COMS6998_015 Prac Deep Learning System HW1

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Github:

- Everything used to produce this notebook:
 https://github.com/AllenChenCU/coms6998-dl-sys/tree/main/hw1
- All theory and code are in this notebook, except the code for problem 3. See the below link for problem 3 code.
- Code for Problem 3: https://github.com/AllenChenCU/coms6998-dlsys/blob/main/hw1/prob3_code.py

Problem 1 - Bias Variance Tradeoff, Regularization

1.1 Derive the bias-variance decomposition for a regression problem

$$\begin{split} & \text{MSE} = \frac{1}{t} \sum_{i=1}^{t} (f(x_i) + \epsilon - g(x_i))^2 \\ & \mathbb{E}[\text{MSE}] = \mathbb{E}[\frac{1}{t} \sum_{i=1}^{t} (f(x_i) + \epsilon - g(x_i))^2] \\ & \mathbb{E}[\text{MSE}] = \frac{1}{t} \mathbb{E}[\sum_{i=1}^{t} (f(x_i) - g(x_i))^2 + 2(f(x_i) - g(x_i))\epsilon + \epsilon^2] \\ & \mathbb{E}[\text{MSE}] = \frac{1}{t} \mathbb{E}[\sum_{i=1}^{t} (f(x_i) - g(x_i))^2] + \mathbb{E}[\epsilon^2] \\ & \mathbb{E}[\text{MSE}] = \frac{1}{t} \mathbb{E}[\sum_{i=1}^{t} (f(x_i) - g(x_i))^2] + \sigma^2 \\ & \mathbb{E}[\text{MSE}] = \frac{1}{t} \mathbb{E}[\sum_{i=1}^{t} (f(x_i) - \mathbb{E}[g(x_i)] + \mathbb{E}[g(x_i)] - g(x_i))^2] + \sigma^2 \\ & \mathbb{E}[\text{MSE}] = \frac{1}{t} \mathbb{E}[\sum_{i=1}^{t} (f(x_i) - \mathbb{E}[g(x_i)])^2 + 2(f(x_i) - \mathbb{E}[g(x_i)])(\mathbb{E}[g(x_i)] - g(x_i)) + (\mathbb{E}[\text{MSE}]) \\ & \mathbb{E}[\text{MSE}] = \frac{1}{t} \mathbb{E}[\sum_{i=1}^{t} (f(x_i) - \mathbb{E}[g(x_i)])^2 + (\mathbb{E}[g(x_i)] - g(x_i))^2] + \sigma^2 \\ & \mathbb{E}[\text{MSE}] = \frac{1}{t} \sum_{i=1}^{t} (f(x_i) - \mathbb{E}[g(x_i)])^2 + \frac{1}{t} \mathbb{E}[\sum_{i=1}^{t} (\mathbb{E}[g(x_i)] - g(x_i))^2] + \sigma^2 \\ & \mathbb{E}[\text{MSE}] = Bias^2 + Variance + Noise \end{split}$$

