

# Economic Forecasting

## Dynamic regression models

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University of Alberta | E493 | 2023

- 1 Regression with ARIMA errors
- 2 Stochastic and deterministic trends
- 3 Unit root tests
- 4 Lagged predictors
- 5 Spurious regression and cointegration

## Regression models

$$y_t = \beta_0 + \beta_1 x_{1,t} + \dots + \beta_k x_{k,t} + \varepsilon_t$$

Remarks:

- $y_t$  modeled as function of  $k$  predictors  $x_{1,t}, \dots, x_{k,t}$
- in regression, we assume that  $\varepsilon_t$  is WN
- now we want to allow  $\varepsilon_t$  to be autocorrelated

**Example:**  $\eta_t = \text{ARIMA}(1,1,1)$

$$y_t = \beta_0 + \beta_1 x_{1,t} + \cdots + \beta_k x_{k,t} + \eta_t,$$

$$(1 - \phi_1 B)(1 - B)\eta_t = (1 + \theta_1 B)\varepsilon_t, \text{ where } \varepsilon_t \text{ is white noise.}$$

Remarks:

- be careful in distinguishing  $\eta_t$  from  $\varepsilon_t$
- only the errors  $\varepsilon_t$  are assumed to be white noise
- in ordinary regression,  $\eta_t$  is assumed to be white noise, so  $\eta_t = \varepsilon_t$

If we minimize  $\sum \eta_t^2$  (by using ordinary regression):

- 1 Estimated coefficients  $\hat{\beta}_0, \dots, \hat{\beta}_k$  are no longer optimal as some information ignored.
- 2 Statistical tests associated with the model (e.g., t-tests on the coefficients) are incorrect.
- 3  $p$ -values for coefficients usually too small.
- 4 AIC/BIC/etc of fitted models misleading.

Minimizing  $\sum \varepsilon_t^2$  avoids these problems.

## Regression with ARMA errors

$y_t = \beta_0 + \beta_1 x_{1,t} + \cdots + \beta_k x_{k,t} + \eta_t$ , where  $\eta_t$  is an ARMA process.

### Remarks:

- all variables in the model must be stationary
- if we estimate a model with non-stationary variables, the estimated coefficients can be incorrect
- difference variables until all stationary
- if necessary, apply same differencing to all variables

## Regression with ARIMA errors

Any regression with an  $\text{ARIMA}(p,d,q)$  error can be rewritten as a regression with an ARMA error by differencing all variables  $d$  times.

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**Original data:**

$$y_t = \beta_0 + \beta_1 x_{1,t} + \cdots + \beta_k x_{k,t} + \eta_t$$

$$\phi(B)(1 - B)^d \eta_t = \theta(B)\varepsilon_t$$



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**Original data:**

$$y_t = \beta_0 + \beta_1 x_{1,t} + \cdots + \beta_k x_{k,t} + \eta_t$$
$$\phi(B)(1 - B)^d \eta_t = \theta(B)\varepsilon_t$$

**After differencing all variables:**

$$y'_t = \beta_1 x'_{1,t} + \cdots + \beta_k x'_{k,t} + \eta'_t$$
$$\phi(B)\eta'_t = \theta(B)\varepsilon_t$$
$$y'_t = (1 - B)^d y_t$$

Model with ARIMA(1,1,1) errors:

$$y_t = \beta_0 + \beta_1 x_{1,t} + \cdots + \beta_k x_{k,t} + \eta_t$$

$$(1 - \phi_1 B)(1 - B)\eta_t = (1 + \theta_1 B)\varepsilon_t$$

**Model with ARIMA(1,1,1) errors:**

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$$(1 - \phi_1 B)(1 - B)\eta_t = (1 + \theta_1 B)\varepsilon_t$$

**Equivalent to model with ARIMA(1,0,1) errors:**

$$y'_t = \beta_1 x'_{1,t} + \cdots + \beta_k x'_{k,t} + \eta'_t$$

$$(1 - \phi_1 B)\eta'_t = (1 + \theta_1 B)\varepsilon_t$$

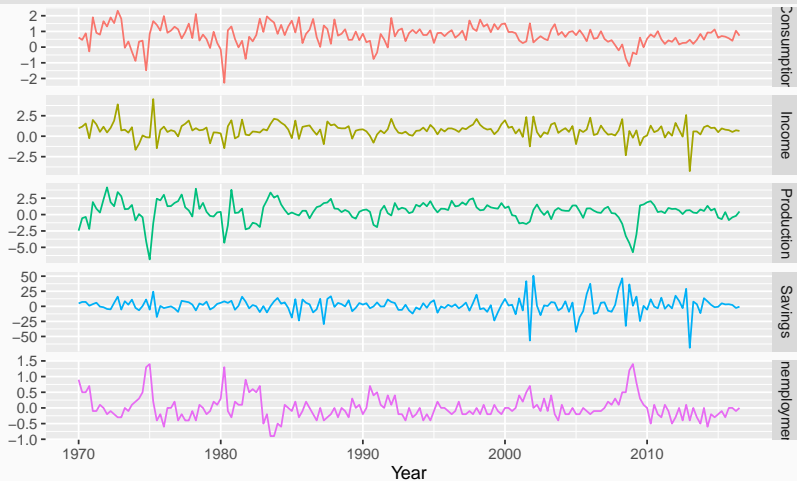
where  $y'_t = y_t - y_{t-1}$ ,  $x'_{t,i} = x_{t,i} - x_{t-1,i}$  and  $\eta'_t = \eta_t - \eta_{t-1}$ .

Remarks:

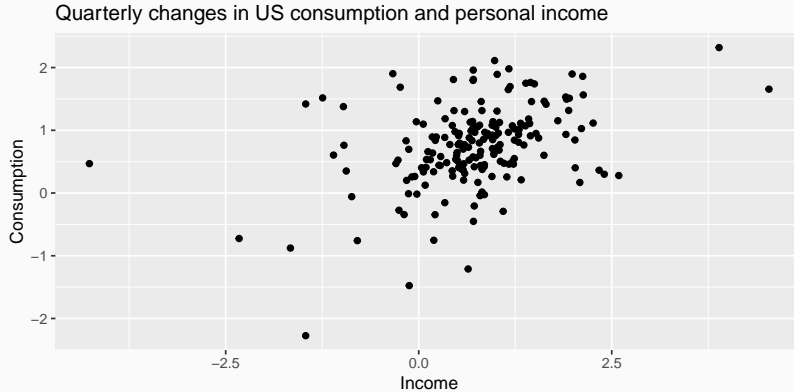
- check that all variables are stationary
- if not, apply differencing where appropriate (use the same differencing for all variables to preserve interpretability)
- fit regression model with ARIMA errors
- check that  $\varepsilon_t$  series looks like white noise
- repeat procedure for all subsets of predictors to be considered, and select model with lowest AIC/AICc value

