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# Lab 2 - Calibration

— Meta Quest 3 Spatial Anchor —

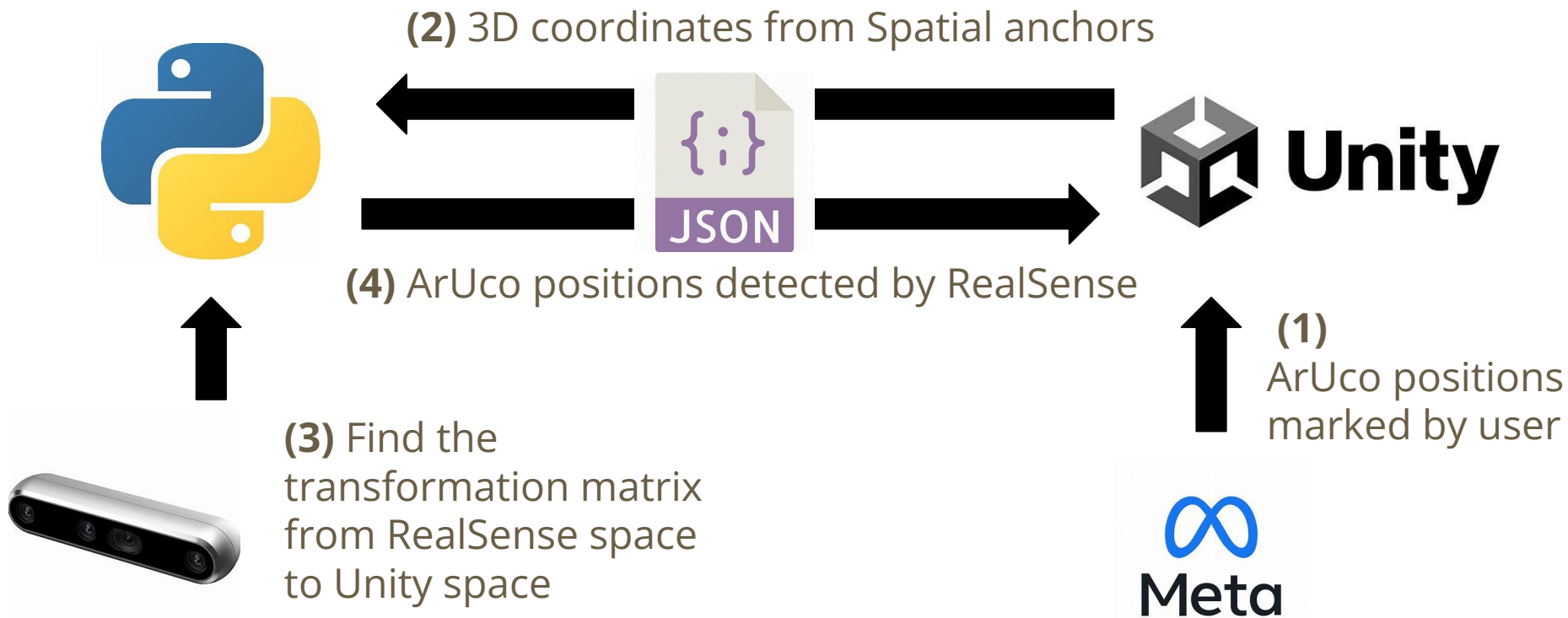
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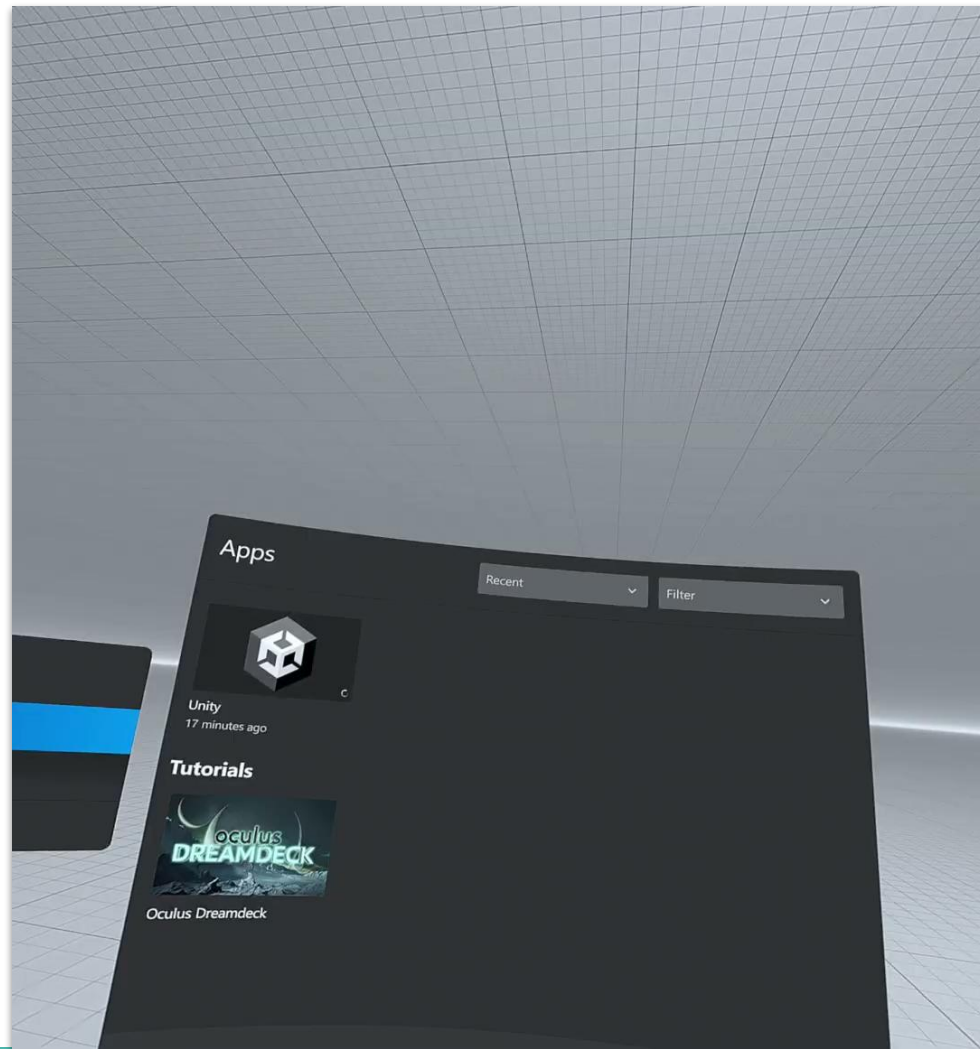
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# Lab Schedule

- 9/12 Lab 1 - Marker Detection
- 9/19 Lab 2 - Calibration
- 9/26 Lab 3 - Game Design 1
- 10/3 Lab 4 - Game Design 2
- 10/10 National Holiday (No Class)
- 10/17 UIST (No Physical class)
- 10/24 Midterm Demo

# What we will do





# Outline

- **Installation & Setup**
- **Camera & Controllers Tracking**
- **Spatial Anchor**
- **Calibration**
- **Server Client**
- **To Do**

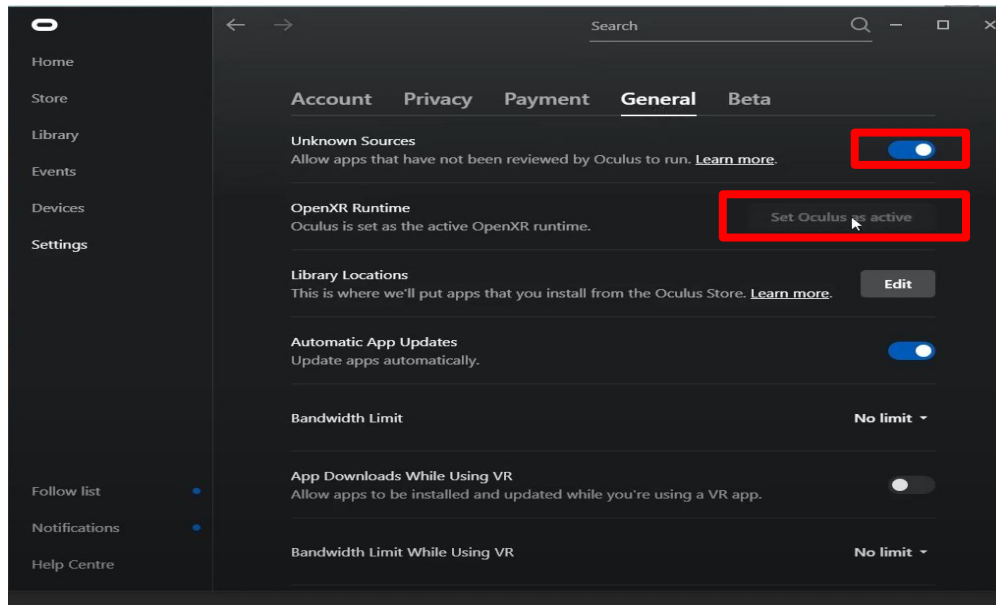
# Installation & Setup

# Quest Link

- Download Quest Link app and connect headset. [Link](#)

# Settings

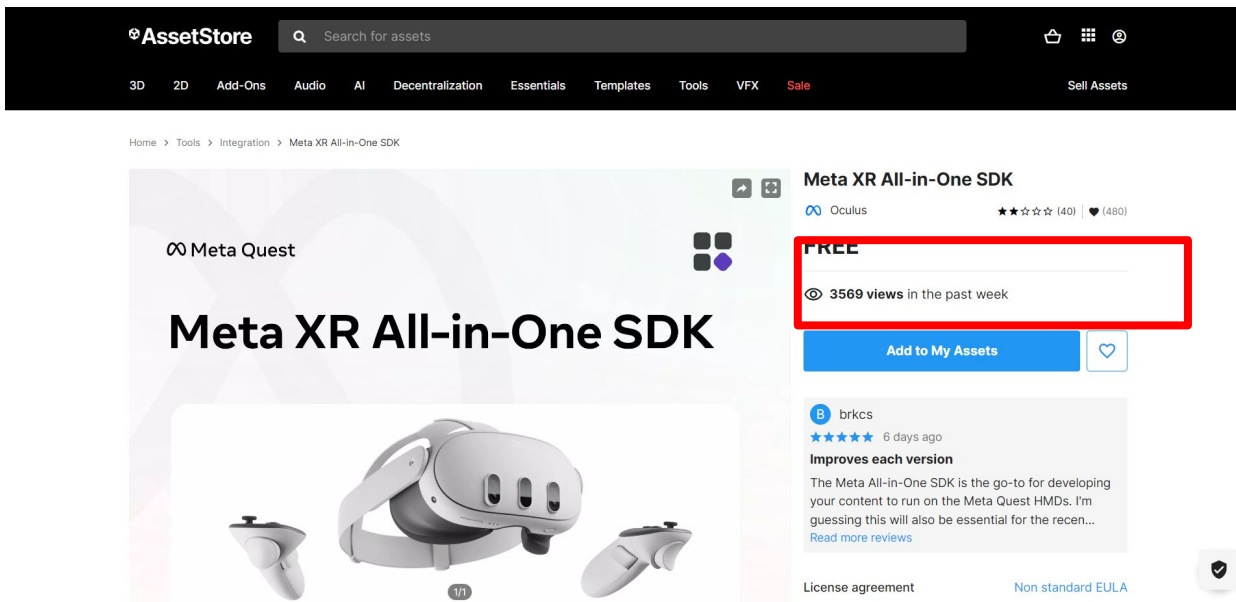
- Go to Settings > General.
- Allow Unknown Source, and switch OpenXR Runtime to “Set Oculus as Active”.



