
# High Performance Computing with Python

## Final Report

Jonas Bürgel

5500163

jonas.buergel@mail.de

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# Contents

# 1

# Introduction

# 2

# Methods

## 2.1 Probability Density Function (PDF)

The Probability Density Function (PDF) is a concept that describes the probability of finding a particle at a certain position. In this project, the PDF is used to track the individual trajectories of particles in phase space. Usually this would require solving a very large number of equations. Because solving these equations would be too costly, only the averages over the volumes in the phase space are taken using the PDF. The PDF, denoted as $f(\mathbf{r}_i, \mathbf{v}_i, t)$, represents the probability density of finding a particle at a certain position $\mathbf{r_i}$ and velocity $\mathbf{v_i}$ at a given time $t$.

## 2.2 Boltzmann Transport Equation (BTE)

The equation formulates the evolution of motion for the PDF over time. The Boltzmann Transport Equation (BTE) consists of two parts. The first part is *streaming* and resembles only the moving of particles. The second part is called *collision* and deals with the interaction between particles while moving.

### 2.2.1 Streaming

The probability density of the PDF is able to move, which is described by the Boltzmann Transport Equation (BTE). BTE transports the probability density distributions at a specific velocity in real space. While transporting, the influence of the velocity and acceleration are considered. The combined effect of velocity and acceleration leads to the streaming of density.

The whole Boltzmann Transport Equation is denoted as

$$\frac{\partial f\left(\mathbf{r}, \mathbf{v}, t\right)}{\partial t} + \mathbf{v}\nabla_{\mathbf{r}} f\left(\mathbf{r}, \mathbf{v}, t\right) + \mathbf{a}\nabla_{\mathbf{v}} f\left(\mathbf{r}, \mathbf{v}, t\right) = C(f)\cdot \tag{2.1}$$

The l.h.s. of the equation denotes the streaming part that was just explained and the r.h.s. the collision, explained in the following part.

### 2.2.2 Collision

Only applying streaming resembles a probability of collision of 0%, which is not realistic. To account for collisions, an additional term is introduced into the equation to represent the collision process that occurs at each time step. In reality, collisions between particles result in an almost instantaneous exchange of energy and momentum. However, these collisions occur in extremely short time intervals on the order of femtoseconds ($10^{-15}$ seconds), making it impractical to measure them directly in the model. Therefore, the collision process is approximated as an instantaneous process. Because of this instantaneous, it cannot be represented as a differential equation, which normally describes continuous changes. Instead, a probabilistic approach is taken to describe the effects of collisions.

In the previous section 2.2.1, the Boltzmann Transport Equation (BTE) was introduced (eq. (2.1)), where the right term represents the collision process. To simplify this collision term, a relaxation time approximation is commonly used. This approximation assumes that the probability density function (PDF) $f(\mathbf{r}, \mathbf{v}, t)$ relaxes towards a local equilibrium distribution, denoted as $f^{eq}(\mathbf{r}, \mathbf{v}, t)$. By interpreting the streaming term as the total time derivative of the PDF, the BTE can be reformulated as follows:

$$\frac{d}{dt} f(\mathbf{r}, \mathbf{v}, t) = -\frac{f(\mathbf{r}, \mathbf{v}, t) - f^{eq}(\mathbf{r}, \mathbf{v}, t)}{\tau}. \tag{2.2}$$

The included equilibirum function can is denoted as

$$f_i^{eq}(\rho(\mathbf{r}), \mathbf{u}(\mathbf{r})) = w_i \rho(\mathbf{r}) \left[1 + 3\mathbf{c}_i \cdot \mathbf{u}(\mathbf{r}) + \frac{9}{2}(\mathbf{c}_i \cdot \mathbf{u}(\mathbf{r}))^2 - \frac{3}{2}|\mathbf{u}(\mathbf{r})|^2\right]. \tag{2.3}$$