## Example: US consumption expenditure

```
autoplot(uschange[,1:5], facets = TRUE, colour=TRUE) +  
  ylab("") + xlab("Year") + guides(colour="none")
```



# US personal consumption and income



## US personal consumption and income

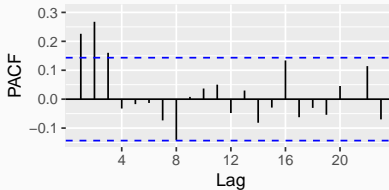
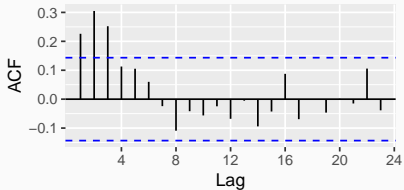
```
# fit regression
(fit <- auto.arima(uschange[,1], xreg=uschange[,2]))

## Series: uschange[, 1]
## Regression with ARIMA(1,0,2) errors
##
## Coefficients:
##          ar1      ma1      ma2  intercept      xreg
##          0.692  -0.576   0.198         0.599   0.203
## s.e.    0.116    0.130   0.076         0.088   0.046
##
## sigma^2 = 0.322:  log likelihood = -157
## AIC=325.9   AICc=326.4   BIC=345.3
```

# US personal consumption and income

```
ggtdisplay(residuals(fit, type='regression'),  
  main="Regression errors")
```

Regression errors

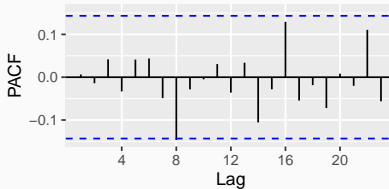
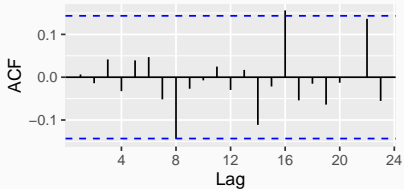




# US personal consumption and income

```
ggtstdisplay(residuals(fit, type='response'),  
             main="ARIMA errors")
```

ARIMA errors

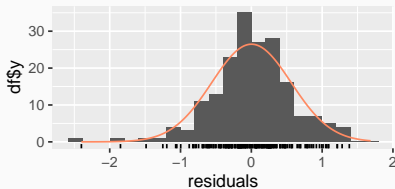
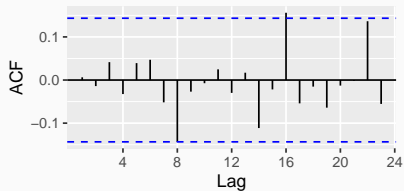


# US personal consumption and income

```
# check residuals
```

```
checkresiduals(fit, test=FALSE)
```

Residuals from Regression with ARIMA(1,0,2) errors

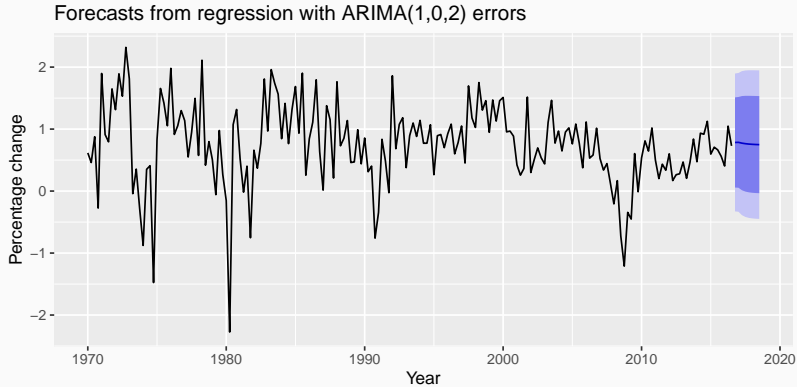


```
# check residuals
```

```
checkresiduals(fit, plot=FALSE)
```

```
##  
##  Ljung-Box test  
##  
## data:  Residuals from Regression with ARIMA(1,0,2) errors  
## Q* = 5.9, df = 5, p-value = 0.3  
##  
## Model df: 3.    Total lags used: 8
```

# US personal consumption and income



## Remarks:

- to forecast a regression model with ARIMA errors, we need to forecast the regression part of the model and the ARIMA part of the model and combine the results
- some predictors are known into the future (e.g., time trend, dummies)
- separate forecasting models may be needed for other predictors
- forecast intervals ignore the uncertainty in forecasting the predictors

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# Nonstationary time series

A convenient way of representing an economic time series  $y_t$  is through the so-called *trend-cycle decomposition*:

$$y_t = TD_t + \eta_t$$

$$TD_t = \text{deterministic trend}$$

$$\eta_t = \text{random cycle/noise}$$

For simplicity, assume

- $TD_t = \beta_0 + \beta_1 t$
- $\phi(B)\eta_t = \theta(B)\varepsilon_t$  is ARIMA process with  $d \geq 0$

Definitions:

- the series  $y_t$  is called **trend stationary** if the roots of  $\phi(z) = 0$  are outside the unit circle
- the series  $y_t$  is called **difference stationary** if  $\phi(z) = 0$  has one root on the unit circle and the others outside the unit circle



## Difference stationary AR(2)

Let  $\phi(B)\eta_t = \varepsilon_t$  with  $\phi(B) = 1 - \phi_1 B - \phi_2 B^2$ . Assume that  $\phi(z) = 0$  has one root equal to unity and the other root real valued with absolute value less than 1. Factor  $\phi(B)$  so that

$$\begin{aligned}\phi(B) &= (1 - \phi^* B)(1 - B) = \phi^*(B)(1 - B) \\ \phi^*(B) &= 1 - \phi^* B \text{ with } |\phi^*| < 1\end{aligned}$$

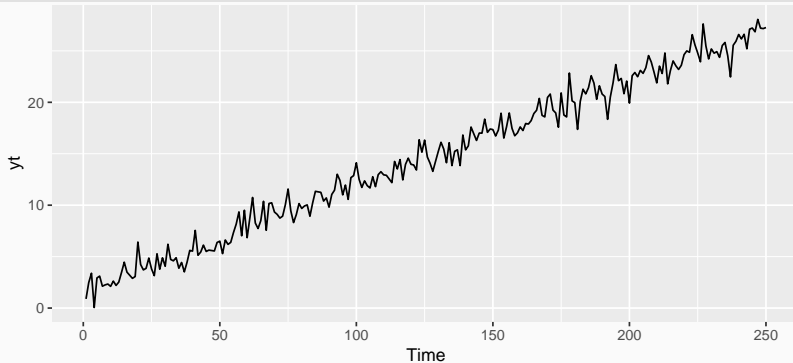
Then

$$\phi(B)\eta_t = (1 - \phi^* B)(1 - B)\eta_t = (1 - \phi^* B)\eta'_t$$

so that  $\eta'_t$  follows an AR(1) process.