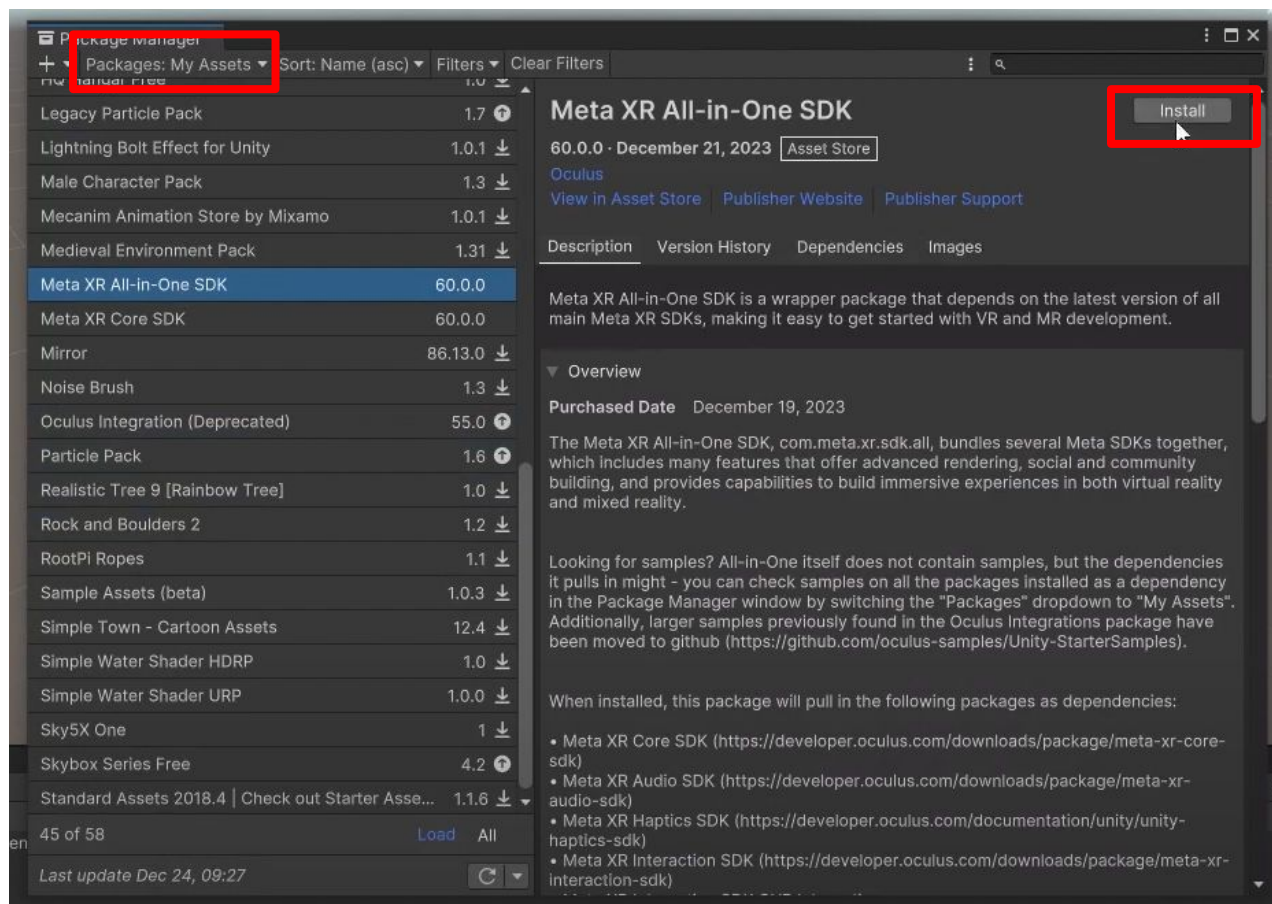


# Meta XR All-in-One SDK [Link](#)

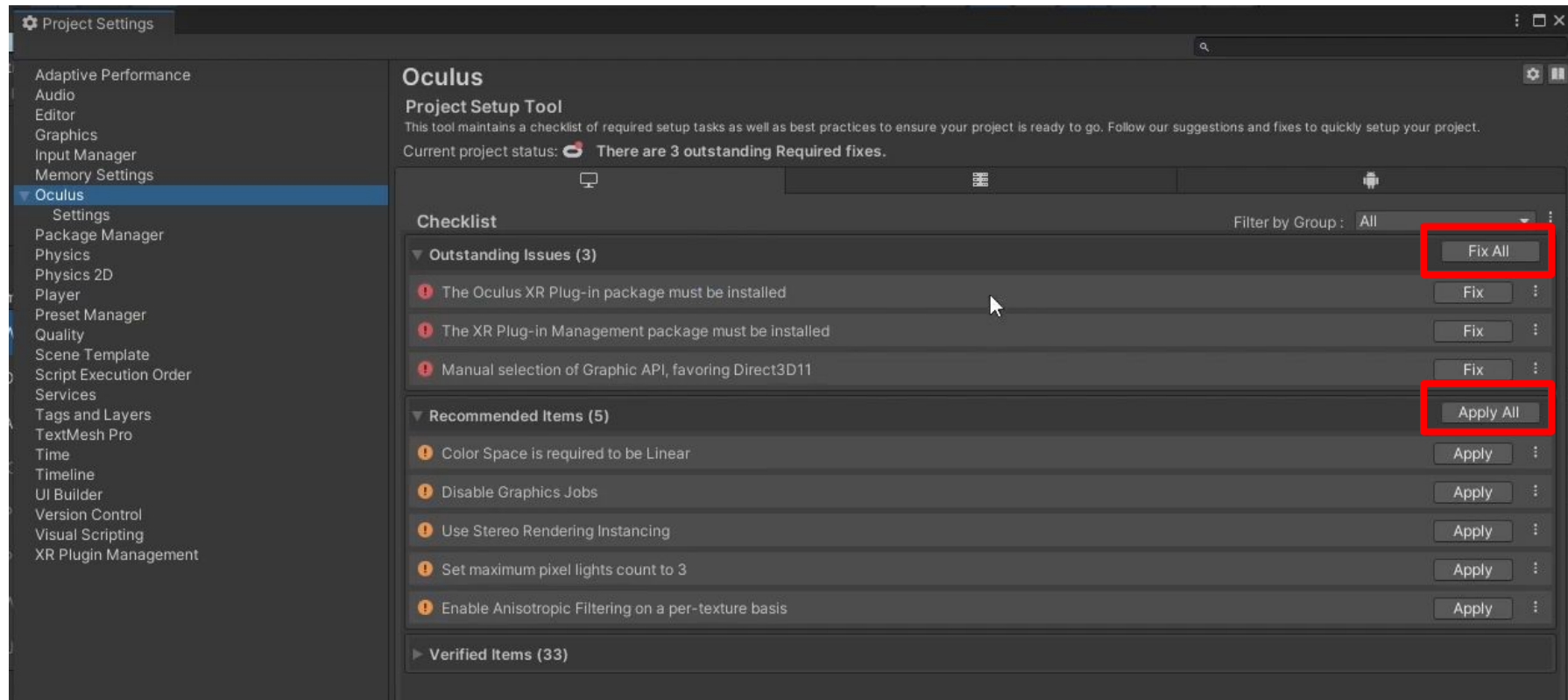
- Download and import to Unity project. [Link](#)