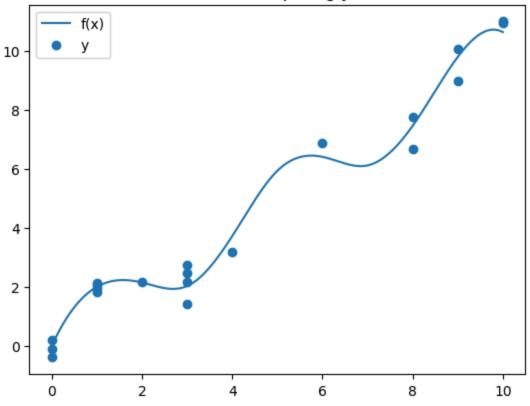
1.2 Scatter plot for y and f(x)

```
y(x) = x + sin(1.5x) + N(0, 0.3) f(x) = x + sin(1.5x)
```

```
In [1]: %load ext autoreload
        %autoreload 2
        import numpy as np
        import pandas as pd
        import random
        import math
        import matplotlib.pyplot as plt
        from scipy.interpolate import interp1d
        random.seed(42)
        def y_func(x, mu, sigma):
             noise = random.gauss(mu=mu, sigma=sigma)
             return x + math.sin(1.5*x) + noise
        def f func(x):
             return x + math.sin(1.5*x)
        MU = 0
        SIGMA = math.sqrt(0.3)
        N = 20
        XMAX = 10
        X = [random.randint(0, XMAX) for _ in range(N)]
        Y = [y_func(x, MU, SIGMA) for x in X]
        F = [f_func(x) \text{ for } x \text{ in } X]
        # display dataset
        dataset = pd.DataFrame(\{"x": X, "y": Y, "f(x)": F\})
        print(dataset)
        # Plot
        X_1 = np.arange(XMAX + 1)
        F_1 = [f_func(x) \text{ for } x \text{ in } X_1]
        x = np.linspace(0, XMAX, 500)
        smooth_func = interp1d(X_1, F_1, kind='cubic')
        plt.title("Problem 1.2: Comparing y and f(x)")
        plt.plot(x_smooth, smooth_func(x_smooth), label="f(x)")
        plt.scatter(X, Y, label="y")
        plt.legend()
        plt.show()
```

```
f(x)
     Χ
    10
                    10.650288
0
        11.009942
1
     1
         2.058022
                      1.997495
2
     0
        -0.404395
                      0.000000
3
         3.164831
                      3.720585
     4
4
     3
         2.157397
                      2.022470
5
     3
         2.740578
                      2.022470
6
     2
         2.163936
                      2.141120
7
     1
         1.939259
                      1.997495
8
    10
        10.941554
                     10.650288
                      7.463427
9
     8
         6.667288
10
     1
         1.826454
                      1.997495
11
        10.072367
                      9.803784
12
         6.890502
                      6.412118
13
        -0.131798
                      0.000000
14
         0.206272
                      0.000000
15
     1
         2.133447
                      1.997495
16
     3
         2.450968
                      2.022470
17
         1.412733
                      2.022470
18
     8
         7.774671
                      7.463427
19
         8.974247
                      9.803784
```

Problem 1.2: Comparing y and f(x)



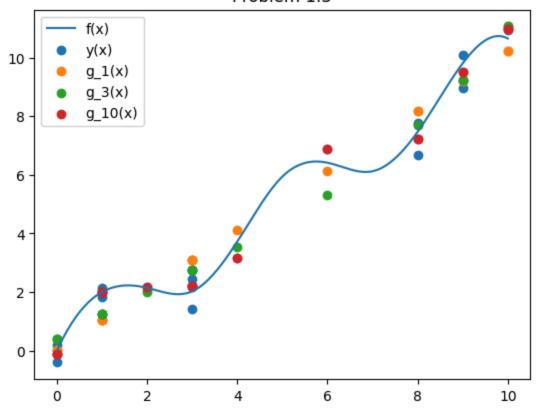
1.3

$$g_n(x) = B_0 + B_1 x + B_2 x^2 + \ldots + B_n x^n$$

In [2]: from sklearn.linear_model import LinearRegression
from sklearn.preprocessing import PolynomialFeatures

```
x train = dataset[["x"]]
 y train = dataset["y"].values
 f train = dataset["f(x)"].values
 # fit estimators
 model poly 1 = LinearRegression().fit(x train, y train)
 dataset["g_1"] = model_poly_1.predict(x_train)
 print(f"Model g 1 intercept: {model poly 1.intercept }")
 print(f"Model g_1 coeefficients: {model_poly_1.coef_}")
 x train poly 3 = PolynomialFeatures(degree=3).fit transform(x train)
 model poly 3 = LinearRegression().fit(x train poly 3, y train)
 dataset["q 3"] = model poly 3.predict(x train poly 3)
 print(f"Model g 3 intercept: {model poly 3.intercept }")
 print(f"Model g_3 coeefficients: {model_poly_3.coef_}")
 x_train_poly_10 = PolynomialFeatures(degree=10).fit_transform(x_train)
 model poly 10 = \text{LinearRegression}().\text{fit}(x \text{ train poly } 10, \text{ y train})
 dataset["g 10"] = model poly 10.predict(x train poly 10)
 print(f"Model g_10 intercept: {model_poly_10.intercept_}")
 print(f"Model g_10 coeefficients: {model_poly_10.coef_}")
 # plot
 X 1 = np.arange(XMAX + 1)
 F 1 = [f func(x) for x in X 1]
 x_{smooth} = np.linspace(0, XMAX, 500)
 smooth func = interp1d(X 1, F 1, kind='cubic')
 dataset.sort_values(["x"], inplace=True)
 plt.title("Problem 1.3")
 plt.plot(x smooth, smooth func(x smooth), label="f(x)")
 plt.scatter(dataset['x'], dataset['y'], label="y(x)")
 plt.scatter(dataset['x'], dataset['q 1'], label="q 1(x)")
 plt.scatter(dataset['x'], dataset['g_3'], label="g_3(x)")
 plt.scatter(dataset['x'], dataset['g_10'], label="g_10(x)")
 plt.legend()
 plt.show()
Model g 1 intercept: 0.026180552877201002
Model g 1 coeefficients: [1.01859347]
Model g_3 intercept: 0.3929045262658426
Model q 3 coeefficients: [ 0.
                                       0.89013749 -0.055449
                                                                0.007310941
Model q 10 intercept: -0.10997356210055464
Model g 10 coeefficients: [ 0.00000000e+00 2.39270701e+00 5.71449973e-01 -
7.67018200e-01
 -5.73316016e-01 7.01805044e-01 -2.76610179e-01 5.62215600e-02
 -6.33669879e-03 3.75754822e-04 -9.14406761e-06]
```