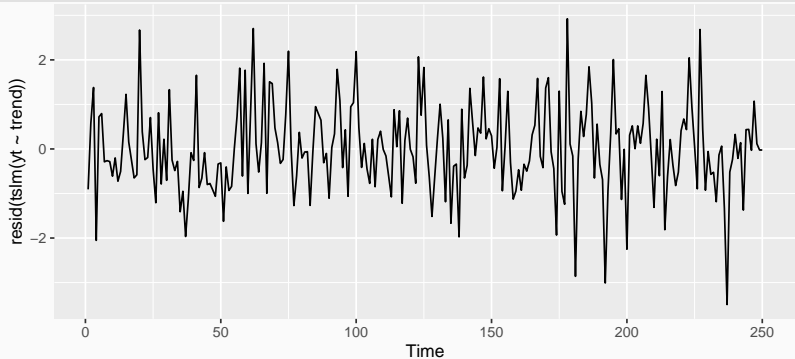
# Trend stationary process

```
# trend stationary process  
yt <- ts(2 + .1*seq(1:250) + rnorm(250))  
autoplot(yt)
```



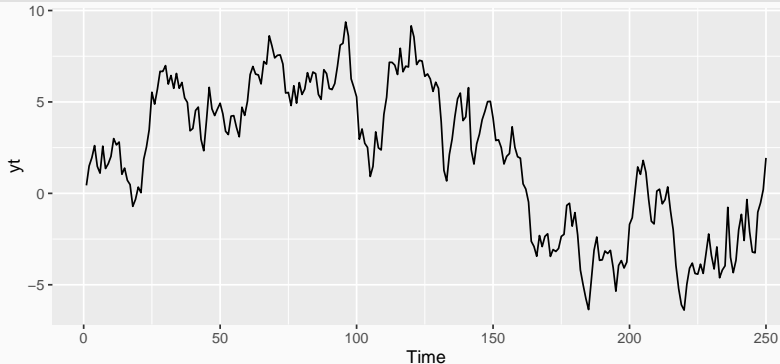
# Trend stationary process

```
# trend stationary process  
autoplot(resid(tslm(yt ~ trend)))
```



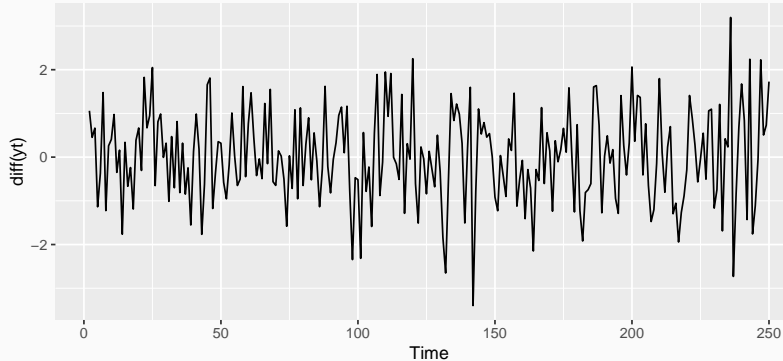
# Difference stationary process

```
# random walk  
yt <- ts(cumsum(rnorm(250)))  
autoplot(yt)
```



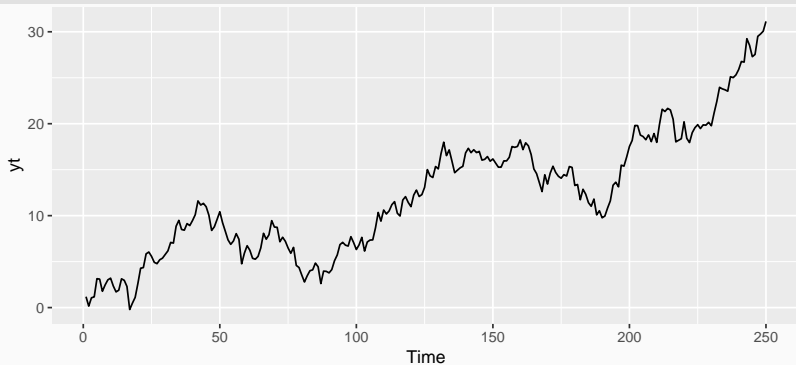
# Difference stationary process

```
# random walk  
autoplot(diff(yt))
```



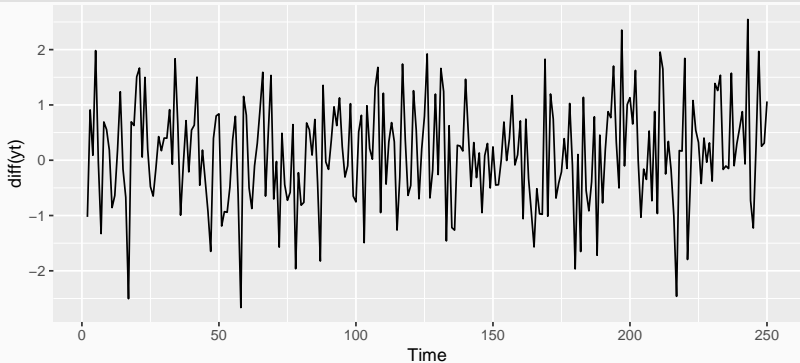
# Difference stationary process

```
# random walk w/ drift  
yt <- ts(cumsum(.2 + rnorm(250)))  
autoplot(yt)
```



## Difference stationary process

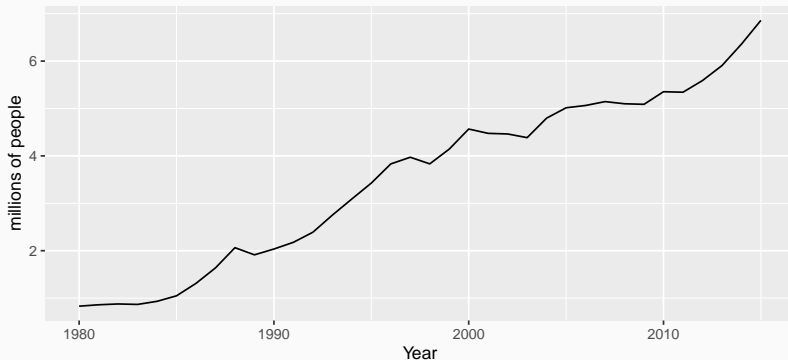
```
# random walk w/ drift  
autoplot(diff(yt))
```



## Example: International visitors

```
autoplot(austa) + xlab("Year") + ylab("millions of people") +  
  ggtitle("Total annual international visitors to Australia")
```

Total annual international visitors to Australia





## Example: International visitors

### Deterministic trend:

```
trend <- seq_along(austa)
(fit1 <- auto.arima(austa, d=0, xreg=trend))
```

```
## Series: austa
## Regression with ARIMA(2,0,0) errors
##
## Coefficients:
##          ar1      ar2  intercept    xreg
##          1.113  -0.380         0.416  0.171
## s.e.   0.160    0.158         0.190  0.009
##
## sigma^2 = 0.0298:  log likelihood = 13.6
## AIC=-17.2   AICc=-15.2   BIC=-9.28
```

