text{(\(\rightarrow\)-intro)} \frac{\Gamma, x : A \rightarrow A \vdash x \Leftarrow A \rightarrow A}{\Gamma \vdash \lambda x.x \Rightarrow (A \rightarrow A) \rightarrow (A \rightarrow A)} \\
\text{(cswitch)} \frac{\Gamma \vdash \lambda x.x \Rightarrow (A \rightarrow A) \rightarrow (A \rightarrow A)}{\Gamma \vdash \lambda x.x \Leftarrow (A \rightarrow A) \rightarrow (A \rightarrow A)} \\
\text{(\(\rightarrow\)-elim)} \frac{\Gamma \vdash \lambda x.x \Leftarrow (A \rightarrow A) \rightarrow (A \rightarrow A)}{\Gamma \vdash (\lambda x.x)(\lambda x.x) \Rightarrow A \rightarrow A} \\
\text{(cswitch)} \frac{\Gamma \vdash (\lambda x.x)(\lambda x.x) \Rightarrow A \rightarrow A}{\Gamma \vdash (\lambda x.x)(\lambda x.x) \Leftarrow A \rightarrow A}
\end{array}
\quad
\begin{array}{c}
\frac{(x : A) \in \Gamma, x : A}{\Gamma, x : A \vdash x \Rightarrow A} \text{(var)} \\
\frac{\Gamma, x : A \vdash x \Rightarrow A}{\Gamma, x : A \vdash x \Leftarrow A} \text{(cswitch)} \\
\frac{\Gamma, x : A \vdash x \Leftarrow A}{\Gamma \vdash \lambda x.x \Rightarrow A \rightarrow A} \text{(\(\rightarrow\)-intro)} \\
\frac{\Gamma \vdash \lambda x.x \Rightarrow A \rightarrow A}{\Gamma \vdash \lambda x.x \Leftarrow A \rightarrow A} \text{(cswitch)}
\end{array}
\end{array}$$

6.5 Y-combinator $\lambda x.(\lambda y.x(yy))(\lambda y.x(yy))$

Here is another important example from the untyped lambda calculus, the **Y**-combinator is defined as $\mathbf{Y} = \lambda x.(\lambda y.x(yy))(\lambda y.x(yy))$. β -reducing the **Y**-combinator applied to a function f , we see that $\mathbf{Y}f = f(\mathbf{Y}f)$. This is precisely the behaviour that allows it to attain recursive behaviour. The **Y**-combinator allows one to define recursive functions. Due to the non-normalising nature of the untyped lambda calculus, it isn't guaranteed that a given function will have a terminating β -reduction sequence. One vital thing the **Y**-combinator provides is an *induction principle* for Church-numerals. It allows one to define functions on Church-numerals by specifying how it acts on zero and on the successor. We will see that the **Y**-combinator *cannot* be typed. This doesn't bode well for the use of Church-numerals in simply typed lambda calculus.

Example 6.5.1. We wish to derive $\Gamma \vdash \lambda x.(\lambda y.x(yy))(\lambda y.x(yy)) \Leftarrow T$ for some type T . We begin by switching and letting $T \equiv A \rightarrow B$ for some A and B . Then we can apply (\rightarrow -intro) to arrive at $\Gamma, x : A \vdash (\lambda y.x(yy))(\lambda y.x(yy)) \Leftarrow B$. Switching then applying (\rightarrow -elim) we need two derivations $\Gamma, x : A \vdash \lambda y.x(yy) \Leftarrow C \rightarrow B$ and $\Gamma, x : A \vdash \lambda y.x(yy) \Leftarrow C$, for some C . Applying switch on the former and then (\rightarrow -intro) we arrive at $\Gamma, x : A, y : C \vdash x(yy) \Leftarrow B$. Yet again, we apply switch and (\rightarrow -elim) to arrive at two derivations: $\Gamma, x : A, y : C \vdash x \Leftarrow D \rightarrow B$ and $\Gamma, x : A, y : C \vdash yy \Leftarrow D$ for some type D . Switching and applying (\rightarrow -elim) on the latter we get another two derivations $\Gamma, x : A, y : C \vdash y \Leftarrow E \rightarrow D$ and $\Gamma, x : A, y : C \vdash y \Leftarrow E$. Observe that only switching and applying (var) can finish this branch of the tree, leading to the hypotheses $\Gamma, x : A, y : C \vdash C \equiv E \rightarrow D$ **type** and $\Gamma, x : A, y : C \vdash C \equiv E$. Clearly these two give us $C \equiv C \rightarrow D$ which is impossible. Hence the **Y**-combinator cannot be typed.

6.6 Function composition $\lambda x.\lambda y.\lambda z.x(yz)$

Here we will try something different, and perhaps more typical. We will provide ourselves with the type. We wish to check that function composition, written as $\lambda x.\lambda y.\lambda z.x(yz)$ has the type we expect it to: $(B \rightarrow C) \rightarrow (A \rightarrow B) \rightarrow (A \rightarrow C)$.

Example 6.6.1. We will show that for some types A , B and C , we have function composition $\Gamma \vdash \lambda x.\lambda y.\lambda z.x(yz) \Leftarrow (B \rightarrow C) \rightarrow (A \rightarrow B) \rightarrow (A \rightarrow C)$. A nice thing about being given the type is that type checking becomes much simpler. In fact, there is very little we actually need to do. Observe that in Appendix C.3 we have a derivation tree. We could write this all out as a proof but it would be pointless. As can be seen the derivation tree is much easier to read. This is the convention we will take for terms with a given type from now on: giving only a derivation tree.

6.7 Currying $\lambda x.\lambda y.\lambda z.x(y, z)$

Here is an interesting function that is quite useful. In mathematics we typically don't make too much distinction between a function that maps to a set of functions and a function that maps from tuples. Written in set-theoretic notation, this can be seen as a “power law” for sets: $C^{A \times B} = (C^B)^A$. In functional programming, this seemingly pointless distinction becomes quite useful. Partial-application of functions literally are partial applications. For example if there was a function **add** : $A \rightarrow B \rightarrow C$ (notice this is really $A \rightarrow (B \rightarrow C)$ but we have right-associativity for \rightarrow), we can get a function **add** a : $B \rightarrow C$. This would be particularly awkward to do if it were defined as **add** : $A \times B \rightarrow C$ instead. On top of this we can compose functions nicely. This is all standard practice in functional programming languages such as Haskell.

Example 6.7.1. The following statement is true: $\Gamma \vdash \lambda x.\lambda y.\lambda z.x(y, z) \Leftarrow (A \rightarrow B \rightarrow C) \rightarrow (A \times B \rightarrow C)$ for some types A , B and C . A full derivation is given in C.4.

6.8 Uncurrying $\lambda x.\lambda y.x(\text{fst}(y))(\text{snd}(y))$

Suppose we wanted to begin with a function $\Gamma \vdash f \Leftarrow A \rightarrow B \rightarrow C$ and turn it into a function $f' \Leftarrow A \times B \rightarrow C$. This ought to be the “opposite” of currying a function.

Example 6.8.1. We wish to derive $\Gamma \vdash \lambda x.\lambda y.x(\text{fst}(y))(\text{snd}(y)) \Leftarrow (A \rightarrow B \rightarrow C) \rightarrow A \times B \rightarrow C$. A full derivation is given in C.5.

6.9 Curry-Uncurry

We will now show that composing curry with uncurry gives us the identity. Unfortunately our λ -terms will get too large for the page, so we will write them in a more compact manner.

Example 6.9.1 (Curry-Uncurry). We will assume the following:

- $\Gamma \vdash \mathbf{C} \equiv \lambda x.\lambda y.\lambda z.x(y, z) : (A \times B \rightarrow C) \rightarrow A \rightarrow B \rightarrow C$ denotes the function Curry.

- $\Gamma \vdash \mathbf{U} \equiv \lambda x. \lambda y. x(\text{fst}(y))(\text{snd}(y)) : (A \rightarrow B \rightarrow C) \rightarrow A \times B \rightarrow C$ denotes the function `Uncurry`.
- $\Gamma \vdash \mathbf{B} \equiv \lambda x. \lambda y. \lambda z. x(yz) : ((A \rightarrow B \rightarrow C) \rightarrow A \times B \rightarrow C) \rightarrow ((A \times B \rightarrow C) \rightarrow A \rightarrow B \rightarrow C) \rightarrow (A \times B \rightarrow C) \rightarrow (A \times B \rightarrow C)$ is the composition of two functions, conveniently with the correct types for `curry` and `uncurry`.