Problem 1.3



Estimator g_1 is underfitting, and estimator g_{10} is overfitting.

1.4

$$Bias^2 = rac{1}{t}\sum_{i=1}^t (f(x_i) - \mathbb{E}[g(x_i)])^2$$

The term $f(x_i)$ is the truth value at x_i

The Term expected value of the prediction $\mathbb{E}[g(x_i)]$ is the average of the prediction for x_i across all possible datasets

$$Variance = rac{1}{t}\mathbb{E}[\sum_{i=1}^{t}(\mathbb{E}[g(x_i)] - g(x_i))^2]$$

$$MSE = \frac{1}{t} \sum_{i=1}^{t} (f(x_i) + \epsilon - g(x_i))^2$$

```
In [3]: from collections import defaultdict
    from sklearn.model_selection import train_test_split
    from sklearn.metrics import mean_squared_error
    from sklearn.linear_model import Ridge

# config
MU = 0
SIGMA = math.sqrt(0.3)
N = 50 # dataset size
N_test = 10
N_train = 40
```

```
XMAX = 10
M = 100 # number of datasets
DEGREE = 15 # try polynomial regression up to degree DEGREE
random.seed(21)
np.random.seed(21)
x = np.linspace(0, XMAX, N)
x = np.random.permutation(x)
X_train = np.array(x[:N_train])
X_test = np.array(x[N_train:])
def simulate(degree, X_train, X_test, regularize=False):
   y preds = []
   y_{tests} = []
    for _ in range(M):
        # Generate dataset
        y_train = np.array([y_func(x, MU, SIGMA) for x in X_train])
        y_test = np.array([y_func(x, MU, SIGMA) for x in X_test])
        # Transform dataset
        poly_transformer = PolynomialFeatures(degree=degree)
        X train poly = poly transformer.fit transform(np.expand dims(X train
        X_test_poly = poly_transformer.transform(np.expand_dims(X_test, axis
        # Train
        if regularize:
            model = Ridge(alpha=0.5).fit(X_train_poly, y_train)
        else:
            model = LinearRegression().fit(X_train_poly, y_train)
        # Predict
        y_pred = model.predict(X_test_poly)
        y_preds.append(y_pred)
        y tests.append(y test)
    y_preds = np.stack(y_preds, axis=0)
    y_tests = np.stack(y_tests, axis=0)
    f = np.array([f_func(x) for x in X_test])
    # compute MSE
    mse = mean squared error(y tests, y preds)
    # compute bias-squared
    exp_preds = np.mean(y_preds, axis=0)
    bias_squared = np.mean(np.square(f - exp_preds))
    variance = np.mean(np.mean(np.square(exp_preds - y_preds), axis=0))
    computed_noise = mse - (bias_squared + variance)
    return {
        "mse": float(mse),
        "bias_squared": float(bias_squared),
        "variance": float(variance),
```

```
"computed_noise": float(computed_noise),
}

results_map = {}

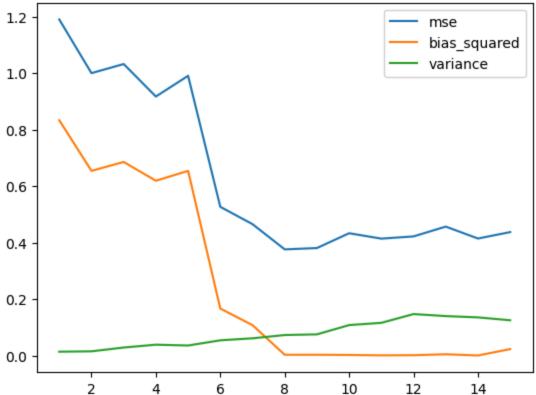
for d in range(1, DEGREE + 1):
    results_map[f"g_{d}"] = simulate(d, X_train, X_test)

results_df = pd.DataFrame(results_map)
display(results_df)
complexity = np.arange(1, 16)

# plot
plt.title("Model complexity vs Error")
plt.plot(complexity, results_df.T["mse"].values, label="mse")
plt.plot(complexity, results_df.T["bias_squared"].values, label="bias_squared")
plt.plot(complexity, results_df.T["variance"].values, label="variance")
plt.legend()
plt.show()
```