## Example: International visitors

### Deterministic trend:

```
trend <- seq_along(austa)
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```
## Series: austa
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## Coefficients:
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## s.e.    0.160    0.158        0.190  0.009
##
## sigma^2 = 0.0298:  log likelihood = 13.6
## AIC=-17.2   AICc=-15.2   BIC=-9.28
```

$$y_t = 0.42 + 0.17t + \eta_t$$

$$\eta_t = 1.11\eta_{t-1} - 0.38\eta_{t-2} + \varepsilon_t, \quad \varepsilon_t \sim \text{NID}(0, 0.0298).$$

## Example: International visitors

### Stochastic trend:

```
#  
(fit2 <- auto.arima(austa, d=1))  
  
## Series: austa  
## ARIMA(0,1,1) with drift  
##  
## Coefficients:  
##          ma1  drift  
##          0.301  0.173  
## s.e.    0.165  0.039  
##  
## sigma^2 = 0.0338:  log likelihood = 10.62  
## AIC=-15.24   AICc=-14.46   BIC=-10.57
```

## Example: International visitors

### Stochastic trend:

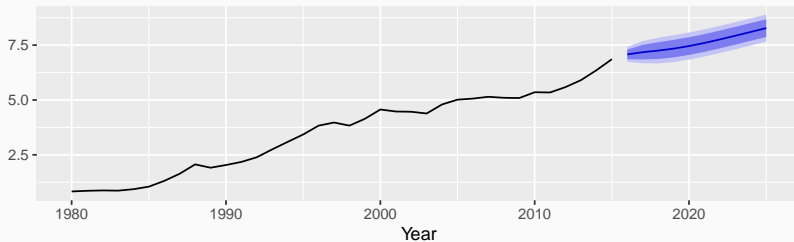
```
#  
(fit2 <- auto.arima(austa, d=1))  
  
## Series: austa  
## ARIMA(0,1,1) with drift  
##  
## Coefficients:  
##          ma1  drift  
##          0.301  0.173  
## s.e.    0.165  0.039  
##  
## sigma^2 = 0.0338:  log likelihood = 10.62  
## AIC=-15.24   AICc=-14.46   BIC=-10.57
```

$$y'_t = 0.17 + \eta'_t$$

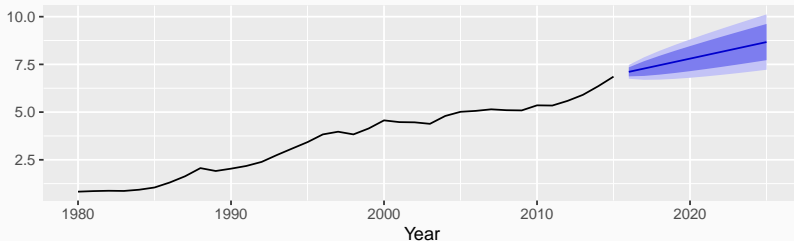
$$\eta'_t = 0.30\varepsilon_{t-1} + \varepsilon_t, \quad \varepsilon_t \sim \text{NID}(0, 0.0338).$$

## Example: International visitors

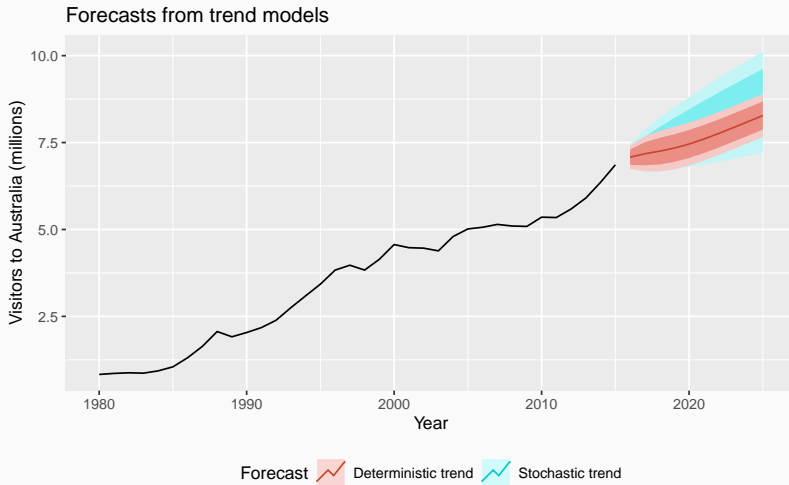
Forecasts from linear trend with AR(2) error



Forecasts from ARIMA(0,1,1) with drift



## Example: International visitors



### Remarks:

- point forecasts are almost identical
- prediction intervals differ substantially
- stochastic trends have much wider prediction intervals because the errors are non-stationary
- be careful of forecasting with deterministic trends too far ahead

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These tests consider the following hypotheses:

$$H_0 : \quad \phi = 1 \quad (\text{i.e., } \phi(z) = 0 \text{ has a unit root})$$

$$H_1 : \quad |\phi| < 1 \quad (\text{i.e., } \phi(z) = 0 \text{ has root outside unit circle})$$

Remarks:

- the most popular of these tests are the Dickey-Fuller (ADF) test and the Phillips-Perron (PP) test
- the ADF and PP tests differ mainly in how they treat serial correlation in the test regressions

Conceptually the unit root tests are straightforward. In practice, however, there are some difficulties:

- unit root tests generally have nonstandard and non-normal asymptotic distributions
- these distributions do not have convenient closed form expressions and critical values must be calculated using simulation methods
- the distributions are affected by the inclusion of deterministic terms (e.g. constant, time trend, dummy variables), and so different sets of critical values must be used for test regressions with different deterministic terms

## Dickey-Fuller unit root tests

The Dickey-Fuller (ADF) test is based on estimating the test regression:

$$y_t = TD_t + \phi y_{t-1} + \sum_{j=1}^p \psi_j y'_{t-j} + \varepsilon_t$$

$TD_t$  = deterministic terms

$y'_{t-j}$  : captures serial correlation

The ADF t-statistic is

$$ADF_t = t_{\phi=1} = \frac{\hat{\phi} - 1}{SE(\hat{\phi})}$$

Alternative formulation of the ADF test regression:

$$y'_t = TD_t + \pi y_{t-1} + \sum_{j=1}^p \psi_j y'_{t-j} + \varepsilon_t$$

$$\pi = \phi - 1$$

Under the null hypothesis  $\phi = 1$ ,  $\pi = 0$ , and the ADF t-statistic is

$$ADF_t = t_{\pi=0} = \frac{\hat{\pi}}{SE(\hat{\phi})}$$

When testing for unit roots, it is crucial to specify the null and alternative hypotheses appropriately to characterize the trend properties of the data at hand:

