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**San Andrés**

Departamento de Economía (Department of Economics)

Maestría en Economía (MS in Economics)

**Online Appendix**

**Economic Policy Uncertainty and Foreign Investment in  
Emerging Economies. An empirical study for Brazil, Chile,  
Colombia, and Greece**

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# Economic Policy Uncertainty and Foreign Investment in Emerging Economies. An empirical study for Brazil, Chile, Colombia, and Greece

## **Abstract**

In this file you are the Impulse Response Functions (IRFs) corresponding to the Structural Vector Autoregressive (SVARs) model estimations. They are reported by model and the sections are organized by country and identification assumption.

## **Resumen**

En este archivo se encuentran todas las funciones de respuesta al impulso (IRFs) para las estimaciones de los modelos de vectores autoregresivos estructurales (SVARs). Se reportan por modelo y las secciones se organizan por país y supuesto de identificación.

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# 1 Brazil

## 1.1 First Ordering

### 1.1.1 FDI with EMBI as control. VAR (1)

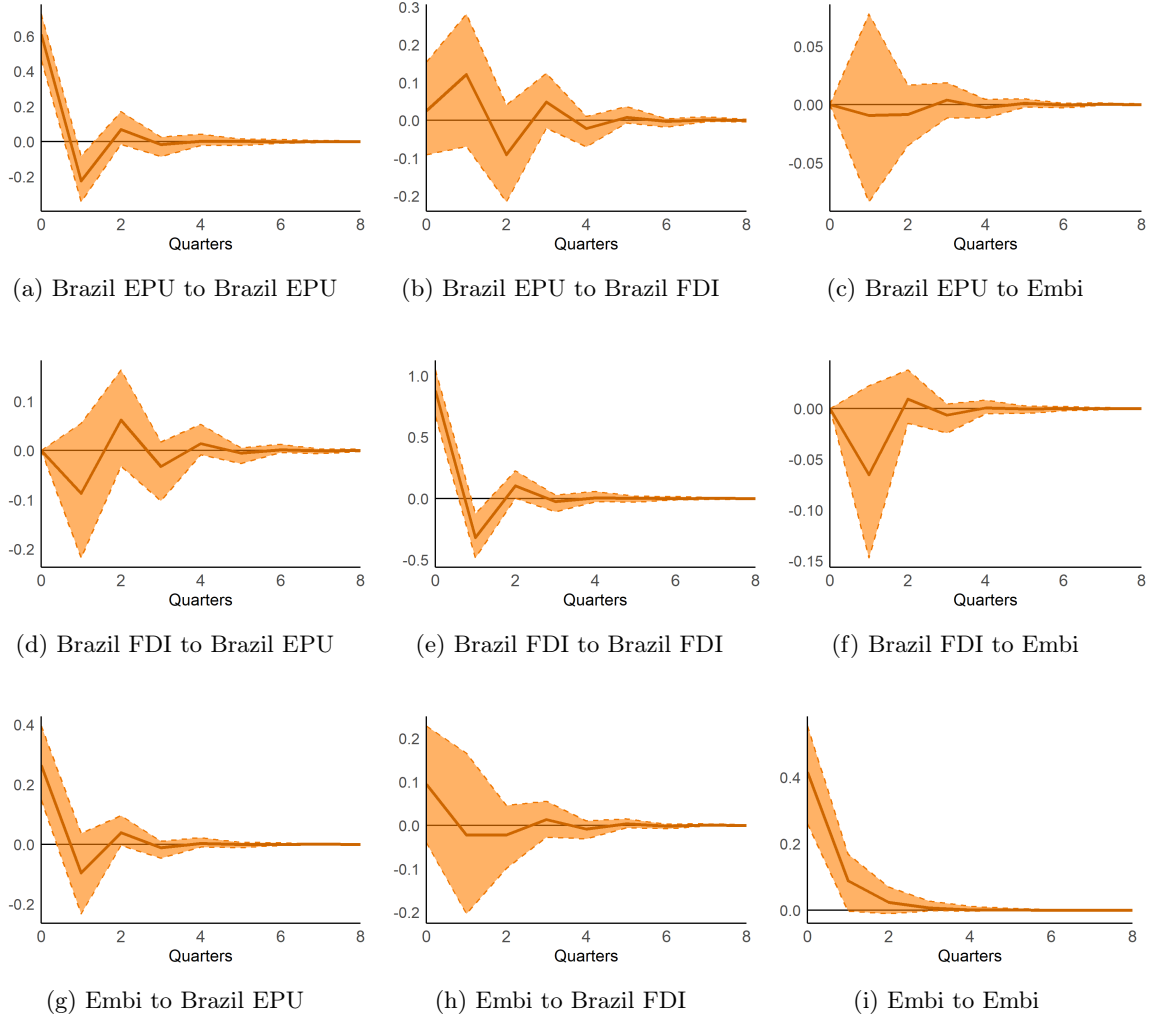


Figure 1: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. First ordering (EPU first) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-2020Q1. VAR(p) refers to the lag specification of the model.

### 1.1.2 FDI with Fed rate as control. VAR (1)

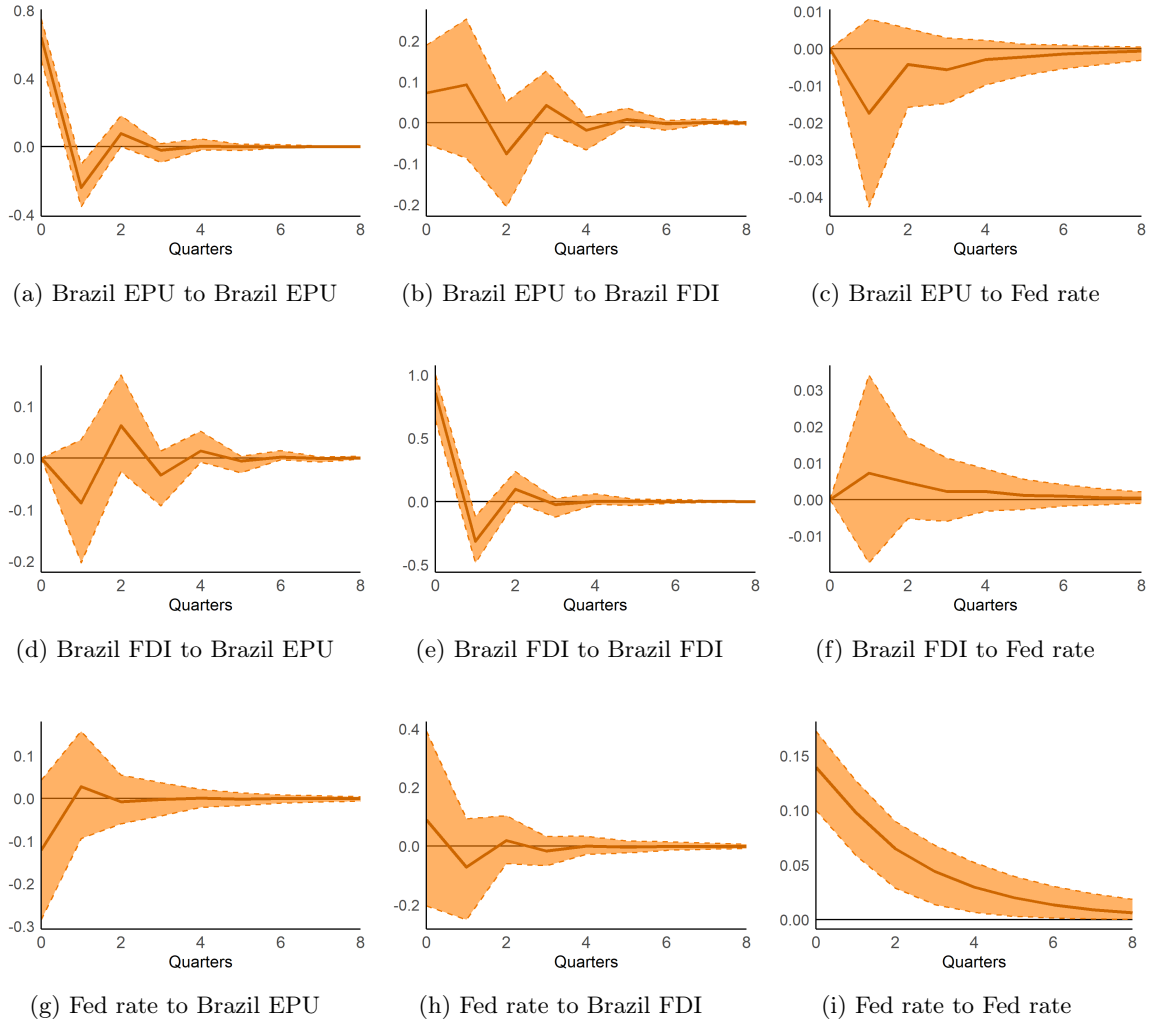


Figure 2: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. First ordering (EPU first) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