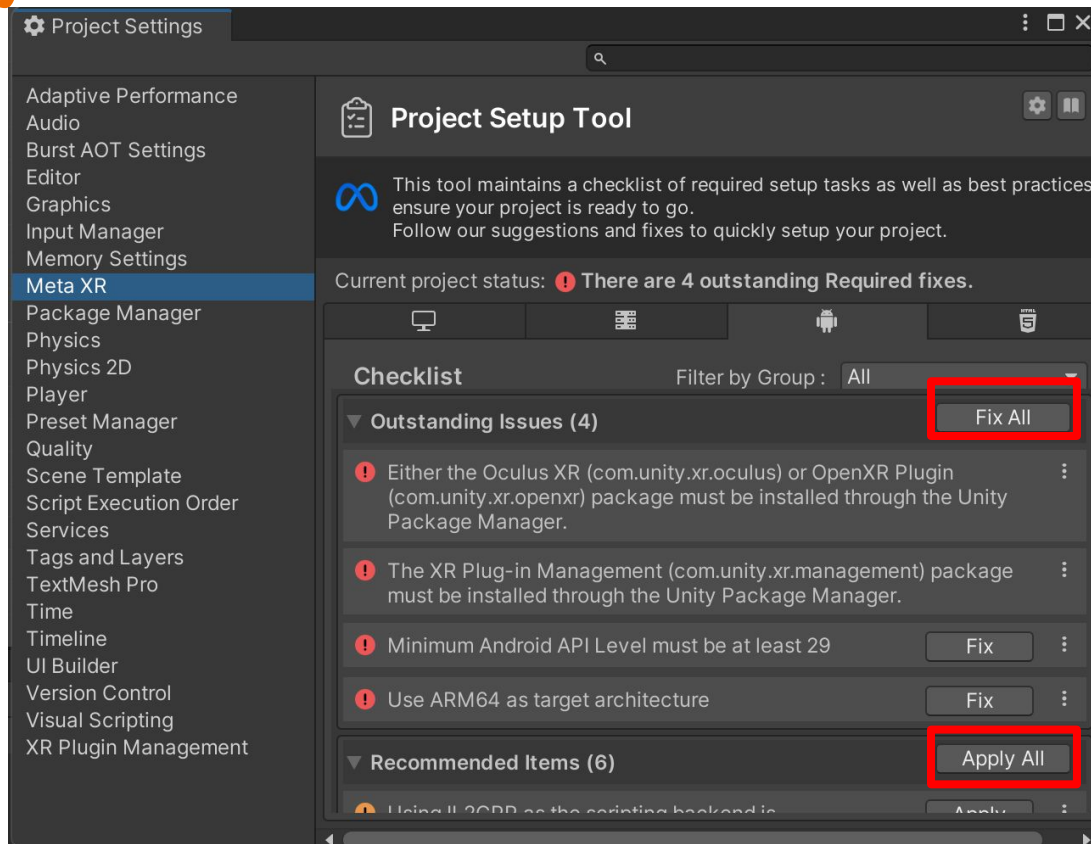
# Install Package



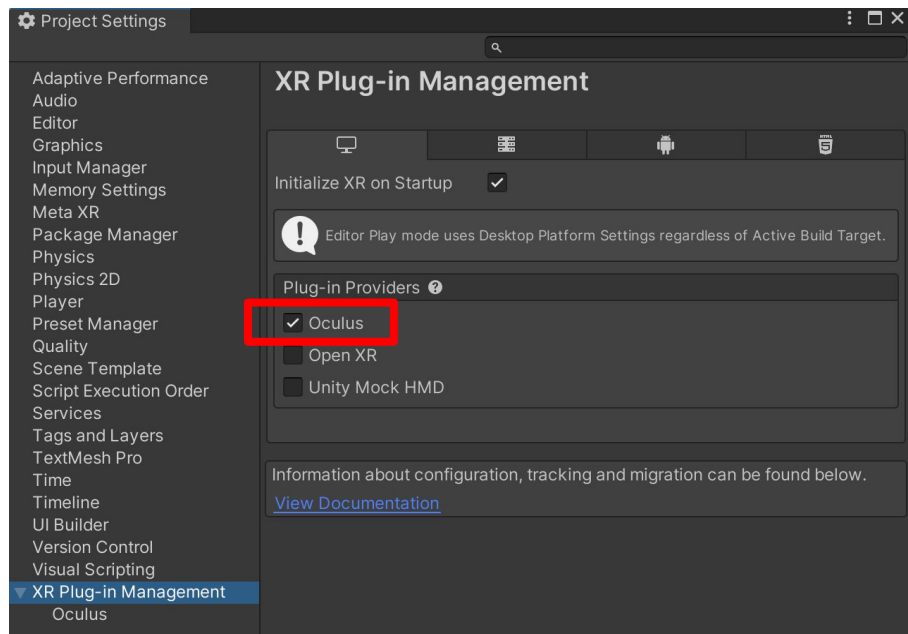
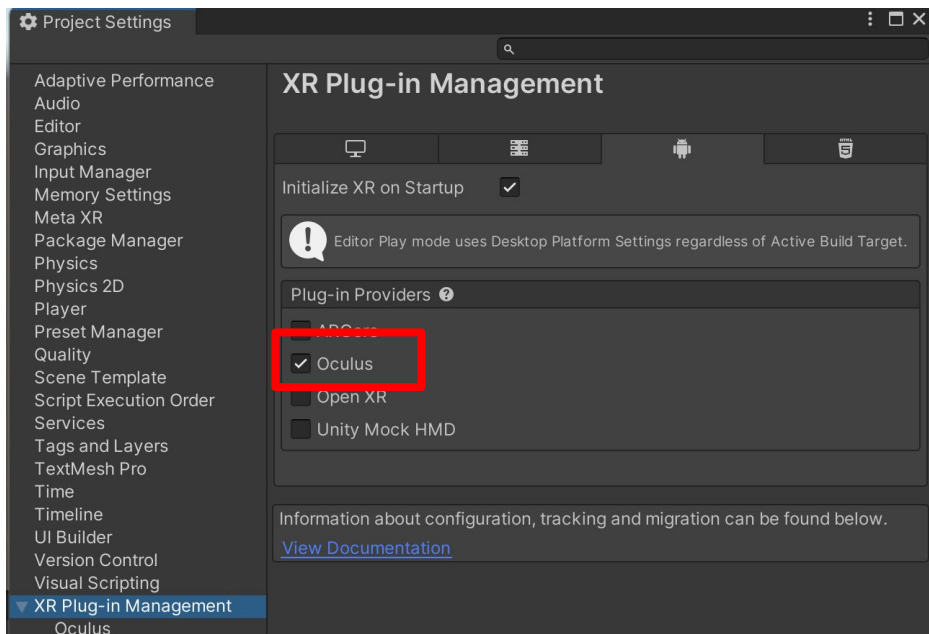
# Fix and Apply



