# Lecture 12 — Autoparallelization

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### **Automatic Parallelization**

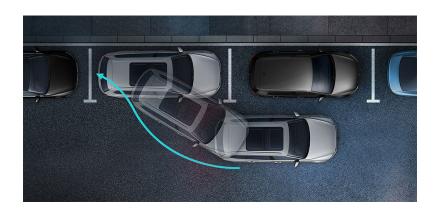


Image Credit: Volkswagen

Wait...autonomous vehicles is a different course...

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### Three Address Code

- An intermediate code used by compilers for analysis and optimization.
- Statements represent one fundamental operation—we can consider each operation atomic.
- Statements have the form:

```
result := operand_1 operator operand_2
```

 Useful for reasoning about data races, and easier to read than assembly.
 (separates out memory reads/writes).

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- GIMPLE is the three address code used by gcc.
- To see the GIMPLE representation of your code use the -fdump-tree-gimple flag.
- To see all of the three address code generated by the compiler use fdump-tree-all. You'll probably just be interested in the optimized version.

■ Use GIMPLE to reason about your code at a low level without having to read assembly.

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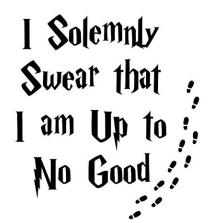
# The restrict Keyword

A feature available as of C99: "The restrict type qualifier allows programs to be written so that translators can produce significantly faster executables."

■ gcc 5+ support C11 or better by default.

restrict means: you are promising the compiler that the pointer will never alias (another pointer will not point to the same data) for the lifetime of the pointer.

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# Example of restrict (1)

Pointers declared with restrict must never point to the same data.

From Wikipedia:

```
void updatePtrs(int* ptrA, int* ptrB, int* val) {
   *ptrA += *val;
   *ptrB += *val;
}
```

Would declaring all these pointers as restrict generate better code?

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# Example of restrict (2)

#### Let's look at the GIMPLE:

```
void updatePtrs(int* ptrA, int* ptrB, int* val) {
   D.1609 = *ptrA;
   D.1610 = *val;
   D.1611 = D.1609 + D.1610;
   *ptrA = D.1611;
   D.1612 = *ptrB;
   D.1610 = *val;
   D.1613 = D.1612 + D.1610;
   *ptrB = D.1613;
}
```

■ Could any operation be left out if all the pointers didn't overlap?

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# Example of restrict (3)

```
void updatePtrs(int* ptrA, int* ptrB, int* val) {
    D.1609 = *ptrA;
    D.1610 = *val;
    D.1611 = D.1609 + D.1610;
    *ptrA = D.1611;
    D.1612 = *ptrB;
    D.1610 = *val;
    D.1613 = D.1612 + D.1610;
    *ptrB = D.1613;
}
```

- If ptrA and val are not equal, you don't have to reload the data on line 7.
- Otherwise, you would: there might be a call updatePtrs(&x, &y, &x);

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# Example of restrict (4)

#### Hence, this markup allows optimization:

```
void updatePtrs(int* restrict ptrA,
    int* restrict ptrB,
    int* restrict val)
```

Note: you can get the optimization by just declaring ptrA and val as restrict; ptrB isn't needed for this optimization

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# Summary of restrict

■ Use restrict whenever you know the pointer will not alias another pointer (also declared restrict)

It's hard for the compiler to infer pointer aliasing information; it's easier for you to specify it.

⇒ compiler can better optimize your code (more perf!)

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# Summary of restrict



Caveat: don't lie to the compiler, or you will get undefined behaviour.

Aside: restrict is not the same as const. const data can still be changed through an alias.

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# Automatic Parallelization of Example Code

Let's try automatic parallelization.

Compiling with solarisstudio and automatic parallelization yields the following:

```
% solarisstudio—cc —O3 —xautopar —xloopinfo omp_vector.c
"omp_vector.c", line 5: PARALLELIZED, and serial version generated
"omp_vector.c", line 15: not parallelized, call may be unsafe
```

How will this code compare to our manual efforts? (If you weren't in class, you'll have to try it yourself.)

**Note:** solarisstudio generates two versions of the code, and decides, at runtime, if the parallel code would be faster.

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## **Example Code to Parallelize**

```
#include < stdlib . h>
void setup(double *vector, int length) {
    int i;
    for (i = 0; i < length; i++)
        vector[i] += 1.0;
int main()
    double *vector;
    vector = (double*) malloc(sizeof(double)*1024*1024);
    for (int i = 0; i < 1000; i++)
        setup (vector, 1024*1024);
    // if you don't read vector, compiler NOPs everything
    printf("%f\n", vector[0]);
```

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# Automatic Parallelization of Example Code

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## Autoparallelization implementation: OpenMP



Under the hood, most parallelization frameworks use OpenMP, which we'll see next lecture.

For now: you can control the number of threads with the OMP\_NUM\_THREADS environment variable.

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# Automatic Parallelization in gcc

gcc (since 4.3) can also auto-parallelize loops via Graphite.

Parallelization has been getting better, but not super well-maintained.

