数据科学与计算机学院

School of Data and Computer Science

Concepts of Embedded Systems

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Outline

- What is an Embedded System?
 - Examples
- Characteristics of Embedded Systems
 - Embedded Systems vs. General Purpose Systems
 - Embedded Systems vs. Cyber Physical systems
- Trends in Embedded Systems
- Embedded Systems Design
- Future of Embedded Systems



What is an Embedded System?

Many definitions exist:

Embedded Systems = Information processing systems embedded into a larger product.

-- Peter Marwedel, TU Dortmund

Embedded Software = Software integrated with physical processes. The technical problem is managing time and concurrency in computational systems.

-- Edward A. Lee, UC Berkeley



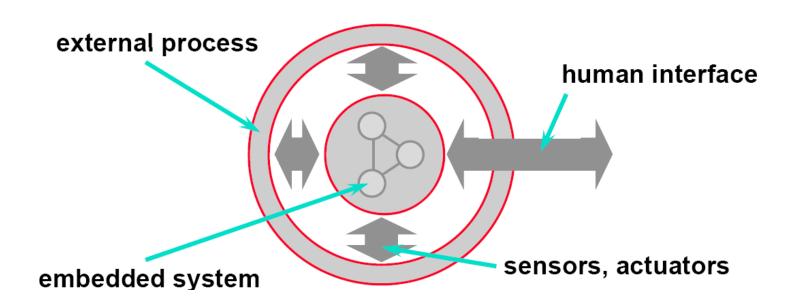
Yet Another Definition ...

Embedded Systems = Information processing systems that are:

- application domain specific (not general purpose)
- tightly coupled to their environment
- <u>Examples of application domains</u>: automotive electronics, avionics, multimedia, consumer electronics, etc.
- <u>Environment</u>: type and properties of input/output information.
- <u>Tightly coupled</u>: the environment dictates what the system's response behavior must be. ("ES cannot synchronize with environment")



Embedded Systems



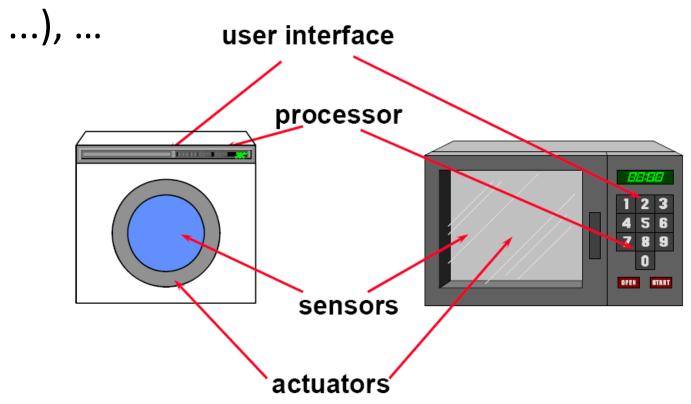
What they do:

- Sense environment(input signals)
- Process input information
- Respond in real-time (output signals)



Examples: Consumer Electronics

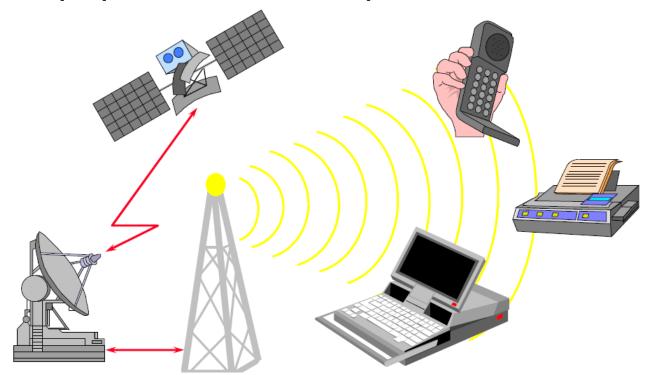
 MP3 audio, digital camera, Home electronics (washing machine, microwave cooker/oven,





Examples: Telecommunication

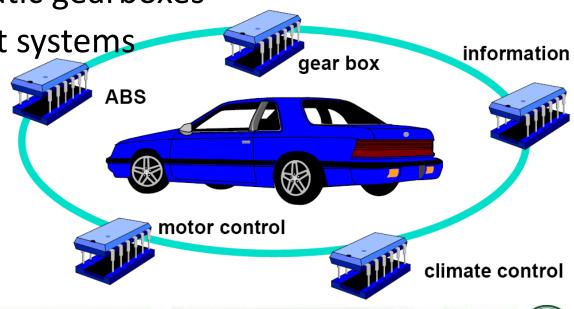
Wireless communication (GSM/3G base station, switch, router, access point, ...), enduser equipment, mobile phone...





Examples: Automotive Electronics

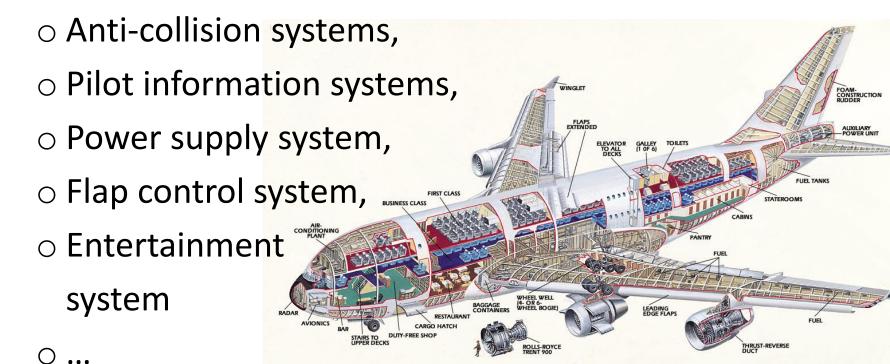
- A car is an integrated control, communication, and information system.
 - Anti-lock braking systems (ABS)
 - Electronic stability control
 - Efficient automatic gearboxes
 - Blind-angle alert systems
 - Airbags
 - O ...





Examples: Avionics

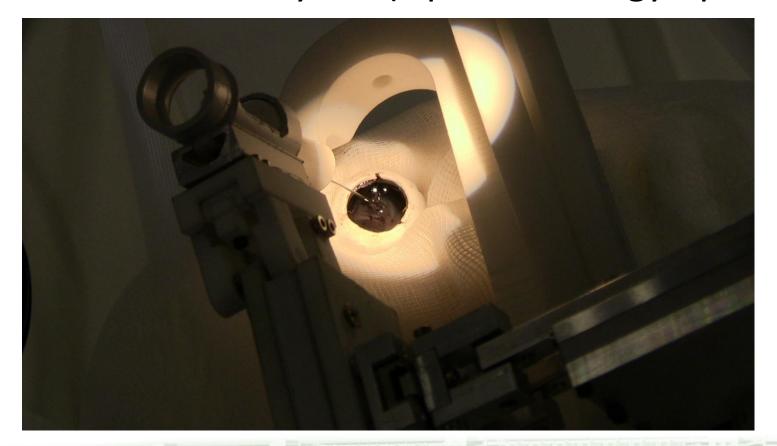
- A plan is another integrated control, communication, and information system.
 - Flight control systems,





Examples: Medical Systems

The future of surgery is not in blood and guts,
 but in bits and bytes. (Ophthalmology operation)



<u>Video</u>



Examples: Robotics

NASA Curiosity Rover

Curiosity Rover (Mars Science Lab) Length: 3m/10ft Weight: 900kg Width: 2.8m Mast height: 2.1m Arm reach:: 2.2m Robot arm and tool head

Sony Robotic Dog





Examples: Gaming



MS XBOX & Kinect



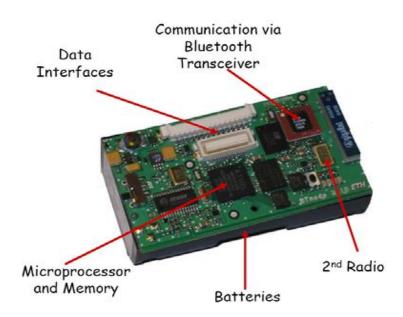


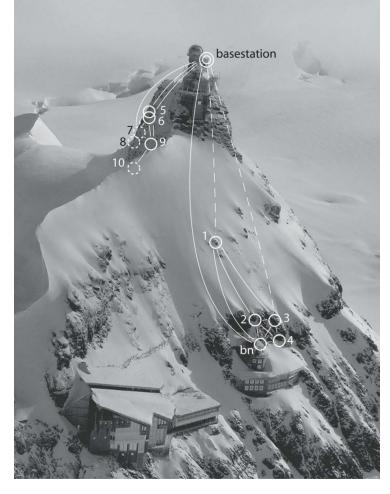


Examples: (Wireless) Sensor Network

 Sensor networks (civil engineering, buildings, environmental monitoring, traffic, emergency situations)

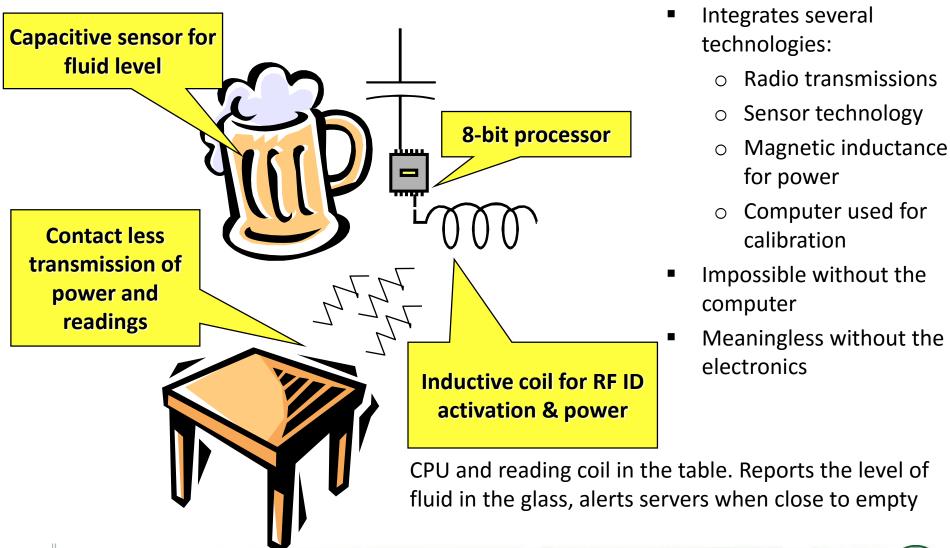
Smart products, wearable/ubiquitous computing







Smart Beer Glass



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Characteristics of Embedded Systems (1)

- Must be dependable
 - Reliability: R(t) = probability of a system working correctly at time t provided that it was working at t = 0
 - Maintainability: M(d) = probability of a system working correctly d time units after error occurred
 - Availability: A(t) = probability of system working at time t
 - Safety: no harm to be caused by failing system
 - Security: confidential and authentic communication
 - Even perfectly designed systems can fail if the assumptions about the workload and possible errors turn out to be wrong.
 - Making the system dependable must not be an after-thought, it must be considered from the very beginning.



Characteristics of Embedded Systems (2)

Must be efficient

- Energy efficient
 - Many ES are mobile systems powered by batteries
 - Customers expect long run-times from batteries but
 - Battery technology improves at a very slow rate
- Code-size efficient (especially for systems on a chip)
 - Typically there are no hard discs or huge memories to store code
- Run-time efficient
 - Meet time constraints with least amount of HW resources and energy – only necessary HW should be present working at as low as possible Vdd and fclk
- Weight efficient (especially for portable ES)
- Cost efficient (especially for high-volume ES)



Characteristics of Embedded Systems (3)

- Many ES must meet real-time constraints
 - A real-time system must react to stimuli from the controlled object (or the operator) within the time interval dictated by the environment.
 - For real-time systems, right answers arriving too late (or even too early) are wrong.

"A real-time constraint is called hard, if not meeting that constraint could result in a catastrophe" [Kopetz, 1997].

- All other time-constraints are called soft.
- A guaranteed system response has to be explained without statistical arguments.



Characteristics of Embedded Systems (4)

- ES are connected to physical environment through sensors and actuators.
- Hybrid Systems, i.e., composed of analog and digital parts
- Typically, ES are reactive systems

"A reactive system is one which is in continual interaction with is environment and executes at a pace determined by that environment" [Bergé, 1995].

- Behavior depends on input and current state.
 - > automata model appropriate



Characteristics of Embedded Systems (5)

- All ES are dedicated systems
 - Dedicated towards a certain application:
 - Knowledge about the behavior at design time can be used to minimize resources and to maximize robustness
 - O Dedicated user interface:
 - No mice, no large keyboards and monitors

Not every ES has all of the above characteristics, thus

We can define the term "Embedded System" as follows: Information processing systems having most of the above characteristics are called embedded systems.



Comparison

Embedded Systems

- Execute few applications that are known at design-time
- Non programmable by the end user
- Fixed run-time requirements (additional computing power not useful)
- Important criteria
 - Cost
 - Power consumption
 - Predictability
 - O ...

General Purpose Systems

- Execute broad class of applications
- Programmable by the end user
- Faster is better

- Important criteria
 - Cost
 - Average speed



Yet Another Name? Cyber-Physical Systems

Definition of Cyber-Physical System

- Defined by those with Money
 - Smart electric grid
 - Smart transportation
- Wikipedia
 - A full-fledged CPS is typically designed as a network of interacting elements with physical input and output instead of as standalone devices
- Cyber-Physical (cy-phy) Systems (CPS) are integrations of computation with physical processes [Edward Lee, 2006].
- Cyber-physical system (CPS) =
 Embedded System (ES) + physical environment



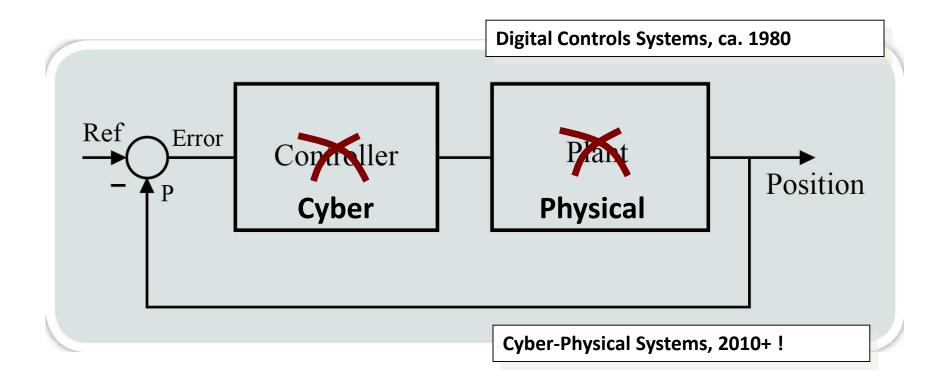
Cyber-Physical Systems and Embedded Systems

■ CPS = ES + physical environment

Cyber-physical systems **Embedded systems** ("computers in physical environments" Embedded systems ("small computers")

What is a Cyber-Physical System?

Extreme view:





Definition According to National Science Foundation (US)

- Cyber-physical systems (CPS) are engineered systems that are built from and depend upon the synergy of computational and physical components.
- Emerging CPS will be coordinated, distributed, and connected, and must be robust and responsive.
- The CPS of tomorrow will need to far exceed the systems of today in capability, adaptability, resiliency, safety, security, and usability.
- Examples of the many CPS application areas include the smart electric grid, smart transportation, smart buildings, smart medical technologies, next-generation air traffic management, and advanced manufacturing.
- http://www.nsf.gov/funding/pgm_summ.jsp?pims_id=503286



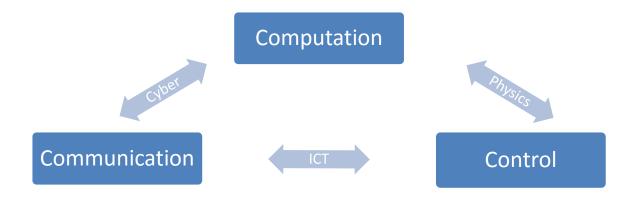
Definition According to Akatech

- The physical world and the virtual world or cyber-space are merging; cyber-physical systems are developing. Future cyber-physical systems will contribute to security, efficiency, comfort and health systems as never before, and as a result, they will contribute to solving key challenges of our society, such as the aging population, limited resources, mobility, or energy transition.
 - [Akatech: Cyber-Physical Systems. Driving force for innovation in mobility, health, energy and production, http://www.acatech.de/de/ publikationen/stellungnahmen/kooperationen/detail/artik el/cyber-physical-systems-innovationsmotor-fuermobilitaet-gesundheit-energie-und-produktion.html]



Cyber-Physical Systems vs. Embedded Systems

- More safe
- CPS = systems of (embedded) systems
 - ES is sub-system of CSP
- The 3C concept
 - Computation, communication, and control



New name for funding ...



Content of an Embedded Systems Course

- ES focus
 - Hardware interfacing
 - Interrupts
 - Memory systems
 - C programming
 - Assembly language
 - FPGA design
 - RTOS design
 - O ...

- CPS focus
 - Modeling
 - Timing
 - Dynamics
 - Imperative logic
 - Concurrency
 - Verification
 - O ...

-- Edward A. Lee, UC Berkeley



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Trends in Embedded Systems

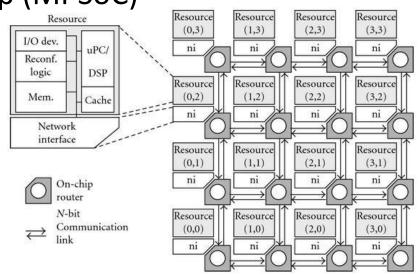
- In the past Embedded Systems were called Embedded (micro-)Controllers
- They appeared typically in control dominated applications:
 - Traffic lights control
 - Elevators control
 - Washing machines and dishwashers
 - Electronic Control Unit (ECU)
 - O ...
- They were implemented using a single μProcessor or dedicated HW (sequential circuit)
- All this is rapidly changing nowadays.
 - O How And Why?



Trend 1: Higher Degree of Integration

Moore's Law: the number of transistors that can be placed on a chip has doubled approximately every two years

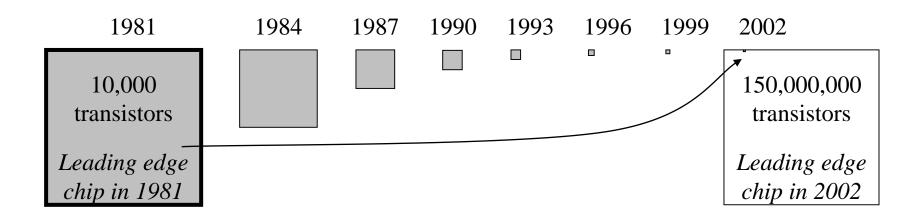
- Microprocessor, microcontroller
- System-on-Chip (SoC)
 - Processor + memory + I/O-units + communication structure
- Multi-processor System on a Chip (MPSoC)
 - Processor Co-processor
 - (Heterogeneous) Multi-processor
 - Network on Chip
 - Identical tiles
 - Scalable system





Graphical Illustration of Moore's law

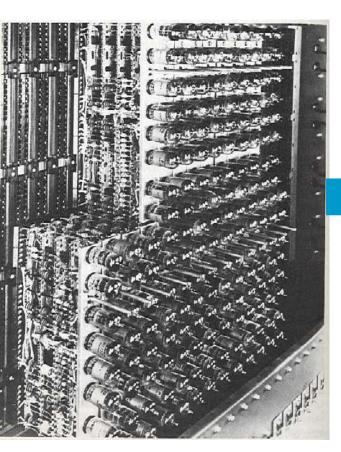
Moore's law is the observation that, over the history of computing hardware, the number of transistors on integrated circuits doubles approximately every two years.