This means we want to derive the following:

$$\Gamma \vdash \mathbf{BUC} \equiv \lambda x. x : (A \times B \rightarrow C) \rightarrow (A \times B \rightarrow C)$$

Luckily we won't do this by hand and we will instead use a property of our type theory: *Canonicity*. This says that the normal form of a type is canonical. This means that reducing our terms to $\beta\eta$ -normal form will be equal by reflexivity. Clearly $\lambda x. x$ is in normal form so we need to work on the left hand side.

First let us reduce **BU**:

$$\begin{aligned} \mathbf{BU} &= (\lambda x. \lambda y. \lambda z. x(yz))(\lambda x. \lambda y. x(\text{fst}(y))(\text{snd}(y))) \\ &= (\lambda a. \lambda b. \lambda c. a(bc))(\lambda x. \lambda y. x(\text{fst}(y))(\text{snd}(y))) \\ &\rightarrow_{\beta} \lambda b. \lambda c. (\lambda x. \lambda y. x(\text{fst}(y))(\text{snd}(y)))(bc) \\ &\rightarrow_{\beta} \lambda b. \lambda c. \lambda y. bc(\text{fst}(y))(\text{snd}(y)) \end{aligned}$$

We are now in normal form for **BU** so we can reduce the whole of **BUC**:

$$\begin{aligned} \mathbf{BUC} &= \mathbf{BU}(\lambda i. \lambda j. \lambda k. i(j, k)) \\ &\rightarrow_{\beta} (\lambda b. \lambda c. \lambda y. bc(\text{fst}(y))(\text{snd}(y)))(\lambda i. \lambda j. \lambda k. i(j, k)) \\ &\rightarrow_{\beta} \lambda c. \lambda y. (\lambda i. \lambda j. \lambda k. i(j, k))c(\text{fst}(y))(\text{snd}(y)) \\ &\rightarrow_{\beta} \lambda c. \lambda y. (\lambda j. \lambda k. c(j, k))(\text{fst}(y))(\text{snd}(y)) \\ &\rightarrow_{\beta} \lambda c. \lambda y. (\lambda k. c(\text{fst}(y), k))(\text{snd}(y)) \\ &\rightarrow_{\beta} \lambda c. \lambda y. c(\text{fst}(y), \text{snd}(y)) \\ &\rightarrow_{\eta} \lambda c. \lambda y. cy \\ &\rightarrow_{\eta} \lambda c. c \end{aligned}$$

Hence we clearly have

$$\Gamma \vdash \mathbf{BUC} \equiv \lambda x. x : (A \times B \rightarrow C) \rightarrow (A \times B \rightarrow C)$$

Remark 6.9.2. This example suggests an algorithm for deciding whether or not two terms are judgmentally equal. We mentioned this as one of the natural problems to consider in type theory. Simply take the $\beta\eta$ -normal form and compare terms. Since $\beta\eta$ -reduction is strongly normalising (Lemma 5.8.5), we see that equality of terms in simply typed lambda calculus is in fact decidable!

Remark 6.9.3. We note that we have not formally defined what it means to have a canonical form, but we can simply claim that canonicity holds for our simply typed lambda calculus.

6.10 Swap $\lambda t.(\text{snd}(t), \text{fst}(t))$

This example demonstrates a simple operation that manipulates a data structure. We will later show that composing this function with itself is the identity.

Example 6.10.1. The type of $\lambda t.(\text{snd}(t), \text{fst}(t))$ is $A \times B \rightarrow B \times A$. Intuitively, this function simply swaps the order in an ordered pair. Here is a derivation tree showing that $\Gamma \vdash \lambda t.(\text{snd}(t), \text{fst}(t)) \Leftarrow B \times A \rightarrow A \times B$.

$$\begin{array}{c}
\begin{array}{c}
(\text{var}) \frac{(t : A \times B) \in \Gamma, t : A \times B}{\Gamma, t : A \times B \vdash t \Rightarrow A \times B} \\
(\text{cswitch}) \frac{\Gamma, t : A \times B \vdash t \Rightarrow A \times B}{\Gamma, t : A \times B \vdash t \Leftarrow A \times B} \\
(\times\text{-elim}_2) \frac{\Gamma, t : A \times B \vdash \text{snd}(t) \Rightarrow B}{\Gamma, t : A \times B \vdash \text{snd}(t) \Leftarrow B} \\
(\text{cswitch}) \frac{\Gamma, t : A \times B \vdash \text{snd}(t) \Leftarrow B}{\Gamma, t : A \times B \vdash (\text{snd}(t), \text{fst}(t)) \Rightarrow B \times A} \\
(\times\text{-intro}) \frac{\Gamma, t : A \times B \vdash (\text{snd}(t), \text{fst}(t)) \Rightarrow B \times A}{\Gamma, t : A \times B \vdash (\text{snd}(t), \text{fst}(t)) \Leftarrow B \times A} \\
(\rightarrow\text{-intro}) \frac{\Gamma \vdash \lambda t.(\text{snd}(t), \text{fst}(t)) \Rightarrow B \times A}{\Gamma \vdash \lambda t.(\text{snd}(t), \text{fst}(t)) \Leftarrow B \times A}
\end{array}
\quad
\begin{array}{c}
(\text{var}) \frac{(t : A \times B) \in \Gamma, t : A \times B}{\Gamma, t : A \times B \vdash t \Rightarrow A \times B} \\
(\text{cswitch}) \frac{\Gamma, t : A \times B \vdash t \Rightarrow A \times B}{\Gamma, t : A \times B \vdash t \Leftarrow A \times B} \\
(\times\text{-elim}_1) \frac{\Gamma, t : A \times B \vdash \text{fst}(t) \Rightarrow A}{\Gamma, t : A \times B \vdash \text{fst}(t) \Leftarrow A} \\
(\text{cswitch}) \frac{\Gamma, t : A \times B \vdash \text{fst}(t) \Leftarrow A}{\Gamma, t : A \times B \vdash (\text{snd}(t), \text{fst}(t)) \Rightarrow B \times A}
\end{array}
\end{array}$$

6.11 Swap-Swap

We will now demonstrate that the swap function composes with itself to give the identity.

Example 6.11.1. We follow a similar argument to example 6.9.1. Let $\Gamma \vdash \mathbf{S} \equiv \lambda t.(\text{snd}(t), \text{fst}(t)) : A \times B \rightarrow B \times A$. We wish to show that $\Gamma \vdash \mathbf{BSS} \equiv \lambda x.x : A \times B \rightarrow A \times B$. First we compute \mathbf{BS} :

$$\begin{aligned}
\mathbf{BS} &= (\lambda x.\lambda y.\lambda z.x(yz))(\lambda t.(\text{snd}(t), \text{fst}(t))) \\
&\rightarrow_\beta \lambda y.\lambda z.(\lambda t.(\text{snd}(t), \text{fst}(t)))(yz) \\
&\rightarrow_\beta \lambda y.\lambda z.(\text{snd}(yz), \text{fst}(yz))
\end{aligned}$$

Now we can reduce \mathbf{BSS} :

$$\begin{aligned}
\mathbf{BSS} &= (\mathbf{BS})\mathbf{S} \\
&= (\lambda y.\lambda z.(\text{snd}(yz), \text{fst}(yz)))\mathbf{S} \\
&\rightarrow_\beta \lambda z.(\text{snd}(\mathbf{S}z), \text{fst}(\mathbf{S}z)) \\
&\Rightarrow_\beta \lambda z.(\text{snd}(\text{snd}(z), \text{fst}(z)), \text{fst}(\text{snd}(z), \text{fst}(z))) \\
&\Rightarrow_\beta \lambda z.(\text{fst}(z), \text{snd}(z)) \\
&\rightarrow_\eta \lambda z.z
\end{aligned}$$

So we have shown $\Gamma \vdash \mathbf{BSS} \equiv \lambda x.x : A \times B \rightarrow A \times B$.