I think gcc can insert a runtime check of loop iteration count.



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# Automatic Parallelization in gcc

#### Magic incantation:

```
gcc -02 -floop-parallelize-all
    -ftree-parallelize-loops=4 -fopt-info
```

-floop-parallelize-all: parallelize all the things

-ftree-parallelize-loops=N: use N threads

**Note:** gcc uses OpenMP but overrides OMP\_NUM\_THREADS with N above.

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### Sample - fopt - info output

```
$ gcc L11-omp_vector.c -02 \
   -floop-parallelize-all -ftree-parallelize-loops=4 -fopt-info
L11-omp_vector.c:14:3: note: parallelizing inner loop 1
L11-omp_vector.c:23:3: note: loop nest optimized
L11-omp_vector.c:15:15: note: parallelizing inner loop 4

line 14: for (i = 0; i < length; i++) {
   line 15: vector[i] += 1.0;
   line 23: for (int i = 0; i < 1000; i++) {</pre>
```

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# Understanding Automatic Parallelization in gcc

Want to better understand? Look at the assembly code to see the parallelizations (obviously, impractical for a large project).

[Or, you can use objdump on files compiled with -g.]

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# gcc assembly output



#### Older gcc generated a . s file with:

```
call GOMP_parallel_start
leaq 80(%rsp), %rdi
call setup._loopfn.0
call GOMP_parallel_end
```

**Note:** gcc also parallelizes main.\_loopfn.2 and main.\_loopfn.3, although it looks like it serves little purpose.

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#### Single loop:

```
for (i = 0; i < 1000; i++)
x[i] = i + 3;
```

#### Nested loops with simple dependency:

```
for (i = 0; i < 100; i++)
  for (j = 0; j < 100; j++)
      X[i][j] = X[i][j] + Y[i-1][j];</pre>
```

#### Single loop with not-very-simple dependency:

```
for (i = 0; i < 10; i++)
X[2*i+1] = X[2*i];
```

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### More Loops gcc Can Handle

### Single loop with if statement:

```
for (j = 0; j <= 10; j++)
if (j > 5) X[i] = i + 3;
```

#### Triangle loop:

```
for (i = 0; i < 100; i++)
    for (j = i; j < 100; j++)
        X[i][j] = 5;</pre>
```

Examples from: http://gcc.gnu.org/wiki/AutoparRelated

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# Summary of Conditions for Automatic Parallelization

From Chapter 10 of Oracle's *Fortran Programming Guide* <sup>1</sup> translated to C, a loop must:

- have a recognized loop style, e.g., for loops with bounds that don't vary per-iteration;
- have no dependencies between data accessed in loop bodies for each iteration;
- not conditionally change scalar variables read after the loop terminates, or change any scalar variable across iterations; and
- have enough work in the loop body to make parallelization profitable.

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http://download.oracle.com/docs/cd/E19205-01/819-5262/index.html

### Let's Race



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## Example Code to Parallelize (once more)

```
#include < stdlib . h>
void setup(double *vector, int length) {
    int i;
    for (i = 0; i < length; i++)
        vector[i] += 1.0;
int main()
    double *vector;
    vector = (double*) malloc(sizeof(double)*1024*1024);
    for (int i = 0; i < 1000; i++)
        setup (vector, 1024*1024);
    // if you don't read vector, compiler NOPs everything
    printf("%f\n", vector[0]);
```

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What can we do to parallelize this code?

Option 1:

Option 2:

Option 3:

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What can we do to parallelize this code?

**Option 1:** horizontal  $\equiv \equiv \equiv \equiv$ 

■ Create 4 threads; each thread does 1000 iterations on its own sub-array.

Option 2:

Option 3:

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What can we do to parallelize this code?

**Option 1:** horizontal  $\equiv \equiv \equiv \equiv$ 

■ Create 4 threads; each thread does 1000 iterations on its own sub-array.

**Option 2:** bad horizontal ≡≡≡≡

■ 1000 times, create 4 threads which each operate once on the sub-array.

Option 3:

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What can we do to parallelize this code?

**Option 1:** horizontal 
$$\equiv \equiv \equiv \equiv$$

■ Create 4 threads; each thread does 1000 iterations on its own sub-array.

```
Option 2: bad horizontal ≡≡≡≡
```

■ 1000 times, create 4 threads which each operate once on the sub-array.

```
Option 3: vertical |||| ||| ||||
```

 Create 4 threads; for each element, the owning thread does 1000 iterations on that element.

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### Manual Parallelization Demo

Methodology: compiling with solarisstudio, flags -03 -lpthread.

Which manual option performs better?

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## **Comparing Parallelization Results**

How does autoparallelization compare to manual parallelization?

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# **Comparing Parallelization Results**

How does autoparallelization compare to manual parallelization?

- Relative ordering: **Option 3** > Automatic > **Option 1**
- Automatic parallelization of Option 1 was better than manual, why?

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# **Comparing Parallelization Results**

How does autoparallelization compare to manual parallelization?

