

Probability Model Components

Ω = sample space = set of all possible outcomes of an experiment

An event is a subset of Ω .

$P(E)$ = probability of the event E . $P(\cdot)$ is a function that maps events to the unit interval $[0, 1]$.

Probability Axioms

1. For any event E ,

$$0 \leq P(E) \leq 1.$$

2. $P(\Omega) = 1$

3. For disjoint events E_1, E_2, \dots ,

$$P\left(\bigcup_{i=1}^{\infty} E_i\right) = \sum_{i=1}^{\infty} P(E_i)$$

Other Probability Rules and Concepts

1. *Rule of Complements.* $P(E) = 1 - P(E^C)$

2. *General Addition Rule.* For any n events E_1, E_2, \dots, E_n ,

$$\begin{aligned} P(\cup_i E_i) &= \sum_i P(E_i) - \sum_{i < j} P(E_i \cap E_j) + \sum_{i < j < k} P(E_i \cap E_j \cap E_k) - \sum_{i < j < k < \ell} P(E_i \cap E_j \cap E_k \cap E_\ell) \\ &\quad + \dots + (-1)^{n+1} P(\cap_{i=1}^n E_i) \end{aligned}$$

3. *Conditional Probability.* Think of this whenever you need to compute a conditional probability. For events A and B , as long as $P(B) \neq 0$, define the conditional probability of A given that B occurs to be

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

4. *Law of Total Probability* This is VERY USEFUL. Think of this when you try to "condition on" an event to calculate the probability of another. Let E_1, \dots, E_n partition Ω . For any event E we have

$$P(B) = \sum_{k=1}^n P(B|E_k) P(E_k)$$

5. *Bayes's Rule.* Also very useful. Think of this whenever you need to compute a conditional probability.

$$P(E^*|B) = \frac{P(B|E^*) P(E^*)}{\sum_{k=1}^n P(B|E_k) P(E_k)}$$

6. *Independence.* Two events E_1 and E_2 are independent if

$$P(E_1 | E_2) = P(E_1)$$

$$\Leftrightarrow P(E_2 | E_1) = P(E_2) \Leftrightarrow P(E_1 \cap E_2)$$

Events E_1, \dots, E_n are mutually independent if $\forall S \subset \{1, \dots, n\}$

$$= P(E_1) P(E_2)$$

$$P\left(\bigcap_{k=1}^n E_k\right) = \prod_{k=1}^n P(E_k)$$

Pairwise independence does not imply mutual independence in general.

7. *A Multiplication Rule.*

$$P(\cap_{i=1}^n E_i) = P(E_1)P(E_2|E_1)P(E_3|E_2, E_1) \cdots P(E_n|E_1, E_2, \dots, E_{n-1})$$

~~Example 1~~ What's the chance current flows from A to B if switches are connected like this? Given the system fails, what is the probability that switch #5 is down?

Random Variables

A real random variable is a function

$$X: \Omega \rightarrow \mathbb{R}$$

Ω : Sample space

\mathbb{R} : Set of all real numbers.

The cumulative distribution function (cdf) of X is

$$F(x) = P(X \leq x) \quad \forall x \in \mathbb{R}$$

and has the properties

- (i) $\lim_{x \rightarrow -\infty} F(x) = 0$
- (ii) $\lim_{x \rightarrow +\infty} F(x) = 1$
- (iii) $F(x)$ is non decreasing
- (iv) $F(x)$ is right continuous.

A random variable whose possible values form a countable set is called discrete. The probability mass function (pmf) of the discrete random X is

$$P(X=x) = p(x) \leftarrow \text{pmf of } X.$$

The cdf of a discrete random variable is a step function:

A random variable X is a continuous random variable if there exists a function f such that the cdf F can be expressed as

$$F(x) = \int_{-\infty}^x f(t) dt$$

The function f is called the probability density function of the random variable, and if F is differentiable, then $f(x) = F'(x)$. The density f satisfies

1. $f(x) \geq 0 \quad \forall x \in \mathbb{R}$
2. $\int_{\mathbb{R}} f(x) dx = 1$

The expected value (or mean) of X is

$$\mu_x = \begin{cases} \sum x p(x) & \text{if } x \text{ is discrete.} \\ \int_{-\infty}^{\infty} x f(x) dx & \text{if } x \text{ is continuous.} \end{cases}$$