- if the observed data does not exhibit an increasing or decreasing trend, then the appropriate null and alternative hypotheses should reflect this
- the trend properties of the data *under the alternative hypothesis* will determine the form of the test regression used
- the type of deterministic terms in the test regression will influence the asymptotic distributions of the unit root test statistics

# Critical values

```
# standard normal quantiles
```

```
qnorm(c(.01,.05,.10))
```

```
## [1] -2.326 -1.645 -1.282
```

```
# DF asymptotic critical values (requires urca package)
```

```
qunitroot(c(.01,.05,.1), trend="nc", statistic="t")
```

```
## [1] -2.565 -1.941 -1.617
```

```
qunitroot(c(.01,.05,.1), trend="c", statistic="t")
```

```
## [1] -3.430 -2.861 -2.567
```

```
qunitroot(c(.01,.05,.1), trend="ct", statistic="t")
```

```
## [1] -3.958 -3.410 -3.127
```

## Choosing the lag length for the ADF test

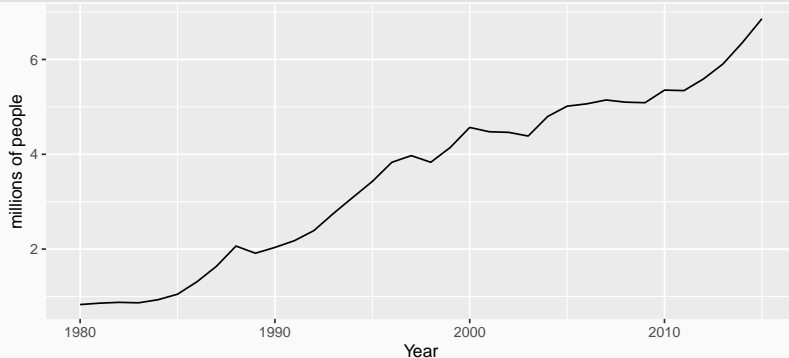
An important practical issue for the implementation of the ADF test is the specification of the lag length  $p$ .

- if  $p$  is too small then the remaining serial correlation in the errors will bias the test
- if  $p$  is too large then the power of the test will suffer
- Monte Carlo experiments suggest it is better to err on the side of including too many lags
- model selection criteria can be used to select  $p$  (AIC better than BIC)

## Example: International visitors

```
# plot series
```

```
autoplot(austa) + xlab("Year") + ylab("millions of people")
```





## Example: International visitors

```
# ADF test, levels
test1 <- ur.df(y = austa, type = 'trend', selectlags = "AIC", lags = 8)
summary(test1)
```

```
## Value of test-statistic is: -1.7707 4.092 1.88
```

```
##
```

```
## Critical values for test statistics:
```

```
##      1pct  5pct 10pct
```

```
## tau3 -4.15 -3.50 -3.18
```

```
## phi2  7.02  5.13  4.31
```

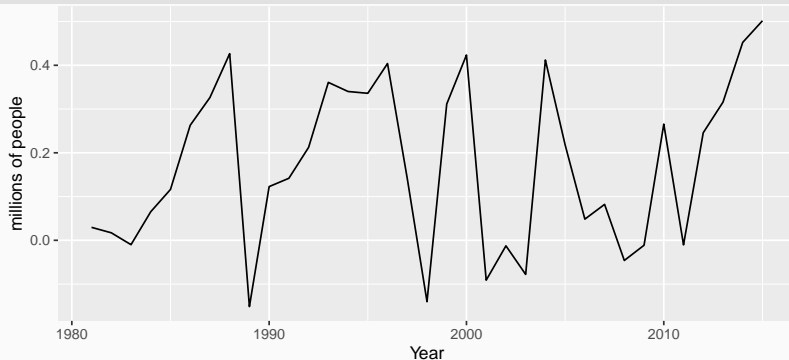
```
## phi3  9.31  6.73  5.61
```

- $t_{\pi=0} = -1.771 > -3.18$  (10% critical value) so we fail to reject the unit root hypothesis for  $y_t$

## Example: International visitors

```
# plot series
```

```
autoplot(diff(austa)) + xlab("Year") + ylab("millions of people")
```



## Example: International visitors

```
# ADF test, first diff
test2 <- ur.df(y = diff(austa), type = 'drift', selectlags = "AIC", lags = 8)
summary(test2)
```

```
## Value of test-statistic is: -3.0961 5.0284
```

```
##
```

```
## Critical values for test statistics:
```

```
##      1pct  5pct 10pct
```

```
## tau2 -3.58 -2.93 -2.60
```

```
## phi1  7.06  4.86  3.94
```

- $t_{\pi=0} = -3.096 < -2.93$  (5% critical value) so we reject the unit root hypothesis for the first difference of  $y_t$

## How to determine $d$ ?

Unit root tests can be used to determine  $d$ :

- 1 test for a unit root in  $y_t$  - if  $H_0$  is rejected, then  $d = 0$
- 2 if  $H_0$  is not rejected, then test for a unit root in  $y'_t$  - if  $H_0$  is rejected, then  $d = 1$
- 3 if  $H_0$  is not rejected, then test for a unit root in  $y''_t$  - if  $H_0$  is rejected, then  $d = 2$
- 4 continue until  $H_0$  is rejected

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Sometimes a change in  $x_t$  does not affect  $y_t$  instantaneously.

Sometimes a change in  $x_t$  does not affect  $y_t$  instantaneously.

### Examples

- $y_t$  = sales,  $x_t$  = advertising
- $y_t$  = stream flow,  $x_t$  = rainfall
- $y_t$  = size of herd,  $x_t$  = breeding stock

Sometimes a change in  $x_t$  does not affect  $y_t$  instantaneously.

### Examples

- $y_t$  = sales,  $x_t$  = advertising
- $y_t$  = stream flow,  $x_t$  = rainfall
- $y_t$  = size of herd,  $x_t$  = breeding stock

Remarks:

- these are dynamic systems with input ( $x_t$ ) and output ( $y_t$ )
- $x_t$  is often a leading indicator
- there can be multiple predictors



## Lagged predictors

The model includes present and past values of  $x_t$ .

$y_t = a + \nu_0 x_t + \nu_1 x_{t-1} + \dots + \nu_k x_{t-k} + \eta_t$ , where  $\eta_t$  is an ARIMA process.

The model includes present and past values of  $x_t$ .

$y_t = a + \nu_0 x_t + \nu_1 x_{t-1} + \dots + \nu_k x_{t-k} + \eta_t$ , where  $\eta_t$  is an ARIMA process.