The equilibrium function introduces some additional quantities, namely the density $\rho(\mathbf{r})$, velocity $\mathbf{u}(\mathbf{r})$ and $w_i$. $w_i$ is defined for a D2Q9 lattice as seen in eq. (2.4). The other two quantities can be calculated using the following formulas.

$$w_i = \left(\frac{4}{9}, \frac{1}{9}, \frac{1}{9}, \frac{1}{9}, \frac{1}{9}, \frac{1}{36}, \frac{1}{36}, \frac{1}{36}, \frac{1}{36}\right) \tag{2.4}$$

$$\rho(\mathbf{r}) = \sum_i f_i \tag{2.5}$$

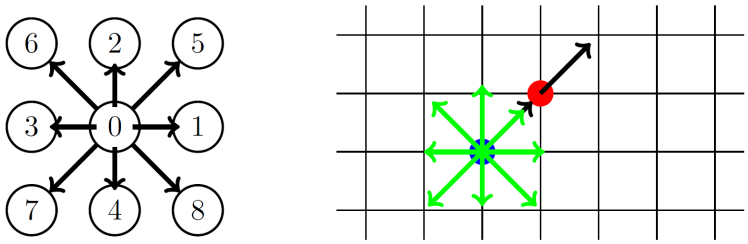
$$\mathbf{u}(\mathbf{r}) = \frac{1}{\rho(\mathbf{r})} \sum_i \mathbf{c}_i f_i(\mathbf{r}) \tag{2.6}$$

## 2.3 Lattice Bolzmann Scheme

In order to discretize the Boltzmann Transport Equation (BTE), it is necessary to incorporate both velocity and position space into the discrete scheme representation. An effective approach involves utilizing a 2D grid, as illustrated in fig. 2.1. The grid represents the position space as coordinates of the x and y coordinates.

Each position holds a probability density value, resembled by the value at that point. The velocities are included when introducing a third dimension, that separates the different streaming directions. To get the probability density function back, only the sum of all different directions in one point is needed. The probability density function can be reconstructed by simply summing the values for all different directions at a given point.

The streaming, as explained in section 2.2.1, is applied by moving the values of the points in one of 9 directions in their respective dimension. The collision process can be implemented by employing the functions described in section 2.2.2. During collisions, densities may be transferred between different dimensions within the scheme.




(a) (b)

Figure 2.1: Visualization of the underlying grid including labled directions.
(a) directions with given labels
(b) streaming example of one particle

# 3

# Implementation

## 3.1 Setup

This section deals with the topic of setting up this project and to navigate through it. It is intended to readers who want to run the experiments themselves or help to dig into the exact implementations.

### 3.1.1 Environement

This project was developed using pyenv and pip. Pyenv was selected due to its ability to create a virtual Python environment while still utilizing pip as the native package manager, distinguishing it from alternatives like anaconda.

The project's requirements are outlined in the requirements.txt file, and the desired Python version is specified in the .python-version file, generated by pyenv. To install the requirements, execute the following commands in the project's top directory within a Bash environment:

```
#!/bin/bash
pyenv install 3.11
pyenv local 3.11
source venv/bin/activate
pip install -r requirements.txt
```

### 3.1.2 Code Structure

The project consists of three primary folders: *src/shared*, *src/experiments*, and *tests*. The *tests* folder contains code dedicated to programmatic validation of the implementations, primarily comprising unit tests. The *src/shared* folder contains code that is shared among all experiments conducted in the

project. This includes implementations for streaming and collision in the lib file, among others. Lastly, the *src/experiments* folder contains experiment-specific code, including plotting functionalities tailored to each experiment.

## 3.2 Probability Density Function

The probability density function is modelled as a *numpy* array with 3 dimensions, namely: channels, x-direction and y-direction in this order. While the number of channels allways has to be exactly 9, the x and y dimensions may vary in size and are independent of each other. These constraints to the probability density function are assumed by all implemented functions and have to hold at all time.