### 1.1.3 FDI with GDP as control. VAR (1)

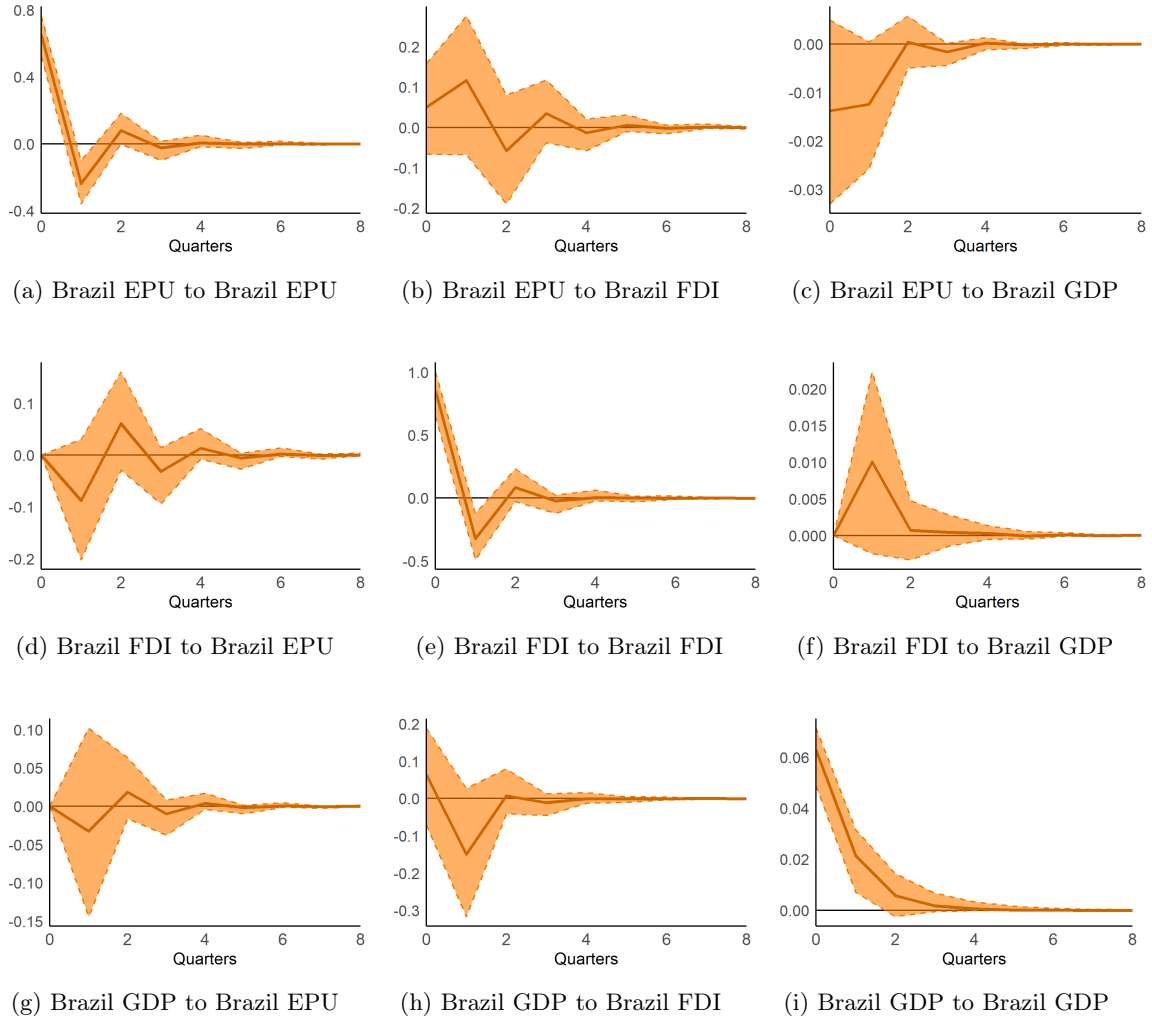


Figure 3: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. First ordering (EPU first) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

### 1.1.4 FDI with Global EPU as control. VAR (1)

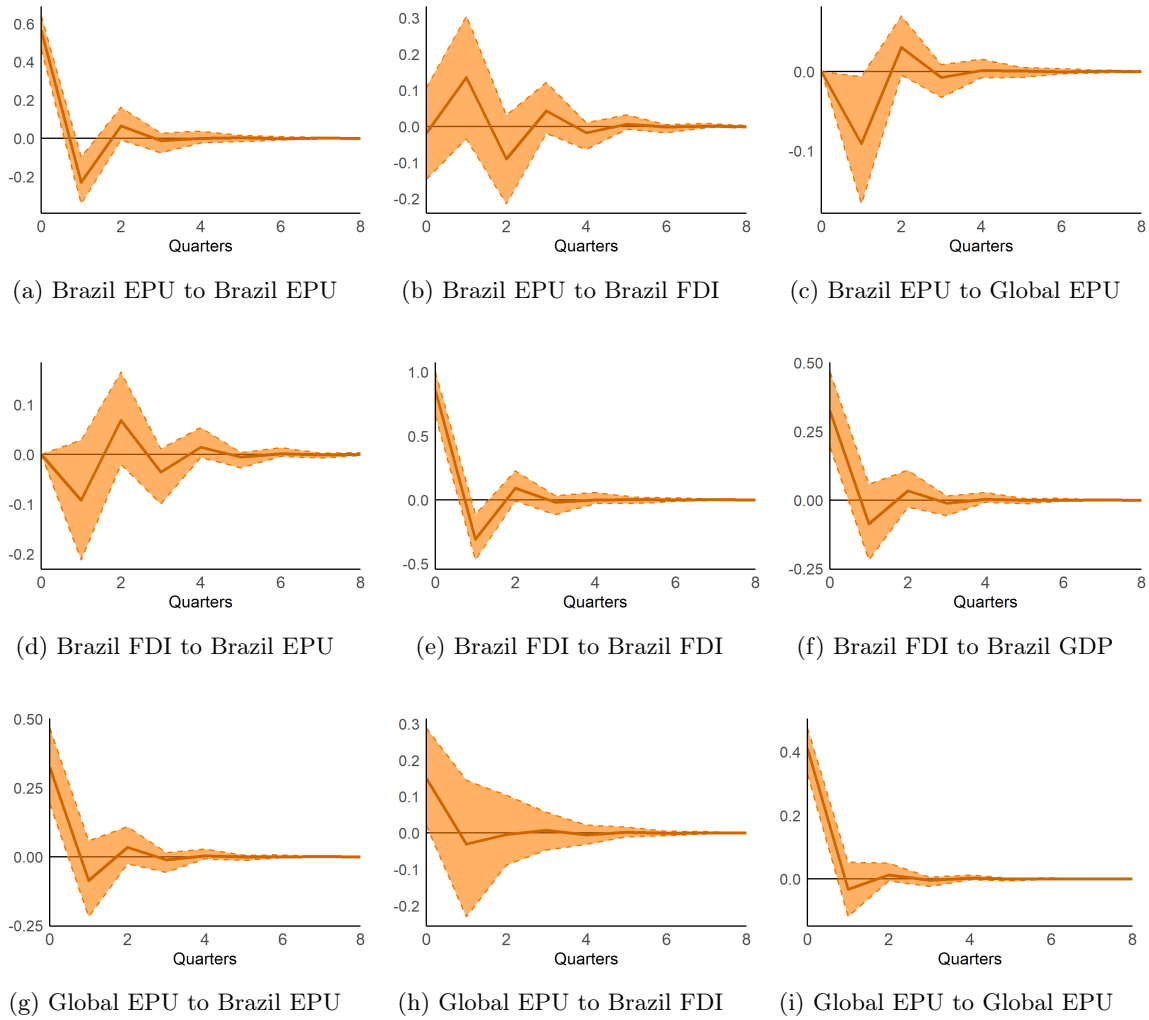


Figure 4: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. First ordering (EPU first) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