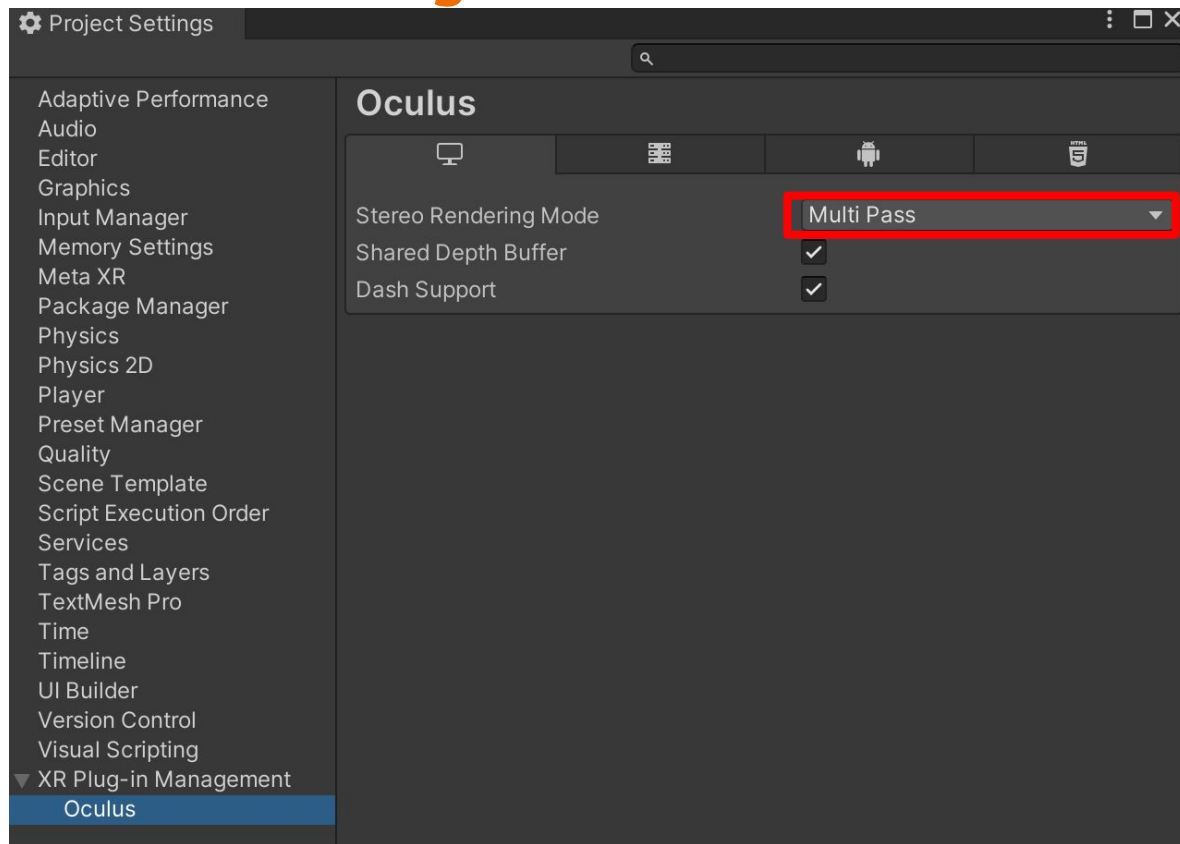
# Fix and Apply



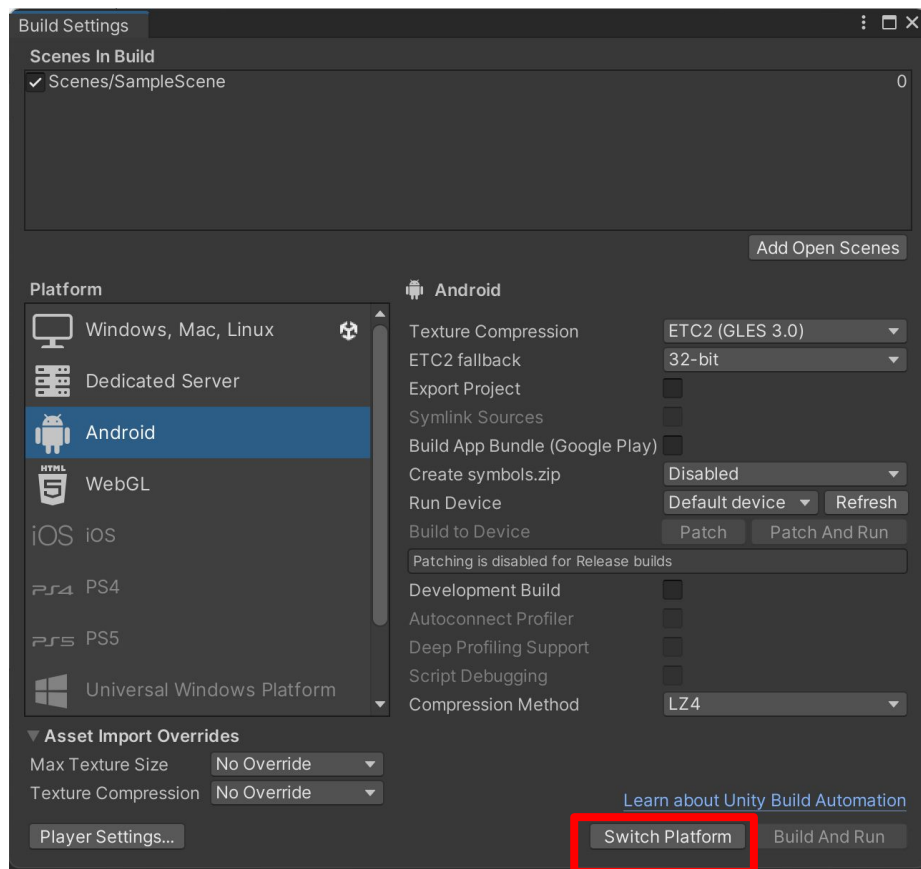
# XR Plug-in Management



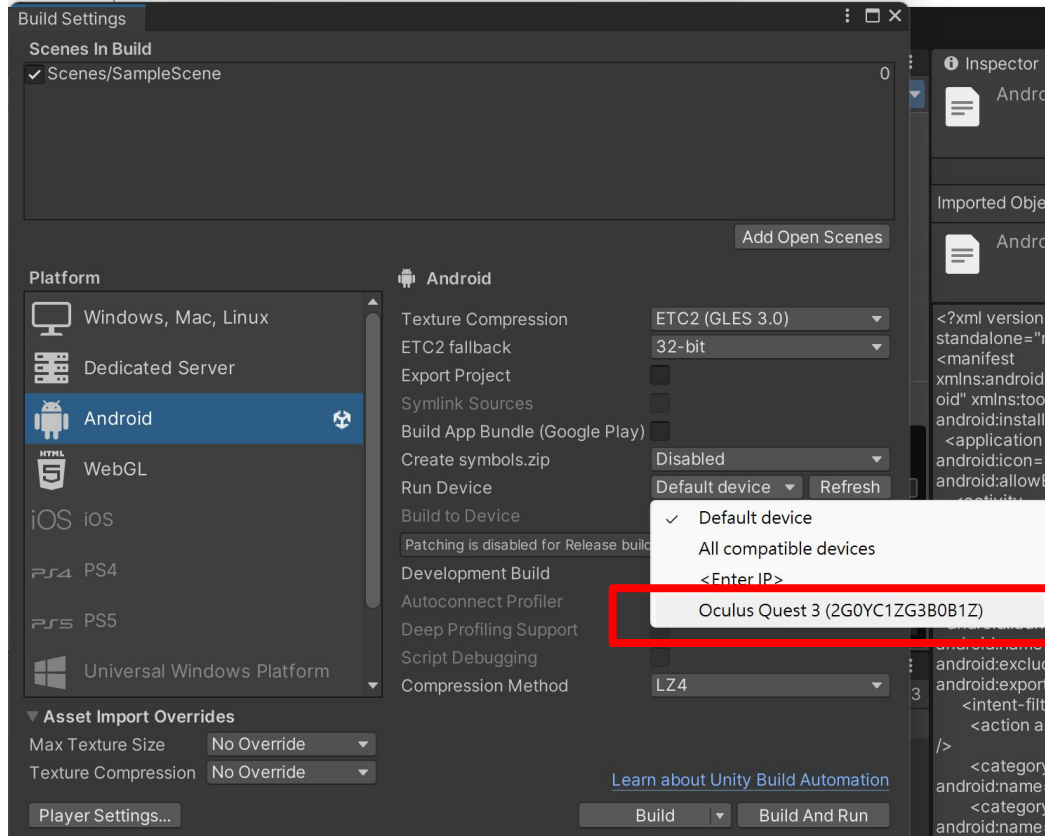
# Change Stereo Rendering Mode



# Switch to Android Platform



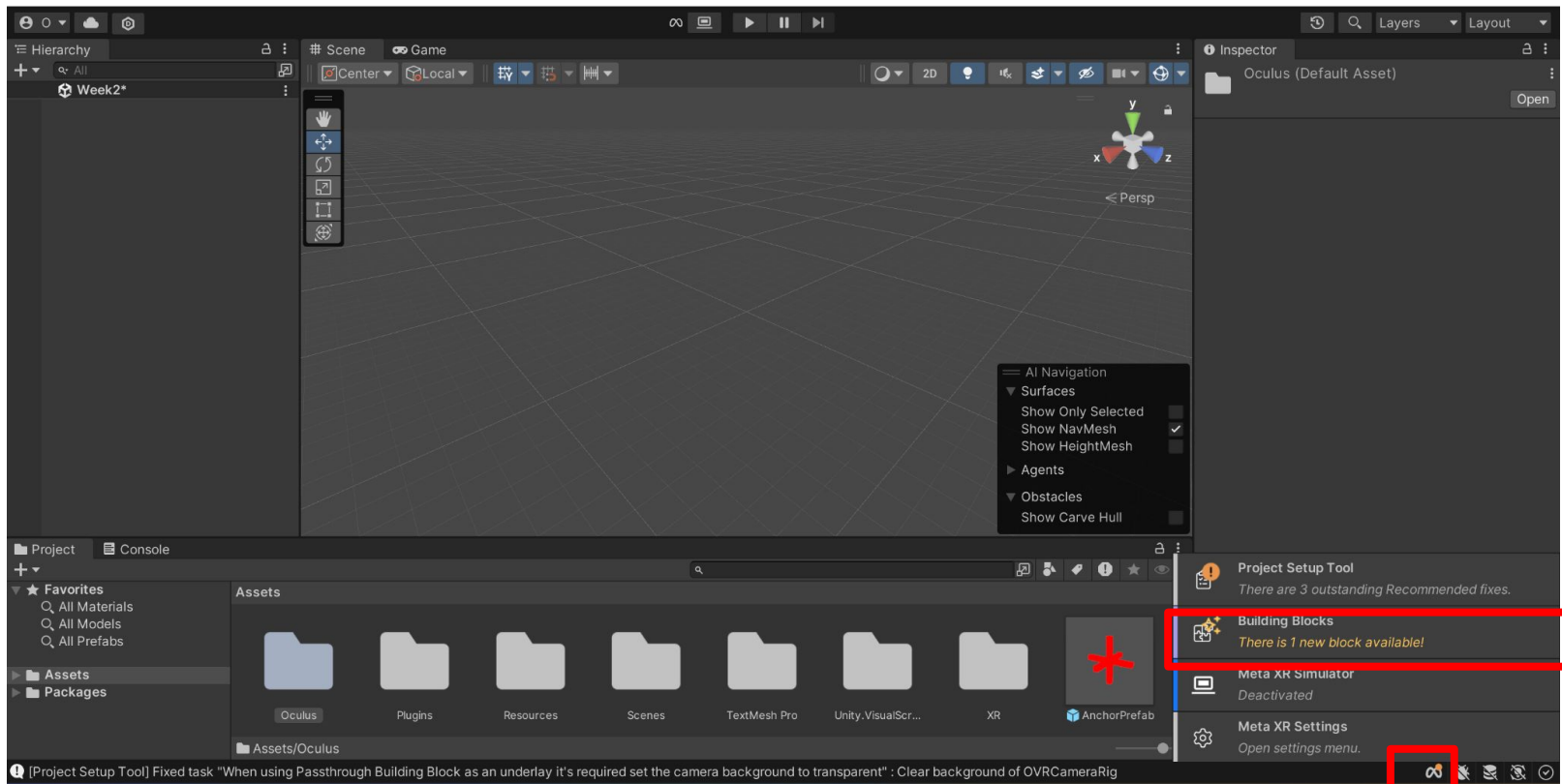
# Refresh “Run Device” and select Quest 3



