

# Bill of materials

| Item                                    | Total price (\$) | Remarks   |
|---|------------------|---|
| <a href="#">LEGO bricks</a>             | ~60              | I recommend buying extra bricks in different sizes.   |
| <a href="#">Raspberry Pi</a>            | 10-50            | Any model works.  |
| <a href="#">Raspberry Pi camera</a>     | 25               |   |
| <a href="#">Camera flex cable</a>       | 3                | A long cable (>40cm) is preferred if the Raspberry Pi cannot be placed closer to the camera.                        |
| <a href="#">Magnifying lens</a>         | 10               | M12 thread  |
| <a href="#">Micro SD card</a>           | 10               | Raspberry Pi operating system. Minimum 16GB is recommended.   |
| <a href="#">HDMI display</a>            | 50-150           | Optional if an HDMI display is already available. The price varies depending on the size and the model.             |
| <a href="#">Arduino board</a> x2        | 20               | One for the mainboard, one for the controller. Any Arduino board with enough number of IO pins should work.         |
| <a href="#">Stepper motor driver</a> x6 | 30               | Any other 5V compatible driver should work. Microstepping was not needed in this project.                           |
| <a href="#">Stepper motor</a> x6        | 15               | 28BYJ-48, 5V, 1/64 gear ratio   |
| <a href="#">JST-XH 5P 4S cables</a>     | 7                | A few of these cables are required to extend the default cable of the stepper motor (28BYJ-48)                      |
| <a href="#">High-power LED</a>          | 4                |   |
| <a href="#">High-power LED driver</a>   | 14               |   |
| <a href="#">Light diffuser</a>          | 3                | An LED backlight module is modified by replacing the low-power LED by a high-power one                              |
| <a href="#">Potentiometer</a>           | 1                | LED intensity control using pulse-width modulation.   |
| <a href="#">Thumb joysticks</a> x3      | 12               | Three joysticks for X, Y, Z, Camera, Tilt, and Rotation.  |
| <a href="#">5V power supply</a>         | 20               | At least 3A is preferred. A more powerful supply may be needed if the display is also powered from the same supply. |
| <a href="#">DC-DC converter</a>         | 3                | In case the LED and its driver require more than 5V.  |
| <a href="#">OLED display</a>            | 3                | Displays the LED intensity or any other information on the controller.  |
| <a href="#">USB connector</a> (type A)  | 0.5              | Connection between the mainboard and the controller (mainboard side).   |
| <a href="#">USB connector</a> (micro)   | 0.5              | Connection between the mainboard and the controller (controller side).  |
| <a href="#">JST XH connector set</a>    | 5                | Connectors for the stepper motors and the LED   |
| <a href="#">DC barrel connector</a>     | 1                | In case a separate DC input (e.g. 12V) is needed for the LED  |
| <b>OVERALL TOTAL</b>                    | <b>~300</b>      |   |

- The prices and the links are for exemplary components that were used in this prototype.
- Any other compatible model should work in principle.
- The total price varies significantly depending on the vendor and the model. For example, the type of the Raspberry Pi and the display makes a big difference in the price.
- The cost of 3D-printed parts is not included.
- There are also a few other accessories needed, like USB cables, an HDMI cable, optionally a mouse and a keyboard, an ON/OFF switch, screws and nuts, and printed circuit boards (PCBs).