	g_1	g_2	g_3	g_4	g_5	g_6	g_
mse	1.190326	1.000286	1.032534	0.917501	0.990884	0.526866	0.46559
bias_squared	0.833505	0.654311	0.685812	0.619258	0.654237	0.166760	0.10789
variance	0.013945	0.015273	0.028701	0.038775	0.035863	0.054237	0.06135
computed_noise	0.342875	0.330703	0.318021	0.259469	0.300784	0.305870	0.29635





The Best model has a polynomial degree of 8, where it has the lowest MSE and the optimal balance between bias_squared and variance.

1.5 Regularization

```
In [5]: import warnings
warnings.filterwarnings("ignore")

results_map = {}

results_map[f"g_10"] = simulate(10, X_train, X_test, False)
results_map[f"g_10_L2"] = simulate(10, X_train, X_test, True)

results_df = pd.DataFrame(results_map)
results_df
```

```
        mse
        0.408168
        0.376128

        bias_squared
        0.001975
        0.015525

        variance
        0.090800
        0.077387

        computed_noise
        0.315392
        0.283216
```

Going from the unregularized order 10 polynomial model to regularized model,

- 1. MSE decreased slightly
- 2. $Bias^2$ increased
- 3. Variance decreased

Therefore, the regularized model has a higher bias, lower variance, and lower MSE.

This is because the regularized model penalized complex model with larger coefficients, so that the model doesn't fit too closely to the data. This leads to better generalization to unseen data. Thus, it results in lower MSE on testing dataset. Bias increased because regularization simplified the model, and variance decreased because it limited the model's complexity.

Problem 2 - Precision, Recall, ROC

2.1

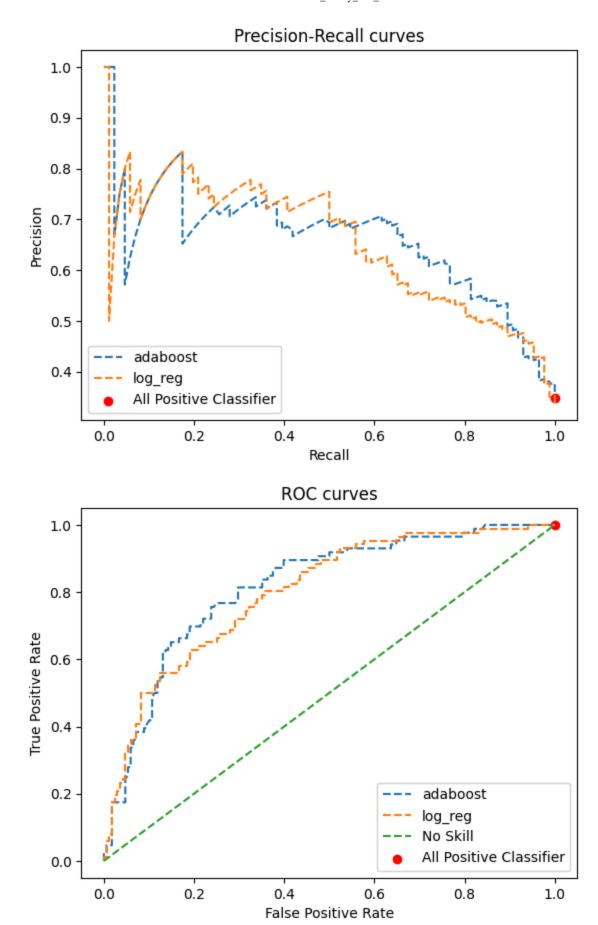
Q: Does true negative matter for both ROC and PR curve? Argue why each point on ROC curve corresponds to an unique point on PR curve.

