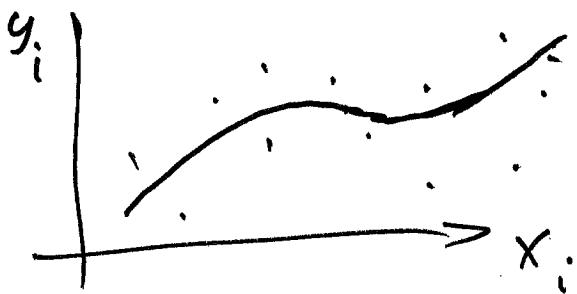


# Curve fitting

#4

 $(x_i, y_i)$ 

$$\underline{y_i = f(x_i) + \varepsilon_i}$$

$$f(x) = a_1 f_1(x) + a_2 f_2(x) + \dots + a_m f_m(x)$$

$$a = \begin{bmatrix} a_1 \\ \vdots \\ a_m \end{bmatrix}$$

$$F(x) = F_x = [f_1(x) \dots f_m(x)]$$

$$y = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$$

$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$\varepsilon = \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

$$y = F_x a + \varepsilon$$

m - fixed

n - big enough.

$$Q(a) = \sum_{i=1}^n (y_i - f_a(x_i))^2 \underset{a}{\sim} \min$$

$$Q(a) = \|y - Ba\|^2 =$$

$$= \|B(a - (B^T B)^{-1} B^T y)\|^2$$

$$+ \|y\|^2 - \|B(B^T B)^{-1} B^T y\|^2$$

$$B = \begin{bmatrix} F_{x_1} \\ F_{x_2} \\ \vdots \\ F_{x_n} \end{bmatrix} = \begin{bmatrix} f_1(x_1) & \cdots & f_m(x_1) \\ \vdots & \ddots & \vdots \\ f_1(x_n) & \cdots & f_m(x_n) \end{bmatrix} \stackrel{n \times m}{=} \boxed{\quad}$$

If  $\hat{a} = (B^T B)^{-1} B^T g \Rightarrow Q(\hat{a}) \sim \min$

Columns of B are independent.

$n \geq m$ ,  $f_1, \dots, f_m$  - lin indep  
 $x_1, \dots, x_n$  "random enough"

Col. of B indep  $\Rightarrow B u = 0 \Rightarrow u = 0$

$$B^T B = \begin{matrix} n & \square \\ \square & m \end{matrix}$$

$$\text{rank } B = m$$

$$\underbrace{B^T B u = 0}_{\square} \Rightarrow u = 0$$

$$0 = \langle B^T B u, u \rangle = \langle B u, B u \rangle = \|B u\|^2$$

$$\Rightarrow \|B u\| = 0 \Rightarrow B u = 0 \Rightarrow u = 0$$

$\Rightarrow \text{rank } B^T B = m \Rightarrow B^T B \text{ is invertible}$

$\exists ! \hat{\alpha} : Q(\hat{\alpha}) \sim \min.$

$$\hat{\alpha} = (\mathbf{B}^T \mathbf{B})^{-1} \mathbf{B}^T \mathbf{y}$$

$$\begin{matrix} (\mathbf{x}_1, y_1) \\ \vdots \\ (\mathbf{x}_n, y_n) \\ (\mathbf{x}_{n+1}, y_{n+1}) \end{matrix} \Rightarrow \mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_n \\ y_{n+1} \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} f_1(\mathbf{x}_1) & \cdots & f_m(\mathbf{x}_1) \\ \vdots & \ddots & \vdots \\ f_1(\mathbf{x}_n) & \cdots & f_m(\mathbf{x}_n) \\ \vdots & \ddots & \vdots \\ f_1(\mathbf{x}_{n+1}) & \cdots & f_m(\mathbf{x}_{n+1}) \end{bmatrix}$$

$$\mathbf{B}^T \mathbf{y} = \begin{bmatrix} F_1 \\ \vdots \\ F_n \end{bmatrix}^T \mathbf{y} \quad | \quad F_i = F_{\mathbf{x}_i} = F(\mathbf{x}_i)$$

$$= [F_1^T \cdots F_n^T] \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = y_1 F_1^T + \cdots + y_n F_n^T$$

