Week7

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```
[2]: # Importing neccesary libraries
import matplotlib.pyplot as plt
from matplotlib.animation import FuncAnimation
import numpy as np
```

1 Simulated Annealing on a mathematical function

```
[3]: '''
     * The following function SA is used to calculate the global optimal of any \Box
      ⇔single or multivariable function.
     * The function takes the argumenst func, stpoint, T, lr as required arguments and _{\sqcup}
      ⇔max_iter, tol as key arguments
         - func is the function whose global minima is to be caculated, the argument \sqcup
      ⇔should be a function
         - stpoint is the starting point from where we go to optima,
              the argument should be numpy array containg the starting point of the L
      \neg variables
         - T is temprature, argument should be a float or int
         - lr is the learning rate, argment should be a float
         - max_i iter is the number of iteration to reach the optima. (by default it is u
      \hookrightarrow taken 1000)
              - In case of optima not holding upto the tolerance specified this will _{\sqcup}
      \hookrightarrow number of times
              the Annealing is performed
         - tol argument is the tolearnce(by defalut 1e-6) that if crossed then \Box
      ⇔terminate the annealing to save time
     def SA(func, stpoint, T, lr, max_iter=1000, tol=1e-6):
         current_val = stpoint
```

```
current_cost = func(stpoint)
best_val = stpoint
best_cost = func(stpoint)
for i in range(max_iter):
    dx = (np.random.random_sample(*current_val.shape) - 0.5) * T
    new val = current val + dx
    new_cost = func(new_val)
    if new cost < current cost:</pre>
        current cost = new cost
        current_val = new_val
        if new_cost < best_cost:</pre>
            best_cost = new_cost
            best_val = new_val
    else:
        prob = np.exp(-(new_cost - current_cost) / T)
        if np.random.rand() < prob:</pre>
             current_cost = new_cost
             current_val = new_val
    T *= lr
    if T < tol:
        break
return best val, best cost
```

1.1 Approach

The logic is same as the shown in the Week7 Presentation, I have just generalized the function using numpy arrays so that the function can be performed on multivariable functions too.

1.2 Observations

- I have observed that learning rate and temprature play a important role in determing the optima for this method, if the learning rate is too small then the algorith will halt because (tolerance would have be crossed) before even reaching the minimum and if too large then it will overstep the minimum and halt (because number of iteration will run out).
- The temprature play role in determining the probability of wheter or not move to next state; thus taking too small of temprature will halt the algorithm as tolerance will break the algorithm before reaching the the optima as the probability will become zero, too large of temprature and the number of iterations will be less to reach the optima.
- Also it is noticied that the annealing returns diffrent values on repeated running this is due to fact that I am using np.random which while name suggest random has at the end some algoritm that doesn't generate the random number perfectly, also the number of iterations, Temprature, learning rate also play role as explained above so it is expected to get diffrent answers, the ideal case would be infinite number of iteration, 0 tolerance, and infinitely small learning rate which is pratically not possible and effective, but the answers will be nearby of optima.

Hence both temprature and learning rate should be kept in mind while using the Simulated Annealing

```
[4]: # Single variable example
def yfunc(x):
    return x**2 + np.sin(8*x)

x,y = SA(yfunc,np.array(-2),3,0.95)
print(f'Minimum value found: {y} at {x}')
```

Minimum value found: -0.9625919296336447 at -0.18955444346549477

```
[5]: # Two variable example
def yfunc2(x):
    return x[0]**2 + np.sin(8*x[1])

x,y = SA(yfunc2,np.array([-2,-2]),3,0.95)
print(f'Minimum value found: {y} at {x}')
```

Minimum value found: -0.9955813938860566 at [-0.06635419 -0.98104665]

2 Travelling Salesman Problem

```
[98]: '''
     Functions:
         * read cities
         ⇔cites from the file
         and returns a numpy array containig the same
         * pythagores
             - Takes two arguments A and B which are the cordinates of city A and \Box
       \hookrightarrow city B and returns
             the distance between them using pythagores theorm
         * total_distance
             - Takes two arguments a list of thesequence contains the order of \Box
       ⇒moment from city to city and
             second argument the cordinates of all the cities
             - This function returns the overall disatnce of path specified by \Box
       ⇔sequence travelled by the salesman
         * SA cities
             - Takes arguments the cordinates of all the cities, Temprature, learning \Box
       ⇔rate, and same key arguments
             as above and performs the simulated annealing on it.
             - This returns the sequence and distance of the path after simulation
     import random
```