Rewrite model as

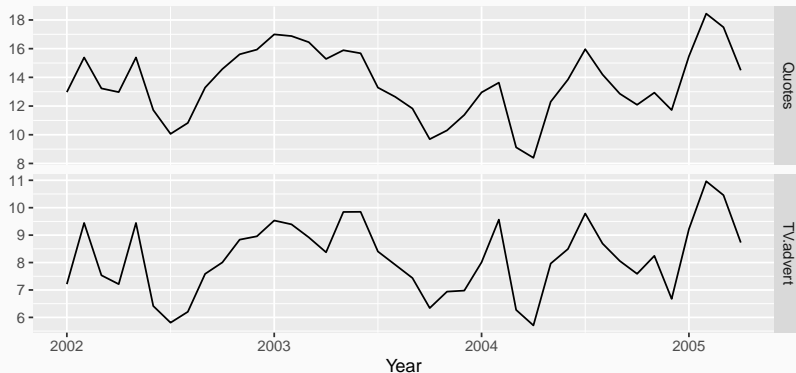
$$\begin{aligned} y_t &= a + (\nu_0 + \nu_1 B + \nu_2 B^2 + \dots + \nu_k B^k) x_t + \eta_t \\ &= a + \nu(B) x_t + \eta_t \end{aligned}$$

- $\nu(B)$  is called a *transfer function* since it describes how change in  $x_t$  is transferred to  $y_t$
- $x$  can influence  $y$ , but  $y$  is not allowed to influence  $x$

## Example: Insurance quotes and TV adverts

```
# plot  
autoplot(insurance, facets=TRUE) +  
  xlab("Year") + ylab("") + ggtitle("Insurance advertising and quotations")
```

Insurance advertising and quotations



## Example: Insurance quotes and TV adverts

```
# generate lagged predictors
Advert <-
  cbind(
    AdLag0 = insurance[, "TV.advert"],
    AdLag1 = lag(insurance[, "TV.advert"], -1),
    AdLag2 = lag(insurance[, "TV.advert"], -2),
    AdLag3 = lag(insurance[, "TV.advert"], -3)
  )
Advert <- head(Advert, NROW(insurance))
# restrict data so models use same fitting period
fit1 <- auto.arima(insurance[4:40, 1], xreg=Advert[4:40, 1], stationary=TRUE)
fit2 <- auto.arima(insurance[4:40, 1], xreg=Advert[4:40, 1:2], stationary=TRUE)
fit3 <- auto.arima(insurance[4:40, 1], xreg=Advert[4:40, 1:3], stationary=TRUE)
fit4 <- auto.arima(insurance[4:40, 1], xreg=Advert[4:40, 1:4], stationary=TRUE)
# evaluate fit
c(fit1$aicc, fit2$aicc, fit3$aicc, fit4$aicc)

## [1] 68.50 60.02 62.83 65.46
```

## Example: Insurance quotes and TV adverts

```
# fit model
(fit <- auto.arima(insurance[,1], xreg=Advert[,1:2], stationary=TRUE))

## Series: insurance[, 1]
## Regression with ARIMA(3,0,0) errors
##
## Coefficients:
##          ar1      ar2      ar3  intercept  AdLag0  AdLag1
##          1.412  -0.932   0.359         2.039    1.256    0.162
## s.e.    0.170    0.255   0.159         0.993    0.067    0.059
##
## sigma^2 = 0.217:  log likelihood = -23.89
## AIC=61.78   AICc=65.4   BIC=73.43
```

## Example: Insurance quotes and TV adverts

```
# fit model
(fit <- auto.arima(insurance[,1], xreg=Advert[,1:2], stationary=TRUE))

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##
## sigma^2 = 0.217:  log likelihood = -23.89
## AIC=61.78   AICc=65.4   BIC=73.43
```

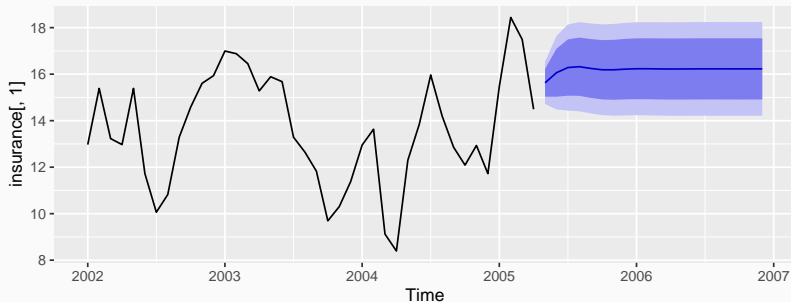
$$y_t = 2.04 + 1.26x_t + 0.16x_{t-1} + \eta_t,$$

$$\eta_t = 1.41\eta_{t-1} - 0.93\eta_{t-2} + 0.36\eta_{t-3} + \varepsilon_t,$$

## Example: Insurance quotes and TV adverts

```
fc <- forecast(fit, h = 20,  
              xreg = cbind(  
                AdLag0 = rep(10,20),  
                AdLag1 = c(Advert[40,1], rep(10,19))  
              ))  
autoplot(fc)
```

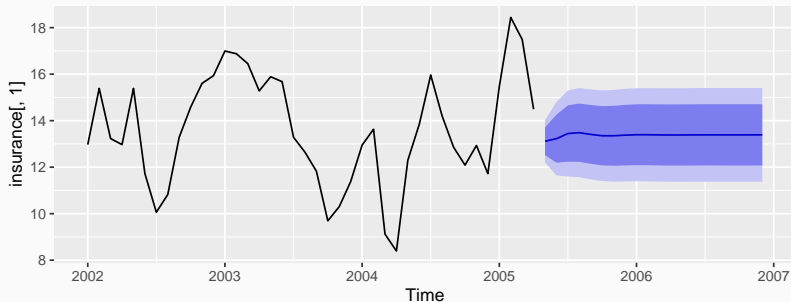
Forecasts from Regression with ARIMA(3,0,0) errors



## Example: Insurance quotes and TV adverts

```
fc <- forecast(fit, h = 20,  
              xreg = cbind(  
                AdLag0 = rep(8,20),  
                AdLag1 = c(Advert[40,1], rep(8,19))  
              ))  
autoplot(fc)
```

Forecasts from Regression with ARIMA(3,0,0) errors

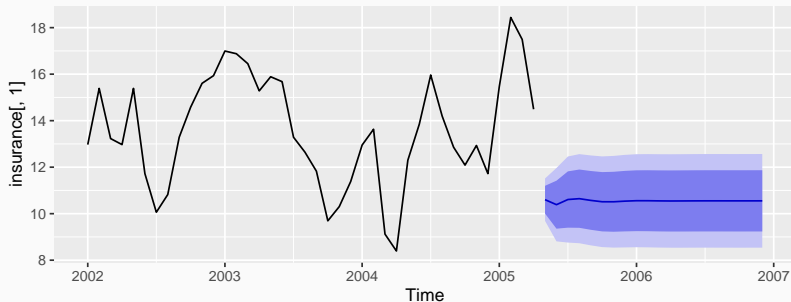




## Example: Insurance quotes and TV adverts

```
fc <- forecast(fit, h = 20,  
              xreg = cbind(  
                AdLag0 = rep(6,20),  
                AdLag1 = c(Advert[40,1], rep(6,19))  
              ))  
autoplot(fc)
```

Forecasts from Regression with ARIMA(3,0,0) errors



- 1 Regression with ARIMA errors
- 2 Stochastic and deterministic trends
- 3 Unit root tests
- 4 Lagged predictors
- 5 Spurious regression and cointegration

# Models with Nonstationary Variables

## Granger and Newbold (1974, JoE)

Consider two independent and unrelated  $I(1)$  processes.

```
# simulate two rw
yt <- ts(cumsum(rnorm(250)))
xt <- ts(cumsum(rnorm(250)))

# regression (1) in levels
reg1 <- tslm(yt ~ xt)

# regression (2) in differences
reg2 <- tslm(diff(yt) ~ diff(xt))
```

# Models with Nonstationary Variables

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Consider two independent and unrelated  $I(1)$  processes.