### 1.1.5 PI with EMBI as control. VAR (1)

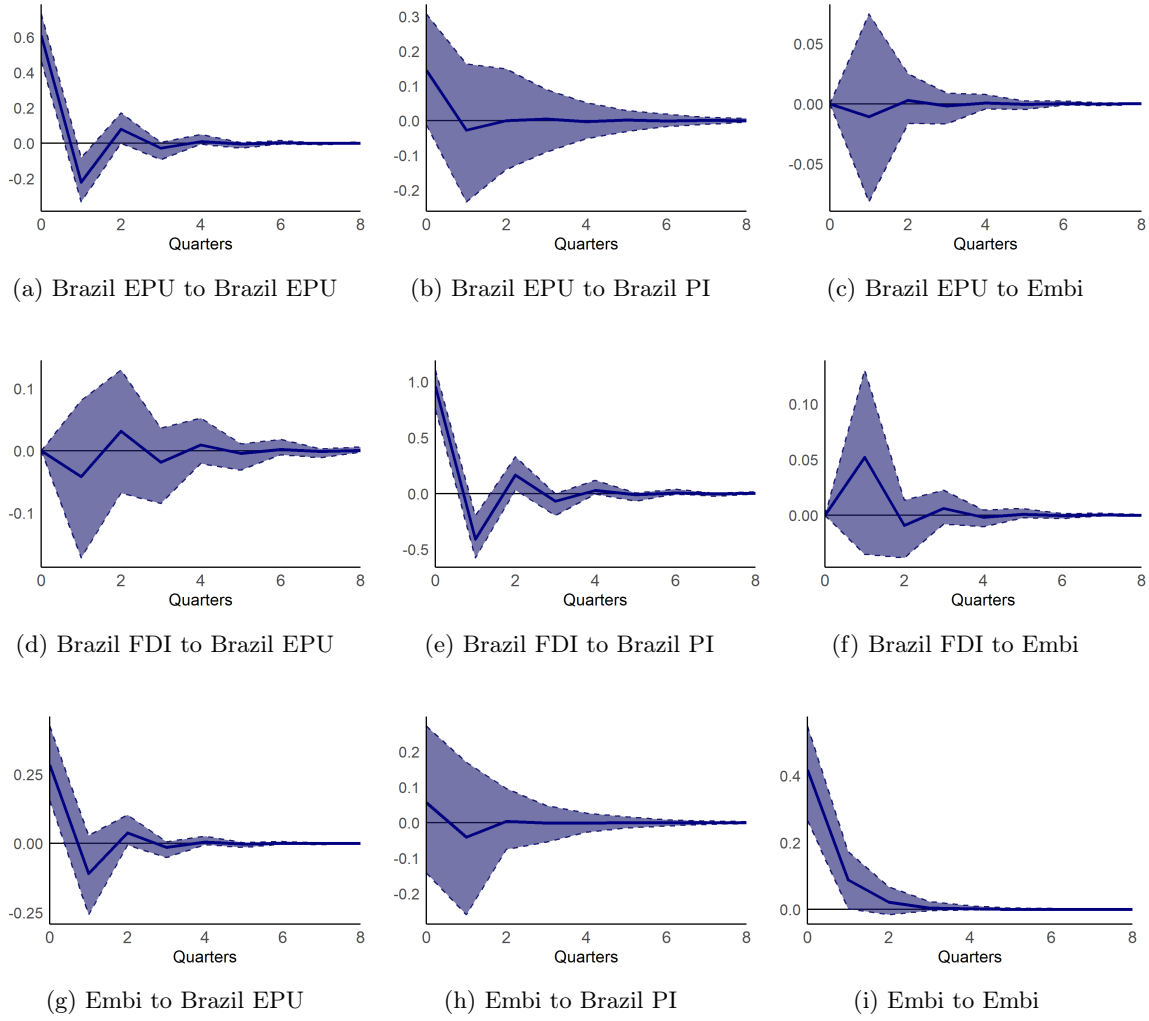


Figure 5: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. First ordering (EPU first) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.



### 1.1.6 PI with Fed rate as control. VAR (1)

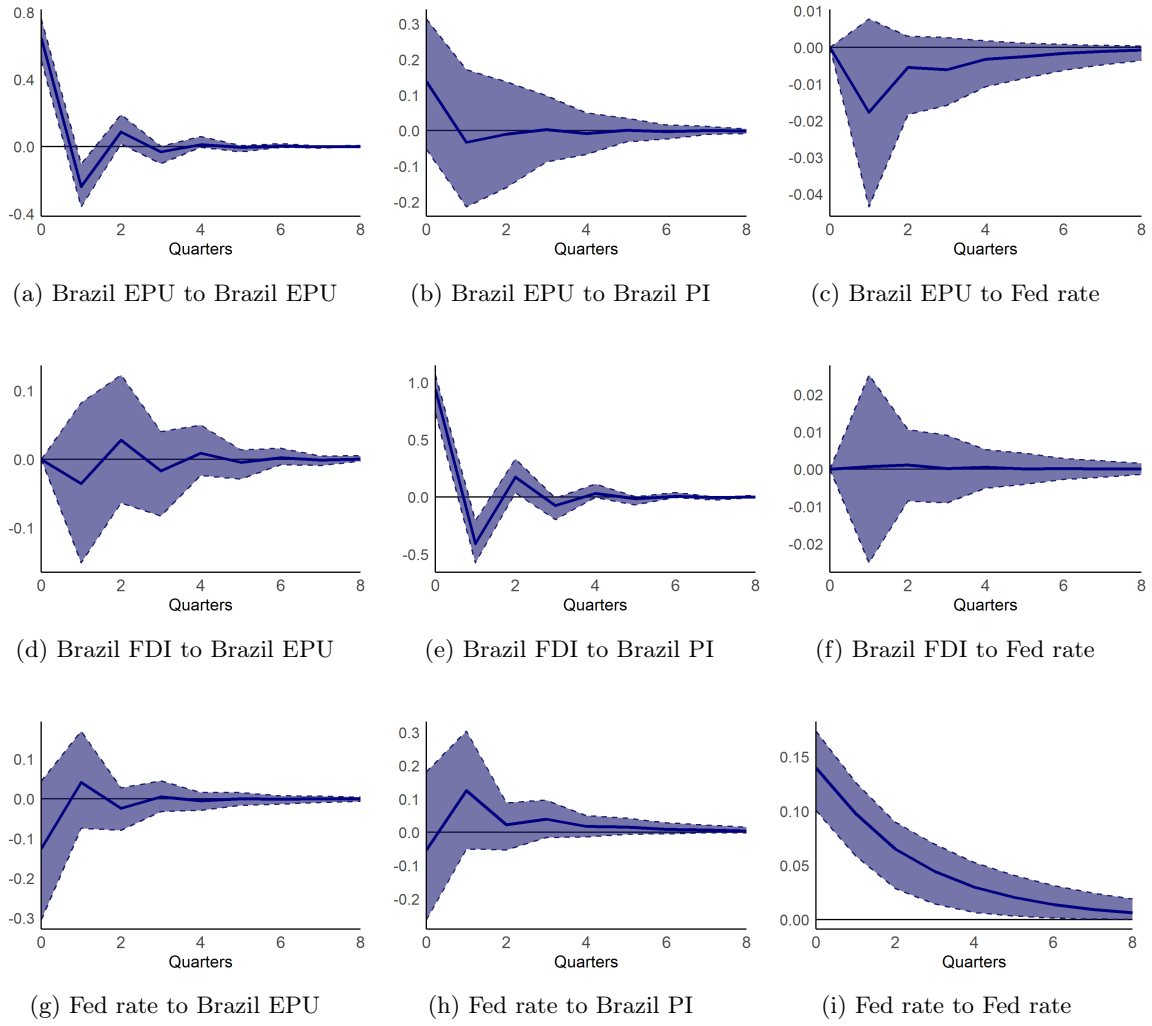


Figure 6: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. First ordering (EPU first) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

### 1.1.7 PI with GDP as control. VAR (1)

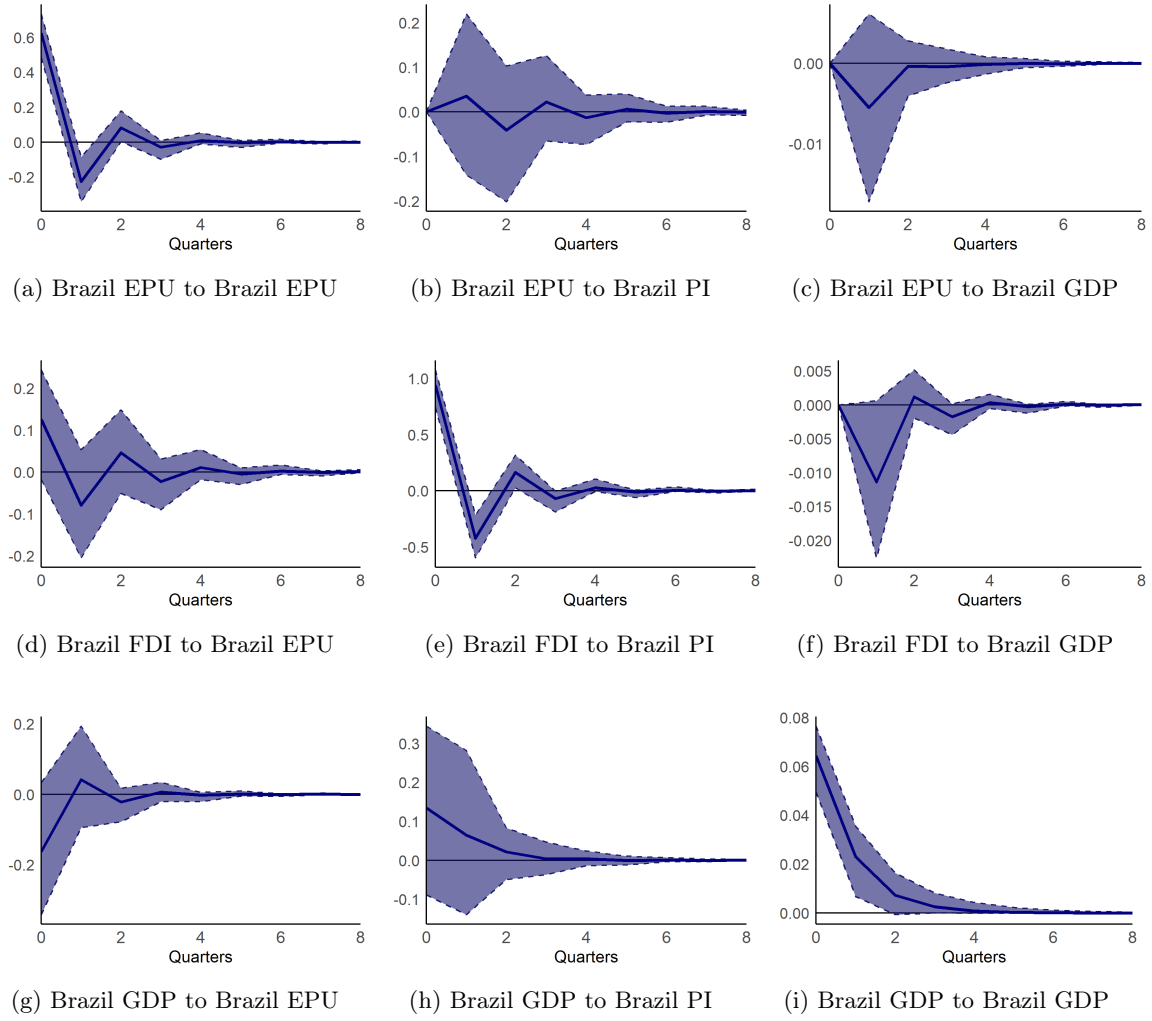


Figure 7: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. First ordering (EPU first) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