$$= \sum_{i=1}^n y_i F_i^T = \sum_{i=1}^n y_i \begin{bmatrix} f_1(\mathbf{x}_i) \\ \vdots \\ f_m(\mathbf{x}_i) \end{bmatrix} = \sum_{i=1}^n y_i = \mathbf{0}$$

$$(\mathbf{x}_i, y_i) \mapsto \mathbf{z}_i = y_i \begin{bmatrix} f_1(\mathbf{x}_i) \\ \vdots \\ f_m(\mathbf{x}_i) \end{bmatrix} \quad | m \text{-vector}$$

$$B^T B = \left[ F_1^T \dots F_n^T \right] \begin{bmatrix} F_1 \\ \vdots \\ F_n \end{bmatrix} - m \times m$$

9

$$= F_1^T F_1 + \dots + F_n^T F_n =$$

$$= \sum_{i=1}^n \underbrace{F_i^T F_i}_{= T_i} = \sum_{i=1}^n T_i = T$$

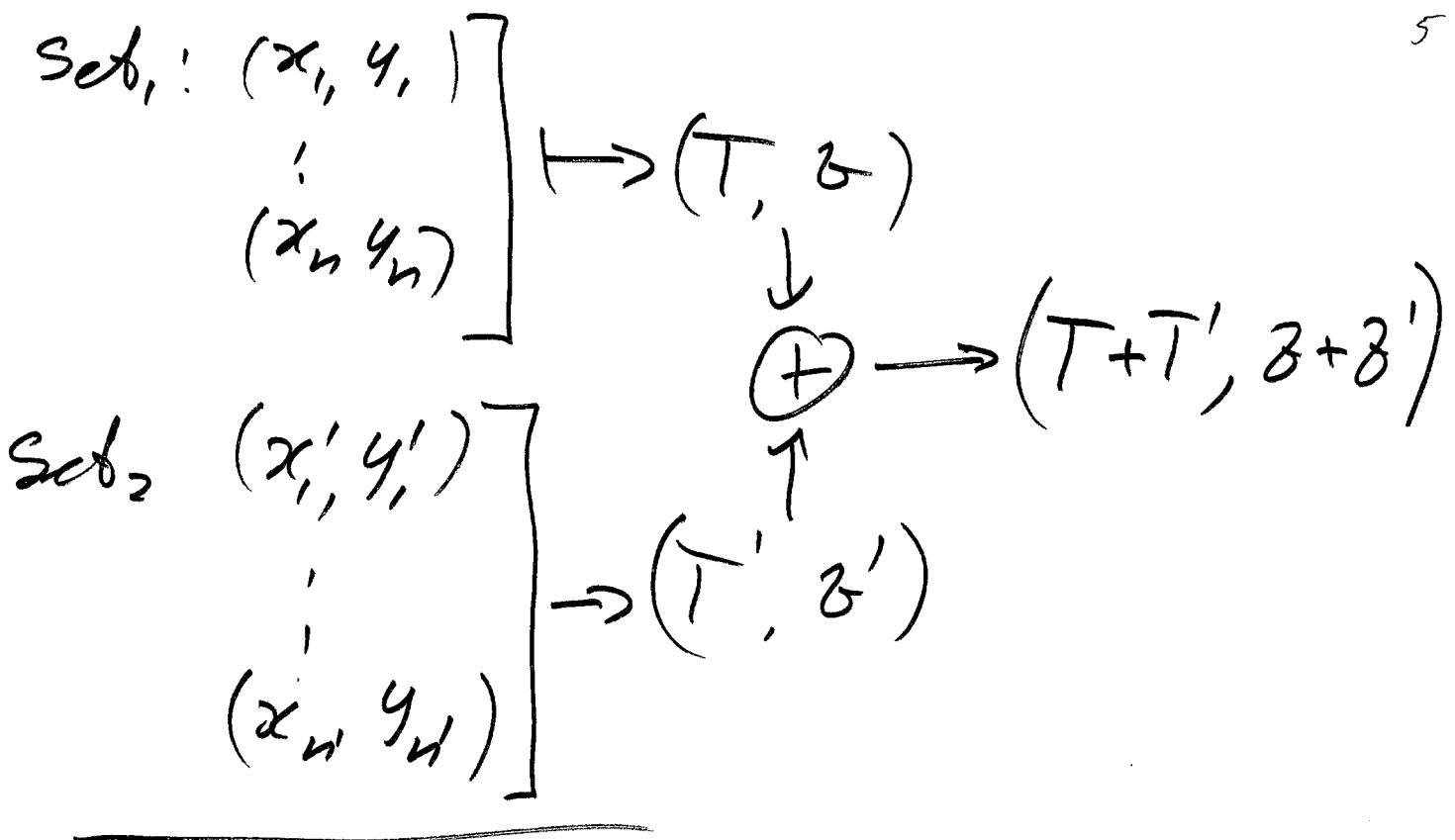
$$T_i = F_i^T F_i = \begin{bmatrix} f_1(x_i) \\ \vdots \\ f_m(x_i) \end{bmatrix} [f_1(x_i) \dots f_m(x_i)] =$$