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# simulate two rw
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# regression (1) in levels
reg1 <- tslm(yt ~ xt)

# regression (2) in differences
reg2 <- tslm(diff(yt) ~ diff(xt))
```

What do you expect?

# Models with Nonstationary Variables

```
# estimates
```

```
coeftest(reg1)
```

```
##  
## t test of coefficients:  
##  
##           Estimate Std. Error t value Pr(>|t|)  
## (Intercept)  -8.2953     0.5720   -14.5 < 2e-16 ***  
## xt           -0.3123     0.0744    -4.2 3.8e-05 ***  
## ---  
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

```
# R2
```

```
summary(reg1)$r.squared
```

```
## [1] 0.06635
```

# Models with Nonstationary Variables

```
# estimates
```

```
coeftest(reg2)
```

```
##  
## t test of coefficients:  
##  
##           Estimate Std. Error t value Pr(>|t|)  
## (Intercept) -0.0348    0.0619   -0.56   0.574  
## diff(xt)     0.1166    0.0659    1.77   0.078 .  
## ---  
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

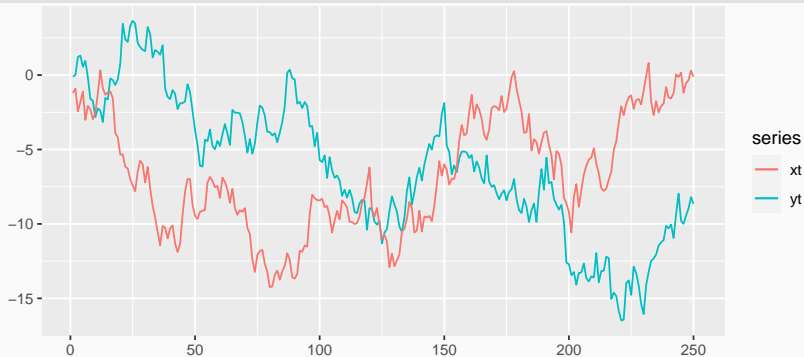
```
# R2
```

```
summary(reg2)$r.squared
```

```
## [1] 0.01253
```

# Models with Nonstationary Variables

```
# plot time series  
autoplot(yt, series="yt") +  
  autolayer(xt, series="xt") + xlab("") + ylab("")
```

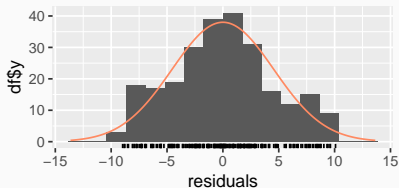
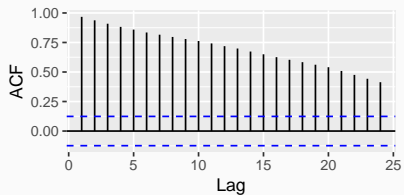
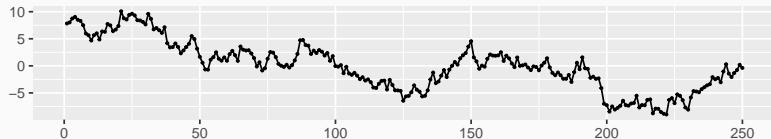


# Models with Nonstationary Variables

```
# check residuals
```

```
checkresiduals(reg1, test = FALSE)
```

Residuals from Linear regression model



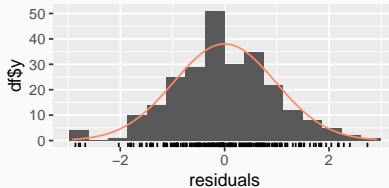
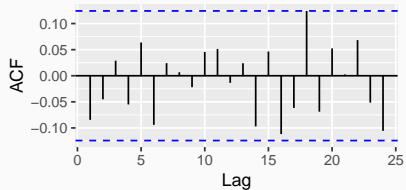
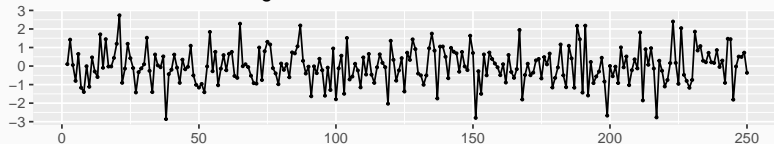


# Models with Nonstationary Variables

```
# check residuals
```

```
checkresiduals(reg2, test = FALSE)
```

Residuals from Linear regression model



# Models with Nonstationary Variables

## Granger and Newbold (1974, JoE)

Consider two independent and unrelated  $I(1)$  processes with drift.

```
# simulate two rw
yt <- ts(cumsum(.5 + rnorm(250)))
xt <- ts(cumsum(.3 + rnorm(250)))

# regression (3) in levels
reg3 <- tslm(yt ~ xt)

# regression (4) in differences
reg4 <- tslm(diff(yt) ~ diff(xt))
```

# Models with Nonstationary Variables

## Granger and Newbold (1974, JoE)

Consider two independent and unrelated  $I(1)$  processes with drift.

```
# simulate two rw  
yt <- ts(cumsum(.5 + rnorm(250)))  
xt <- ts(cumsum(.3 + rnorm(250)))  
  
# regression (3) in levels  
reg3 <- tslm(yt ~ xt)  
  
# regression (4) in differences  
reg4 <- tslm(diff(yt) ~ diff(xt))
```

What do you expect?

# Models with Nonstationary Variables

```
# estimates
```

```
coeftest(reg3)
```

```
##  
## t test of coefficients:  
##  
##           Estimate Std. Error t value Pr(>|t|)  
## (Intercept) -10.9848    1.3627   -8.06 3.2e-14 ***  
## xt           3.4546    0.0512   67.53 < 2e-16 ***  
## ---  
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

```
# R2
```

```
summary(reg3)$r.squared
```

```
## [1] 0.9484
```

