

Lecture 28 — Profiler Guided Optimization

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Using static analysis,
the compiler makes its best predictions
about runtime behaviour.

Example: branch prediction.

```
void whichBranchIsTaken(int a, int b)
{
    if (a < b) {
        puts("a is less than b.");
    } else {
        puts("b is >= a.");
    }
}
```

```
void devirtualization(int count)
{
    for (int i = 0; i < count; i++)
    {
        (*p) (x, y);
    }
}
```

```
void switchCaseExpansion(int i)
{
    switch (i)
    {
        case 1:
            puts("I took case 1.");
            break;
        case 2:
            puts("I took case 2.");
            break;
    }
}
```

How can we know where we go?

- could provide hints...

Java HotSpot virtual machine:
updates predictions on the fly.

So, just guess.
If wrong, the Just-in-Time compiler adjusts &
recompiles.

The compiler runs and it does its job and that's it;
the program is never updated with newer
predictions if more data becomes known.

C: usually no adaptive runtime system.

POGO:

- observe actual runs;
- predict the future.

So, we need multi-step compilation:

- compile with profiling;
- run to collect data;
- recompile with profiling data to optimize.

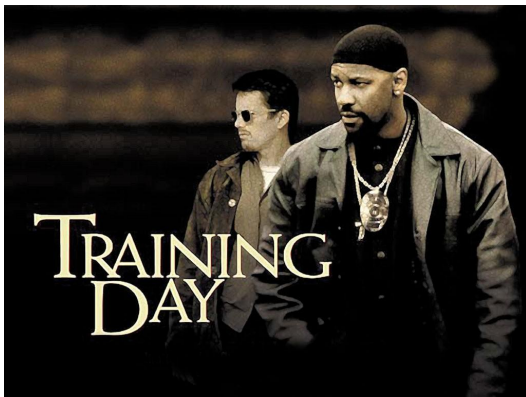
First, generate an executable with instrumentation.

The compiler inserts a bunch of probes into the generated code to record data.

- Function entry probes;
- Edge probes;
- Value probes.

Result: instrumented executable
plus empty database file (for profiling data).

Step Two: Training Day



Second, run the instrumented executable.

Real-world scenarios are best.

Ideally, spend training time on perf-critical sections.

Use as many runs as you can stand.

Don't exercise every part of the program
(ain't SE 465 here!)

That would be counterproductive.

Usage data must match real world scenarios,
or compiler gets misfacts about what's important.

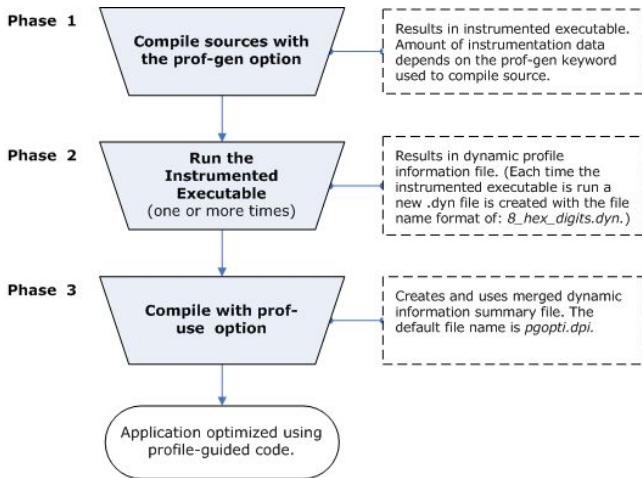
Or you might end up teaching it that almost nothing
is important... (“everything's on the exam!”)

Finally, compile the program again.

Inputs: source plus training data.

Outputs: (you hope) a better output executable than from static analysis alone.

Summary Graphic



Not necessary to do all three steps for every build.

Re-use training data while it's still valid.

Recommended dev workflow:

- dev A performs these steps,
checks the training data into source control
- whole team can use profiling information for
their compiles.

Not fixing all the problems in the world

What does it mean for it to be better?

The algorithms will aim for speed in areas that are “hot”.

The algorithms will aim for minimal code size in areas that are “cold” .

Less than 5% of methods compiled for speed.

Can combine multiple training runs and manually give suggestions about important scenarios.

The more a scenario runs in the training data, the more important it will be, from POGO's point of view.

Can merge multiple runs with user-assigned weightings.

With the theory behind us, perhaps a demonstration about how it works is in order.

Let us consider an example using the N-Body problem.

You could look at the video
<https://www.youtube.com/watch?v=zEsdBcu4R00&t=21m45s>
(from 21:45 to 34:23).