The n^{th} moment of the random variable X is

$$E(X^n) = \begin{cases} \sum x^n p(x) & \text{if } x \text{ is discrete} \\ \int_{-\infty}^{\infty} x^n f(x) dx & \text{if } x \text{ is continuous.} \end{cases}$$

and the n^{th} central moment is

$$E[(x - \mu_x)^n]$$

The second central moment is called the variance:

$$\begin{aligned} \text{Var}(x) &= E[(x - \mu)^2] \\ &= E(x^2) - [E(x)]^2 \end{aligned}$$

The random variables X_1, \dots, X_n are independent if

$$P(X_1 = x_1, \dots, X_n = x_n) = \prod_{i=1}^n P(X_i = x_i) \quad \text{if discrete}$$

$$f(x_1, \dots, x_n) = \prod_{i=1}^n f(x_i) \quad \text{if continuous}$$

Common Discrete Distributions

Distribution	pmf $p(x)$	mgf $\phi(t)$	Mean	Variance
Uniform(a,b) <i>Models outcome of experiment with equally likely outcomes in</i>	$\frac{\mathbf{1}\{x \in \{a, a+1, \dots, b\}\}}{b-a+1}$	$\frac{e^{at} - e^{(b+1)t}}{(b-a+1)(1-e^t)}$	$\frac{a+b}{2}$	$\frac{(b-a+1)^2-1}{12}$
Bernoulli(p) <i>Models number of successes in 1 trial</i>	$p^x(1-p)^{1-x}\mathbb{1}\{x \in \{0, 1\}\}$	$(pe^t + (1-p))$	p	$p(1-p)$
Binomial(n, p) <i>Models number of successes in n trials</i>	$\binom{n}{x}p^x(1-p)^{n-x}\mathbb{1}\{x \in \{0, 1, \dots, n\}\}$	$(pe^t + 1 - p)^n$	np	$(1-p)p$
Poisson(λ) <i>Models number of events occurring in a continuous time</i>	$\frac{e^{-\lambda}\lambda^x}{x!}\mathbb{1}\{x \in \{0, 1, 2, \dots\}\}$	$e^{-\lambda(1-e^t)}$	λ	λ
Geometric(p) <i>Models number of trials until the first success</i>	$p(1-p)^{x-1}\mathbb{1}\{x \in \{1, 2, 3, \dots\}\}$	$\frac{pe^t}{1-(1-p)e^t}$	$\frac{1}{p}$	$\frac{1-p}{p^2}$
Negative Binomial(r, p) <i>Models number of trials until r^{th} success</i>	$\binom{x-1}{r-1}p^r(1-p)^{x-r}, r \in \mathbb{Z}^+, x \in \{r, r+1, \dots\}$	$\left(\frac{pe^t}{1-(1-p)e^t}\right)^r$	$\frac{r}{p}$	$\frac{r(1-p)}{p^2}$

~~**Theorem 2** The geometric distribution is the only discrete distribution with the memoryless property.~~

~~**Proof**~~

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Common Continuous Distributions

Distribution	pdf $f(x)$	mgf $\phi(t)$	Mean	Variance
Uniform(a, b) <i>Models outcome of experiment that's equally likely to occur anywhere in (a, b)</i>	$\frac{1}{b-a} \mathbb{1}\{a \leq x \leq b\}$	$\frac{e^{tb}-e^{ta}}{t(b-a)}$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$
Exponential(λ) <i>Continuous analog of the geometric</i>	$\lambda e^{-\lambda x} \mathbb{1}\{x \geq 0\}$	$\frac{\lambda}{\lambda-t}$	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$
Gamma(k, λ) <i>also called Erlang(k, λ) when $k \in \mathbb{Z}^+$. Continuous analog of the negative binomial</i>	$\frac{\lambda e^{-\lambda x} (\lambda x)^{k-1}}{(k-1)!} \mathbb{1}\{x \geq 0\}$	$\left(\frac{\lambda}{\lambda-t}\right)^k$	$\frac{k}{\lambda}$	$\frac{k}{\lambda^2}$
Normal(μ, σ^2)	$\frac{1}{\sqrt{2\pi}\sigma} e^{-(x-\mu)^2/(2\sigma^2)}, x \in \mathbb{R}$	$e^{\mu t + \sigma^2 t^2/2}$	μ	σ^2