7 Extensions of simply typed lambda calculus

7.1 Introduction

Historically the addition of a natural numbers type with a recursion principle \mathbb{N} was done by Gödel in his “*System T*” of Higher-Order recursion [23]. This is different than just having *encoded* numbers in type theory. For example in $\lambda_{\rightarrow \times}$ we have *Church numerals* [37, 46]. It is possible to define the basic operations of arithmetic, including subtraction.

Church-Encodings are what are known as impredicative encodings, whereby the terms of the types are the same as the desired one but the eliminators are not present. This is demonstrated for Church-encodings of the natural numbers by the fact that it is *impossible* to define recursion over the natural numbers in $\lambda_{\rightarrow \times}$ [46].

This isn’t the case for *untyped* lambda calculus however. It is well-known that untyped lambda calculus can have recursive definitions, see Example 6.5.1. But they come at a cost, not every term in untyped lambda calculus is normalising. This corresponds to a computation which doesn’t halt and is intimately related to the halting problem [6, 7]. A natural numbers type can however be added to $\lambda_{\rightarrow \times}$ leading to a type theory that is “equivalent”, in some sense, to Gödel’s system T. Though not all presentations are the same, for example comparing [24] with no products and [46] with products. So we are not too worried about our type theory being so different from Gödel’s.

We will also look at some other types such as sums and 0 and eventually exhibit the properties of this type theory as a propositional logic, as the Curry-Howard correspondence suggests.

7.2 Natural numbers

We add natural numbers. This will be our first example of an *inductive type*.

Definition 7.2.1. The *natural numbers type* \mathbb{N} is defined by the following rules. First we begin with the formation rule.

$$\frac{}{\Gamma \vdash \mathbb{N} \text{ type}} \text{ (N-form)}$$

We next introduce our two introduction rules. The term 0 is of type \mathbb{N} , and given any $n : \mathbb{N}$, then $s(n) : \mathbb{N}$ also. We call $s : \mathbb{N} \rightarrow \mathbb{N}$ the *successor function* and $s(n)$ is the *successor* of n .

$$\frac{}{\Gamma \vdash 0 \Rightarrow \mathbb{N}} \text{ (N-intro}_1\text{)} \quad \frac{\Gamma \vdash n \Leftarrow \mathbb{N}}{\Gamma \vdash s(n) \Rightarrow \mathbb{N}} \text{ (N-intro}_2\text{)}$$

Our elimination principle tells us how to build functions out of this type. This is our induction principle. The term $c : A$ corresponds to the value of the function at 0. The term $f : \mathbb{N} \rightarrow A \rightarrow A$ takes in the previous $n : \mathbb{N}$, and the previous value a from A , and gives the next value $f(n)(a) : A$.

$$\frac{\Gamma \vdash f \Leftarrow \mathbb{N} \rightarrow A \rightarrow A \quad \Gamma \vdash c \Leftarrow A}{\Gamma \vdash \mathbf{ind}_{\mathbb{N}}(f, c) \Rightarrow \mathbb{N} \rightarrow A} \text{ (N-elim)}$$

Now we want these rules to compute how we intended them to. So we add computation rules for behaviour at 0.

$$\frac{\Gamma \vdash f \Leftarrow \mathbb{N} \rightarrow A \rightarrow A \quad \Gamma \vdash c \Leftarrow A}{\Gamma \vdash \mathbf{ind}_{\mathbb{N}}(f, c)(0) \equiv c : A} (\mathbb{N}\text{-}\beta_1)$$

And computation rules for behaviour at a successor.

$$\frac{\Gamma \vdash f \Leftarrow \mathbb{N} \rightarrow A \rightarrow A \quad \Gamma \vdash c \Leftarrow A \quad \Gamma \vdash n \Leftarrow \mathbb{N}}{\Gamma \vdash \mathbf{ind}_{\mathbb{N}}(f, c)(s(n)) \equiv f(n)(\mathbf{ind}_{\mathbb{N}}(f, c)(n)) : A} (\mathbb{N}\text{-}\beta_2)$$

All rules can be found in Appendix B.1.

Remark 7.2.2. What we have defined is a more powerful programming language than the STLC. In fact we can define many arithmetic functions on this, and most importantly, recursive functions. We won't however provide any examples, since we find this extremely tedious to show!

7.3 Empty type

Definition 7.3.1. The *empty type* is defined by the following rules:

$$\frac{}{\Gamma \vdash \mathbf{0} \text{ type}} (\mathbf{0}\text{-form}) \quad \frac{\Gamma \vdash A \text{ type}}{\Gamma \vdash \mathbf{ind}_{\mathbf{0}} \Rightarrow \mathbf{0} \rightarrow A} (\mathbf{0}\text{-elim})$$

The first is the formation rule (**0-form**), simply asserting that the empty type exists. Notice how there are no constructors. This is precisely because the empty type is, well, empty. The second is the elimination rule, supposing we had a term $t : \mathbf{0}$, then we could inhabit any type A . For reference the rules are in Appendix B.2.

The empty type acts as our *absurdity* in type theory. If we consider types A as logical propositions, then the type $A \rightarrow \mathbf{0}$ can be considered *not* A . For if we had a proof of A , we would have a proof of $\mathbf{0}$ which is *absurd*.

Remark 7.3.2. Notice that as a consequence, any type $\mathbf{0} \rightarrow A$ is inhabited by a single term. In fact, if we had some sort of equality of types (judgmental equality is too strict), we could show that “ $\mathbf{0} \rightarrow A = \mathbf{1}$ ”. If we write $\mathbf{0} \rightarrow A$ in a more suggestive notation $A^{\mathbf{0}}$ then we can see what we mean.

7.4 Sum types

Definition 7.4.1. *Sum types* are given by the following collection of rules. A *type theory with sum types* is understood to include these rules. These are summarised in Appendix B.3. We begin with the formation rule of the sum type. This is pretty typical, given two types A and B , we have a sum type $A + B$.

$$\frac{\Gamma \vdash A \text{ type} \quad \Gamma \vdash B \text{ type}}{\Gamma \vdash A + B \text{ type}} (+\text{-form})$$

Terms of the sum type are where things get interesting. We see that terms either come as labelled terms of A or labelled terms of B . The labelling allows for the determination of where the term came from, in from the left (inl) or in from the right (inr).

$$\frac{\Gamma \vdash a \Leftarrow A}{\Gamma \vdash \text{inl}(a) \Rightarrow A + B} (+\text{-intro}_1)$$

$$\frac{\Gamma \vdash b \Leftarrow B}{\Gamma \vdash \text{inr}(b) \Rightarrow A + B} (+\text{-intro}_2)$$

Next our elimination rule specifies how to define functions coming out of the sum type $A + B$. Given functions $f : A \rightarrow C$ and functions $g : B \rightarrow C$, we can construct a function $\mathbf{ind}_+(f, g) : A + B \rightarrow C$.

$$\frac{\Gamma \vdash f \Leftarrow A \rightarrow C \quad \Gamma \vdash g \Leftarrow B \rightarrow C}{\Gamma \vdash \mathbf{ind}_+(f, g) \Rightarrow A + B} (+\text{-elim})$$

And finally we need to make sure that this function computes as we expect it to. If a term $t : A + B$ is of the form $\text{inl}(a)$, then applying $\mathbf{ind}_+(f, g)$ to $\text{inl}(a)$ is the same as applying f to a . If a term $t : A + B$ is of the form $\text{inr}(b)$, then applying $\mathbf{ind}_+(f, g)$ to $\text{inr}(b)$ is the same as applying g to b .

$$\frac{\Gamma \vdash a \Leftarrow A \quad \Gamma \vdash f \Leftarrow A \rightarrow C \quad \Gamma \vdash g \Leftarrow B \rightarrow C}{\Gamma \vdash \mathbf{ind}_+(f, g)(\text{inl}(a)) \equiv f(a) : C} (+\beta_1)$$

$$\frac{\Gamma \vdash b \Leftarrow B \quad \Gamma \vdash f \Leftarrow A \rightarrow C \quad \Gamma \vdash g \Leftarrow B \rightarrow C}{\Gamma \vdash \mathbf{ind}_+(f, g)(\text{inr}(b)) \equiv g(b) : C} (+\beta_2)$$

Sum types earn their name from how they interact with the unit type and the empty type. Clearly $A + \mathbf{0}$ is basically a version of A where all the elements are labelled with inl . If we had an internal notion of equality, we could show that “ $A + \mathbf{0} = A$ ”. An even more rich interaction occurs with the unit type $\mathbf{1}$. Consider the type $\mathbf{1} + \mathbf{1}$. It has two elements, $\text{inl}(\ast)$ and $\text{inr}(\ast)$, as we can see the labels are very handy. This can be considered as the definition of a *two element type*. It quickly generalises to all finite types, typically denoted \mathbf{Fin}_n or \mathbf{n} for some natural number n . The elimination principle for such a type would essentially say: to construct $\mathbf{n} \rightarrow A$, we must pick n terms of the type A .