```
def read_cities(file):
    with open(file, 'r') as f:
        number_of_cities = int(f.readline())
        cities = np.zeros((number_of_cities, 2))
        for i in range(number_of_cities):
            x, y = map(float, f.readline().split())
            cities[i] = [x, y]
    return cities
def pythagores(A,B):
    return np.sqrt(np.sum((A - B) ** 2))
def total_distance(sequence,cities_list):
    distance = 0
    for i in range(len(sequence)):
        distance +=_
 pythagores(cities_list[sequence[i]], cities_list[sequence[(i+1)%len(sequence)]])
    return distance
def rand(k,s):
    i = random.randint(k, s-1)
    j = random.randint(k,s-1)
    while(i==j):
        j = random.randint(k,s-1)
    return i,j
def change_path(order,i,j):
    \#i, j = random.sample(range(n), 2)
    'Reverses the order of cities between two cities i and j'
    return order[:i] + order[i:j+1][::-1] + order[j+1:]
def SA_cities(cities, T, lr, max_iter=10000, tol=1e-6):
    start = list(range(len(cities)))
    #random.shuffle(start)
    n = len(cities)
    best_val = start
    best_cost = total_distance(start,cities)
    for i in range(max_iter):
        \#dx = (np.random.random_sample(*current_val.shape) - 0.5) * T
        current_cost = total_distance(start,cities)
        #np.random.shuffle(start)
        k, j=rand(0,len(cities)-1)
        start = change_path(start,min(k,j),max(k,j))
        new val = start
        \#new\_val = current\_val + dx
        new_cost = total_distance(new_val,cities)
```

```
if new_cost < current_cost:
    current_cost = new_cost
    current_val = new_val
    if new_cost < best_cost:
        best_cost = new_cost
        best_val = new_val

else:
    prob = np.exp(-(new_cost - current_cost) / T)
    if np.random.rand() < prob:
        current_cost = new_cost
        current_val = new_val
    else:
        start = change_path(start,min(k,j),max(k,j))

T *= lr

return best_val, best_cost</pre>
```

2.1 Approach

- The algorithm as the simlar logic as the simulated annealing performed on a function, here first I assume the start sequence as the sequence given in file and the path length as the best_cost, the current_cost is the path legth of the previous order, then I use np.random.shuffle shuffles the sequence and calculate the new cost using pythagores function, and store the new sequence in new_val
- If the new cost turn out to be less then current cost then the probabilty to move to next state is one hence move to next state, if the new cost is less than best cost then update the variables otherwise continue
- In case that the new cost is more than current cost then use exponential to calculate the probabilty of wherether or not move to next state, if moving to next state the update the variable, here I dont change best cost because if it has not met first condional then its is by default not best cost

```
[99]: # For 10 cities
citys = read_cities('tsp_10.txt')
x,y = SA_cities(citys,4,0.95,max_iter=10000)
print(f'Order: {x}')
print()
print(f'Path lenght: {y}')
```

Order: [8, 2, 0, 6, 5, 4, 3, 1, 7, 9]

Path lenght: 34.076561394636684

```
[100]: # For 100 cities
    citys = read_cities('tsp_100.txt')
    x,y = SA_cities(citys,4,0.95)
    print(f'Order: {x}')
    print()
    print(f'Path lenght: {y}')
    # ls=[]
    # for i in range(1000):
    # x,y = SA_cities(citys,4,0.95)
```

Order: [18, 6, 76, 16, 88, 4, 61, 60, 94, 24, 63, 38, 57, 72, 92, 87, 45, 56, 68, 47, 51, 40, 74, 58, 75, 48, 49, 82, 46, 33, 32, 62, 10, 98, 13, 8, 26, 23, 85, 78, 67, 35, 77, 2, 5, 89, 41, 17, 73, 96, 64, 28, 91, 20, 66, 9, 83, 69, 43, 79, 70, 1, 44, 81, 37, 11, 59, 90, 71, 54, 53, 29, 97, 31, 55, 3, 22, 21, 36, 80, 7, 27, 14, 93, 30, 86, 25, 19, 15, 50, 42, 84, 12, 95, 0, 34, 39, 52, 65, 99]

Path lenght: 93.40420219372909

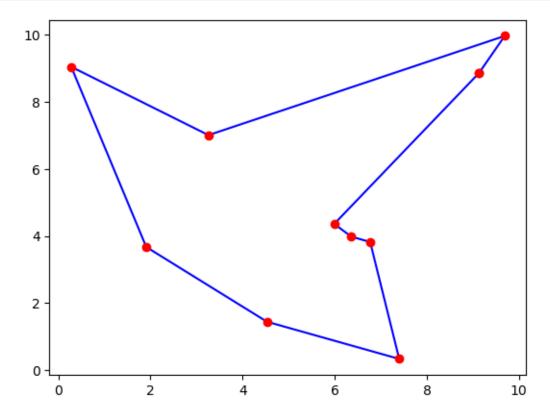
3 Animation and Plots