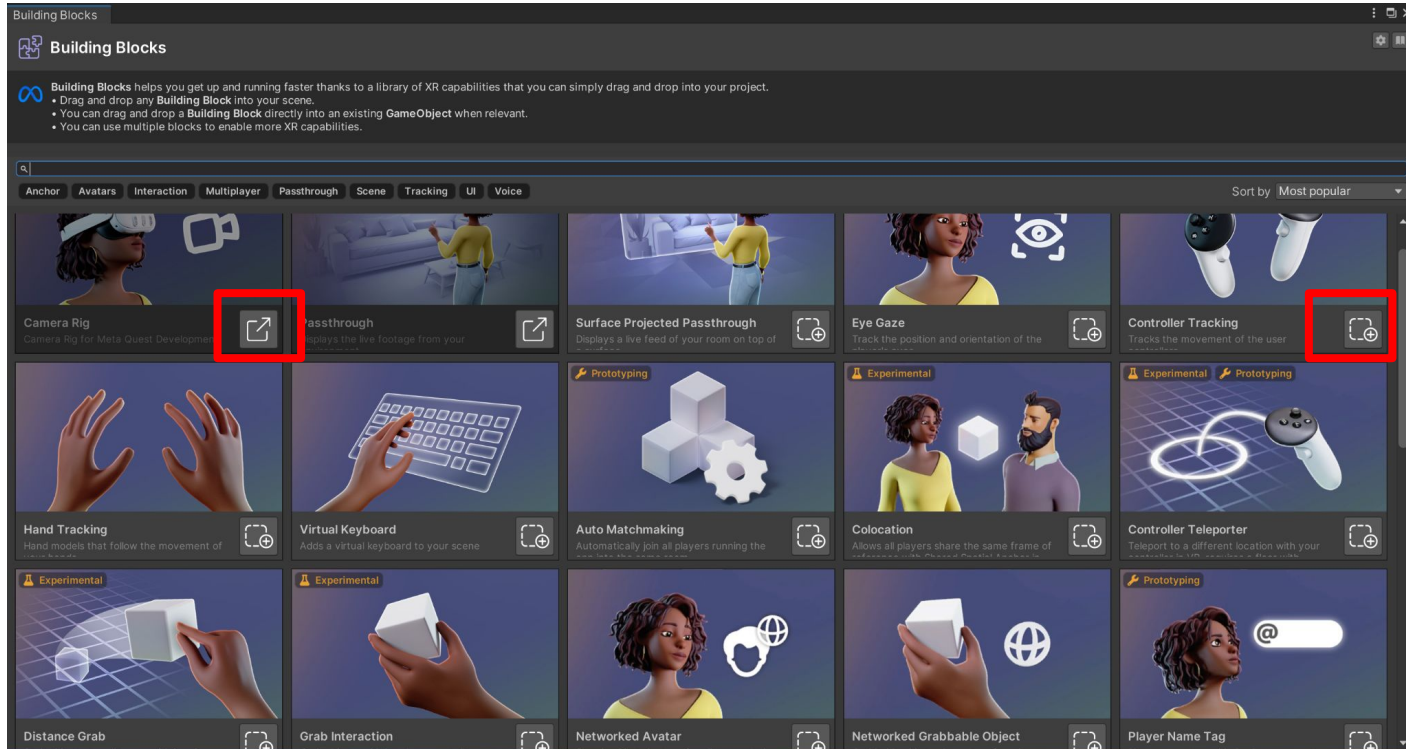


# Camera & Controllers Tracking

# Meta Building Blocks



# Select Camera Rig and Controller Tracking





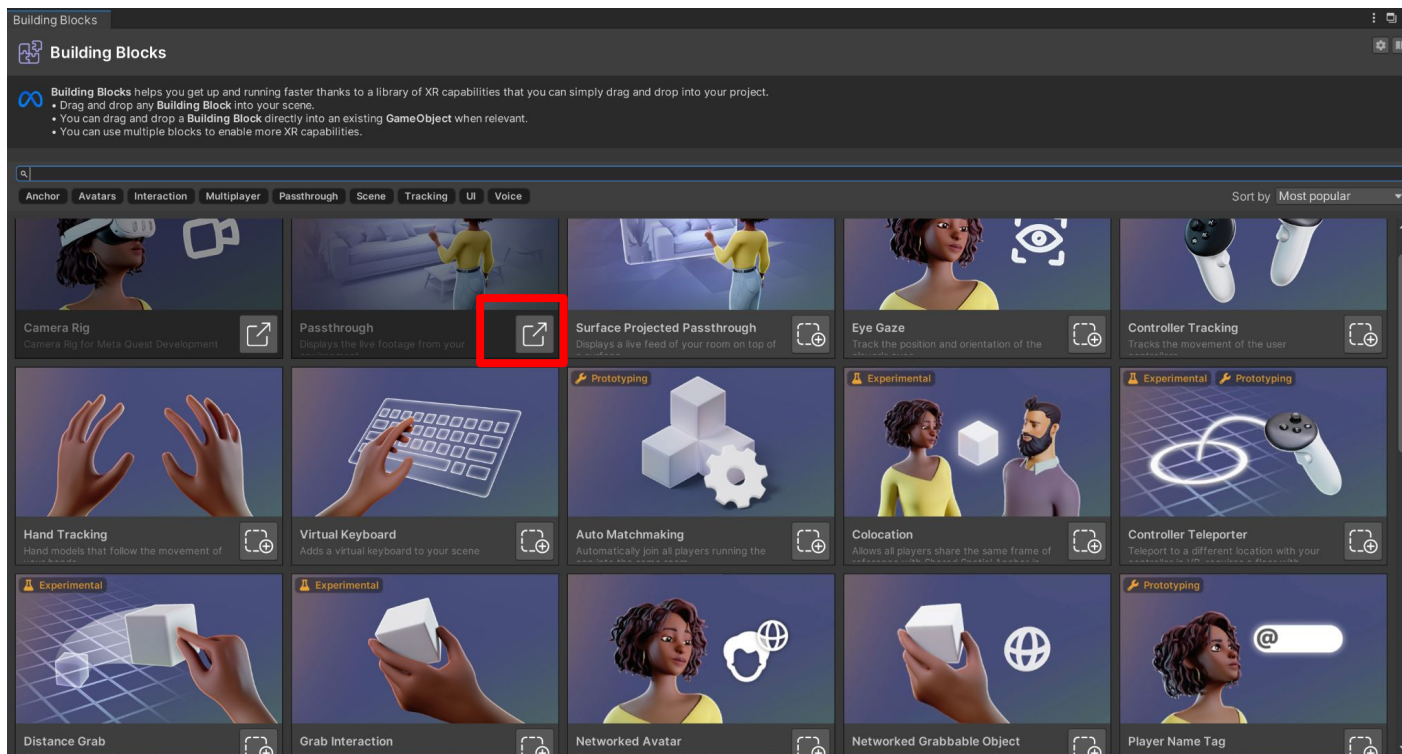
# Spatial Anchor

# Spatial Anchors

- Stable points in real world tracked by Quest 3



# Add Passthrough



# SpatialAnchors.cs

```
7 public class SpatialAnchors : MonoBehaviour
8 {
9     //Specify controller to create Spatial Anchors
10    3 references
11    [SerializeField] private Controller controller;
12    // Spatial Anchor Prefab
13    1 reference
14    public GameObject anchorPrefab;
15
16    // Update is called once per frame
17    0 references
18    void Update()
19    {
20        // Create Anchor when user press the index trigger on specified controller
21        if(OVRInput.GetDown(OVRInput.Button.PrimaryIndexTrigger, controller))
22        {
23            CreateSpatialAnchor();
24        }
25    }
26
27    1 reference
28    public void CreateSpatialAnchor()
29    {
30        GameObject anchor = Instantiate(anchorPrefab, OVRInput.GetLocalControllerPosition(controller), OVRInput.GetLocalControllerRotation(controller));
31        anchor.AddComponent<OVRSpatialAnchor>();
32    }
33 }
```

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搜尋文件

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Labs

Lab 0

Lab 1

Lab 2

Lab 3

Lab 4

名稱

建立日期

修改日期

修改者

大小

AnchorPrefab.prefab

am 11:22

am 11:22

22 KB

✓

Client.py

am 11:22

am 11:22

768 bytes

✓

MoveByController.cs

am 11:22

am 11:22

738 bytes

✓

Server.cs

am 11:22

am 11:22

3 KB

✓

SpatialAnchors.cs

am 11:22

am 11:22

2 KB

✓



# OVRInput

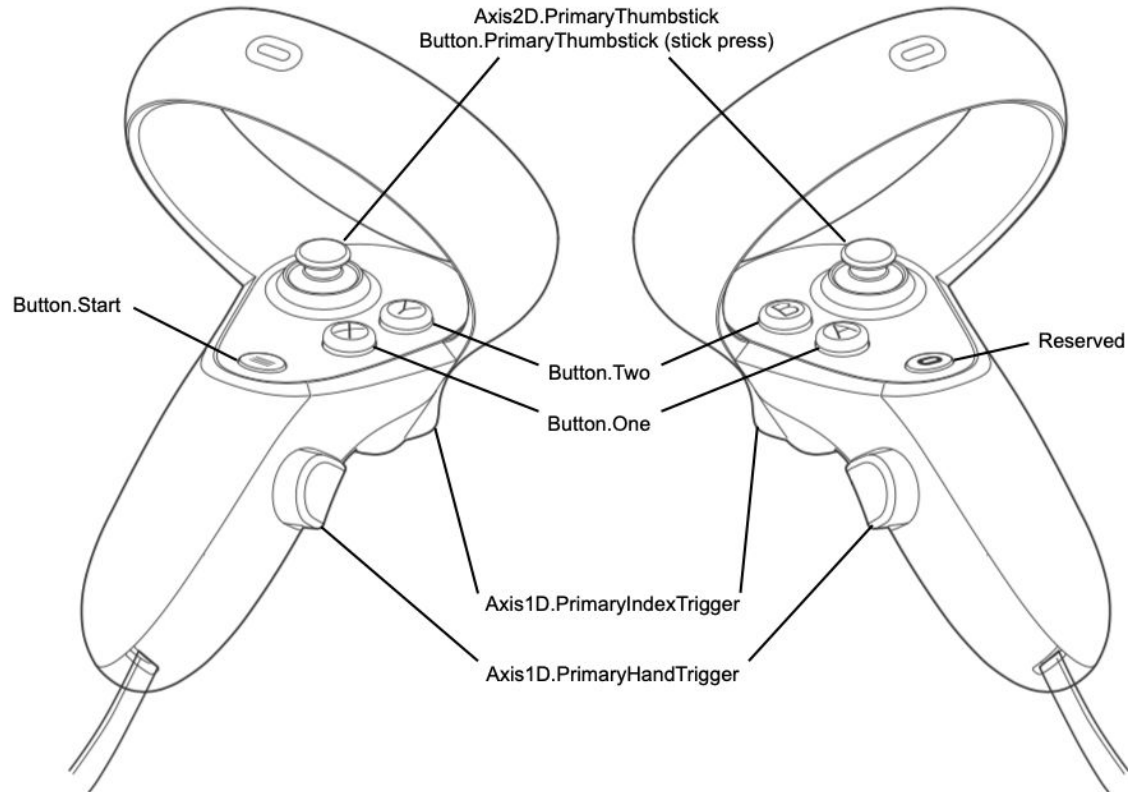
- OVRInput.Get()
  - Return true if currently pressed.
- OVRInput.GetDown()
  - Return true if pressed this frame.
- OVRInput.GetUp()
  - Return true if released this frame.

```
14      // Update is called once per frame
15      0 references
16      void Update()
17      {
18          // Create Anchor when user press the index trigger on specified controller
19          if OVRInput.GetDown(OVRInput.Button.PrimaryIndexTrigger, controller)
20          {
21              CreateSpatialAnchor();
22          }
23      }
```