A: True negative is important in the calculation of false positive rate (FPR), which is the x-axis of the ROC curve. However, true negative does not matter for PR curve since

precision and recall metrics don't use true negative in their calculation. Each point on ROC curve corresponds to an unquie point on PR curve because both corresponding points depend on the same set of predictions at a certain threshold. These predictions at a certain threshold form a specific confusion matrix, which consists of TP, TN, FP, FN that are directly used to calculate precision, recall, false positive rate, and true positive rate. Precision and recalls are used to plot PR curve, and FPR and TPR are used to plot ROC curve.

```
In [6]: from scipy.io import arff
        from sklearn.preprocessing import StandardScaler
        from sklearn.pipeline import Pipeline
        from sklearn.model selection import train test split
        from sklearn.ensemble import AdaBoostClassifier
        from sklearn.linear_model import LogisticRegression
        from sklearn.metrics import roc curve, precision recall curve
        from sklearn.metrics import PrecisionRecallDisplay
        from sklearn.metrics import auc
        from sklearn.metrics. ranking import binary clf curve
        # load data
        arff file = arff.loadarff('dataset 37 diabetes.arff')
        prob2 2 data = pd.DataFrame(arff file[0])
        prob2_2_data['class'] = prob2_2_data['class'].map({b"tested_positive": 1, b"
        X = prob2 2 data[[col for col in prob2 2 data.columns if col != 'class']]
        y = prob2_2_data['class'].values
        # split
        X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.33, re
        def make_pipe(model_name, model):
            return Pipeline([("scaler", StandardScaler()), (model_name, model)])
        results map = {}
        models = [
            ("adaboost", AdaBoostClassifier(n_estimators=100, algorithm="SAMME", rar
            ("log_reg", LogisticRegression()),
        for model_name, model in models:
            pipe = make pipe(model name, model)
            pipe.fit(X_train, y_train)
            y_pred = pipe.predict_proba(X_test)[:, 1]
            fpr, tpr, thresholds_roc = roc_curve(y_test, y_pred)
            precision, recall, thresholds_pr = precision_recall_curve(y_test, y_pred
            auroc = auc(fpr, tpr)
            aupr = auc(recall, precision)
            pi = 268/768 # proportion of positives in dataset
            recallG = [float((r - pi) / ((1-pi)*r + 0.0001)) for r in recall]
            precisionG = [float((p - pi) / ((1-pi)*p + 0.0001)) for p in precision]
            auprg = auc(recallG, precisionG)
            results_map[model_name] = {
```

```
"fpr": fpr,
        "tpr": tpr,
        "precision": precision,
        "recall": recall,
        "thresholds_pr": thresholds_pr,
        "thresholds_roc": thresholds_roc,
        "auroc": auroc,
        "aupr": aupr,
        "auprg": auprg,
   }
plt.title("Precision-Recall curves")
plt.plot(results_map["adaboost"]["recall"], results_map["adaboost"]["precisi
plt.plot(results_map["log_reg"]["recall"], results_map["log_reg"]["precisior
plt.scatter([1], [pi], label="All Positive Classifier", color="red")
plt.ylabel("Precision")
plt.xlabel("Recall")
plt.legend(loc="lower left")
plt.show()
plt.title("ROC curves")
plt.plot(results_map["adaboost"]["fpr"], results_map["adaboost"]["tpr"], '--
plt.plot(results_map["log_reg"]["fpr"], results_map["log_reg"]["tpr"], '--',
plt.plot(np.linspace(0, 1, 100), np.linspace(0, 1, 100), '--', label="No Ski
plt.scatter([1], [1], label="All Positive Classifier", color="red")
plt.ylabel("True Positive Rate")
plt.xlabel("False Positive Rate")
plt.legend()
plt.show()
```



Note: For all positive classifier, we have

```
TPR = 1; FPR = 1; Precision = \frac{P}{(P+N)} = \frac{268}{768}; Recall = 1
```