- Relative ordering: **Option 3** > Automatic > **Option 1**
- Automatic parallelization of Option 1 was better than manual, why?
- Manual Option 3 performed better, even though both used the same number of threads, why?

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### **Lingering Questions about Runtimes**

#### What happened here?

horizontal good:
create 4 threads to do 1000 iterations on sub-arrays.
horizontal bad:
1000 times, create 4 threads to iterate on sub-array.
vertical:

In 2015, perf stat -r 5 gave following task-clocks (in seconds):

	H good	H bad	V	auto
gcc, no opt	2.794	2.953	2.799	
gcc, -03	0.588	1.490	0.980	
solaris, no opt	3.175	3.291	2.966	
solaris, -xO4	0.494	1.453	2.739	0.688

create 4 threads, handle 1 element at a time.

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## Runtimes—Why?

#### Observations:

- Good runs had 5 to 7 cpu-migrations; bad had 4000.
- # cycles varied from 2B to 9.7B (no opt).
- Branch misses varied from 8k to 208k.

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# Case Study 2: Multiplying a Matrix by a Vector

Let's see how automatic parallelization does on a more complicated program (could we parallelize this?):

Reminder: 
$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 14 \\ 32 \end{bmatrix}$$

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# Case Study: Automatic Parallelization, Attempt 1

Well, based on our knowledge, we could parallelize the outer loop.

Let's see what solarisstudio will do for us...

```
% solarisstudio—cc —xautopar —xloopinfo —03—c fploop.c
"fploop.c", line 5: not parallelized, not a recognized for loop
"fploop.c", line 8: not parallelized, not a recognized for loop
```

...it refuses to do anything, guesses?

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# Case Study: Automatic Parallelization, Attempt 2

■ The loop bounds are not constant, since one of the variables may alias row or col, even though int  $\neq$  double.

So, let's add restrict to row and col and see what happens...

```
% solarisstudio—cc —03 —xautopar —xloopinfo —c fploop.c
"fploop.c", line 5: not parallelized , unsafe dependence
"fploop.c", line 8: not parallelized , unsafe dependence
```

Now it recognizes the loop, but still won't parallelize it. Why?

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### Case Study: Automatic Parallelization, Attempt 3

■ out might alias mat or vec, which would make this unsafe

#### Let's add another restrict to out:

```
% solarisstudio—cc —03 —xautopar —xloopinfo —c fploop.c
"fploop.c", line 5: PARALLELIZED, and serial version
generated
"fploop.c", line 8: not parallelized, unsafe dependence
```

Now, we can get the outer loop to parallelize.

■ Parallelizing the outer loop is almost always better than inner loops, and usually it's a waste to do both, so we're done.

**Note:** We can parallelize the inner loop as well (it's similar to the assignment). We'll see that solarisstudio can do it automatically.

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### Reductions



Reductions combine input data into a smaller (summary) set.

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Simplest instance: computing the sum of an array.

Consider the following code:

```
double sum (double *array, int length)
{
  double total = 0;
  for (int i = 0; i < length; i++)
    total += array[i];
  return total;
}</pre>
```

Can we parallelize this?

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### **Reduction Problems**

#### Barriers to parallelization:

- value of total depends on previous iterations;
- addition is actually non-associative for floating-point values (is this a problem?)

Recall that "associative" means:

$$a + (b + c) = (a + b) + c$$
.

In this case, the program probably isn't sensitive to rounding, but you should always consider if an operation is associative.

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### **Automatic Parallelization via Reduction**

If we compile the program with solarisstudio and add the flag -xreduction, it will parallelize the code:

```
% solarisstudio—cc —xautopar —xloopinfo —xreduction —O3 —c sum.c "sum.c", line 5: PARALLELIZED, reduction, and serial version generated
```

**Note:** If we try to do the reduction on fploop.c with restricts added, we'll get the following:

```
% solarisstudio—cc —O3 —xautopar —xloopinfo —xreduction —c fploop.c "fploop.c", line 5: PARALLELIZED, and serial version generated "fploop.c", line 8: not parallelized, not profitable
```

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# **Dealing with Function Calls**

- A general function could have arbitary side effects.
- Production compilers tend to avoid parallelizing any loops with function calls.

Some built-in functions, like sin(), are "pure", have no side effects, and are safe to parallelize.

**Note:** this is why functional languages are nice for parallel programming: impurity is visible in type signatures.

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# Dealing with Function Calls in solarisstudio

- For solarisstudio you can use the -xbuiltin flag to make the compiler use its whitelist of "pure" functions.
- The compiler can then parallelize a loop which uses sin() (you shouldn't replace built-in functions with your own if you use this option).

#### Other options which may work:

- Trank up the optimization level (-x04).
- 2 Explicitly tell the compiler to inline certain functions (-xinline=, or use the inline keyword).

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# **Summary of Automatic Parallelization**

To help the compiler, we can:

- use restrict (make a restricted copy); and,
- make sure that loop bounds are constant (temporary variables).

Some compilers automatically create different versions for the alias-free case and the (parallelized) aliased case.

At runtime, the program runs the aliased case if correct.

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