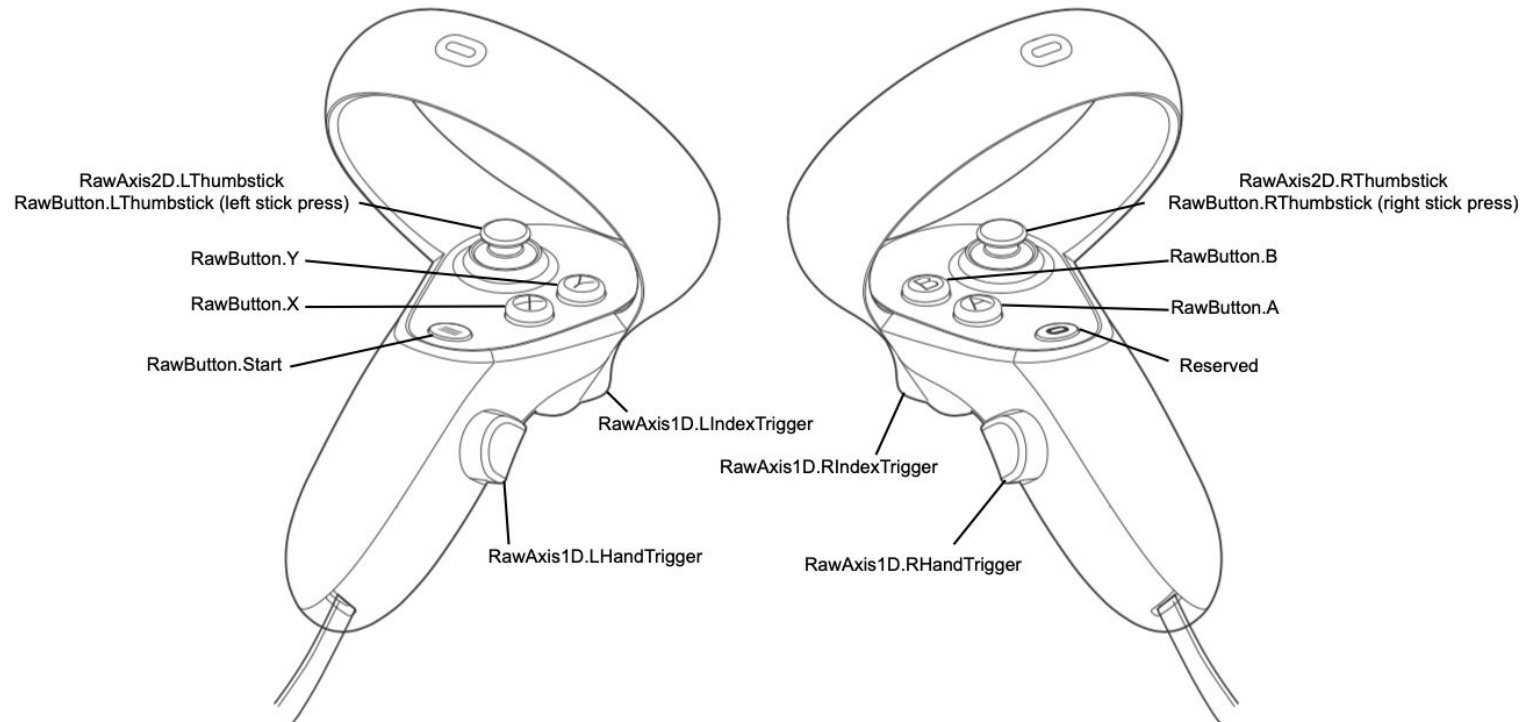
# Control Input Enumerations

Control	Enumerates
<code>OVRInput.Button</code>	Traditional buttons found on gamepads, controllers, and back button.
<code>OVRInput.Touch</code>	Capacitive-sensitive control surfaces found on the controller.
<code>OVRInput.NearTouch</code>	Proximity-sensitive control surfaces found on the controller.
<code>OVRInput.Axis1D</code>	One-dimensional controls such as triggers that report a floating point state.
<code>OVRInput.Axis2D</code>	Two-dimensional controls including thumbsticks. Reports a <code>Vector2</code> state.

# Controller Input Mapping



# Controller Input Mapping (Raw)



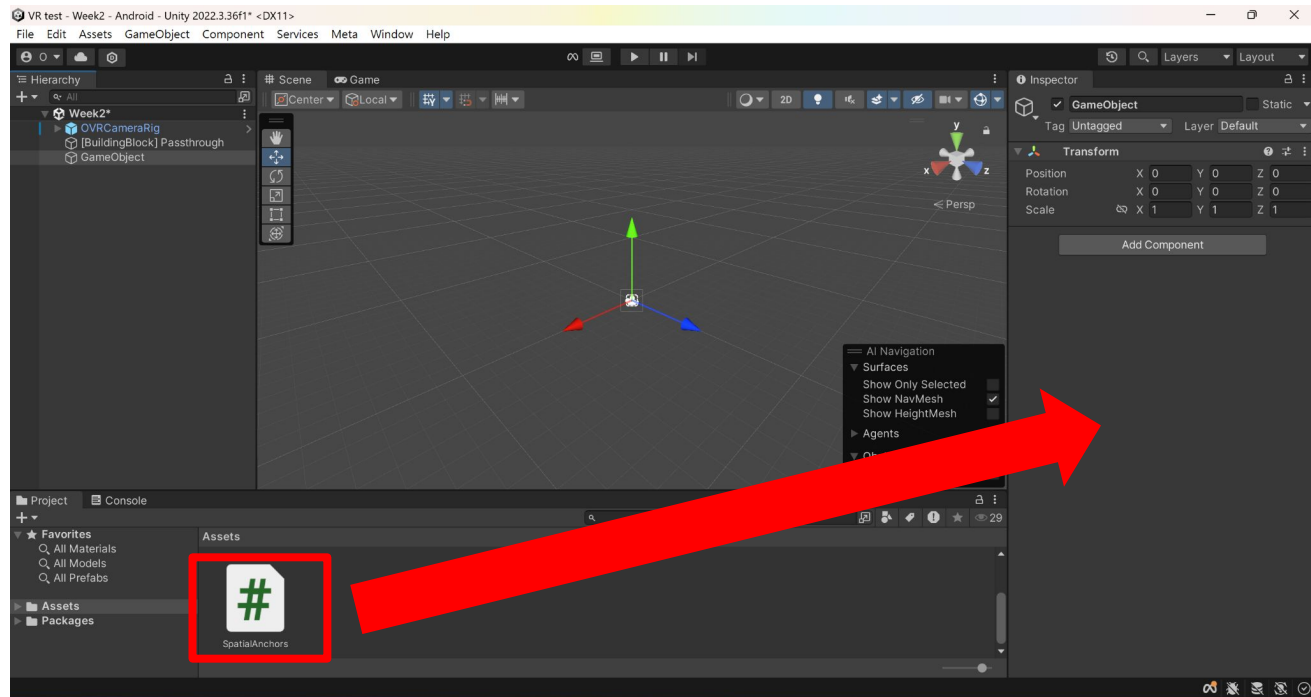
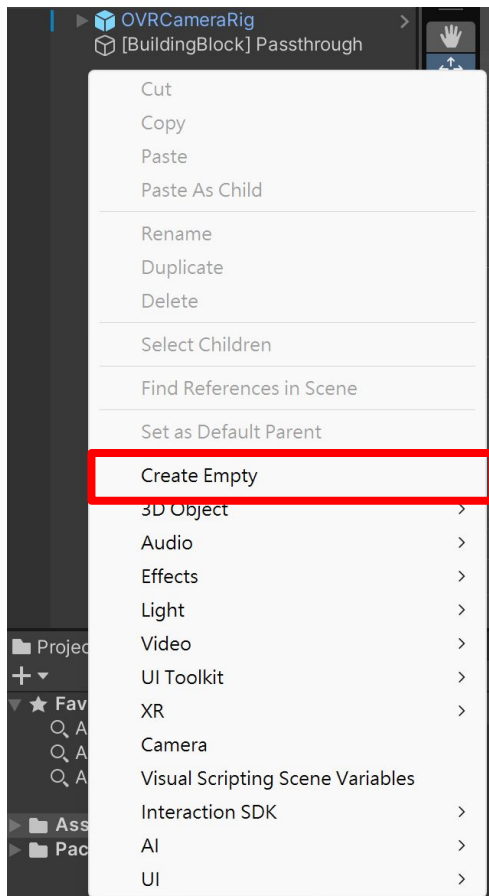
# Instantiate

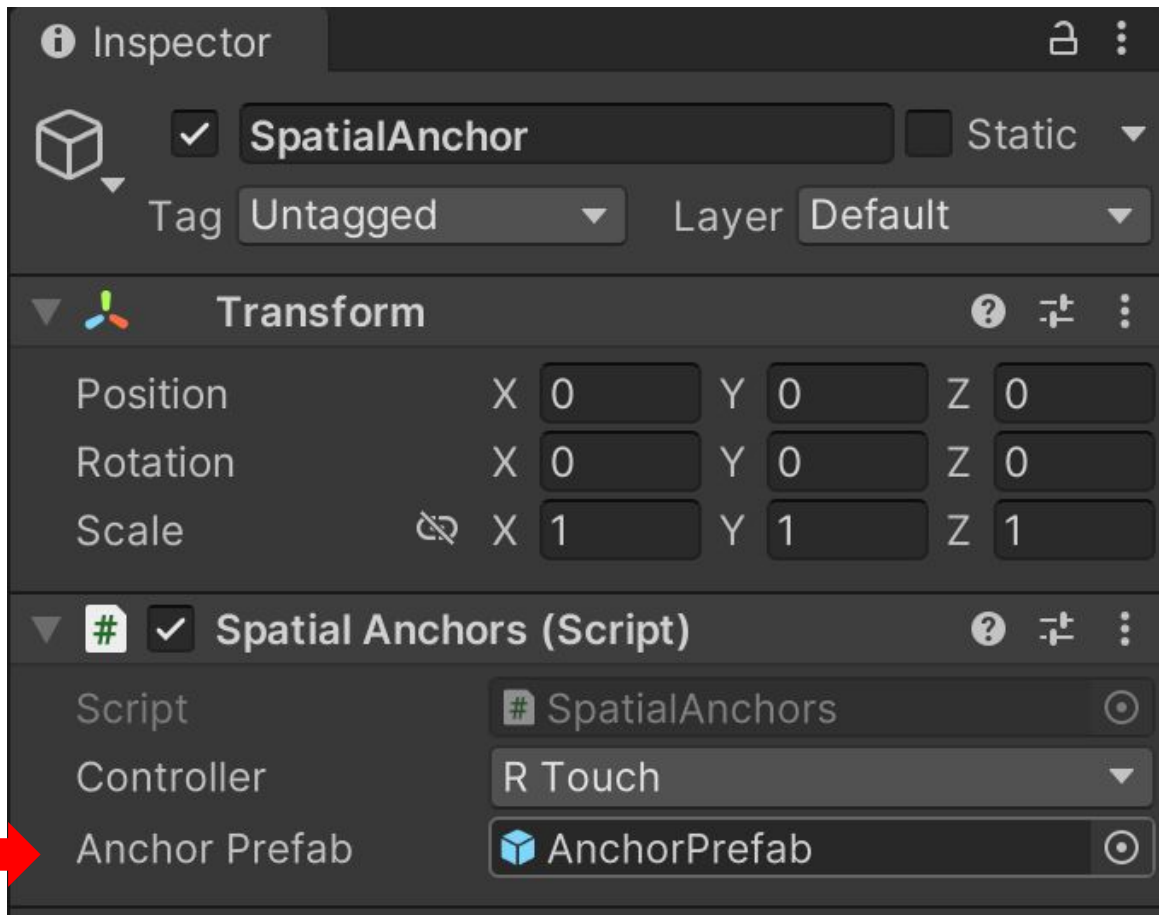
Instantiate(Object original, Vector3 position, Quaternion rotation, Transform parent)

Instantiate(Object original, Vector3 position, Quaternion rotation)