2.3 PR gain curve

```
In [7]: print(f"AUROC for adaboost {results_map["adaboost"]["auroc"]}")
    print(f"AUPR for adaboost {results_map["adaboost"]["aupr"]}")
    print(f"AUPRG for adaboost {results_map["adaboost"]["auprg"]}")

    print(f"AUROC for logistic regression {results_map["log_reg"]["auroc"]}")
    print(f"AUPR for logistic regression {results_map["log_reg"]["aupr"]}")
    print(f"AUPRG for logistic regression {results_map["log_reg"]["auprg"]}")

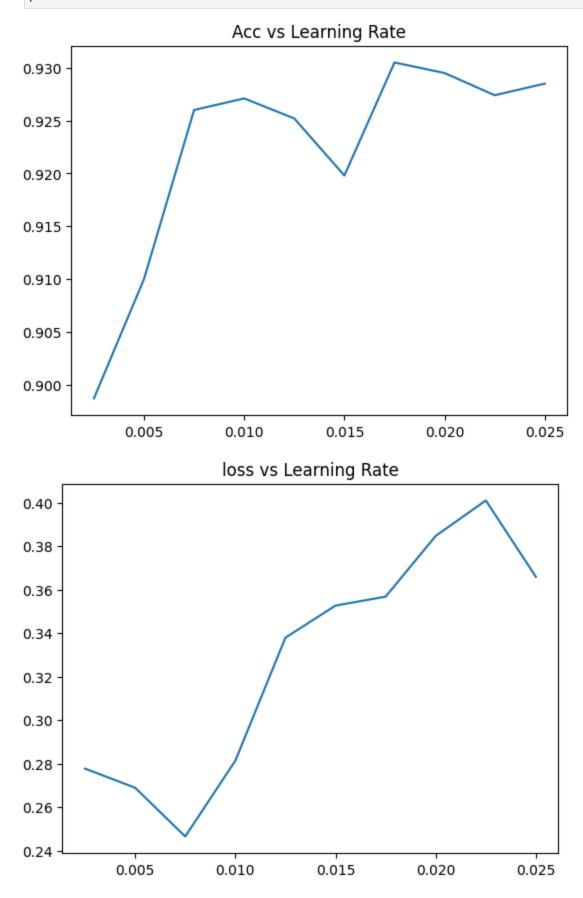
AUROC for adaboost 0.8160991140642303
    AUPR for adaboost 0.6583825843463507
    AUPRG for logistic regression 0.7994878183831672
    AUROC for logistic regression 0.6522517882377267
    AUPRG for logistic regression 3476.754018649303
```

I disagree that PR gain curves should be used over PR curves. There could be unstable values that fall into the negative range when calculating the precision gain and recall gain values. In that case, my AUPRG value ends up becoming larger than 1.

Problem 3 - Learning Rate, Batch Size, FashionMNIST

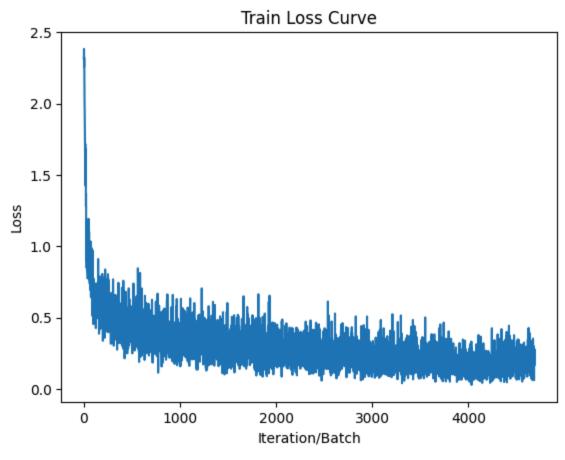
```
In [8]: import ison
        with open("prob3_1_results_1.json", "r") as f:
            prob3 1 results = json.load(f)
        lrs = []
        accs = []
        losses = []
        for i, results in prob3 1 results.items():
            lrs.append(results["lr"])
            accs.append(results["val_acc"][-1])
            losses.append(results["val loss"][-1])
        prob3_1_results_df = pd.DataFrame({"lr": lrs, "acc": accs, "loss": losses})
        prob3_1_results_df.sort_values(["lr"], inplace=True)
        plt.title("Acc vs Learning Rate")
        plt.plot(prob3_1_results_df["lr"], prob3_1_results_df["acc"])
        plt.show()
        plt.title("loss vs Learning Rate")
```