```
[101]: '''
       This is a function that animates the simulate annealing on one variable.
       The first few lines are simple setting the plot and marker.
       * SA_function Next: It is the exact copy-paste of above SA function,
       but here I have used yield instead of return key word so that I can iterate the \sqcup
        \hookrightarrow value \ when \ I \ pass \ it
       in the update23 function.Also return would have halt the program after 1_{\sqcup}
        \hookrightarrow iteration itself
       * init: It is a function to set the plot
       * update23: Function takes the point which is found using SA and updates the \sqcup
        \hookrightarrow list of point that are to be animated
       in the graph while keeping the previous points visible thus appendend the point \sqcup
        in the list, while the marker needs
       to appear moving it is instead of appendtion simply overitten by next value
       * Return the animation object
       %matplotlib notebook
       def animate_SA(func,start_point,T, lr, max_iterations=1000, tolerance=1e-6):
           fig, ax = plt.subplots()
```

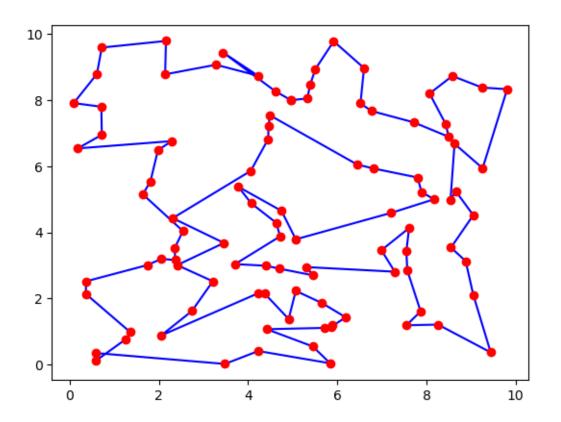
```
ax.set_xlim(-2, 2)
ax.set_ylim(-2, 5)
ax.set_xlabel("x")
ax.set_ylabel("f(x)")
ax.set_title("Simulate Annealing")
xdata, ydata = [], []
line, = ax.plot([], [], 'o', lw=2)
lngood, = ax.plot([], [], 'go', markersize=10)
x_vals = np.linspace(-10, 10, 1000)
y_vals = func(x_vals)
ax.plot(x_vals, y_vals, 'r')
def SA_function(func, stpoint, T, lr, max_iter=1000, tol=1e-6):
    current_val = stpoint
    current_cost = func(stpoint)
    best_val = stpoint
    best_cost = func(stpoint)
    yield best_val, best_cost
    for i in range(max_iter):
        dx = (np.random.random_sample(*current_val.shape) - 0.5) * T
        new_val = current_val + dx
        new_cost = func(new_val)
        yield new_val, new_cost
        if new_cost < current_cost:</pre>
            current_cost = new_cost
            current_val = new_val
            if new_cost < best_cost:</pre>
                best_cost = new_cost
                best_val = new_val
        else:
            prob = np.exp(-(new_cost - current_cost) / T)
            if np.random.rand() < prob:</pre>
                current_cost = new_cost
                current_val = new_val
        T *= 1r
        if T < tol:</pre>
```

```
break
           def init():
               line.set_data([], [])
               return line,
           def update(frame):
               x, y = frame
               xdata.append(x)
               ydata.append(y)
               line.set_data(xdata, ydata)
               lngood.set_data(x, y)
               return line,
           ani = FuncAnimation(fig, update, frames=SA function(func, start point, T, lr, u
        omax_iterations, tolerance), init_func=init, blit=True, repeat=False,interval⊔
        ⇒=100)
           dis = ani
           plt.show()
           return dis
[102]: animate_SA(yfunc,np.array(0),3,0.9)
      <IPython.core.display.Javascript object>
      <IPython.core.display.HTML object>
[102]: <matplotlib.animation.FuncAnimation at 0x16529f8b0>
[103]: '''
       Function to plot the cities, it takes the filename and uses the SA function to_{\sqcup}
        ⇔find the order of the cities
       and and plots it
       111
       def city_map(filename):
           citys = read_cities(filename)
           x_{,-} = SA_{cities}(citys, 4, 0.95)
           order = [citys[num] for num in x]
           x_values = [array[0] for array in order]
           y_values = [array[1] for array in order]
           x_values.append(x_values[0])
           y_values.append(y_values[0])
           plt.plot(x_values,y_values,'b')
           plt.plot(x_values,y_values,'ro')
```

```
[104]: %matplotlib inline city_map('tsp_10.txt')
```



```
[107]: city_map('tsp_100.txt')
```



[]: