

The goal is to analyse the Differentiation Matrix properties

Given a large set of nodes $\{\vec{x}_i\}_{i=1}^n$ located in \mathbb{R}^d .

1. Infinitely smooth Radial function $\phi(\cdot)$

A local interpolant takes the form $S(\vec{x}) = \sum_{j=1}^m \lambda_j \phi((\vec{x} - \vec{x}_j))$
where \vec{x}_j is the central node and $\{\vec{x}_{i,j}\}_{j=1}^m$ are its m neighbours

We can impose the interpolation condition at each neighbouring node.

Let's denote $\{\phi(\vec{x}_{i,j})\}_{j=1}^m$ by \vec{F}

Define the collocation matrix $A_i = [\phi((\vec{x}_{i,j} - \vec{x}_i))]_{j=1}^m$, s.t. $A_i \vec{F} = \vec{f}$ (1)

We wish to find the weights $\{w_j\}_{j=1}^m$ s.t. $\sum_{j=1}^m w_j \phi(\vec{x}_{i,j}) = L_i g(\vec{x})|_{\vec{x}=\vec{x}_i}$

New denote $\{w_j\}_{j=1}^m$ by \vec{w} , and $(L_i g(\vec{x})|_{\vec{x}=\vec{x}_i})_{j=1}^m$ by \vec{g}_i , so, in matrix form, we seek \vec{w} s.t. $\vec{F}^\top \vec{w} = \vec{g}_i$ (2)

We can apply the differential operator L to the local interpolant.

$L_i S(\vec{x}) = \sum_{j=1}^m \lambda_j L_i \phi((\vec{x} - \vec{x}_{i,j}))$ and evaluate it at the central point $\vec{x} = \vec{x}_i$.

$$L_i g(\vec{x}_i) \approx L_i S(\vec{x}_i) = \sum_{j=1}^m \lambda_j L_i \phi((\vec{x}_i - \vec{x}_{i,j})) \Big|_{\vec{x}=\vec{x}_i} = \left(L_i \phi((\vec{x}_i - \vec{x}_{i,1})) \Big|_{\vec{x}=\vec{x}_i}, L_i \phi((\vec{x}_i - \vec{x}_{i,2})) \Big|_{\vec{x}=\vec{x}_i}, \dots, L_i \phi((\vec{x}_i - \vec{x}_{i,m})) \Big|_{\vec{x}=\vec{x}_i} \right)^\top \vec{\lambda}$$

From (1) (Since A is invertible) $g_i = B_i \cdot A^{-1} \vec{F}$

$$\text{from (2), } \vec{w} = (B_i \cdot A^{-1})^\top = (A^{-1})^\top B_i^\top = (A^\top)^{-1} B_i^\top$$

$$\text{So } A^\top \vec{w} = B_i^\top$$

Note : A is a local collocation matrix, associated to its cluster center \vec{x}_i .

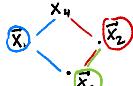
B_i is L applied to the local interpolant and evaluated at \vec{x}_i .

Global Representation :

Consider a graph of each center with its m neighbours

A sort of adjacency matrix can be built.

For instance : $E = \begin{pmatrix} 0 & 1 & 1 & & \dots \\ 1 & 0 & 1 & 1 & \dots \\ 1 & 1 & 0 & & \dots \\ 0 & & & \ddots & \end{pmatrix}$

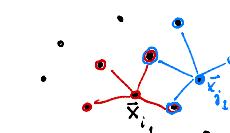


Properties: (1) E is $N \times N$ (N is the total number of nodes)

(2) $\sum_{j=1}^N E_{ij} = m, \forall i$ (m is fixed : the number of neighbours per cluster)

(3) E is not necessarily symmetric

(4) $E_{ii} = 1, \forall i$



Let A be the global collocation matrix, with all the nodes. Similarly, let B be the global differentiated interpolant evaluated at each node.

Let A_i be the local collocation matrix associated to the cluster of which the central node is \bar{x}_i . Similarly, B_i is the local interpolant differentiated and evaluated at the central node (recall it is a row vector).

The neighbors of \bar{x}_i are $\{\bar{x}_{i_1}, \bar{x}_{i_2}, \dots, \bar{x}_{i_m}\}$

The indices of the neighbors are the positions of the non-zero entries of $E_{i,:}$.

Let P_i be the $n \times N$ reduction matrix, so

$$\boxed{A_i = P_i A P_i^T}$$

$$\text{For instance, } E_{i,:} = [0 \ 1 \ 0 \ 0 \ 1 \ 1] \quad , \quad P_i = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \quad N=6, m=3 \quad 3 \times 6$$

$$A_i \cdot P_i A P_i^T = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} t_{i_1} & t_{i_2} & t_{i_3} & \cdots & t_{i_6} \\ t_{i_1} & t_{i_2} & & & \\ \vdots & & & & \\ t_{i_1} & t_{i_2} & t_{i_3} & t_{i_4} & t_{i_5} & t_{i_6} \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} t_{i_1} & t_{i_2} & t_{i_3} \\ t_{i_2} & t_{i_3} & t_{i_4} \\ t_{i_3} & t_{i_4} & t_{i_5} \\ t_{i_4} & t_{i_5} & t_{i_6} \end{bmatrix}$$

central node index

$$\text{Similarly, } B_i = P_i (C_i) B P_i^T = [0 \ 0 \ 0 \ 0 \ 1 \ 0] \begin{bmatrix} L & t_{i_1} & t_{i_2} & \cdots & t_{i_6} \\ t_{i_1} & L & t_{i_2} & & \\ \vdots & & & & \\ t_{i_1} & t_{i_2} & t_{i_3} & t_{i_4} & t_{i_5} & t_{i_6} \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = [L \ t_{i_1} \ L t_{i_2} \ L t_{i_3} \ L t_{i_4}]$$

so the local cluster differentiation weights satisfy

$$A_i^T \bar{w}_i = B_i^T \quad \text{Here, } A_i \text{ is symmetric, so } A_i \bar{w}_i = B_i^T$$

$$P_i A P_i^T \bar{w}_i = P_i B^T P_i (C_i)^T$$

$$\bar{w}_i = (P_i A P_i^T)^{-1} (P_i B^T P_i (C_i)^T)$$

Building the Differentiation Matrix:

\bar{w}_i contains the entries of the i^{th} row, along the non-zero columns of $E_{i,:}$.

$$\text{So } D_i = P_i^T (C_i) \bar{w}_i^T P_i$$

$$N \times 1 \quad m \times n \quad m \times N$$

$$\begin{aligned} \text{So } D &= \sum_{i=1}^N P_i^T (C_i) \bar{w}_i^T P_i \\ &\quad \text{i.e. row of } B \\ &= \sum_{i=1}^N \underbrace{P_i^T (C_i) (P_i (C_i) B P_i^T)}_{\text{zero matrix}} \underbrace{(P_i A^T P_i^T)^{-1} P_i}_{\bar{w}_i^T} \\ &\quad \text{except 1 at } (i,i) \end{aligned}$$

Note: For the symmetric version of D :

$$W_i = (P_i A P_i^T)^{-1} (P_i B P_i^T)$$

$$m \times m \quad m \times n \quad n \times m$$

$$D = \sum_{i=1}^N P_i^T (P_i A P_i^T)^{-1} (P_i B P_i^T) P_i$$