### 1.1.8 PI with Global EPU as control. VAR (1)

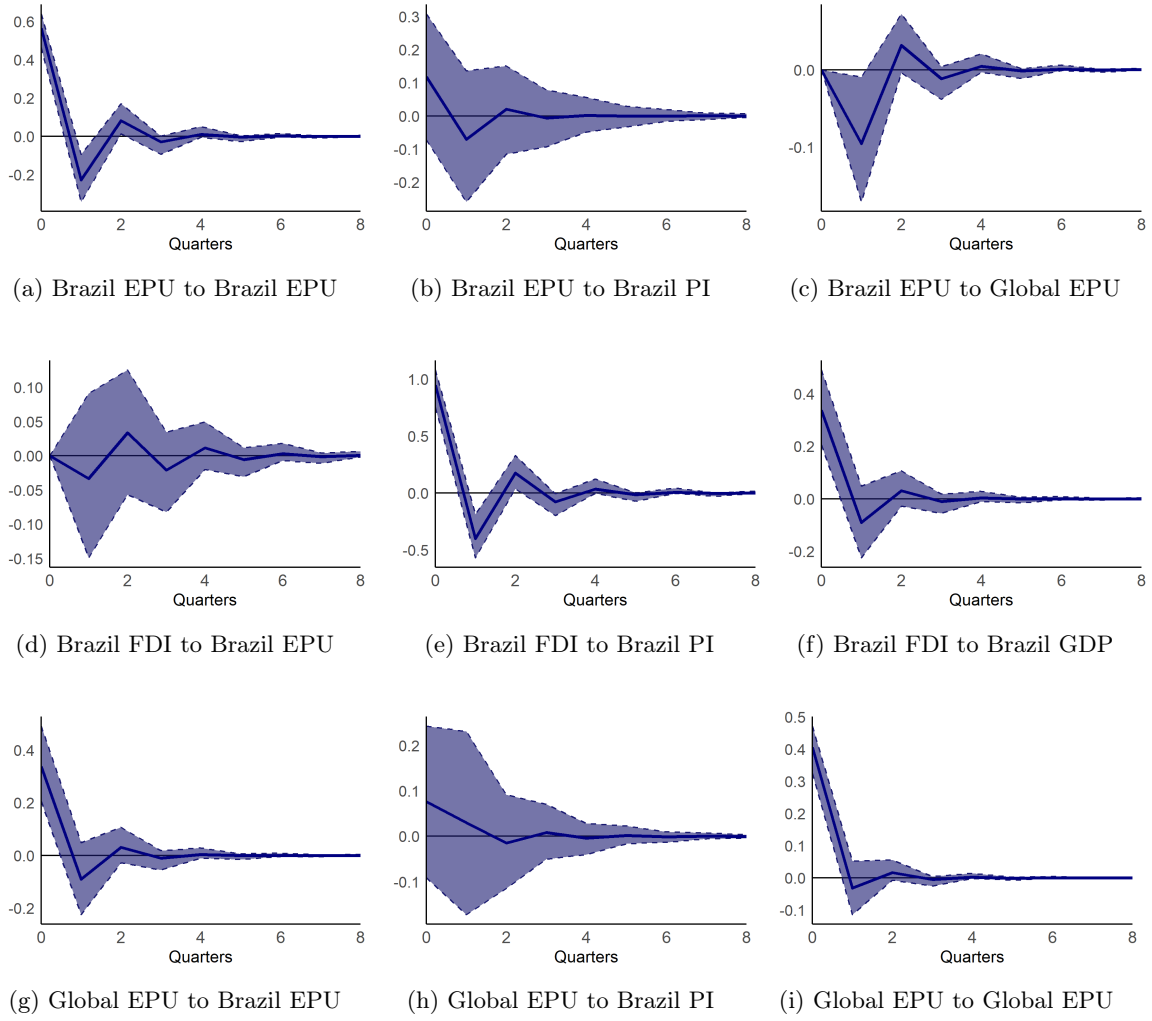


Figure 8: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. First ordering (EPU first) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-2020Q1. VAR(p) refers to the lag specification of the model.

## 1.2 Second Ordering

### 1.2.1 FDI with EMBI as control. VAR (1)

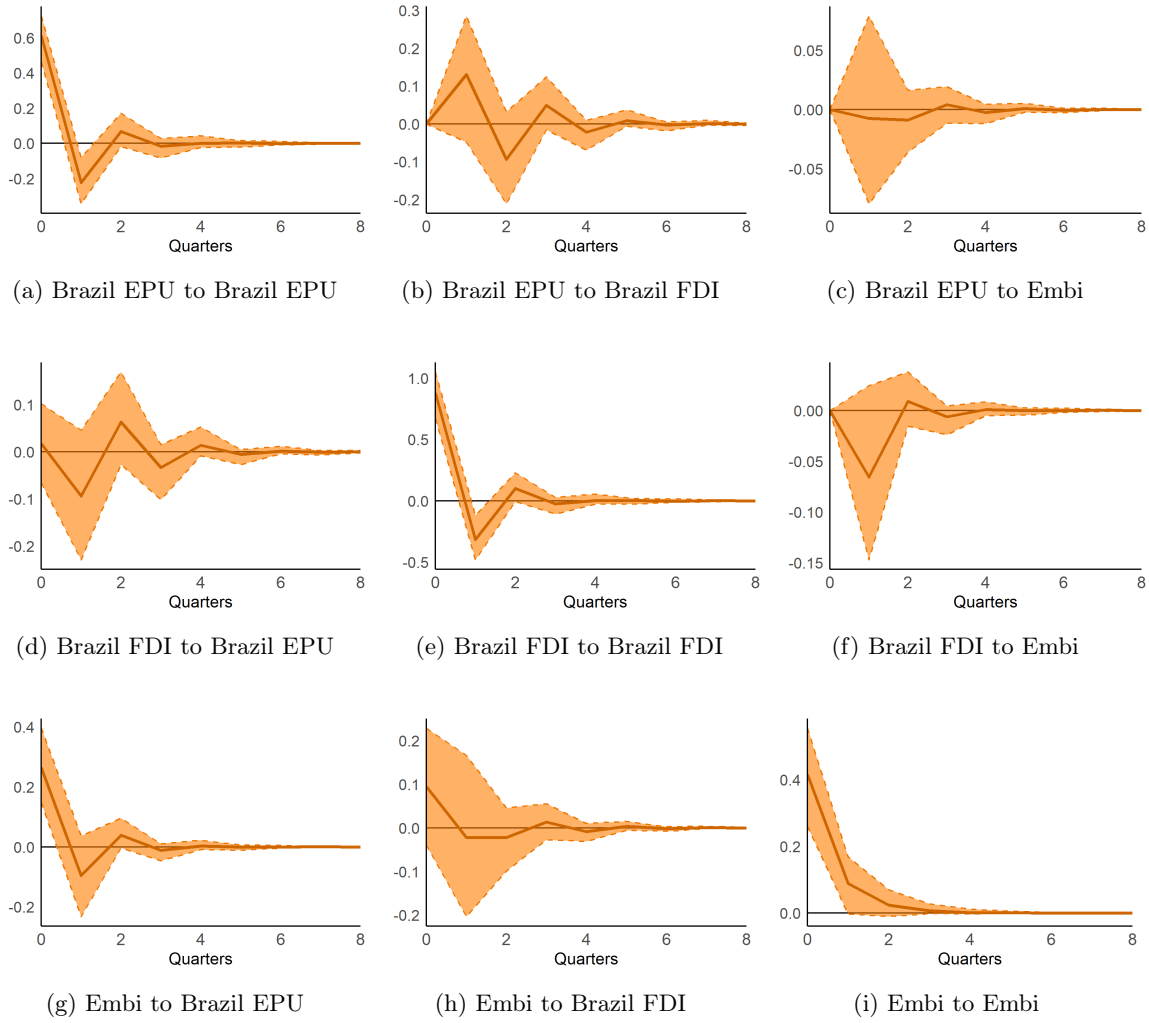


Figure 9: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. Second ordering (EPU last) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-2020Q1. VAR(p) refers to the lag specification of the model.