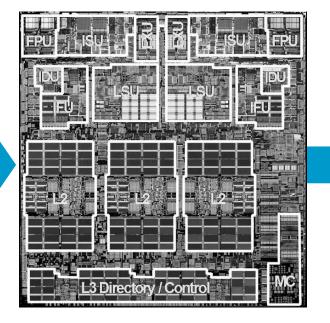
- Something that doubles frequently grows more quickly than most people realize!
 - A 2002 chip could hold about 15,000 1981 chips inside itself



Graphical Illustration of Moore's law



IBM 701 calculator (1952)

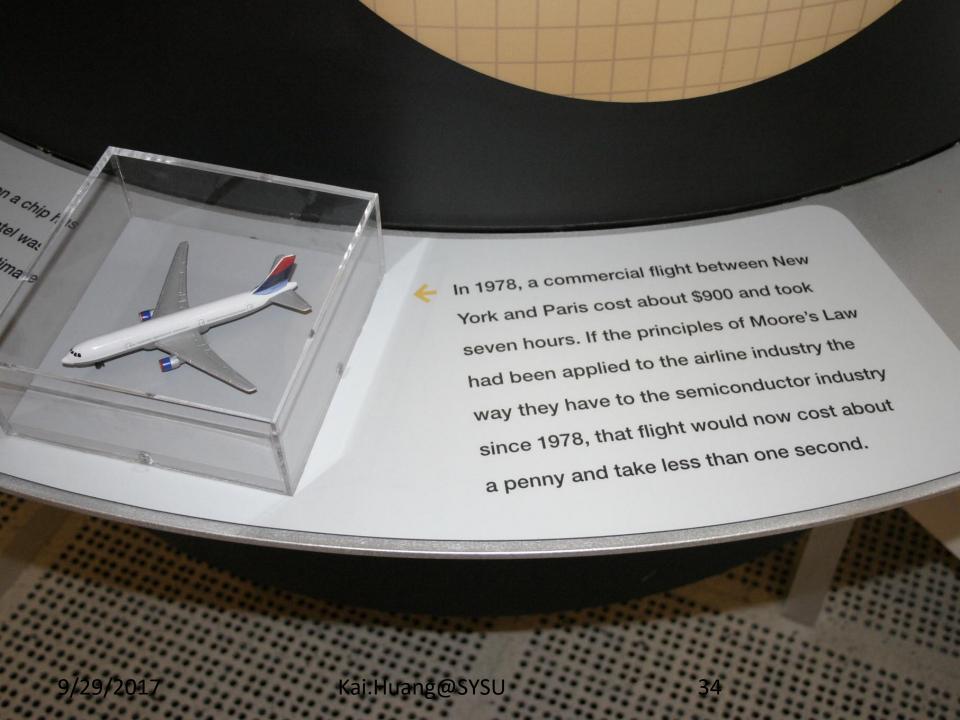


IBM Power 5 IC (2004)



IBM PowerXCell 8i (2008)





Trend 2: Towards Multi-Processor Systems

Complexity of ES is increasing, thus

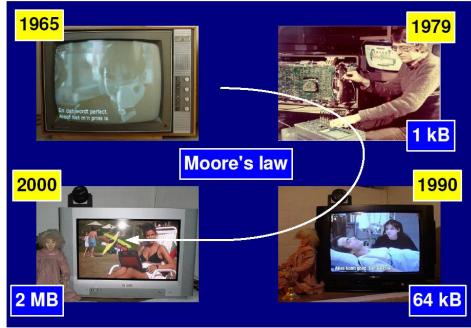
- A single uProcessor is sufficient for some consumer products
 - Application performance demands relatively low
- For other systems such as cars and aircrafts a network of processors is needed
 - Due to performance requirements
 - Due to safety requirements (a single failed component should not cause total system failure)
- For some systems such as mobile devices a network of heterogeneous processors is needed
 - Due to run-time efficiency requirements
 - Due to power efficiency