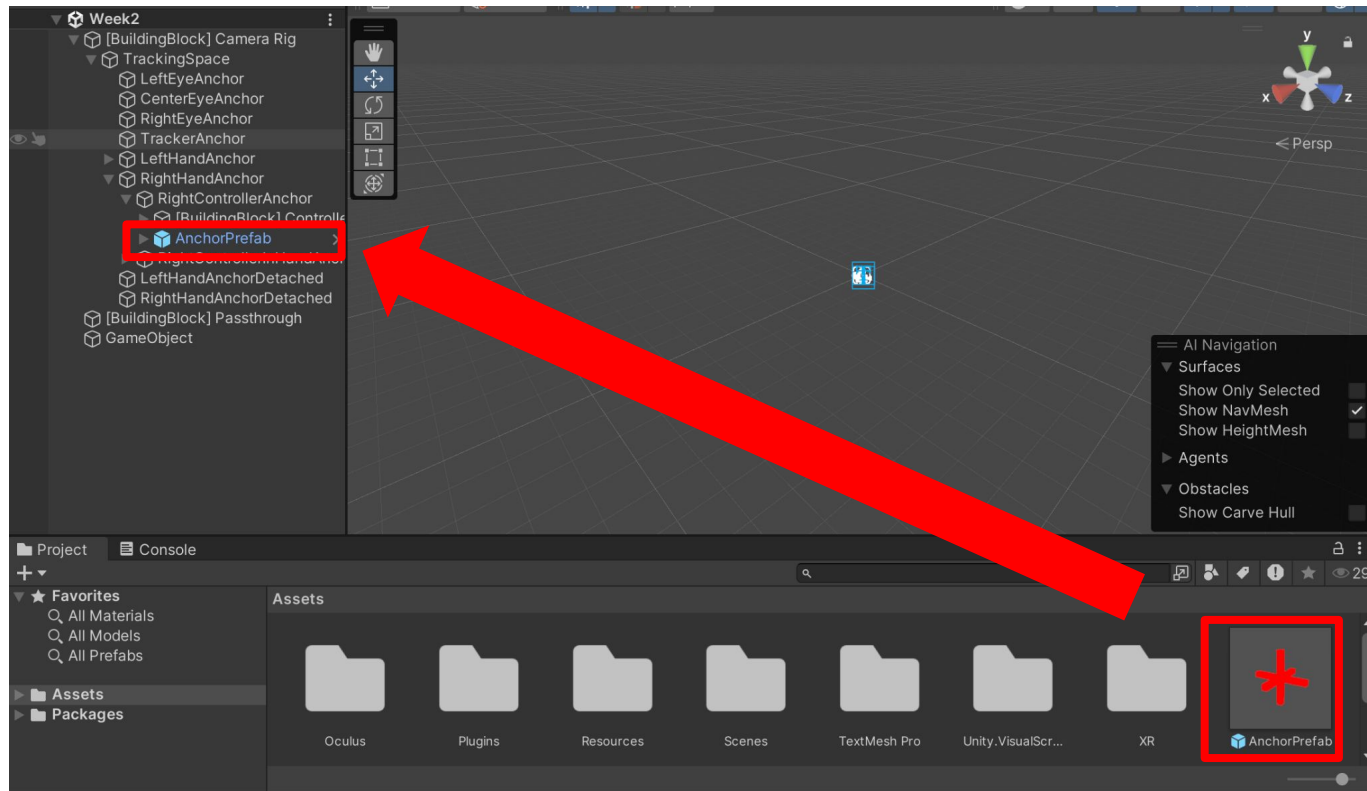
```
24 public void CreateSpatialAnchor()  
25 {  
26     GameObject anchor = Instantiate(anchorPrefab, OVRInput.GetLocalControllerPosition(controller)  
27                                     , OVRInput.GetLocalControllerRotation(controller));  
28     anchor.AddComponent<OVRSpatialAnchor>();  
29 }
```

original	An existing object that you want to make a copy of.
position	Position for the new object.
rotation	Orientation of the new object.
parent	Parent that will be assigned to the new object.
instantiateInWorldSpace	When you assign a parent Object, pass true to position the new object directly in world space. Pass false to set the Object's position relative to its new parent.





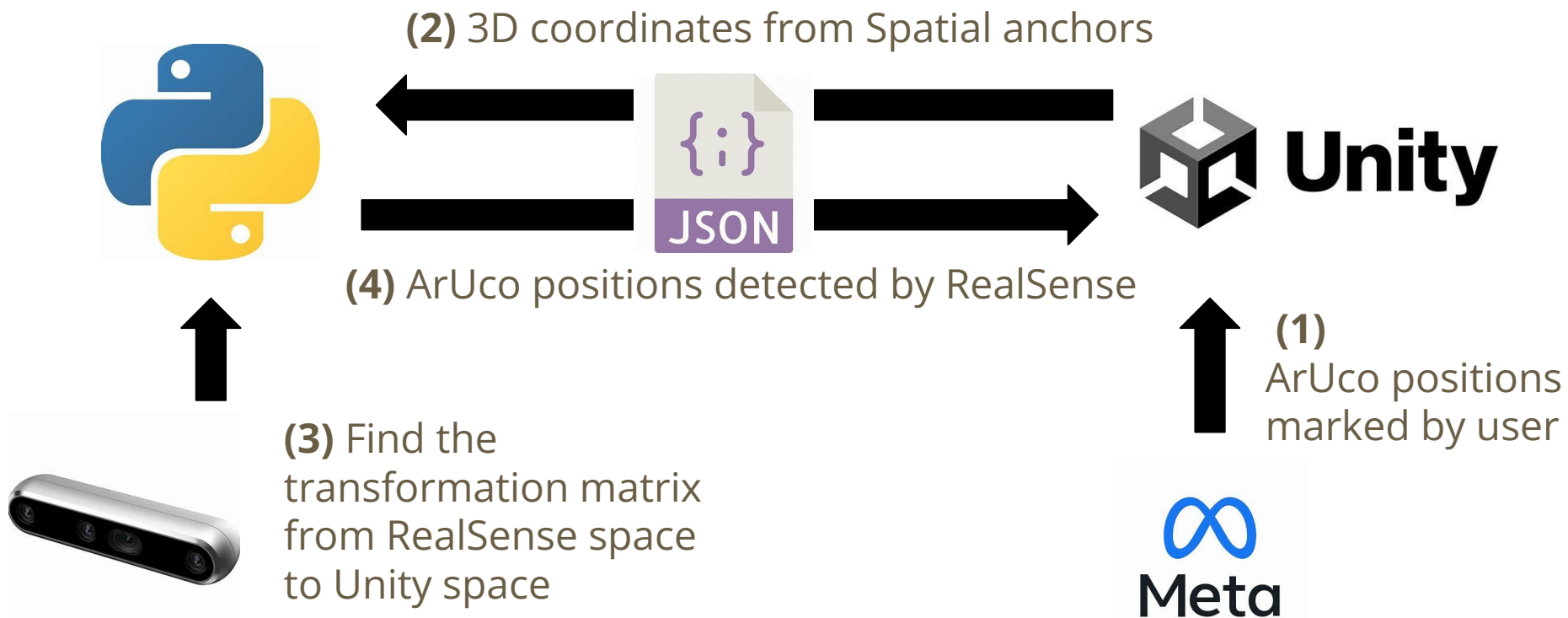
# Indicate where the anchor will be create.







# Calibration

# Calibration Architecture

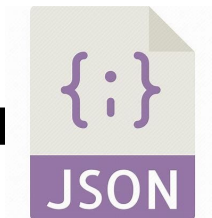
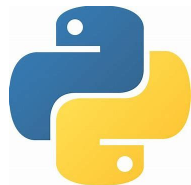


# Finding transformation matrix

	RealSense		Unity	
ArUco 1	$(x, y, z)$	$\cdot T$	$= (x, y, z)$	Spatial Anchor 1
ArUco 2	$(x, y, z)$	$\cdot T$	$= (x, y, z)$	Spatial Anchor 2
ArUco 3	$(x, y, z)$	$\cdot T$	$= (x, y, z)$	Spatial Anchor 3
		$\vdots$		
ArUco n	$(x, y, z)$	$\cdot T$	$= (x, y, z)$	Spatial Anchor n

Solve n linear equations to find 3D Transformation matrix T.

# Spawn new objects



**Unity**

**Detected  
New ArUco**

$$(x, y, z) \cdot T = (x, y, z)$$

**Create New Game Object  
At (x, y, z)**

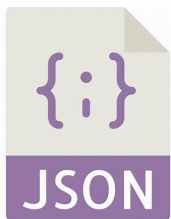
# Server Client

# Server Client

Client



3D coordinates from Spatial anchors



ArUco positions detected by RealSense

Server



**Unity**



A simple server that send message to clients every two second.

```
17  const string hostIP = "127.0.0.1"; // Select your IP  
    1 reference  
18  const int port = 80; // Select your port
```

互動系統設計與實作 (CSIE5646) > 文件 > Labs > Lab 2

搜尋文件  已選擇 0 個項目 [+ 資料夾](#) [上傳](#)

名稱	建立日期	修改日期	修改者	大小	
AnchorPrefab.prefab	am 11:22	am 11:22		22 KB	✓
Client.py	am 11:22	am 11:22		768 bytes	✓
MoveByController.cs	am 11:22	am 11:22		738 bytes	✓
<b>Server.cs</b>	am 11:22	am 11:22		3 KB	✓
SpatialAnchors.cs	am 11:22	am 11:22		2 KB	✓

# Unity

```
// Receive message from client
int i;
while ((i = stream.Read(buffer, 0, buffer.Length)) != 0)
{
    data = Encoding.UTF8.GetString(buffer, 0, i);
    Message message = Decode(data);
    // Add received message to que
    lock(Lock)
    {
        MessageQueue.Add(message);
    }
}
client.Close();
```



# Unity

```
private void Update()
{
    // Send message to client every 2 second
    if(Time.time > timer)
    {
        Message msg = new Message();
        msg.some_string = "From Server";
        msg.some_int = 1;
        msg.some_float = .1f;
        SendMessageToClient(msg);
        timer = Time.time + 2f;
    }
    // Process message que
    lock(Lock)
    {
        foreach (Message msg in MessageQueue)
        {
            // Unity only allow main thread to modify GameObjects.
            // Spawn, Move, Rotate GameObjects here.
            Debug.Log("Received Str: " + message.some_string + " Int: " + message.some_int + " Float: " + message.some_float);
        }
        MessageQueue.Clear();
    }
}
```

# Unity - To Do

- Send Spatial Anchor positions to Python
- Create Anchor from ArUco coordinates send by Python
  - Create all anchors from Python under the same parent.
  - Implement script to move the parent. (For manual calibration)
- Implement your own message format.
  - ArUco Id
  - x,y,z coordinates
  - Rotation
  - etc.

```
24 // Define your own message
25 [Serializable]
   8 references
26 public class Message
27 {
   2 references
28     public string some_string;
   2 references
29     public int some_int;
   2 references
30     public float some_float;
31 }
```











# Python

A simple client that echo message from server.

```
8  HOST = "127.0.0.1" # The server's hostname or IP address
9  PORT = 80          # The port used by the server
```

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 Server.cs	am 11:22	am 11:22		3 KB	
 SpatialAnchors.cs	am 11:22	am 11:22		2 KB	

# Python - To Do

1. Receive Spatial Anchor positions from Unity.
2. Find the 3D transformation matrix that maps RealSense space to Unity Space.
  - a. Use `numpy.linalg.lstsq` to find the least square solution.
3. Use the 3D transformation matrix to transform ArUco position detected by RealSense to Unity space.
4. Send ArUco position detected by RealSense to Unity.