~~Theorem 3 The exponential distribution is the only continuous distribution with the memoryless property.~~

~~Proof See homework~~

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Functions of Random Variables

If X is a random variable and g is a function such that $g: \mathbb{R} \rightarrow S$ where $S \subset \mathbb{R}$, then $Y = g(X)$ is also a random variable. If X and Y are continuous random variables, we get the pdf of Y by

1. finding the cdf of Y ,
2. differentiating the cdf of Y to find the pdf of Y

Example 4 Let U be a Uniform($0, 1$) random variable. What is the distribution of $X = -\log U$? What is the distribution of $Y = \lambda^{-1} X$?

Multivariate Distributions

The distribution of the discrete random vector (X_1, \dots, X_n) is characterized by the joint probability mass function

$$p(x_1, \dots, x_n) = P(X_1 = x_1, \dots, X_n = x_n)$$

Example 5 Suppose an experiment can result in exactly one of r distinct outcomes, and the experiment is performed n times where the outcomes are independent. Let

$$p_i = P(\text{experiment results in outcome } i), \quad \sum_{i=1}^r p_i = 1$$

and

$$X_i = \text{number of times outcome } i \text{ occurs}$$

Then

$$P(X_1 = x_1, \dots, X_r = x_r) = n! \prod_{i=1}^r \frac{p_i^{x_i}}{x_i!}$$

The distribution of the continuous random vector is characterized by the joint cumulative distribution function F :

$$F(x_1, \dots, x_n) = P(X_1 \leq x_1, \dots, X_n \leq x_n) = \int_{(-\infty, x_1]} \cdots \int_{(-\infty, x_1]} f(s_1, \dots, x_n) ds_1 \cdots ds_n$$

Some Nice Relationships Between Random Variables

Assuming independence,

1. $X_i \sim \text{Bernoulli}(p) \Rightarrow \sum_i X_i \sim \text{binomial}(n, p)$
2. $X_i \sim \text{binomial}(n_i, p) \Rightarrow \sum_{i=1}^n X_i \sim \text{binomial}(\sum_i n_i, p)$
3. $X_i \sim \text{Poisson}(\lambda_i) \Rightarrow \sum_i X_i \sim \text{Poisson}(\sum_i \lambda_i)$
4. X_1, \dots, X_r iid $\text{geometric}(p) \Rightarrow \sum_{i=1}^r X_i \sim \text{negative binomial}(r, p)$
5. $X_1, \dots, X_k \sim \text{iid exp}(\lambda) \Rightarrow \sum_{i=1}^k X_i \sim \text{Erlang}(k, \lambda)$

Useful Laws/Rules/etc.

1. $E[\sum_{i=1}^n a_i g_i(X_i) + b] = \sum_{i=1}^n a_i E g_i(X_i) + nb$, regardless of whether or not the X_i are independent.
2. $\text{Var}(\sum_{i=1}^n a_i g_i(X_i) + b) = \sum_{i=1}^n a_i^2 \text{Var}(g_i(X_i)) + 2 \sum_{1 \leq i < j \leq n} a_i a_j \text{Cov}(g_i(X_i), g_j(X_j))$
3. *Law of Total Expectation.*

$$E[X] = \sum_k E[X|A_k]P(A_k) \text{ for disjoint and exhaustive } A_k.$$

4. *Conditional Variance Formula.*

5. *Tower Property.* $E[X|Y] = E[E[X|Y, Z]|Y]$. Also

$$EX = E[E[X|Y]] = \sum_y E[X|Y = y]P(Y = y) \text{ if } Y \text{ is discrete.}$$

$$EX = E[E[X|Y]] = \int_{\mathbf{R}} E[X|Y = y]f_Y(y)dy \text{ if } Y \text{ is continuous.}$$