Trend 3: Software Increasing

Implementing ES in specialized HW brings lack of flexibility (changing standards) and very expensive masks, thus

- Most of the functionality will be implemented in software
 - On the average, a human "touches" about 50 to 100 micro-processors per day
 - State-of-art car has 70~100 micro-processors
- Exponential increase in software complexity





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Embedded Systems Design (1)

Embedded Systems Design is NOT just a special case of either hardware (Computer/Electrical Engineering) or software (SoftwareEngineering/Computer Science) design.

- An embedded system performs computation that is subject to physical constraints, i.e., interaction with a physical environment and execution on a physical (implementation) platform
 - Interaction constraints: deadlines, throughput, jitter
 - Execution constraints: available resources, power, failure rates
- It has functional requirements (expected services), and it has non-functional requirements (performance, power, cost, robustness, etc.)



Embedded Systems Design (2)

- Computer Science provides (software) functionality for Instruction Set Architectures (ISA) which are characterized by
 - Instruction set
 - Organization (program counter, register file, memory)
 - Both independent of any logical implementation and physical realization
- Computer/Electrical Engineering deals with
 - Logical implementation
 - Physical realization
- Embedded Systems design discipline needs to combine these two approaches, because non-functional behavior (such as timing, cost, power, robustness, etc.) is a crucial issue
 - o when there are real-time constraints imposed by the environment
 - when to predict non-functional behavior using abstract models that cannot be well specified if the relation between functional behavior and non-functional behavior is obscure



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Future of Embedded Systems

- Embedded Systems are everywhere
- Embedded Systems market is much larger than the market of PC-like systems
 - Post-PC era in which information processing is more and more moving away from just PCs to embedded systems
- Embedded Systems provide the basic technology for Ubiquitous/Pervasive computing:
 - Model of human-computer interaction in which information processing has been thoroughly integrated into everyday objects and activities
 - Key goals is to make information available anytime, anywhere
 - Building Ambient Intelligence into our environment



Embedded systems are everywhere

















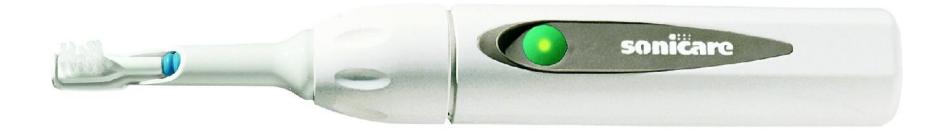
Our daily lives depend on embedded systems



From Your Bathroom...

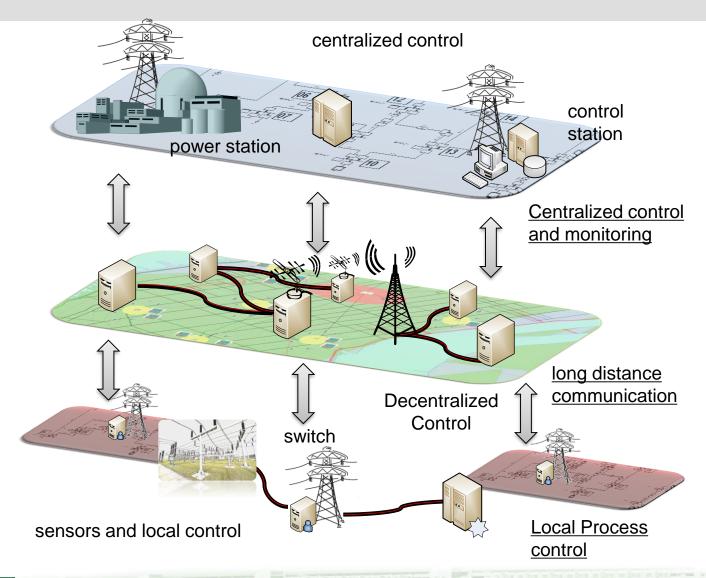
Product: Sonicare Plus toothbrush.

Microprocessor: 8-bit Zilog Z8.



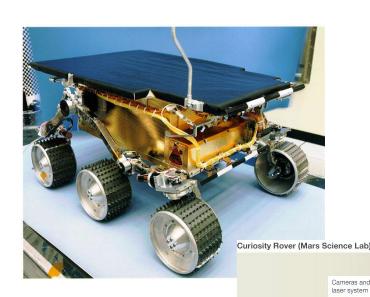


To Smart Grid





To Outer space



1996: NASA's Mars Sojourner Rover. Microprocessor: 8-bit Intel 80C85.

2012: NASA's Curiosity Rover, with uC/OS-II RT OS

Length: 3m/10ft Weight: 900kg

Six wheels on rocker-boaie system

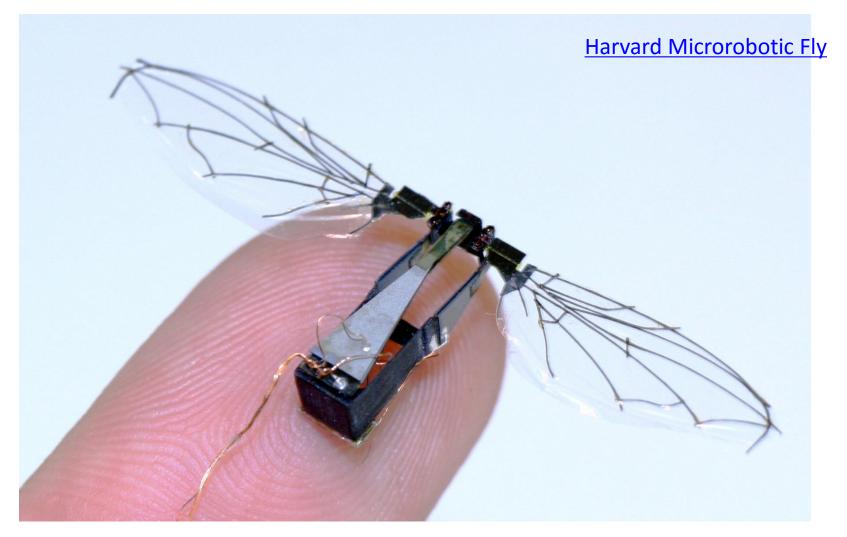
Robot arm and tool head

Big...





And Small...





Automotive Electronics

- 40% of the vehicle's costs and 90% of new innovation related to software or electronics
- 100-fold increase of code lines in two decades



Electronic **Injections Check Control Speed Control Central Locking**



Electronic Gear Control Electronic Air Condition ASC Anti Slip Control **ABS** Telephone

Seat Heating Control Autom. Mirror Dimming

Navigation System

CD-Changer ACC Adaptive Cruise Control **Airbags DSC Dynamic Stability** Control **Adaptive Gear** Control Xenon Light **BMW** Assist RDS/TMC Speech Recognition Emergency Call... 1990

I-Drive Personalization **Software Update** Force Feedback Poli...

ALC

ACC Stop&Go **BFD**

KSG 42 voltage **Internet Portal GPRS, UMTS Telematics** Online Services BlueTooth Car Office Local Hazard Warning Integrated Safety **System** Steer/Brake-By-Wire Lane Keeping Assist.

1970

1980 9/29/2017

Kai.Huang@SYSU

2020

Evolution of Handsets and Technology





Evolution of Handsets and Technology

iPhone Version









iPhone 8





<u>video</u>



Take-off Message

- Everything is embedded systems
- Everywhere is embedded systems
- The future is Embedded Systems

