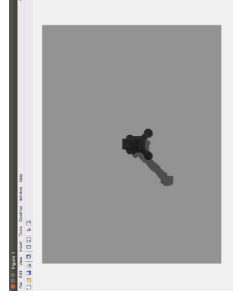


Esquema de conexiones de red GUI-ROS por IP

192.168.0.1



/Phantom/base_link/camera_sensor

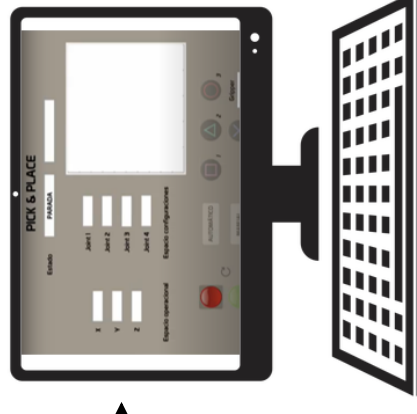


192.168.0.2



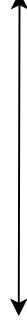
MAESTRO

192.168.0.3



ESCLAVO

Conexión IP



/Phantom_sim