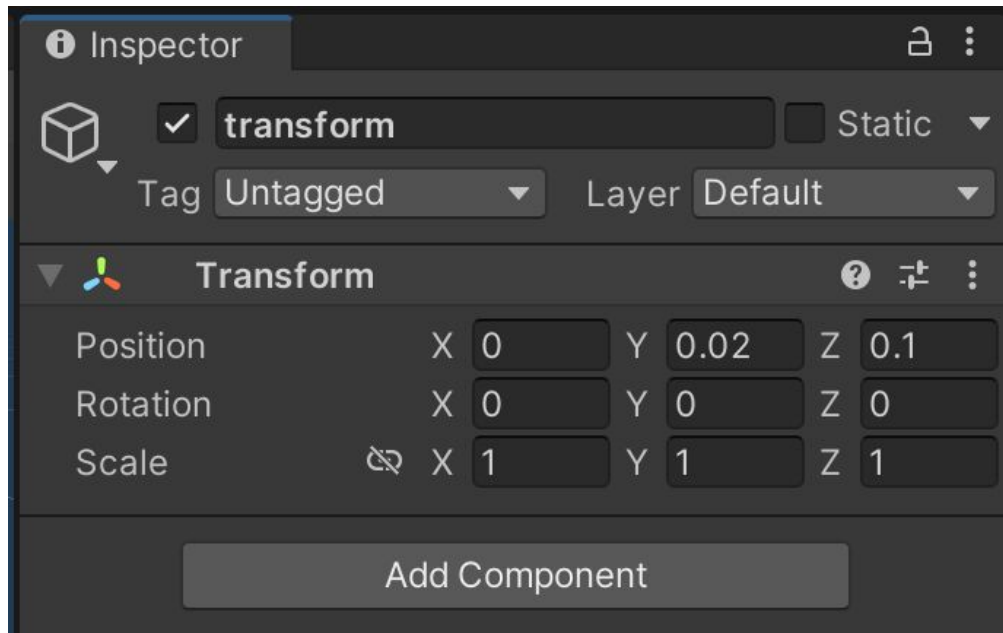
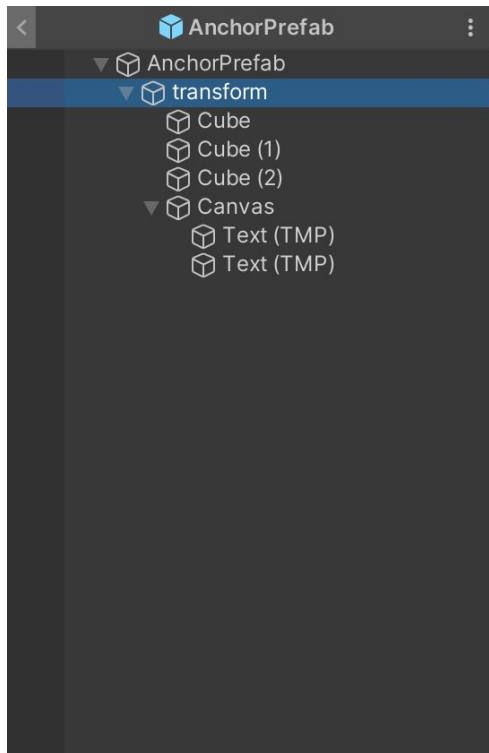
**To Do**

# Basic - 1

- Modify the Transform in Anchor Prefab, and add physical objects to controller for user to create anchor at contact area.



# Modify the Transform in Anchor Prefab

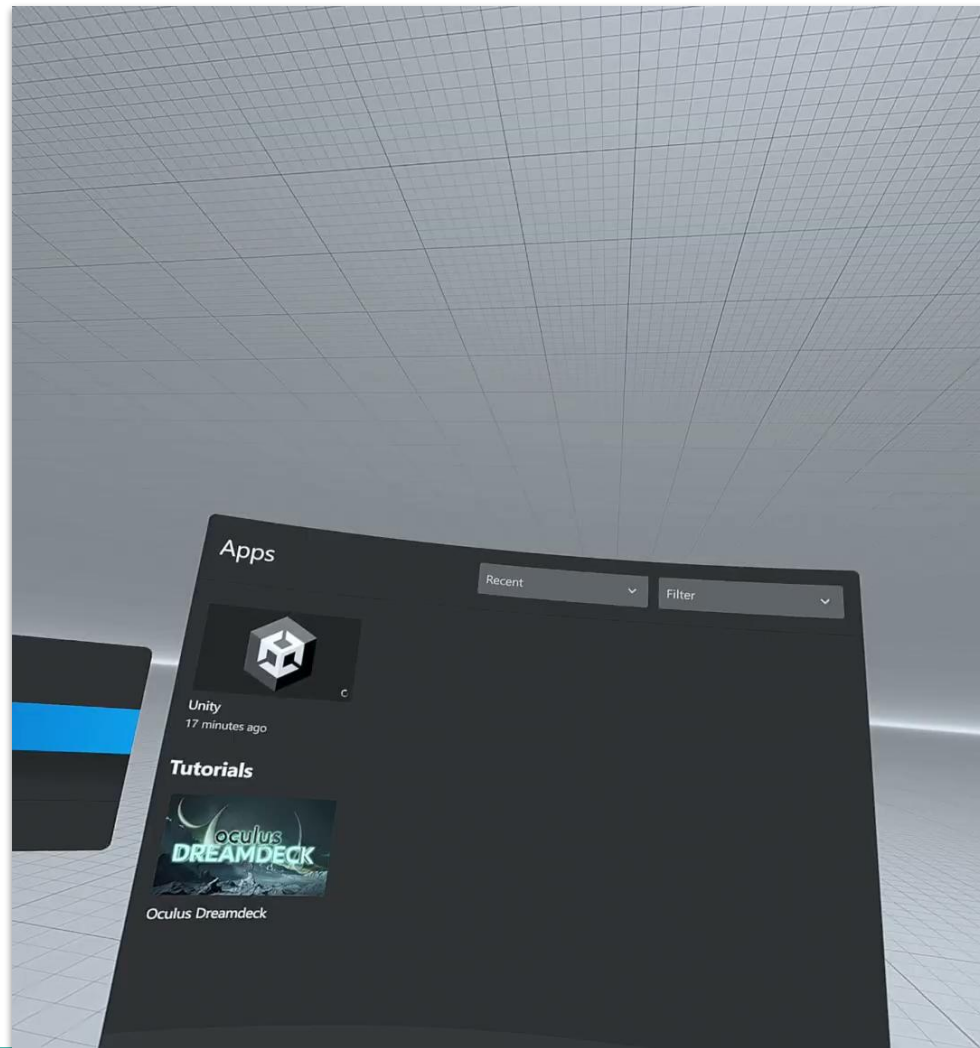


# Basic - 2

## Implement the calibration process.

- User can mark ArUco position with spatial anchors.
- User can see and adjust manually the anchors detected by RealSense in VR.





# Report

- Summarize what you did in this lab.
  - Show the basic and bonus you implemented.
  - Use screenshots & video demos to show your results.
- What you did to improve this device. Or how you can improve this device.
- Anything related to this lab.

# Hints

- Instantiate all objects from RealSense under the same parent.
- Add a script to move the parent object by Quest controller.
  - Every child will move with the parent.
  - Add rotation and movement on z-axis.

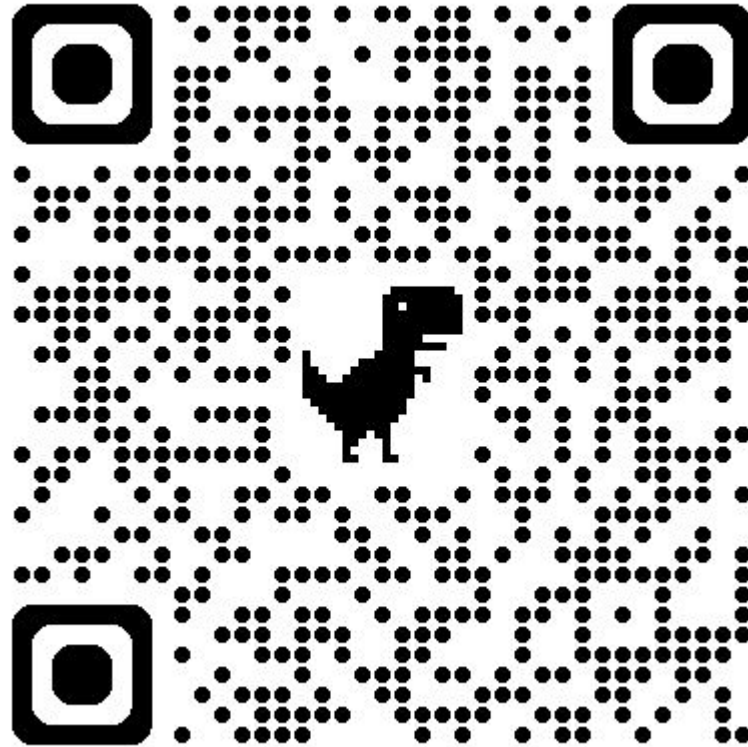
```
void Update()
{
    // Get value from controller thumb stick.
    Vector2 axis = OVRInput.Get(OVRInput.Axis2D.PrimaryThumbstick, controller);
    // Move the GameObject on xy plane.
    transform.Translate(new Vector3(axis.x, 0, axis.y) * speed * Time.deltaTime, Space.World);
}
```

# Hints

Server client message should support future applications.

- Spawn new objects in game according to the ArUcos IDs detected.
  - Is it a new one ? or the previous frame didn't detected it ?
- Track the movement and rotations of ArUco IDs.
  - How to distinguish between error and real movement ?
- Destroy game objects if the ArUco IDs are removed.
  - Is it removed ? or player accidentally blocked it ?

# Feedbacks



<https://forms.gle/RkRvD5nYEznGr2Jd7>