Of course, there are differences such as $(\mathbf{1} + \mathbf{1}) + \mathbf{1}$ and $\mathbf{1} + (\mathbf{1} + \mathbf{1})$, however these can be removed, or more rather, shown to be irrelevant, when there is an internal notion of equality. In that sense “ $(\mathbf{1} + \mathbf{1}) + \mathbf{1} = \mathbf{1} + (\mathbf{1} + \mathbf{1})$ ”.

Remark 7.4.2. In programming languages such as C, one could roughly say that the “types” of C correspond to regular types. In that way *structs*, which allow programmers to pair data structures together, can be thought of as product types. Then sum types would correspond to what are known as *unions*. Intuitively, these are overlapping data

structures. We must be careful not to take this analogy too far however since \mathbf{C} is missing many properties we would generally expect from a type theory.

Remark 7.4.3. For mathematicians, sum types are simply “disjoint unions” of types. If we pretended that types were sets then this would correspond exactly. The notation for sum types arises from the categorical semantics, where sums are modelled by coproducts (categorical versions of disjoint unions) [36].

7.5 Properties of the extended lambda calculus

All of the normalisation properties can be extended to include the reductions defined in the extended lambda calculus. Most importantly this means System \mathbf{T} is strongly normalising, every computation terminates after finitely many steps. We have recursive functions which is something we could not do in the plain simply typed lambda calculus, however we are no where near as powerful as the *untyped* lambda calculus. It is possible to generalise to *inductive types* of all sorts, leading to well-founded tree types.

It is possible to extend languages further such that they break strong normalisation. This may not seem like an ideal thing to do but it is in fact very useful from a programming point of view. There is a theorem called the *Blum Size Theorem (BST)* which states that, given any blow-up factor, say 2^{2^n} , there is a total function (a function that can be defined in system \mathbf{T}) such that the shortest program in \mathbf{T} , is larger than the shortest program in PCF (the extended version of \mathbf{T} that is not strongly normalising) by this factor! [24].

So we have seen that features can be added to the simply typed lambda calculus, with many of them preserving desirable properties, but sometimes in order to get practical outcomes, we might need to give up some nice properties. This is a common theme in the study of programming semantics, and is rarely considered in the mathematical considerations of simply typed lambda calculus, from what we have observed.

Remark 7.5.1. Finally we remark about the style of the rules presented here. We have purposefully not included the congruence rules since these can be readily derived at this point. The congruence rules for \mathbf{N} for example get very long and messy.

8 Curry-Howard correspondence

8.1 Introduction

In this section we outline a detailed history of what is known as the Curry-Howard correspondence. This is an important thing to consider since there are many powerful ideas that get uncovered in this story. They will shape the future of thought on the subject, so it is worthwhile to understand what was motivating mathematicians and computer scientists at the time.

Many of these ideas were developed before the comprehension of the modern idea of a computer! So in a way it is quite remarkable that these ideas were even considered. Hence we will discuss their original motivations.

This story will develop our ideas of what needs to be added to the simply typed lambda calculus going forward. How these ideas will behave with what we have studied, and finally what the future of the subject looks like.

8.2 Mathematical logic

At the beginning of the 20th century, Whitehead and Russell published their *Principia Mathematica* [43], demonstrating to mathematicians of the time that formal logic could express much of mathematics. It served to popularise modern mathematical logic leading to many mathematicians taking a more serious look at topic such as the foundations of mathematics.

One of the most influential mathematicians of the time was David Hilbert. Inspired by Whitehead and Russell's vision, Hilbert and his colleagues at Göttingen became leading researchers in formal logic. Hilbert proposed the *Entscheidungsproblem* (decision problem), that is, to develop an “effectually calculable procedure” to determine the truth or falsehood of any logical statement. At the 1930 Mathematical Congress in Königsberg, Hilbert affirmed his belief in the conjecture, concluding with his famous words “Wir müssen wissen, wir werden wissen” (“We must know, we will know”). At the very same conference, Kurt Gödel announced his proof that arithmetic is incomplete [22], not every statement in arithmetic can be proven.

This however did not deter logicians, who were still interested in understanding why the *Entscheidungsproblem* was not attainable. For this, a formal definition of “effectively calculable” was required. So along came three candidate definitions of what it meant to be “effectively calculable”: λ -calculus, published in 1936 by Alonzo Church [7]; *recursive functions*, proposed by Gödel in 1934 later published in 1936 by Stephen Kleene [35]; and finally *Turing machines* in 1937 by Alan Turing [52].

8.3 λ -calculus

λ -calculus was discovered by Church at Princeton in the 1930s, originally as a way to define notations for logical formulas. It is a very compact and simple idea, with only three constructs: variables; λ -abstraction; and function application. Curry developed the closely related idea of combinatory logic around the same time [11, 12].

Interestingly, Curry had introduced the notion of *Combinators* into logic for the very same reason we introduced abstract binding trees: to avoid mentioning named variables [46].

It was realised at the time by Church and others that “There may, indeed, be other applications of the system than its use as a logic.” [4, 5]. This meant that λ -calculus was worth studying as a topic of interest in its own right. This became explicitly apparent when Church discovered a way of encoding numbers as terms of λ -calculus, known as the *Church encoding* of the natural numbers. From this addition and multiplication could also be defined.

However the problem of defining a predecessor function alluded Church and his students, in fact Church later became convinced that it was impossible. Fortunately Kleene later discovered, at his dentist's office, how to define the predecessor function [30, 31, 33]. This led to Church to later propose that λ -definability ought to be the definition of “effectively calculable”, culminating into what is now known as Church's Thesis. Church went on to demonstrate that the problem of determining whether or not a given λ -term has a normal form is not λ -definable. This is now known as the Halting Problem. Put differently this says that no program written in the λ -calculus can determine whether a program written in the λ -calculus halts or not.

8.4 Recursive functions

In 1933 Gödel arrived in Princeton, unconvinced by Church's claim that every effectively calculable function was λ -definable. Church responded by offering that if Gödel would propose a different definition, then Church would "undertake to prove it was included in λ -definability". In a series of lectures at Princeton, Gödel proposed what came to be known as "general recursive functions" as his candidate for effective calculability. Kleene later published the definition [35]. Church later outlined a proof that it was equivalent to the λ -calculus [6] and Kleene later published it in detail [32]. This however did not have the intended effect on Gödel, whereby he then became convinced that his own definition was incorrect!

8.5 Turing machines

Alan Turing was at Cambridge when he independently formulated his own idea of what it meant to be "effectively calculable", what is now known today as a *Turing machine*. He used it to show that the Entscheidungsproblem is undecidable, meaning that it cannot be proven to be true or false. Before publication, Turing's advisor Max Newman was worried since Church had already published a solution, but since Turing's approach was sufficiently novel it was published anyway [52]. Turing had added an appendix sketching the equivalence of λ -definability to Turing machines. It was Turing's argument that later convinced Gödel that this was the correct notion of "effectively calculable".

Of course today the argument for Turing machines as a candidate for computation seems obvious. We are surrounded by computers in our daily lives, all based loosely on the idea of a Turing machine. From this it is easy to see that Turing's ideas had a *huge* influence on the notions of computation.