### 1.2.2 FDI with Fed rate as control. VAR (1)

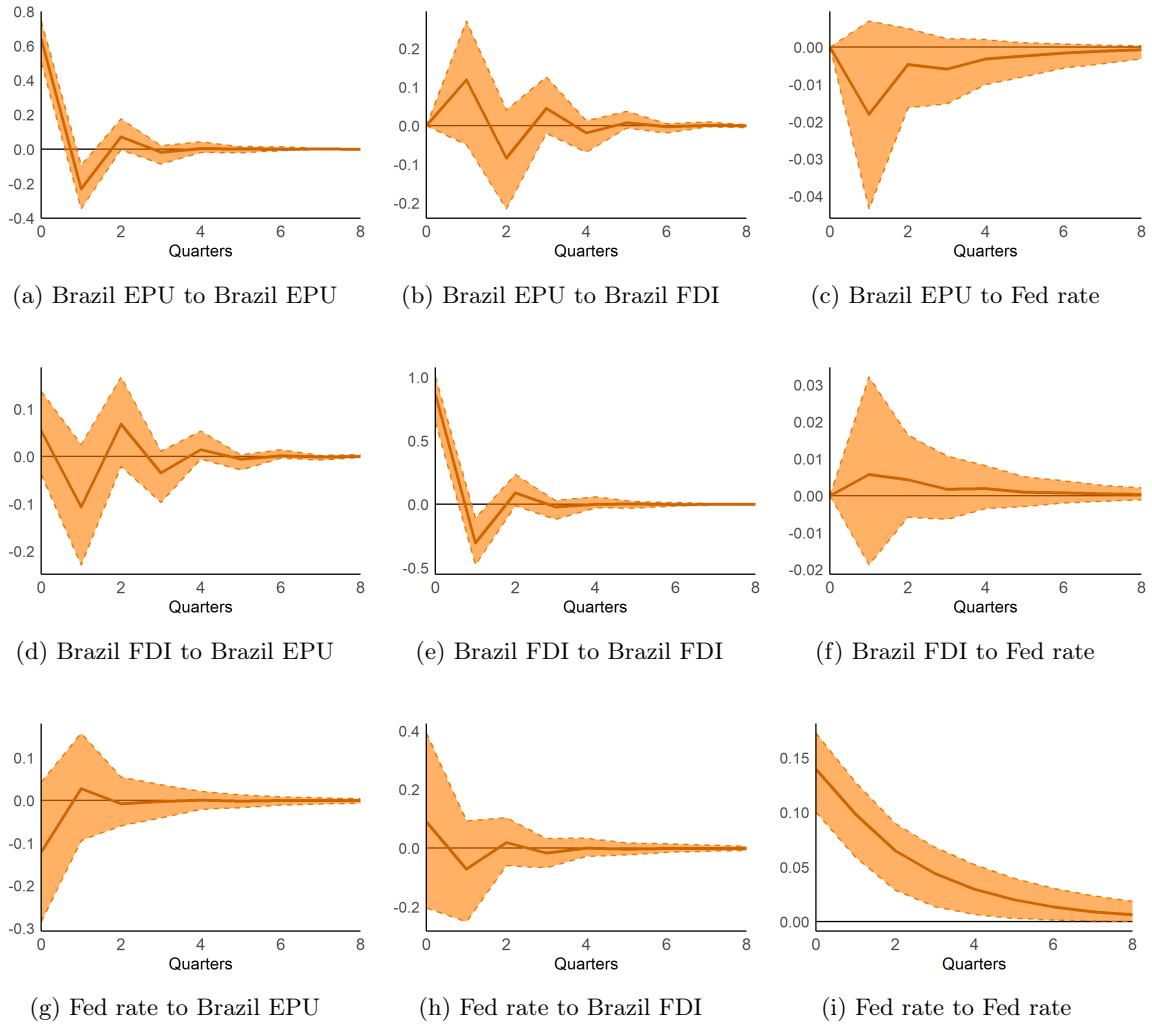


Figure 10: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. Second ordering (EPU last) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

### 1.2.3 FDI with GDP as control. VAR (1)

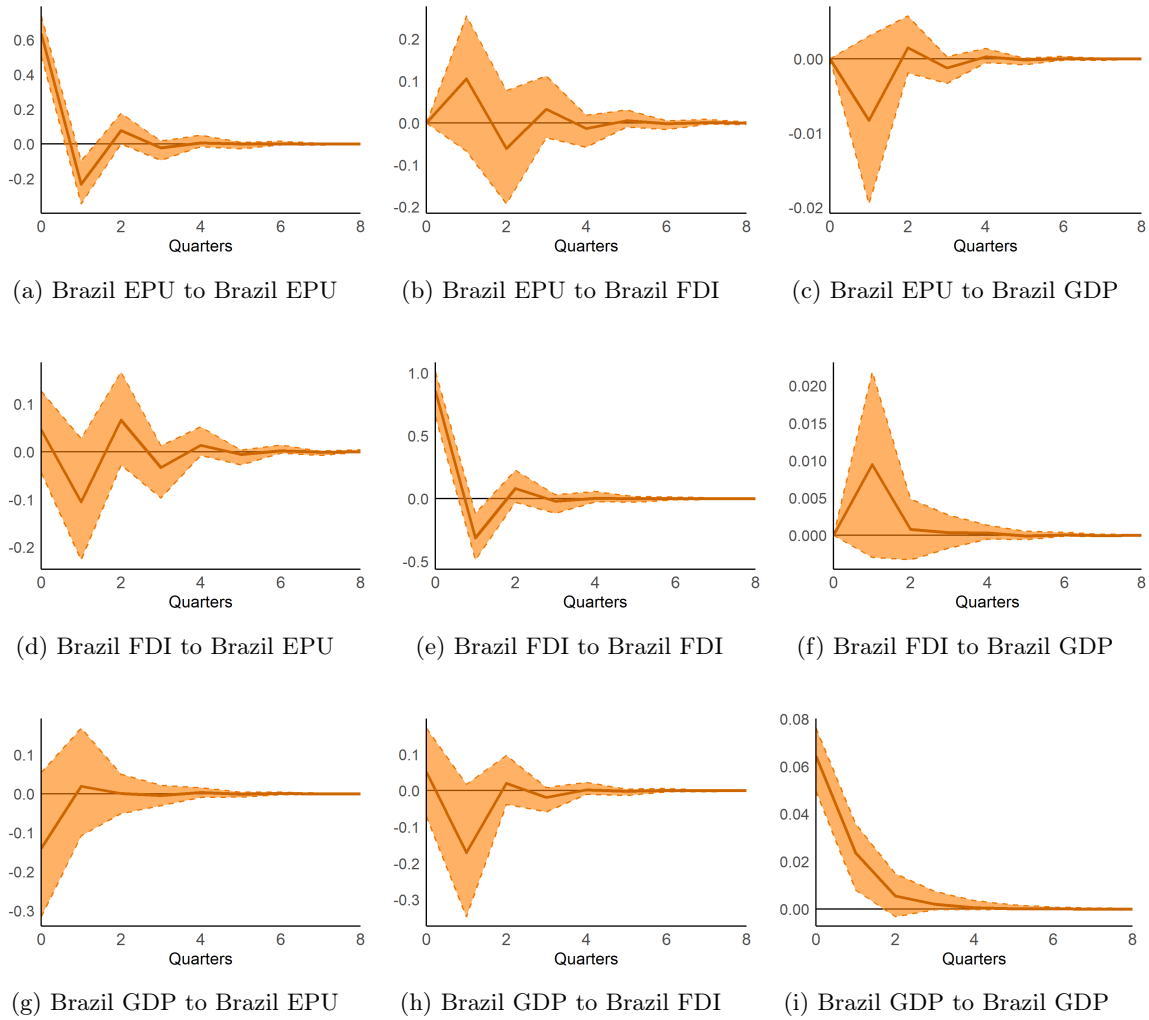


Figure 11: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. Second ordering (EPU last) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

