Dijkstra's Alg

· GOAl: Find shortest path tree (a tree

that contains shortest paths from source s to)
every other node).

Undirected Graph

2
3
4
5
5
5
5
6
14
14
3
6
14
14
3
6
14
14

· How it works

1) Create distTo and edgeTo lists and priority queme PQ (which prioritizes nodes doset to source)

· distTo(V): best known distance from source s to V

· edgeTo(v): best Known vertex predelessor to v

· PQ contains all unvisited vertices in order of dist To

(2) Initialize:

For each index i corresponding to vertex i, set dist To (i) = ∞; except vertex ~ → distro(a) = 0.

· for each index i corresponding to vertex i, set edge to (i) = null.

(3) Repeat:

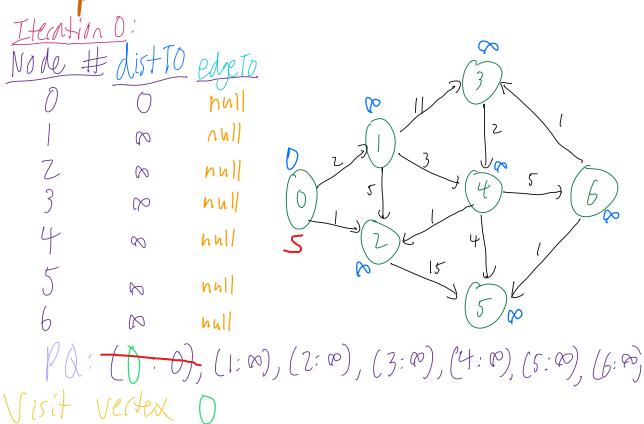
· Visit V: remove closest vertex V from Po

· Relax edges

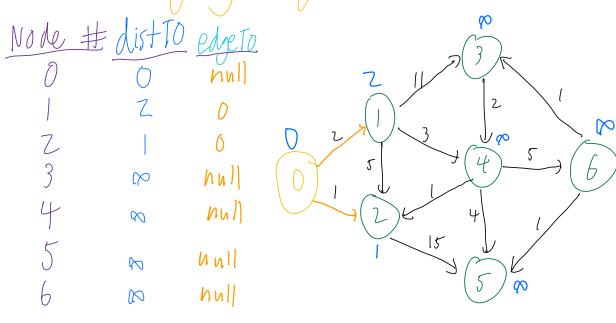
For each outgaing edge e from v: if dist(s,v) + e < distTo &: distTo(x) = dist(s,v) + e edgeTo(x) = V

(4) End: when PQ is empty

· Example:



Relax outhing edges from vertex 0

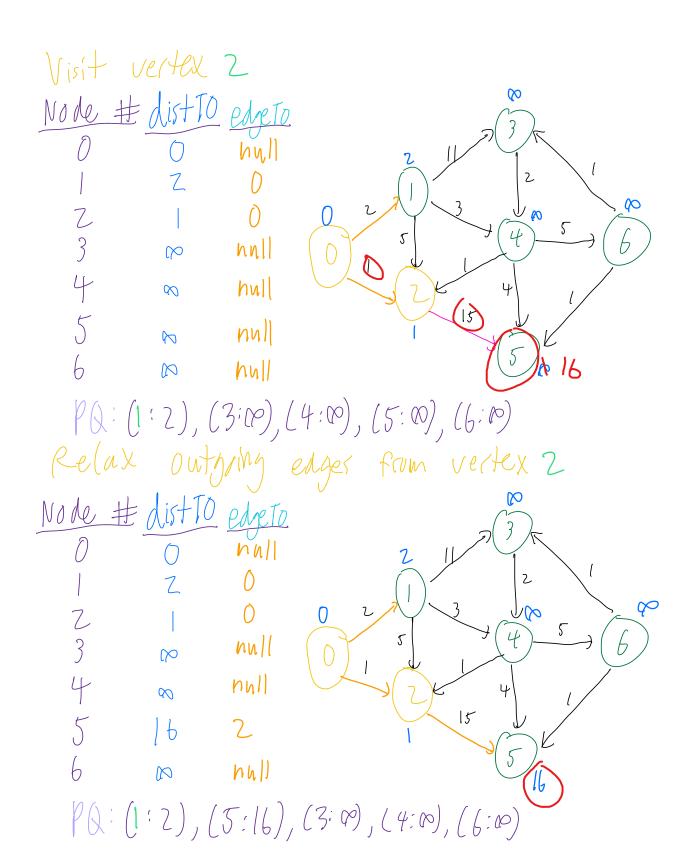


PQ: (1:2), (3:00), (4:00), (5:00), (6:00)

Iteration 2

Note =	# distIC	edeto	$\frac{3}{3}$
0	0	hull	2 11
	2	0	
2		0	0 2 3 4 4 5
3	(null	
4	80	hall	2 4
5	80	hull	15
6	\otimes	null	3 100
W (.	()	(1,)	(2:n) $(1:m)$ $(F m)$ $((:n)$

PQ: (3:1), (1:2), (3:10), (4:10), (5:10), (6:10)



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