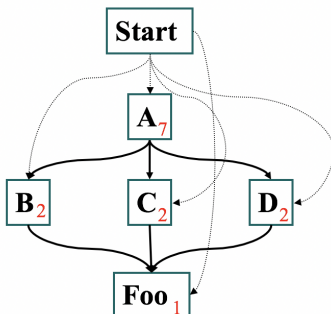
In the optimize phase, compiler uses the training data for:

- 1 Full and partial inlining
- 2 Function layout
- 3 Speed and size decision
- 4 Basic block layout
- 5 Code separation
- 6 Virtual call speculation
- 7 Switch expansion
- 8 Data separation
- 9 Loop unrolling

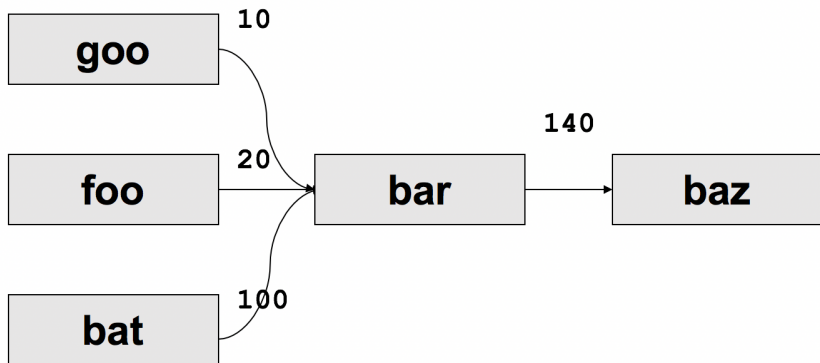
Most performance gains from inlining.

Decisions based on the call graph path profiling.

But: behaviour of function foo may be very different when called from B than when called from D.

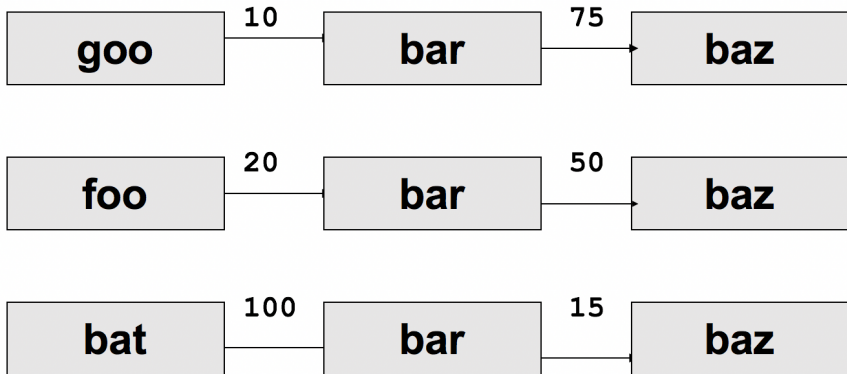


Example 2 of relationships between functions.
Numbers on edges represent the number of invocations:

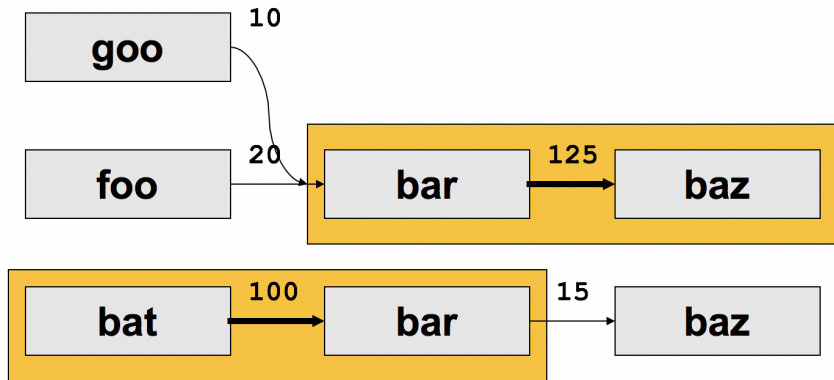


The POGO View of the World

When considering what to do here, POGO takes the view like this:



The POGO View of the World



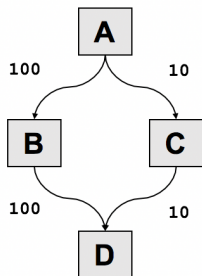
Call graph profiling data also good for packing blocks.

Put most common cases nearby.

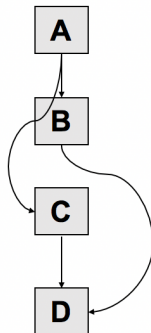
Put successors after their predecessors.

Packing related code = fewer page faults (cache misses).

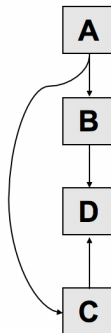
Calling a function in same page as caller = “page locality”.



Default layout



Optimized layout



According to the author, “dead” code goes in its own special block.

Probably not truly dead code (compile-time unreachable).

Instead: code that never gets invoked in training.

OK, how well does POGO work?

The application under test is a standard benchmark suite (Spec2K):

Spec2k:	sjeng	gobmk	perl	povray	gcc
App Size:	Small	Medium	Medium	Medium	Large
Inlined Edge Count	50%	53%	25%	79%	65%
Page Locality	97%	75%	85%	98%	80%
Speed Gain	8.5%	6.6%	14.9%	36.9%	7.9%

We can speculate about how well synthetic benchmarks results translate to real-world application performance...