### 1.2.4 FDI with Global EPU as control. VAR (1)

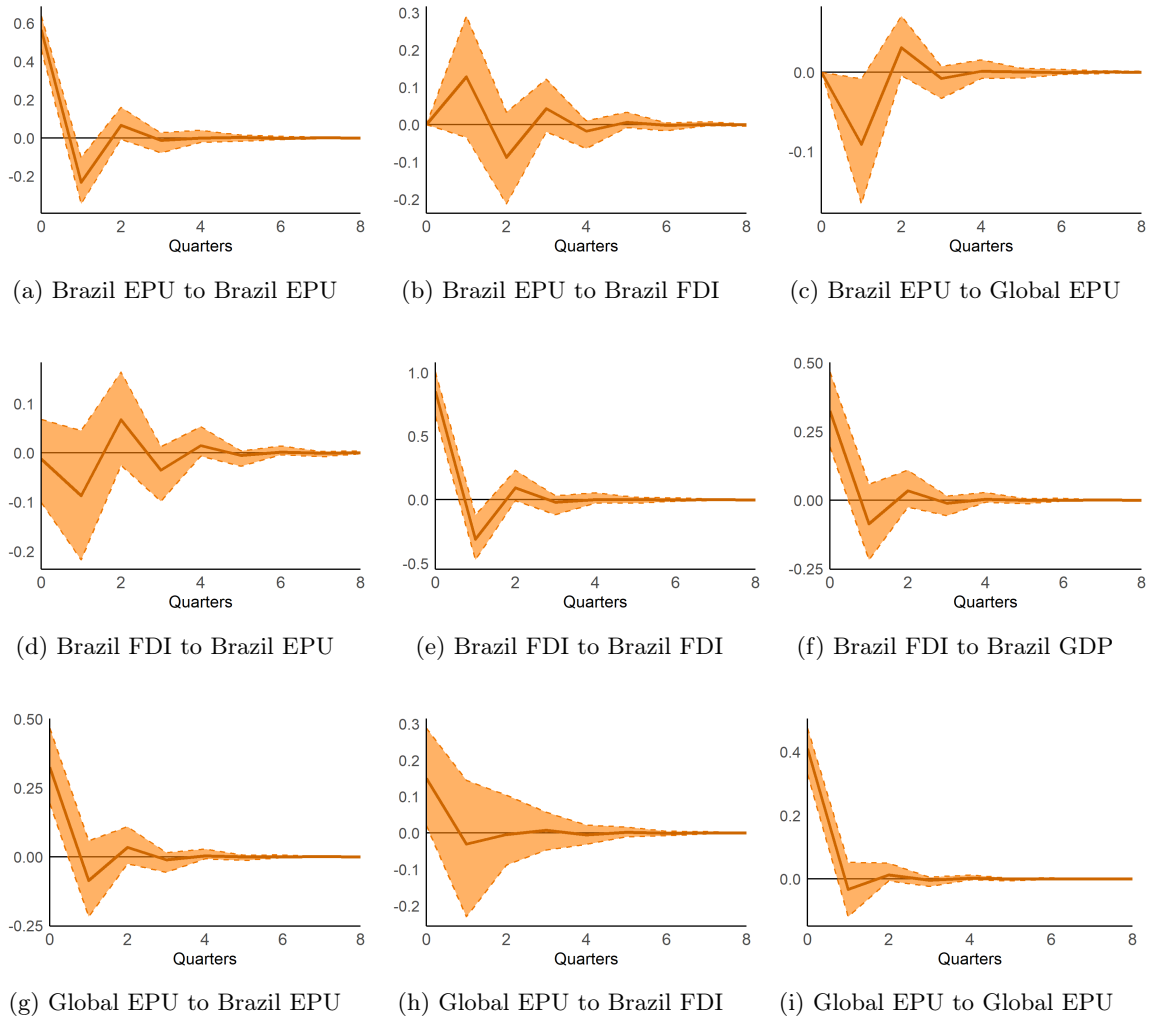


Figure 12: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. Second ordering (EPU last) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

### 1.2.5 PI with EMBI as control. VAR (1)

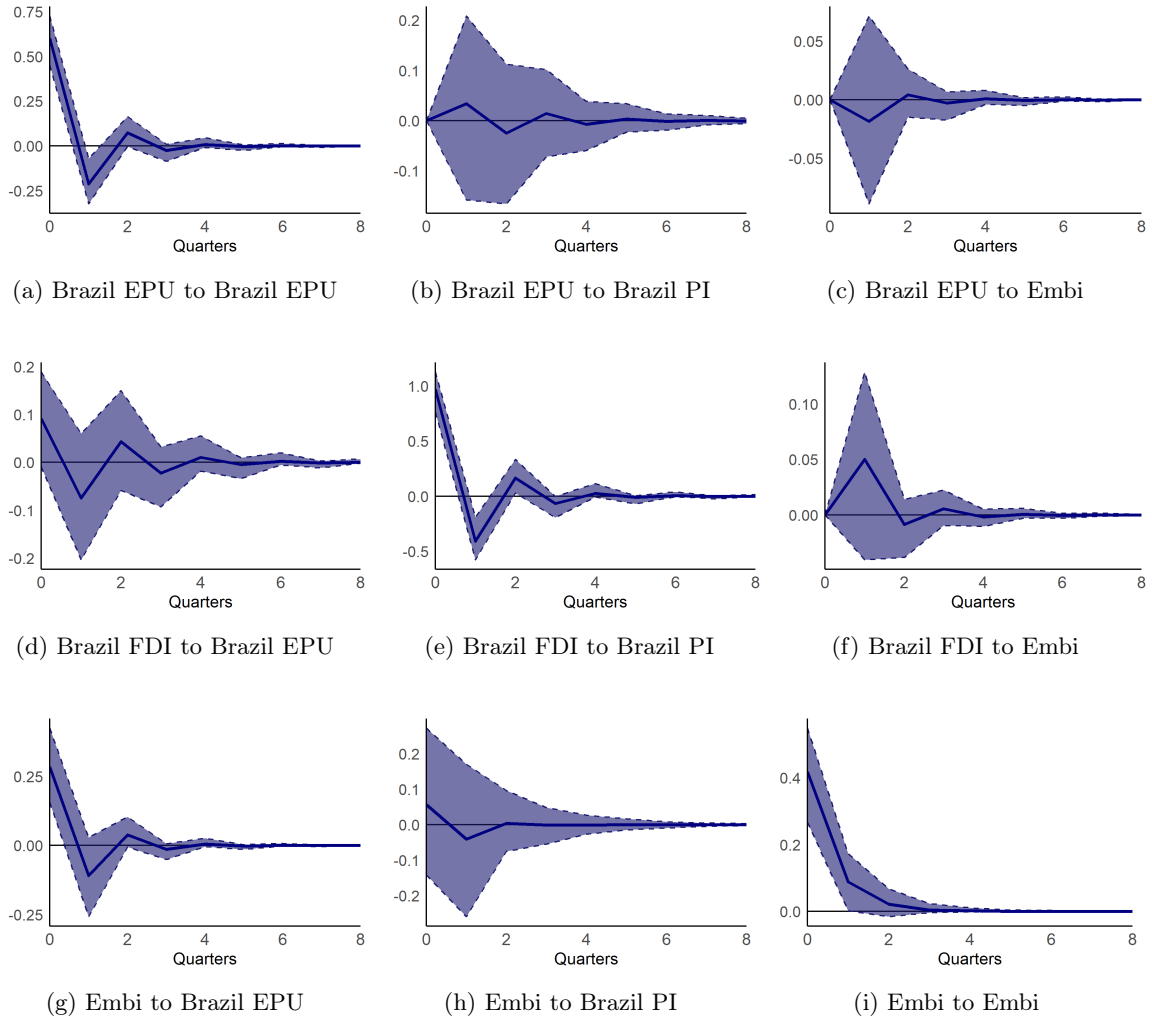


Figure 13: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. Second ordering (EPU last) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.