8.6 The problem with λ -calculus as a logic

Church's students Kleene and Rosser quickly discovered that λ -calculus was inconsistent as a logic [34]. A logic is deemed *inconsistent* if every statement can be proven. For example assuming $1 = 2$ can lead to many bizarre consequences, such as all logical formulas becoming true, one way or another. In that way, arithmetic with the assumption that $1 = 2$, is *inconsistent as a logic*. Curry later published a simplified version of Kleene and Rosser's result which became known as *Curry's paradox* [15]. Curry's paradox was related to Russell's paradox, in that a predicate was allowed to act on itself.

Russell's paradox is typically seen as a paradox of set theory, but can usually be phrased in a much more general manner. The basic idea is this: Let A be the set of all sets that do not contain themselves. The question is, does A belong to itself? Clearly, if it did then it would not be an element of the set. If it did not, then it would have to be an element. Either way there is a contradiction, hence we have a *logical paradox*.

The issue arises with the definition of A . In it we defined it as something quantifying over a lot of things, but most importantly itself. This self reference is exactly the issue that leads to such a paradox. The idea of self-reference isn't that harmful if kept under control however, particularly if a relation is *well-founded*.

But allowing all predicates (formulas quantifying over other formulas), leads to silly situations as above. Much of modern set theory has been developed in order to avoid

being able to write down paradoxical statements as above. We will see many of these ideas in a type theoretic form later on. A good introduction to basic set theory is [28].

What is nice about Church's STLC is that every term has a normal form, or in the language of Turing machines every computation halts [52]. From this consistency of Church's STLC as a logic could be established, not every logical formula is true.

8.7 Types to the rescue

Types were originally introduced as a method to avoid paradoxes occurring in the type-free world. However mathematicians had naturally stratified objects into different categories, without any consideration to types before [20, 29]. Russell was one of the first mathematicians to introduce a formal theory of types [43], precisely to avoid the paradox bearing his name. In order to solve this problem, Church adapted a solution similar to Russell's. The first presentation of a simple theory of types was given in Church's influential paper [8], where he introduced the simply typed lambda calculus.

Being typed had some immediate consequences, especially on the ideas of λ -calculus as a notion of computation. We saw in Example 6.5.1, certain computational properties of the untyped lambda calculus, such as recursion are lost. What we are left with is a strictly weaker programming language. But one that is at least consistent as a system of logic.

8.8 Types in the design of programming languages

[[TODO]]

8.9 Propositions as types

We have previously discussed a condensed form of the two judgements $a \Leftarrow A$ and $a \Rightarrow A$, which we will denote $a : A$. This is in fact the judgement considered without bidirectional type checking, and the one found in most literature on the subject. We had our own reasons for choosing this set up but now we want to discuss how types and propositions are related, hence we will only be mentioning $a : A$.

The basic idea of the propositions as types is to consider types as propositional formulas, and terms as proof of those propositions. Suppose I had a type `TheSkyIsBlue`. Then terms of this type would correspond to evidence or proofs that the sky is indeed blue. Type formers can then be seen as logical connectives. Suppose A is the type "Is a Cow". Terms of A are proofs that what ever we are considering, it *is a cow*. Now suppose there is a type B called "Goes moo". Terms of this type are proofs that what ever we are considering, *goes moo*. Say we want to prove the statement: "If it is a cow, then it goes moo". Proving such a statement would go something like this: Suppose what we are considering is a cow, through this series of logical steps we arrive at the conclusion that it goes moo. If A and B were *propositions*, then it would be agreed that we have proven $A \implies B$. It's as if we have taken a proof of A and turned it into a proof of B . We have types that do exactly that: Function types! So our proof of $A \rightarrow B$ is really just a function $\lambda x.y$ that takes in a proof $x : A$ and gives a proof $y : B$.

Of course implication isn't what logic is all about, a natural question to ask is what conjunction (the fancy word for "and") corresponds to. Proving that "*the sky is blue*" and

“the grass is green”, in a way, requires *two* proofs, one corresponding to each proposition. Let A be the type denoting that the sky is blue and B be the type denoting that the grass is green. Then $A \times B$, the product type, is the type that both these “propositions” hold. How do we construct a term of the product type? Well we need to give a pair (a, b) , which consists of a term $a : A$ and a term $b : B$. Or in other words, to give a proof of $A \times B$ we need to give a proof of a and a proof of B . For a longer list see Table 1.

Curiously, Curry had noticed something similar in [14, footnote 28], though his motivations were far less bovinial: “Note the similarity of the postulates for F and those for P . If in any of the former postulates we change F to P and drop the combinator we have the corresponding postulate for P .” Here P is the combinator for implication and F is a “functionality” combinator, whereby $FABf$ essentially means $f : A \rightarrow B$. There is evidence to suggest that this idea wasn’t new to Curry. Hindley [25] points out that a remark on page 588 of [13] indicates this. Another hint is that the properties of implication (denoted \supset) are named PB, PC, PW and PK, after the combinators B, C, W and K.

The correspondence was made precise (in typed combinatory logic) by Curry and Feys in [16, Chapter 9]. There are two theorems proved in this chapter, under the title of “F-P transformation” (the notation from earlier): Theorem 1 states that inhabited types are provable; Theorem 2 states that the converse. It was a famous “privately circulated” paper of Howard [26] that made the links between cut-elimination and (β) -normalisation.

Such a correspondence was great for type theory since now normalisation of terms could be proven in the world of logic.

It should be noted that Curry and Howard share most of the credit for this work, yet De Bruijn, independently formulated a statement about a correspondence between proofs and objects. He was, furthermore, one of the first to make practical use of it. He developed the “mathematical language” Automath [18].

Remark 8.9.1. We note that other authors had also independently noted a link between proofs and combinators [41].

Remark 8.9.2. We note that some authors like to call this an *isomorphism* but it is not entire clear what a *morphism* is between a logic and a type theory.

9 Conclusion and Future directions

We have seen how type theory developed beyond

Logic	λ -calculus
Logical formula	Type (Def. 4.0.2)
Propositional variable	Type variable (Def. 4.0.2)
Logical connective	Type former (Def. 4.4)
Implication	Function type (Def. 4.4.1)
Conjunction (and)	Product type (Def. 4.4.3)
Disjunction (or)	Sum type (Def. 7.4.1)
Absurdity (false)	Empty type (Def. 7.3.1)
Tautology (truth)	Unit type (Def. 4.4.6)
Proof	Term (Def. 4.0.2)
Assumption	Term variable (Def. 4.0.2)
Introduction	Constructor (Def. 4.4)
Elimination	Destructor (Def. 4.4)
Proof detour	Redex (Def. 5.8.1)
Cut elimination	Reduction (Def. 5.8.1)
Normal proof	Normal form (Def. 5.6.3)
Provability	Inhabitation

Table 1: Here is a table summarising the depth of the correspondence. The table explains the terminology for eliminators/destructors, introducers/constructors.

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Appendices

A Simply typed lambda calculus $\lambda_{\rightarrow \times}$

This is the full-presentation of the simply typed lambda calculus $\lambda_{\rightarrow \times}$. It has function types, product types and a unit type. We also have a set of *atomic* types, usually denoted by A . These don't typically have rules associated to them and can be considered variables of sort ty .

A.1 Syntax

We have two sorts $\mathcal{S} := \{\text{tm}, \text{ty}\}$. Our syntax can be presented in BNF:

$$\text{Term} ::= x \mid \lambda x. a \mid (a, b) \mid ab \mid c$$

$$\text{Type} ::= A \mid \mathbf{1} \mid A \times B \mid A \rightarrow B$$

Or listed as operators:

Op	Sort	Vars	Type args	Term args	Scoping	Syntax
\rightarrow	ty	—	A, B	—	—	$A \rightarrow B$
\times	ty	—	A, B	—	—	$A \times B$
$(-, -)$	tm	—	—	x, y	—	(x, y)
λ	tm	x	A, B	—	M	$\lambda(x : A). M$
App	tm	—	A, B	—	M, N	MN

A.2 Judgements

Judgement	Meaning
$A \text{ type}$	A is a type.
$T \Leftarrow A$	T can be checked to have type A .
$T \Rightarrow A$	T synthesises the type A .
$A \equiv B \text{ type}$	A and B are judgmentally equal types.
$S \equiv T : A$	S and T are judgmentally equal terms of type A s.