The Probability density function follows the scheme described in section 2.3. While the grid in fig. 2.1 resembles the second and third dimension of the PDF, the channels can be imagined as a third dimension on the grid. Each channel resembles one direction of moving as shown in the left part of fig. 2.1. The indices of the channels are in line with the indices of the arrows in the graphic.

## 3.3 Main Routine

The main routine may be seen as a function that is repeated until the experiment is over. It consists of several operators that stay the same in each experiment. For some experiments, not all operators are used or for example the *bounce-back* is only applied to certain walls. **The order of the operators always stays the same and is crucial for a successive experiment**. All possible operators are listed below:

1. collision - handles colliding particles in the simulation
2. slide - applies a steady velocity to on side
3. bounce back - bounces particles back into from certain walls
4. stream - moves all particles

An interested reader may find the exact implementation in *src/shared/boltzmann.py*. As it is redundant and maybe not inline with the exact implementation there won't be code examples at this point. However, it is to mention that all examples follow strictly the formulas explained in chapter 2, so there is no special need in doing so.

# 4

# Results

## 4.1 Shear Wave Decay

The Shear Wave Decay is a common concept in computational physics to measure the kinematic viscosity of a fluid. It is set up by creating an initial sinusoidal velocity profile and measuring the decay rate. All Shear Wave Decay experiments were run with the same parameters as shown in table 4.1.

| Parameter | Value |
|---|---|
| $L_x$ | 100 |
| $L_y$ | 100 |
| $\epsilon$ | 0.01 |
| $t_{\max}$ | 1000 |

Table 4.1: Parameters for the Shear Wave Decay

### 4.1.1 Sinusodial Density

The initial condition is a given by the following equation where $L_x$ resembles the size in x-direction

$$\mathbf{u}(\mathbf{r}, 0) = 0$$
$$\rho(\mathbf{r}, 0) = \rho_0 + \epsilon \sin\left(\frac{2\pi x}{L_x}\right).$$

Because of the initialization the fluid is shaped like a sinusoid wave without any velocity. It is expected that this wave collapses in itself. This is due to the fact that the system tries to reach a state of equilibrium where the mass at each position is the same. Therefore, a flow is created from the higher density area to the lower density area. This flow continues until the mass at the previous lower density area is so dense, that no further flow is created. It now reached a state similar to the beginning however the

dense and low-dense areas swapped which is why the flow will have opposite directions in the next iteration. This process can be seen in fig. 4.1.

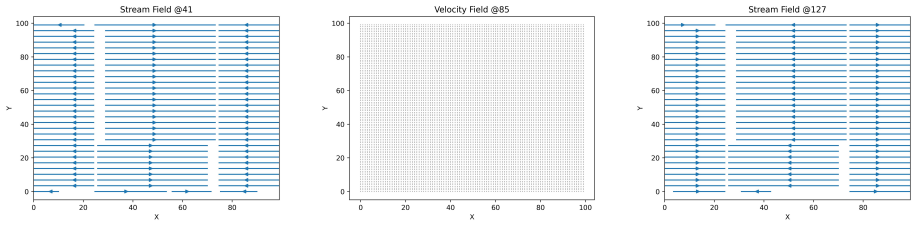



Figure 4.1: Different flow states during the simulation. From piling up at step 41 to a steady state at step 85 to the opposite flow at step 127.

This flow won't hold forever as the newly forming dense areas are always less dense as the once from the previous iteration. The system tries to reach an equilibrium. Over time the piles are shallower and shallower until it reaches the desired equilibrium function with the same density at all positions. The decay is shown through the plots in fig. 4.2.