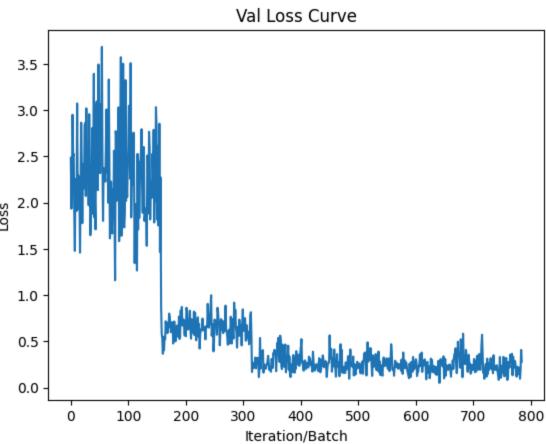
plt.plot(prob3_1_results_df["lr"], prob3_1_results_df["loss"])
plt.show()

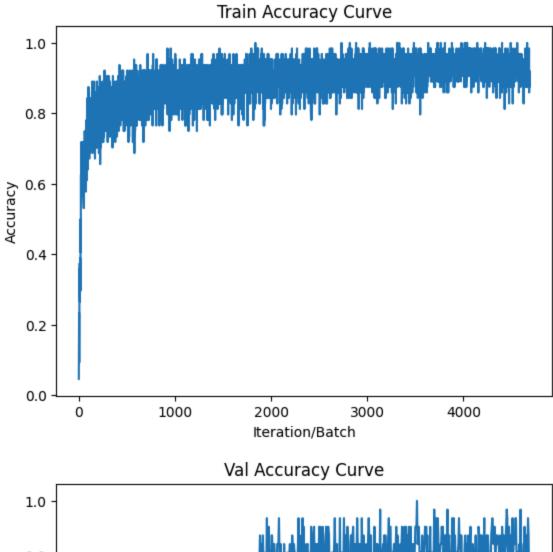


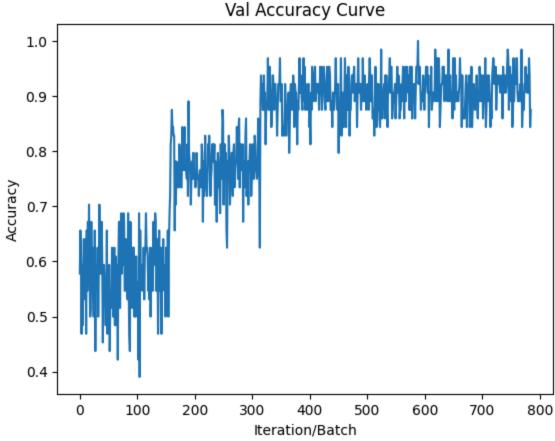
 $lr_{max} = 0.01$

```
In [9]: with open("prob3_2_results_1.json", "r") as f:
            prob3 2 results = json.load(f)
        num_iteration_train = np.arange(len(prob3_2_results["train_batch_losses"]))
        num_iteration_val = np.arange(len(prob3_2_results["val_batch_losses"]))
        plt.title("Train Loss Curve")
        plt.plot(num_iteration_train, prob3_2_results["train_batch_losses"])
        plt.xlabel("Iteration/Batch")
        plt.ylabel("Loss")
        plt.show()
        plt.title("Val Loss Curve")
        plt.plot(num_iteration_val, prob3_2_results["val_batch_losses"])
        plt.xlabel("Iteration/Batch")
        plt.ylabel("Loss")
        plt.show()
        plt.title("Train Accuracy Curve")
        plt.plot(num_iteration_train, prob3_2_results["train_batch_accs"])
        plt.xlabel("Iteration/Batch")
        plt.ylabel("Accuracy")
        plt.show()
        plt.title("Val Accuracy Curve")
        plt.plot(num_iteration_val, prob3_2_results["val_batch_accs"])
        plt.xlabel("Iteration/Batch")
        plt.ylabel("Accuracy")
        plt.show()
```









```
In [10]: with open("prob3_3_results.json", "r") as f:
             prob3_3_results = json.load(f)
         train_losses = prob3_3_results["train_loss"]
         batch_size = 32
         batch_sizes = []
         while batch_size <= 8192:</pre>
             batch_sizes.append(batch_size)
             batch size *= 2
         # each epoch uses one batch_size
         # epoch0: 32
         # epoch1: 64
         # ...
         plt.title("Training Loss vs Batch size")
         plt.plot(batch_sizes, train_losses)
         plt.xlabel("Batch Size")
         plt.ylabel("Loss")
         plt.show()
```

0.5 - 0.4 - 0.2 - 0.1 -

The final model from problem 3.3 as shown in the plot above is similar to the Training Loss curve shown in the plot in Problem 3.2 with cyclical learning rate policy. They both show similar steep downward trend.