A.3 Structural rules

$$\frac{(x : A) \in \Gamma}{\Gamma \vdash x \Rightarrow A} (\text{var}) \quad \frac{\Gamma \vdash t \Rightarrow A \quad \Gamma \vdash A \equiv B \text{ type}}{\Gamma \vdash t \Leftarrow B} (\text{switch})$$

A.4 Admissible rules

$$\frac{\Gamma \vdash t \Rightarrow A}{\Gamma \vdash t \Leftarrow A} (\text{cswitch}) \quad \frac{\Gamma \vdash a \Leftarrow A \quad \Gamma, x : A \vdash \mathcal{J}}{\Gamma \vdash \mathcal{J}[a/x]} (\text{subst})$$

$$\frac{\Gamma \vdash A \text{ type} \quad \Gamma \vdash \mathcal{J}}{\Gamma, x : A \vdash \mathcal{J}} (\text{wkg}) \quad \frac{\Gamma, x : A, y : B \vdash \mathcal{J}}{\Gamma, y : B, x : A \vdash \mathcal{J}} (\text{exg})$$

A.5 Equality rules

$$\begin{array}{c}
\frac{\Gamma \vdash A \text{ type}}{\Gamma \vdash A \equiv A \text{ type}} (\equiv_{\text{type-refl}}) \quad \frac{\Gamma \vdash A \equiv B \text{ type}}{\Gamma \vdash B \equiv A \text{ type}} (\equiv_{\text{type-symm}}) \\
\\
\frac{\Gamma \vdash B \text{ type} \quad \Gamma \vdash A \equiv B \text{ type} \quad \Gamma \vdash B \equiv C \text{ type}}{\Gamma \vdash A \equiv C \text{ type}} (\equiv_{\text{type-tran}}) \\
\\
\frac{\Gamma \vdash t \Leftarrow A}{\Gamma \vdash t \equiv t : A} (\equiv_{\text{term-refl}}) \quad \frac{\Gamma \vdash s \equiv t : A}{\Gamma \vdash t \equiv s : A} (\equiv_{\text{term-symm}}) \\
\\
\frac{\Gamma \vdash t \Leftarrow A \quad \Gamma \vdash s \equiv t : A \quad \Gamma \vdash t \equiv r : A}{\Gamma \vdash s \equiv r : A} (\equiv_{\text{term-tran}}) \\
\\
\frac{\Gamma \vdash A \text{ type} \quad \Gamma \vdash s \equiv t : A \quad \Gamma \vdash A \equiv B \text{ type}}{\Gamma \vdash s \equiv t : B} (\equiv_{\text{term}}\text{-}\equiv_{\text{type}}\text{-cong})
\end{array}$$

A.6 Function type

$$\begin{array}{c}
\frac{\Gamma \vdash A \text{ type} \quad \Gamma \vdash B \text{ type}}{\Gamma \vdash A \rightarrow B \text{ type}} (\rightarrow\text{-form}) \quad \frac{\Gamma, x : A \vdash M \Leftarrow B}{\Gamma \vdash \lambda x. M \Rightarrow A \rightarrow B} (\rightarrow\text{-intro}) \\
\\
\frac{\Gamma \vdash M \Leftarrow A \rightarrow B \quad \Gamma \vdash N \Leftarrow A}{\Gamma \vdash MN \Rightarrow B} (\rightarrow\text{-elim}) \\
\\
\frac{\Gamma, x : A \vdash y \Leftarrow B \quad \Gamma \vdash t \Leftarrow A}{\Gamma \vdash (\lambda x. y)t \equiv y[t/x] : B} (\rightarrow\text{-}\beta) \quad \frac{\Gamma, y : A \vdash My \equiv M'y : B}{\Gamma \vdash M \equiv M' : A \rightarrow B} (\rightarrow\text{-}\eta) \\
\\
\frac{\Gamma \vdash A \equiv A' \text{ type} \quad \Gamma \vdash B \equiv B' \text{ type}}{\Gamma \vdash A \rightarrow B \equiv A' \rightarrow B' \text{ type}} (\rightarrow\text{-}\equiv_{\text{type}}\text{-cong}) \\
\\
\frac{\Gamma, x : A \vdash M \equiv M' : B}{\Gamma \vdash \lambda x. M \equiv \lambda x. M' : A \rightarrow B} (\rightarrow\text{-}\equiv_{\text{term}}\text{-cong}) \\
\\
\frac{\Gamma \vdash M \equiv M' : A \rightarrow B \quad \Gamma \vdash N \equiv N' : A}{\Gamma \vdash MN \equiv M'N' : A \rightarrow B} (\rightarrow\text{-elim-cong})
\end{array}$$

A.7 Product type

$$\begin{array}{c}
\frac{\Gamma \vdash A \text{ type} \quad \Gamma \vdash B \text{ type}}{\Gamma \vdash A \times B \text{ type}} (\times\text{-form}) \quad \frac{\Gamma \vdash a \Leftarrow A \quad \Gamma \vdash b \Leftarrow B}{\Gamma \vdash (a, b) \Rightarrow A \times B} (\times\text{-intro}) \\
\\
\frac{\Gamma \vdash t \Leftarrow A \times B}{\Gamma \vdash \text{fst}(t) \Rightarrow A} (\times\text{-elim}_1) \quad \frac{\Gamma \vdash t \Leftarrow A \times B}{\Gamma \vdash \text{snd}(t) \Rightarrow B} (\times\text{-elim}_2) \\
\\
\frac{\Gamma \vdash x \Leftarrow A \quad \Gamma \vdash y \Leftarrow B}{\Gamma \vdash \text{fst}(x, y) \equiv x : A} (\times\text{-}\beta_1) \quad \frac{\Gamma \vdash x \Leftarrow A \quad \Gamma \vdash y \Leftarrow B}{\Gamma \vdash \text{snd}(x, y) \equiv y : B} (\times\text{-}\beta_2) \\
\\
\frac{\Gamma \vdash \text{fst}(t) \equiv \text{fst}(t') : A \quad \Gamma \vdash \text{snd}(t) \equiv \text{snd}(t') : B}{\Gamma \vdash t \equiv t' : A \times B} (\times\text{-}\eta)
\end{array}$$

$$\frac{\Gamma \vdash A \equiv A' \text{ type} \quad \Gamma \vdash B \equiv B' \text{ type}}{\Gamma \vdash A \times B \equiv A' \times B' \text{ type}} (\times\text{-}\equiv_{\text{type}}\text{-cong})$$

$$\frac{\Gamma \vdash a \equiv a' : A \quad \Gamma \vdash b \equiv b' : B}{\Gamma \vdash (a, b) \equiv (a', b') : A \times B} (\times\text{-}\equiv_{\text{term}}\text{-cong})$$

$$\frac{\Gamma \vdash t \equiv t' : A \times B}{\Gamma \vdash \text{fst}(t) \equiv \text{fst}(t') : A} (\times\text{-elim}_1\text{-cong})$$

$$\frac{\Gamma \vdash t \equiv t' : A \times B}{\Gamma \vdash \text{snd}(t) \equiv \text{snd}(t') : B} (\times\text{-elim}_2\text{-cong})$$

A.8 Unit type

$$\frac{}{\mathbf{1} \text{ type}} (\mathbf{1}\text{-form}) \quad \frac{}{\Gamma \vdash * \Rightarrow \mathbf{1}} (\mathbf{1}\text{-intro})$$

B Extended simply typed lambda calculus

B.1 Natural numbers

$$\frac{}{\Gamma \vdash \mathbb{N} \text{ type}} (\mathbb{N}\text{-form})$$

$$\frac{}{\Gamma \vdash 0 \Rightarrow \mathbb{N}} (\mathbb{N}\text{-intro}_1) \quad \frac{\Gamma \vdash n \Leftarrow \mathbb{N}}{\Gamma \vdash s(n) \Rightarrow \mathbb{N}} (\mathbb{N}\text{-intro}_2)$$

$$\frac{\Gamma \vdash f \Leftarrow \mathbb{N} \rightarrow A \rightarrow A \quad \Gamma \vdash c \Leftarrow A}{\Gamma \vdash \mathbf{ind}_{\mathbb{N}}(f, c) \Rightarrow \mathbb{N} \rightarrow A} (\mathbb{N}\text{-elim})$$

$$\frac{\Gamma \vdash f \Leftarrow \mathbb{N} \rightarrow A \rightarrow A \quad \Gamma \vdash c \Leftarrow A}{\Gamma \vdash \mathbf{ind}_{\mathbb{N}}(f, c)(0) \equiv c : A} (\mathbb{N}\text{-comp}_1)$$

$$\frac{\Gamma \vdash f \Leftarrow \mathbb{N} \rightarrow A \rightarrow A \quad \Gamma \vdash c \Leftarrow A \quad \Gamma \vdash n \Leftarrow \mathbb{N}}{\Gamma \vdash \mathbf{ind}_{\mathbb{N}}(f, c)(s(n)) \equiv f(n)(\mathbf{ind}_{\mathbb{N}}(f, c)(n)) : A} (\mathbb{N}\text{-comp}_2)$$

B.2 Empty type

$$\frac{}{\Gamma \vdash \mathbf{0} \text{ type}} (\mathbf{0}\text{-form}) \quad \frac{\Gamma \vdash A \text{ type}}{\Gamma \vdash \mathbf{ind}_{\mathbf{0}} \Rightarrow \mathbf{0} \rightarrow A} (\mathbf{0}\text{-elim})$$

B.3 Sum type

$$\frac{\Gamma \vdash A \text{ type} \quad \Gamma \vdash B \text{ type}}{\Gamma \vdash A + B \text{ type}} (+\text{-form})$$

$$\frac{\Gamma \vdash a \Leftarrow A}{\Gamma \vdash \text{inl}(a) \Rightarrow A + B} (+\text{-intro}_1)$$

$$\frac{\Gamma \vdash b \Leftarrow B}{\Gamma \vdash \text{inr}(b) \Rightarrow A + B} (+\text{-intro}_2)$$

$$\frac{\Gamma \vdash f \Leftarrow A \rightarrow C \quad \Gamma \vdash g \Leftarrow B \rightarrow C}{\Gamma \vdash \mathbf{ind}_+(f, g) \Rightarrow A + B} (+\text{-elim})$$

$$\frac{\Gamma \vdash a \Leftarrow A \quad \Gamma \vdash f \Leftarrow A \rightarrow C \quad \Gamma \vdash g \Leftarrow B \rightarrow C}{\Gamma \vdash \mathbf{ind}_+(f, g)(\text{inl}(a)) \equiv f(a) : C} (+\beta_1)$$

$$\frac{\Gamma \vdash b \Leftarrow B \quad \Gamma \vdash f \Leftarrow A \rightarrow C \quad \Gamma \vdash g \Leftarrow B \rightarrow C}{\Gamma \vdash \mathbf{ind}_+(f, g)(\text{inr}(b)) \equiv g(b) : C} (+\beta_2)$$

C Examples

C.1 η -rule

$$\begin{array}{c}
\begin{array}{c}
(\times\text{-elim}_1) \frac{\Gamma \vdash t \Leftarrow A \times B}{\Gamma \vdash \text{fst}(t) \Rightarrow A} \quad \frac{\Gamma \vdash t \Leftarrow A \times B}{\Gamma \vdash \text{snd}(t) \Rightarrow B} (\times\text{-elim}_2) \quad (\times\text{-elim}_1) \frac{\Gamma \vdash t \Leftarrow A \times B}{\Gamma \vdash \text{fst}(t) \Rightarrow A} \quad \frac{\Gamma \vdash t \Leftarrow A \times B}{\Gamma \vdash \text{snd}(t) \Rightarrow B} (\times\text{-elim}_2) \\
(\text{cswitch}) \frac{\Gamma \vdash \text{fst}(t) \Leftarrow A}{\Gamma \vdash \text{fst}(t) \Leftarrow A} \quad \frac{\Gamma \vdash \text{snd}(t) \Leftarrow B}{\Gamma \vdash \text{snd}(t) \Leftarrow B} (\text{cswitch}) \quad (\text{cswitch}) \frac{\Gamma \vdash \text{fst}(t) \Leftarrow A}{\Gamma \vdash \text{fst}(t) \Leftarrow A} \quad \frac{\Gamma \vdash \text{snd}(t) \Leftarrow B}{\Gamma \vdash \text{snd}(t) \Leftarrow B} (\text{cswitch}) \\
(\times\text{-}\beta_1) \frac{\Gamma \vdash \text{fst}(\text{fst}(t), \text{snd}(t)) \equiv \text{fst}(t) : A \times B}{\Gamma \vdash (\text{fst}(t), \text{snd}(t)) \equiv t : A \times B} \quad \frac{\Gamma \vdash \text{snd}(\text{fst}(t), \text{snd}(t)) \equiv \text{snd}(t) : A \times B}{\Gamma \vdash (\text{fst}(t), \text{snd}(t)) \equiv t : A \times B} (\times\text{-}\beta_2) \\
(\times\text{-}\eta) \frac{}{\Gamma \vdash (\text{fst}(t), \text{snd}(t)) \equiv t : A \times B}
\end{array}
\end{array}$$

C.2 Function application $\lambda x. \lambda y. xy$

$$\begin{array}{c}
\overline{\Gamma, x : A, y : C \vdash y \Leftarrow C} \quad (\dagger) \\
(\text{var}) \frac{x : A \in \Gamma, x : A, y : C}{\overline{\Gamma, x : A, y : C \vdash x \Rightarrow A}} \quad \frac{}{\overline{\Gamma, x : A, y : C \vdash C \rightarrow D \equiv A \text{ type}}} (***) \quad \vdots \\
(\rightarrow\text{-elim}) \frac{\Gamma, x : A, y : C \vdash x \Leftarrow C \rightarrow D}{\vdots} \quad \overline{\Gamma, x : A, y : C \vdash D \equiv D \text{ type}} \quad (\equiv_{\text{type-refl}}) \\
(\text{switch}) \frac{\Gamma, x : A, y : C \vdash xy \Rightarrow D}{(\rightarrow\text{-intro}) \frac{\Gamma, x : A, y : C \vdash xy \Leftarrow D}{\Gamma, x : A \vdash \lambda y. xy \Rightarrow C \rightarrow D}} \quad \overline{\Gamma, x : A \vdash B \equiv C \rightarrow D \text{ type}} \quad (***) \\
(\text{switch}) \frac{\Gamma, x : A \vdash \lambda y. xy \Leftarrow B}{(\rightarrow\text{-intro}) \frac{\Gamma \vdash \lambda x. \lambda y. xy \Rightarrow A \rightarrow B}{\Gamma \vdash \lambda x. \lambda y. xy \Leftarrow T}} \quad \overline{\Gamma \vdash T \equiv A \rightarrow B \text{ type}} \quad (*)
\end{array}$$

C.3 Function composition $\lambda x.\lambda y.\lambda z.x(yz)$

$$\begin{array}{c}
 \begin{array}{c}
 \text{(var)} \frac{(z : A) \in \Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A}{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash z \Rightarrow A} \quad \text{(var)} \frac{(y : A \rightarrow B) \in \Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A}{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash y \Rightarrow A \rightarrow B} \\
 \text{(cswitch)} \frac{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash z \Rightarrow A \quad \Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash y \Rightarrow A \rightarrow B}{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash yz \Rightarrow B} \quad \text{(cswitch)} \frac{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash z \Leftarrow A \quad \Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash y \Leftarrow A \rightarrow B}{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash yz \Leftarrow B} \\
 \text{(\(\rightarrow\)-elim)} \frac{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash yz \Rightarrow B \quad \Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash yz \Leftarrow B}{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash yz \Leftarrow B} \text{(cswitch)}
 \end{array} \\
 \\
 \begin{array}{c}
 \text{(var)} \frac{(x : B \rightarrow C) \in \Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A}{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash x \Rightarrow B \rightarrow C} \quad \vdots \\
 \text{(cswitch)} \frac{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash x \Rightarrow B \rightarrow C \quad \vdots}{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash x \Leftarrow B \rightarrow C} \quad \vdots \\
 \text{(\(\rightarrow\)-elim)} \frac{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash x \Leftarrow B \rightarrow C}{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash x(yz) \Rightarrow C} \\
 \text{(cswitch)} \frac{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash x(yz) \Rightarrow C}{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash x(yz) \Leftarrow C} \\
 \text{(\(\rightarrow\)-intro)} \frac{\Gamma, x : B \rightarrow C, y : A \rightarrow B, z : A \vdash x(yz) \Leftarrow C}{\Gamma, x : B \rightarrow C, y : A \rightarrow B \vdash \lambda z.x(yz) \Rightarrow A \rightarrow C} \\
 \text{(cswitch)} \frac{\Gamma, x : B \rightarrow C, y : A \rightarrow B \vdash \lambda z.x(yz) \Rightarrow A \rightarrow C}{\Gamma, x : B \rightarrow C, y : A \rightarrow B \vdash \lambda z.x(yz) \Leftarrow A \rightarrow C} \\
 \text{(\(\rightarrow\)-intro)} \frac{\Gamma, x : B \rightarrow C \vdash \lambda y.\lambda z.x(yz) \Rightarrow (A \rightarrow B) \rightarrow (A \rightarrow C)}{\Gamma, x : B \rightarrow C \vdash \lambda y.\lambda z.x(yz) \Leftarrow (A \rightarrow B) \rightarrow (A \rightarrow C)} \\
 \text{(cswitch)} \frac{\Gamma, x : B \rightarrow C \vdash \lambda y.\lambda z.x(yz) \Leftarrow (A \rightarrow B) \rightarrow (A \rightarrow C)}{\Gamma \vdash \lambda x.\lambda y.\lambda z.x(yz) \Rightarrow (B \rightarrow C) \rightarrow (A \rightarrow B) \rightarrow (A \rightarrow C)} \\
 \text{(cswitch)} \frac{\Gamma \vdash \lambda x.\lambda y.\lambda z.x(yz) \Rightarrow (B \rightarrow C) \rightarrow (A \rightarrow B) \rightarrow (A \rightarrow C)}{\Gamma \vdash \lambda x.\lambda y.\lambda z.x(yz) \Leftarrow (B \rightarrow C) \rightarrow (A \rightarrow B) \rightarrow (A \rightarrow C)}
 \end{array}
 \end{array}$$

C.4 Curryng $\lambda x.\lambda y.\lambda z.x(y, z)$

$$\begin{array}{c}
\begin{array}{c}
\text{(var)} \frac{(y : A) \in \Gamma, x : A \times B \rightarrow C, y : A, z : B}{\Gamma, x : A \times B \rightarrow C, y : A, z : B \vdash y \Rightarrow A} \quad \text{(var)} \frac{(z : B) \in \Gamma, x : A \times B \rightarrow C, y : A, z : B}{\Gamma, x : A \times B \rightarrow C, y : A, z : B \vdash z \Rightarrow B} \\
\text{(cswitch)} \frac{}{\Gamma, x : A \times B \rightarrow C, y : A, z : B \vdash y \Leftarrow A} \quad \text{(cswitch)} \frac{}{\Gamma, x : A \times B \rightarrow C, y : A, z : B \vdash z \Leftarrow B} \\
\text{(\(\times\)-intro)} \frac{}{\Gamma, x : A \times B \rightarrow C, y : A, z : B \vdash (y, z) \Rightarrow A \times B}
\end{array} \\
\text{(cswitch)} \frac{}{\Gamma, x : A \times B \rightarrow C, y : A, z : B \vdash (y, z) \Leftarrow A \times B} \\
\begin{array}{c}
\text{(var)} \frac{(x : A \times B \rightarrow C) \in \Gamma, x : A \times B \rightarrow C, y : A, z : B}{\Gamma, x : A \times B \rightarrow C, y : A, z : B \vdash x \Rightarrow A \times B \rightarrow C} \quad \vdots \\
\text{(cswitch)} \frac{}{\Gamma, x : A \times B \rightarrow C, y : A, z : B \vdash x \Leftarrow A \times B \rightarrow C} \quad \vdots \\
\text{(\(\rightarrow\)-elim)} \frac{}{\Gamma, x : A \times B \rightarrow C, y : A, z : B \vdash x(y, z) \Rightarrow C} \\
\text{(cswitch)} \frac{}{\Gamma, x : A \times B \rightarrow C, y : A, z : B \vdash x(y, z) \Leftarrow C} \\
\text{(\(\rightarrow\)-intro)} \frac{}{\Gamma, x : A \times B \rightarrow C, y : A \vdash \lambda z.x(y, z) \Rightarrow B \rightarrow C} \\
\text{(cswitch)} \frac{}{\Gamma, x : A \times B \rightarrow C, y : A \vdash \lambda z.x(y, z) \Leftarrow B \rightarrow C} \\
\text{(\(\rightarrow\)-intro)} \frac{}{\Gamma, x : A \times B \rightarrow C \vdash \lambda y.\lambda z.x(y, z) \Rightarrow A \rightarrow B \rightarrow C} \\
\text{(cswitch)} \frac{}{\Gamma, x : A \times B \rightarrow C \vdash \lambda y.\lambda z.x(y, z) \Leftarrow A \rightarrow B \rightarrow C} \\
\text{(\(\rightarrow\)-intro)} \frac{}{\Gamma \vdash \lambda x.\lambda y.\lambda z.x(y, z) \Rightarrow (A \times B \rightarrow C) \rightarrow A \rightarrow B \rightarrow C} \\
\text{(cswitch)} \frac{}{\Gamma \vdash \lambda x.\lambda y.\lambda z.x(y, z) \Leftarrow (A \times B \rightarrow C) \rightarrow A \rightarrow B \rightarrow C}
\end{array}
\end{array}$$

C.5 Uncurry

$$\begin{array}{c}
\begin{array}{c}
\text{(var)} \\
\text{(cswitch)} \\
\text{(\(\rightarrow\)-elim)}
\end{array}
\frac{
\frac{
\frac{
(y : A \times B) \in \Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \\
\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash y \Rightarrow A \times B \quad \text{(var)} \\
\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash y \Leftarrow A \times B \quad \text{(cswitch)}
}{\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash \text{fst}(y) \Rightarrow A} \quad \text{(\(\times\)-elim}_1\text{)} \\
\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash \text{fst}(y) \Leftarrow A \quad \text{(cswitch)}
}{\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash x(\text{fst}(y)) \Rightarrow A} \\
\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash x(\text{fst}(y)) \Leftarrow A \quad \text{(cswitch)}
\end{array}$$

$$\begin{array}{c}
\vdots \\
\vdots \\
\vdots \\
\vdots \\
\text{(\(\rightarrow\)-elim)} \\
\text{(cswitch)} \\
\text{(\(\rightarrow\)-intro)} \\
\text{(cswitch)} \\
\text{(\(\rightarrow\)-intro)} \\
\text{(cswitch)}
\end{array}
\frac{
\frac{
\frac{
\frac{
(y : A \times B) \in \Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \\
\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash y \Rightarrow A \times B \quad \text{(var)} \\
\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash \text{snd}(y) \Leftarrow B \quad \text{(cswitch)} \\
\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash \text{snd}(y) \Rightarrow B \quad \text{(\(\times\)-elim}_2\text{)} \\
\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash \text{snd}(y) \Leftarrow B \quad \text{(cswitch)}
}{\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash x(\text{fst}(y))(\text{snd}(y)) \Rightarrow C} \\
\Gamma, x : A \rightarrow B \rightarrow C, y : A \times B \vdash x(\text{fst}(y))(\text{snd}(y)) \Leftarrow C \\
\Gamma, x : A \rightarrow B \rightarrow C \vdash \lambda y. \vdash x(\text{fst}(y))(\text{snd}(y)) \Rightarrow A \times B \rightarrow C \\
\Gamma, x : A \rightarrow B \rightarrow C \vdash \lambda y. \vdash x(\text{fst}(y))(\text{snd}(y)) \Leftarrow A \times B \rightarrow C \\
\Gamma \vdash \lambda x. \lambda y. \vdash x(\text{fst}(y))(\text{snd}(y)) \Rightarrow (A \rightarrow B \rightarrow C) \rightarrow A \times B \rightarrow C \\
\Gamma \vdash \lambda x. \lambda y. \vdash x(\text{fst}(y))(\text{snd}(y)) \Leftarrow (A \rightarrow B \rightarrow C) \rightarrow A \times B \rightarrow C
\end{array}$$