### 1.2.6 PI with Fed rate as control. VAR (1)

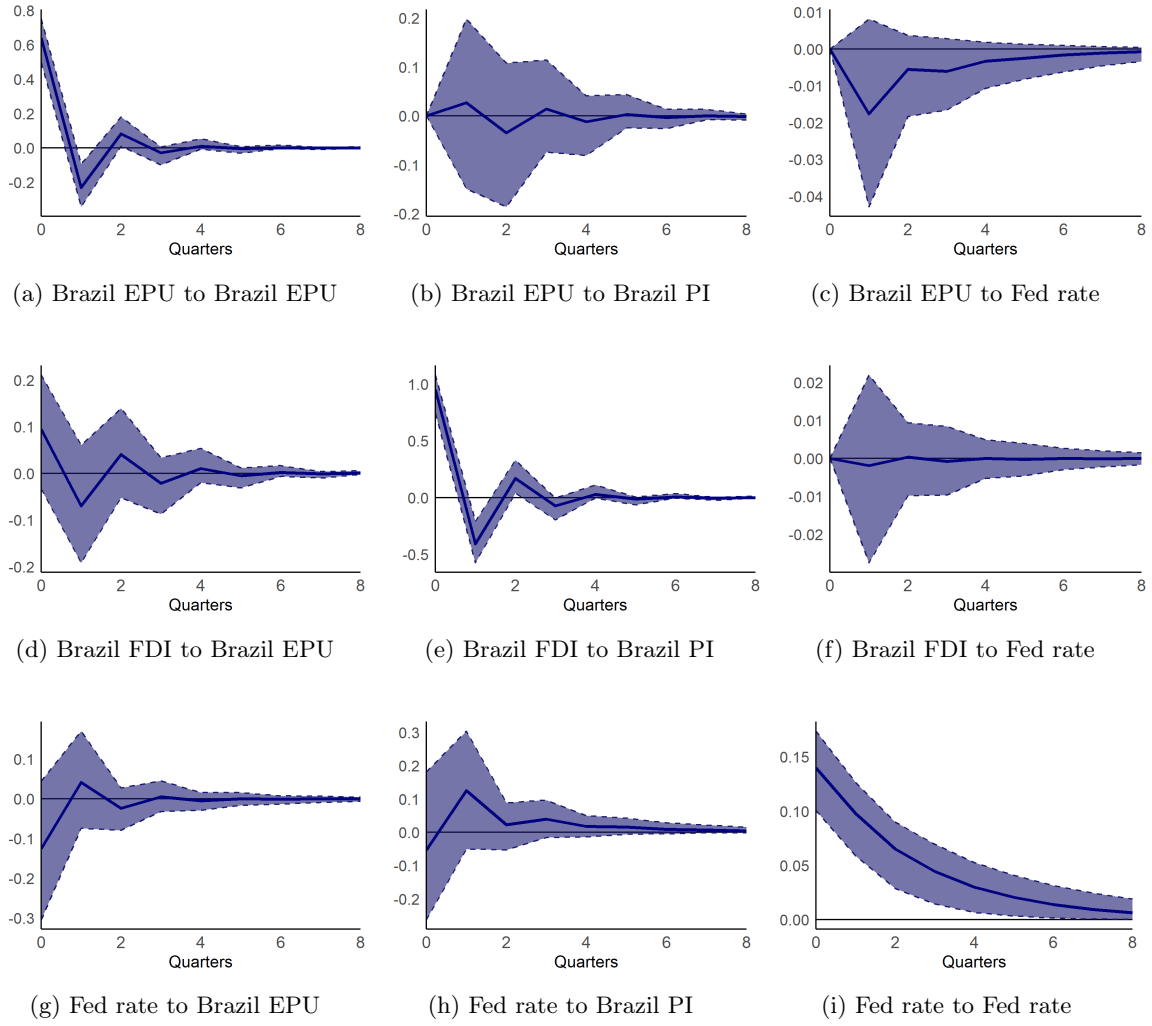


Figure 14: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. Second ordering (EPU last) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

### 1.2.7 PI with GDP as control. VAR (1)

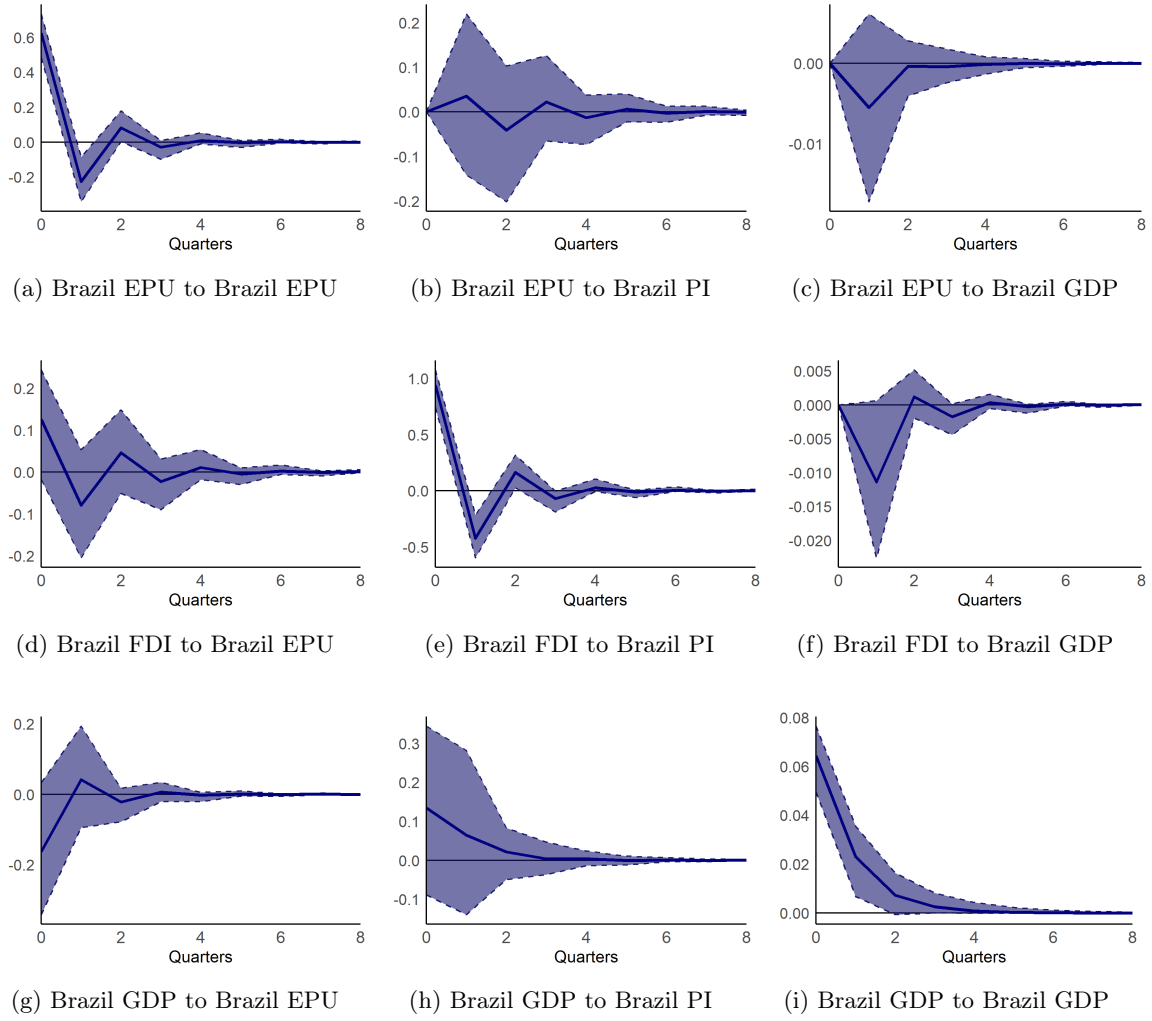


Figure 15: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. Second ordering (EPU last) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

### 1.2.8 PI with Global EPU as control. VAR (1)

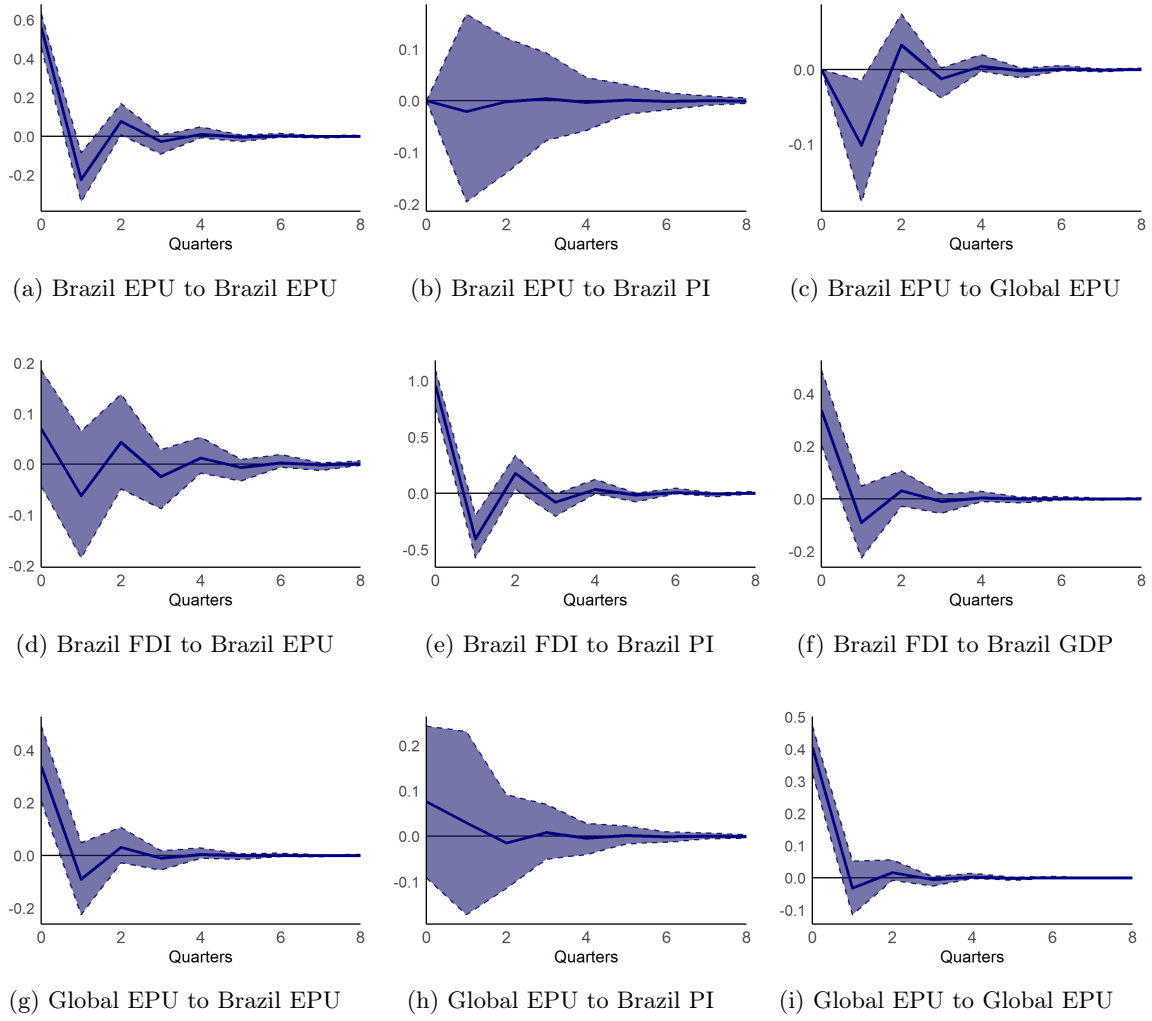


Figure 16: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. Second ordering (EPU last) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