Batch Size

Problem 4 - Convolutional Neural Networks Architectures

Table 1. VGG19 Activation units and paramteters calculation

Layer	Number of Activations (Memory)	parameters (Compute)			
Input	224 * 224 * 3 = 150K	0			
Conv3-64	224 * 224 * 64 = 3.2M	(3 * 3 * 3) * 64 = 1,728			
Conv3-64	224 * 224 * 64 = 3.2M	(3 * 3 * 64) * 64 = 36,864			
Pool2	112 * 112 * 64 = 800K	0			
Conv3-128	112 * 112 * 128 = 1.6M	(3 * 3 * 64) * 128 = 73,728			
Conv3-128	112 * 112 * 128 = 1.6M	(3 * 3 * 128) * 128 = 147,456			
Pool2	56 * 56 * 128 = 400K	0			
Conv3-256	56 * 56 * 256 = 800K	(3 * 3 * 128) * 256 = 294,912			
Conv3-256	56 * 56 * 256 = 800K	(3 * 3 * 256) * 256 = 589,824			
Conv3-256	56 * 56 * 256 = 800K	(3 * 3 * 256) * 256 = 589,824			
Conv3-256	56 * 56 * 256 = 800K	(3 * 3 * 256) * 256 = 589,824			
Pool2	28 * 28 * 256 = 200K	0			
Conv3-512	28 * 28 * 512 = 400K	(3 * 3 * 256) * 512 = 1,179,648			
Conv3-512	28 * 28 * 512 = 400K	(3 * 3 * 512) * 512 = 2,359,296			
Conv3-512	28 * 28 * 512 = 400K	(3 * 3 * 512) * 512 = 2,359,296			
Conv3-512	28 * 28 * 512 = 400K	(3 * 3 * 512) * 512 = 2,359,296			
Pool2	14 * 14 * 512 = 100K	0			
Conv3-512	14 * 14 * 512 = 100K	(3 * 3 * 512) * 512 = 2,359,296			
Conv3-512	14 * 14 * 512 = 100K	(3 * 3 * 512) * 512 = 2,359,296			
Conv3-512	14 * 14 * 512 = 100K	(3 * 3 * 512) * 512 = 2,359,296			
Conv3-512	14 * 14 * 512 = 100K	(3 * 3 * 512) * 512 = 2,359,296			
Pool2	7 * 7 * 512 = 25K	0			
FC	4096	(7 * 7 * 512) * 4096 = 102,760,448			
FC	4096	4096 * 4096 = 16,777,216			
FC	1000	4096 * 1000 = 4,096,000			
TOTAL	16.5M	143,652,544			

4.2

- (a) According to the Googlenet paper, the general idea behind designing an inception module in a CNN is based on finding out how an optimal local sparse structure in a convolutional vision network can be approximated and covered by readily available dense components.
- (b) Calcuate output sizes

Naive version:

Concatenate $(32 \times 32 \times 128) + (32 \times 32 \times 192) + (32 \times 32 \times 96) + (32 \times 32 \times 256)$ at the channel/filter dimension => $(32 \times 32 \times 672)$

Dimension reductions version:

Concatenate $128 + 192 + 96 + 64 = > (32 \times 32 \times 480)$

(c) Calculate number of convolutional operations

Naive version:

Dimension reductions version:

(d) How dimension reductions technique helps?

The inception module with dimension reductions technique is significantly faster than the naive architecture with much lower computational steps. The number of convolutional computation decreased from 1,089,536 to 388,096, which is a 701,440 operations reduction or 64.4% decrease.

Problem 5

= 388,096

Staleness at the start of the compute of the following gradients:

$$g[L_1,1]=0$$

$$g[L_1,2]=0$$

$$g[L_1,3]=1$$

$$g[L_1,4]=0$$

$$g[L_2,1]=2$$

 $g[L_2,2]=0$ (Since PS receives gradients and updates weights from $g[L_1,4]$ and $g[L_2,1]$ at the same time at second 5. The gradients read at the beginning of the compute of $g[L_2,2]$ is not stale)