6. If X_1, \dots, X_n are independent,

$$(a) E[\prod_{i=1}^n g_i(X_i)] = \prod_{i=1}^n E g_i(X_i)$$

$$(b) \text{Var}(\sum_{i=1}^n X_i) = \sum_{i=1}^n \text{Var}(X_i)$$

7. *Law of Total Probability for Random Variables.*

$$P(E) = \sum_{i=1}^{\infty} P(E|X = x_i)P(X = x_i) \text{ if } X \text{ is discrete.}$$

$$P(E) = \int_{\mathbf{R}} P(E|X = x)f(x)dx \text{ if } X \text{ is continuous.}$$

8. For continuous random variables, the conditional density function of X_1 given $X_2 = x_2$ is

$$f_{X_1|X_2}(x_1|x_2) = \frac{f(x_1, x_2)}{f_{X_2}(x_2)}$$

and

$$E[X_1|X_2 = x_2] = \int_{\mathbf{R}} x_1 f_{X_1|X_2}(x_1|x_2)dx_1$$

Transforms

The characteristic function of the random variable X is defined to be

$$\psi_X(t) = Ee^{itX}$$

where $i = \sqrt{-1}$. Characteristic functions always exist and are unique for each random variable: if you know the characteristic function, you know the distribution, and vice-versa.

The moment generating function of the random variable X is defined to be

$$\phi_X(t) = Ee^{tX}$$

They do not exist for some random variables, but when they do, they are unique. The moment generating function and characteristic function of X are related through

$$\phi_X(it) = \psi_X(t)$$

Moment generating functions have the useful property that the n th derivative of the moment generating function evaluated at 0 is the n th moment of the random variable:

$$\frac{d^n}{dt^n} \phi_X(t)|_{t=0} = E[X^n]$$

The Laplace transform L_X of the random variable X is defined to be

$$L_X(t) := Ee^{-tX}$$

Laplace transforms exist for all non-negative random variables and are related to characteristic functions and moment generating functions through

$$L_X(t) = \psi_X(it) \quad L_X(t) = \phi_X(-t)$$

Limit Theorems

Theorem 7 *Markov's Inequality. If X is a nonnegative random variable, then for any $a > 0$*

$$P(X \geq a) \leq \frac{EX}{a}$$

Proof Pages 77 and 78. ■

Theorem 8 *Chebyshev's Inequality. Let X be any random variable with mean μ and variance σ^2 . Then the chance that X is at least k standard deviations from its mean is bounded from above like this:*

$$P(|X - \mu| \geq k\sigma) \leq \frac{1}{k^2}$$

Proof Page 78. ■

Theorem 9 *Classical Central Limit Theorem. Let X_1, X_2, \dots, X_n be independent and identically distributed random variables with mean μ and variance $\sigma^2 < \infty$. Then*

$$P\left(\frac{n^{-1} \sum_{i=1}^n X_i - \mu}{\sigma/\sqrt{n}} \leq z\right) \rightarrow P(Z \leq z)$$

as $n \rightarrow \infty$. Here, Z is normal random variable with mean $\mu = 0$ and variance $\sigma^2 = 1$ (called a standard normal).

Example 10 ~~Pianos weigh 400 lbs on average, with a standard deviation of 25 lbs. Matt's living room floor will support 20,300 lbs. What's the chance his floor will support the 50 pianos he has stored in the living room?~~

Theorem 11 *Strong Law of Large Numbers. Let X_1, X_2, \dots be independent and identically distributed random variables with mean μ . Then*

$$P\left(\left|\lim_{n \rightarrow \infty} n^{-1} \sum_{k=1}^n X_k - \mu\right| > \epsilon\right) = 0$$

In other words,

$$\frac{X_1 + X_2 + \dots + X_n}{n} \rightarrow \mu \quad \text{as } n \rightarrow \infty$$

with probability 1.

Each distribution has a unique Laplace transform when it exists. Also, note $e^{-t} \in [0, 1]$ for all $t > 0$, so Laplace transforms are always in $[0, 1]$.

The probability generating function of the discrete random variable X is defined to be

$$P_X(t) = E s^X$$

When they exist, they uniquely determine distributions of random variables. Probability generating functions have the useful property that probabilities of random variables can be obtained by successive differentiation:

$$\frac{d^k}{ds^k} P_X(s) = k! P(X = k)$$

~~**Example 6** *The sum of independent Poissons is Poisson.*~~