### 1.3 Third Ordering

#### 1.3.1 FDI with GDP as control. VAR (1)

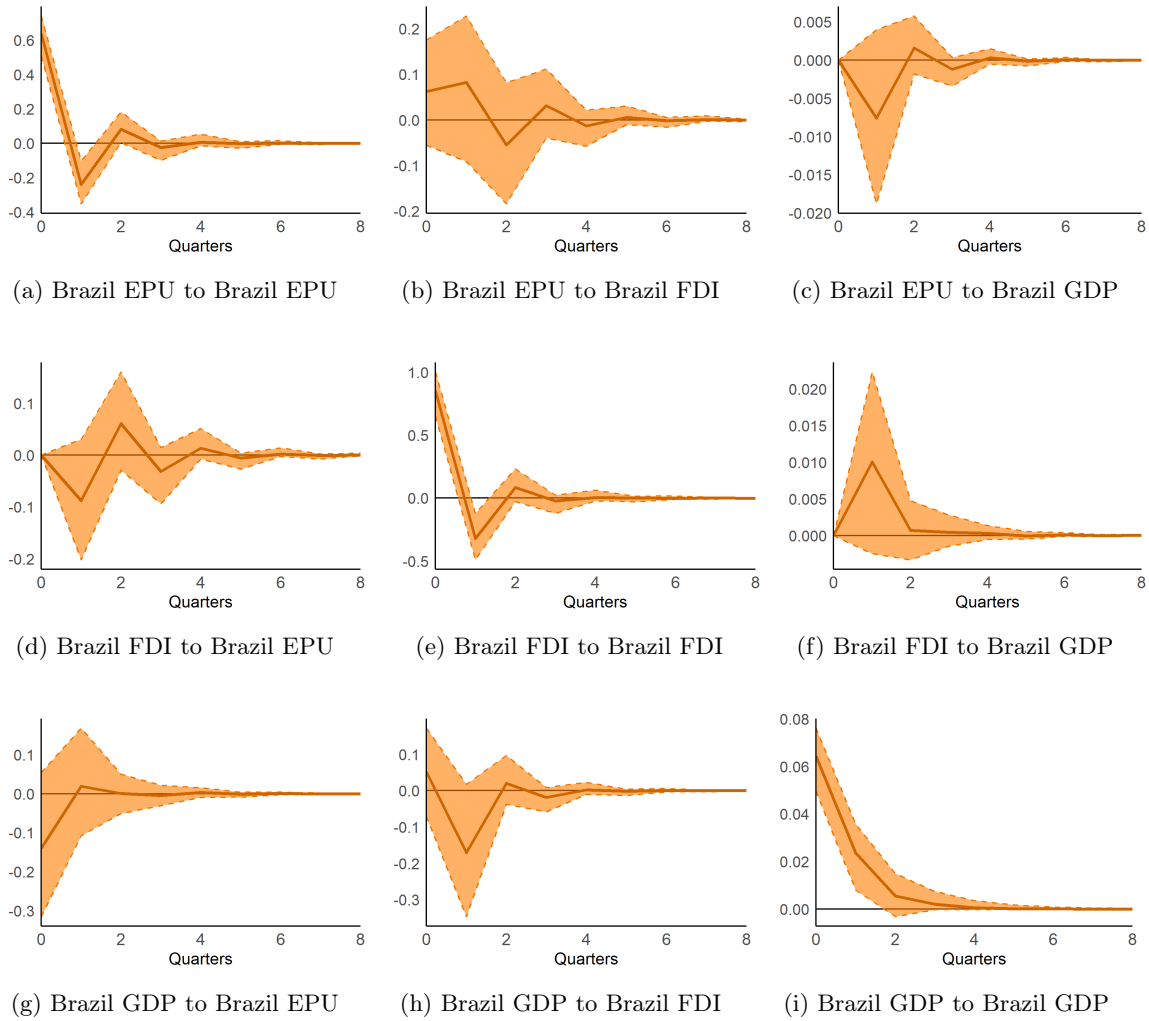


Figure 17: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. Third ordering (EPU intermediate) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-2020Q1. VAR(p) refers to the lag specification of the model.

### 1.3.2 PI with GDP as control. VAR (1)

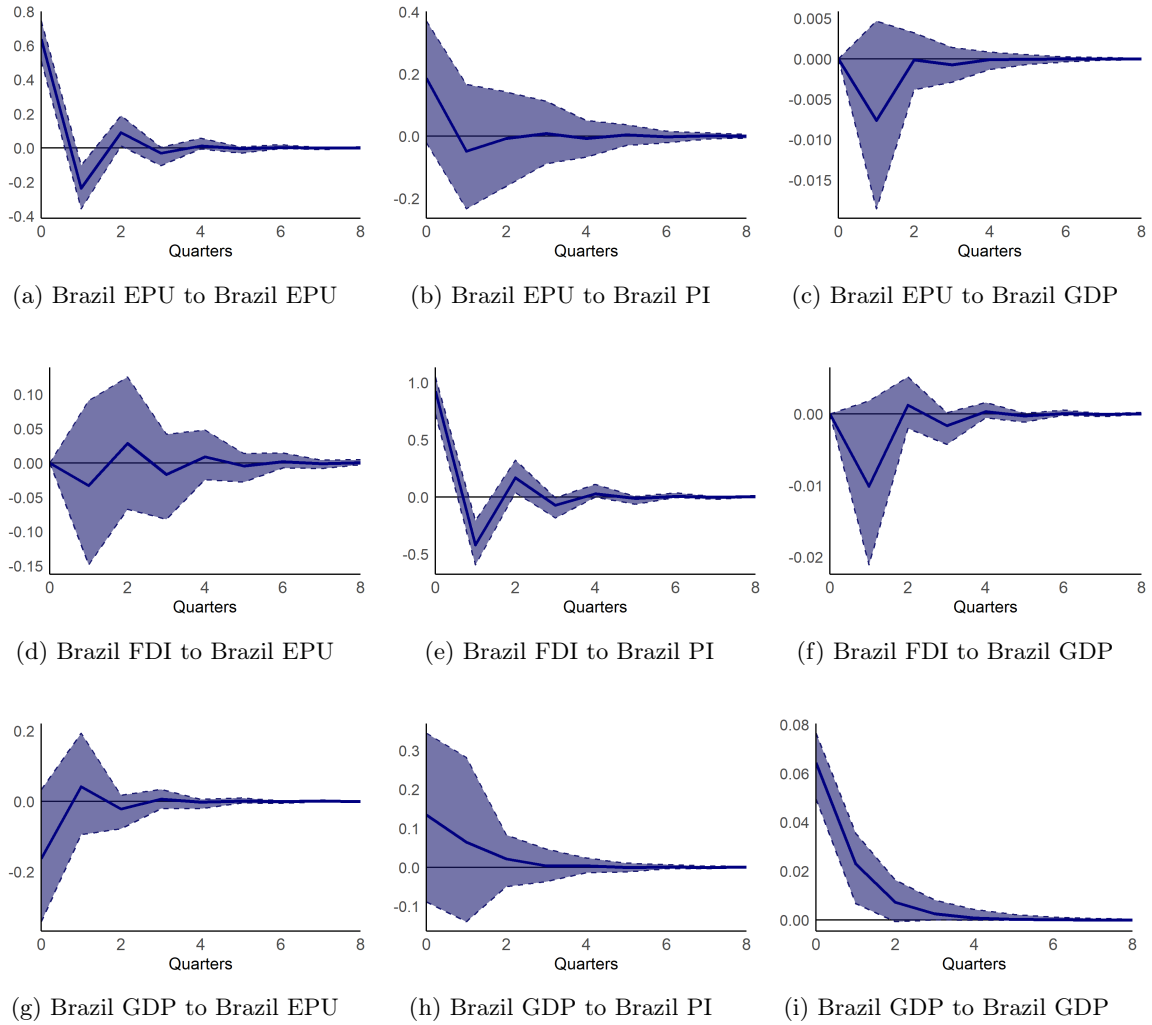


Figure 18: Orthogonalized Impulse Response Functions graphs for a one-standard-deviation shock. Third ordering (EPU intermediate) is used as identification assumption. All variables are quarterly and standardized, with zero mean and unitary variance. Each subfigure correspond to a IRF from one shock to a variable, as subtitle indicates. Sample: 1997Q1-2020Q1, except for the Embi model, which is 1998Q1-202Q1. VAR(p) refers to the lag specification of the model.

## 2 Chile

### 2.1 First Ordering

## 2.2 Second Ordering

## 2.3 Third Ordering



## 3 Colombia

### 3.1 First Ordering

## 3.2 Second Ordering

### 3.3 Third Ordering

## 4 Greece

### 4.1 First Ordering

## 4.2 Second Ordering

### 4.3 Third Ordering