# Models with Nonstationary Variables

```
# estimates
```

```
coeftest(reg4)
```

```
##  
## t test of coefficients:  
##  
##           Estimate Std. Error t value Pr(>|t|)  
## (Intercept)  0.5651    0.0599    9.44  <2e-16 ***  
## diff(xt)     -0.0429    0.0570   -0.75    0.45  
## ---  
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

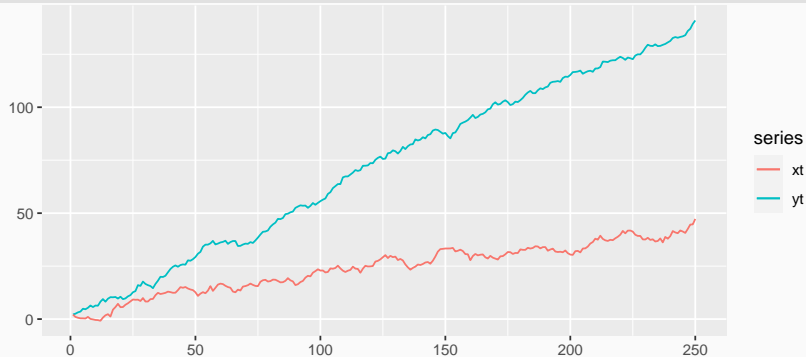
```
# R2
```

```
summary(reg4)$r.squared
```

```
## [1] 0.00229
```

# Models with Nonstationary Variables

```
# plot time series  
autoplot(yt, series="yt") +  
  autolayer(xt, series="xt") + xlab("") + ylab("")
```

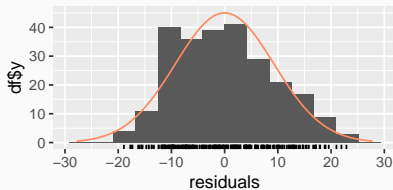
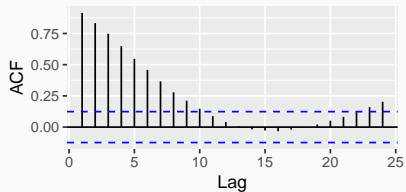
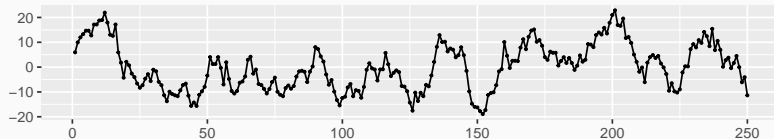


# Models with Nonstationary Variables

```
# check residuals
```

```
checkresiduals(reg3, test = FALSE)
```

Residuals from Linear regression model

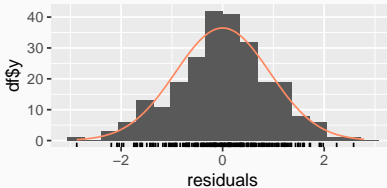
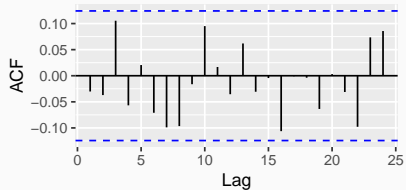
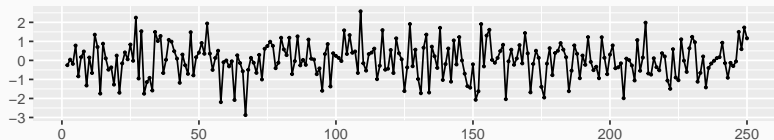


# Models with Nonstationary Variables

```
# check residuals
```

```
checkresiduals(reg4, test = FALSE)
```

Residuals from Linear regression model





## Statistical implications of spurious regression

Let  $y_t$  and  $x_t$  be **two  $I(1)$  time series that are not related**. Consider regressing of  $y_t$  on  $x_t$  giving

$$y_t = \hat{\beta}_0 + \hat{\beta}_1 x_t + \hat{u}_t.$$

Since  $y_t$  is not related with  $x_t$ :

- true value of  $\beta_1$  is zero
- the above is a *spurious regression* and  $\hat{u}_t \sim I(1)$

As a result, if some or all of the variables in a regression are  $I(1)$  then the usual statistical results may or may not hold.

## Statistical implications of spurious regression

The following results about the behavior of  $\hat{\beta}_1$  in the spurious regression are due to Phillips (1986):

- $\hat{\beta}_1$  does not converge in probability to zero but instead converges in distribution to a non-normal random variable not necessarily centered at zero
- the t-statistics for testing  $\beta_1 = 0$  diverge to  $\pm\infty$  as  $T \rightarrow \infty$
- the  $R^2$  from the regression converges to 1 as  $T \rightarrow \infty$  so that the model will appear to fit well even though it is misspecified
- regression with  $I(1)$  data only makes sense when the data are cointegrated

Definition:  $y_t$  and  $x_t$ , both  $I(1)$  time series, are *cointegrated* if there exists a  $\beta_1$  such that

$$y_t - \beta_1 x_t \sim I(0).$$

In words, the nonstationary time series  $y_t$  and  $x_t$  are cointegrated if there is a linear combination of them that is stationary or  $I(0)$ .

- the linear combination is often motivated by economic theory and referred to as a *long-run equilibrium* relationship:

$$y_t = \beta_0 + \beta_1 x_t$$

- intuition:  $I(1)$  time series with a long-run equilibrium relationship cannot drift too far apart from the equilibrium because economic forces will act to restore the equilibrium relationship

In macroeconomics...

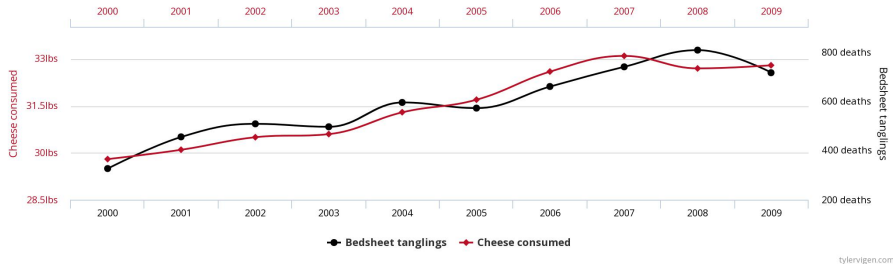
- the equilibrium relationships implied by these economic theories are referred to as *long-run equilibrium* relationships, because the economic forces that act in response to deviations from equilibrium may take a long time to restore equilibrium
- cointegration is modeled using long spans of low frequency time series data measured monthly, quarterly or annually

In finance...

- cointegration may be a high frequency relationship or a low frequency relationship
- cointegration at a high frequency is motivated by arbitrage arguments
- here the terminology long-run equilibrium relationship is somewhat misleading because the economic forces acting to eliminate arbitrage opportunities work very quickly
- cointegration may be appropriately modeled using short spans of high frequency data in seconds, minutes, hours or days

# Your turn

## Per capita cheese consumption correlates with Number of people who died by becoming tangled in their bedsheets



- correlation: 0.9471!
- Source: <http://tylervigen.com/spurious-correlations>