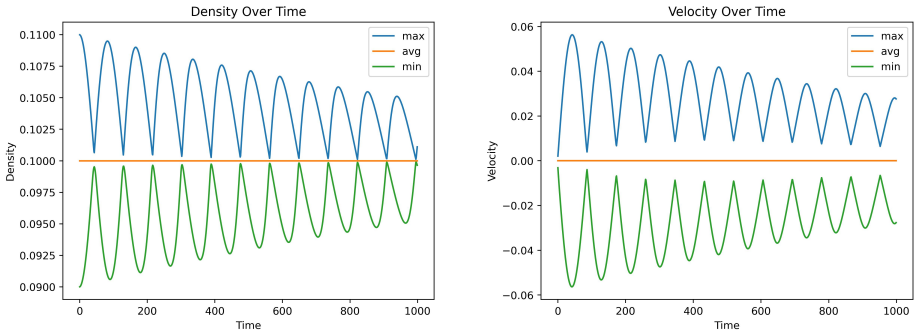



Figure 4.2: Decaying density and velocity over time.

### 4.1.2 Sinusodial Velocity

The initial condition is a given by the following equation where $L_x$ resembles the size in x-direction and $\epsilon$ resembles the initial amplitude

$$u_x(\mathbf{r}, 0) = \epsilon \sin\left(\frac{2\pi x}{L_x}\right)$$
$$\rho(\mathbf{r}, 0) = 1\cdot$$

# 5

# Conclusion

# 6

# Chapter 1

This is an example of a citation [1]. The corresponding paper can be found in the bibliography section at the end of this document.

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Example of normal equation

$$f_i(\mathbf{x}_j + \mathbf{c}_i \cdot \Delta t, t + \Delta t) = f_i(\mathbf{x}_j, t) - \omega \left( f_i(\mathbf{x}_j, t) - f_i^{\mathrm{eq}}(\mathbf{x}_j, t) \right) \tag{6.1}$$

Example of aligned equation:

$$\rho(\mathbf{x}_j, t) = \sum_i f_i(\mathbf{x}_j, t) \tag{6.2}$$

$$\mathbf{u}(\mathbf{x}_j, t) = \frac{1}{\rho(\mathbf{x}_j, t)} \sum_i \mathbf{c}_i f_i(\mathbf{x}_j, t) \tag{6.3}$$

## 6.1 section title

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- Example of a list
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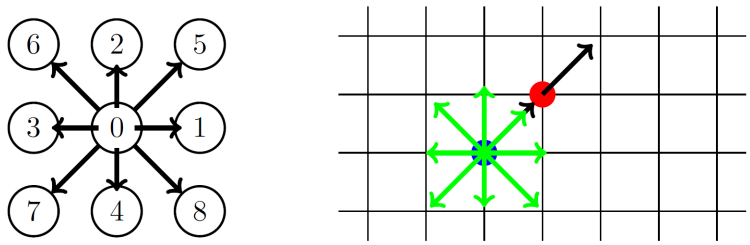
# 7

# Chapter 2




(a) (b)

Figure 7.1: example figure

## 7.1 Section title

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Table 7.1: Sample table

| S. No. | Column#1 | Column#2 | Column#3 |
|---|---|---|---|
| 1 | 50 | 837 | 970 |
| 2 | 47 | 877 | 230 |
| 3 | 31 | 25 | 415 |
| 4 | 35 | 144 | 2356 |
| 5 | 45 | 300 | 556 |

## 7.2 Code listing

here we provide a short example of code listing. For further information you can take look here:

`https://www.overleaf.com/learn/latex/code_listing`

This is just meant to used if you think that there is some relevant part of code to be shown. Please do not append your whole implementation in the report.

```
import numpy as np

def incmatrix(genl1,genl2):
    m = len(genl1)
    n = len(genl2)
    M = None # to become the incidence matrix
    VT = np.zeros((n*m,1), int)  # dummy variable
```

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# Bibliography

[1] Krüger Timm, H Kusumaatmaja, A Kuzmin, O Shardt, G Silva, and E Viggen. *The lattice Boltzmann method: principles and practice.* Springer: Berlin, Germany, 2016.