$$= \begin{bmatrix} f_1^2(x_i) & f_1(x_i) f_2(x_i) \dots f_1(x_i) f_m(x_i) \\ \vdots & \vdots & \ddots & \vdots \\ f_m(x_i) f_1(x_i) & \dots & & f_m^2(x_i) \end{bmatrix}$$

$m \times m$

---


$$\frac{(T, z)}{m \square \underset{m}{\square} \mid m} \quad \hat{a} = T^{-1} z$$



Accumulate:

$$(x_i, y_i) \mapsto (T_i, \beta_i) \Rightarrow (T, \beta)$$

$$(T, \beta) \mapsto \hat{a} = T^{-1}\beta.$$

$\hat{a}$  - unbiased estimate of  $a$ :

$$\hat{a} = \underbrace{(B^T B)^{-1} B^T y}_{= R} = Ry$$

$$y = Ba + \varepsilon$$

$$\begin{aligned}
 \hat{\alpha} - \alpha &= (B^T B)^{-1} B^T y - \alpha \\
 &= (B^T B)^{-1} B^T (B\alpha + \varepsilon) - \alpha \\
 &= \underbrace{((B^T B)^{-1} B^T B - I)\alpha}_{=I} + R\varepsilon
 \end{aligned}$$

$$\begin{aligned}
 &= R\varepsilon \\
 E(\hat{\alpha} - \alpha) &= E R\varepsilon = R E\varepsilon = R \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix} = \\
 &= R \begin{bmatrix} E\varepsilon_1 \\ \vdots \\ E\varepsilon_n \end{bmatrix} = R O = O
 \end{aligned}$$

$\varepsilon_i : \underline{E\varepsilon_i = 0} \quad \text{Var}\varepsilon_i = E\varepsilon_i^2 = \sigma^2$

$E(\hat{\alpha} - \alpha) = 0 \Rightarrow \hat{\alpha}$  - unbiased

Accuracy of  $\hat{\alpha}$ .

$$\begin{aligned}
 \text{Var}(\hat{\alpha}) &= E(\hat{\alpha} - E\hat{\alpha})(\hat{\alpha} - E\hat{\alpha})^T = \\
 &\quad (\text{variance matr. or var-covar matr.})
 \end{aligned}$$

$$= E(\hat{\alpha} - \alpha)(\hat{\alpha} - \alpha)^T = E R\varepsilon \varepsilon^T R^T$$

$$= R E \Sigma \Sigma^T R^T$$

$$E \varepsilon \varepsilon^T = E \begin{bmatrix} \varepsilon_1 \varepsilon_1 & \varepsilon_1 \varepsilon_2 & \cdots & \varepsilon_1 \varepsilon_n \\ \vdots & & & \\ \varepsilon_n \varepsilon_1 & \cdots & \cdots & \varepsilon_n^2 \end{bmatrix}$$

$$E \varepsilon_i^2 = \sigma^2 = \text{Var } \varepsilon_i$$

$\{\varepsilon_i\}$  - indep.  $E \varepsilon_i \varepsilon_j = 0 \stackrel{\text{if } i \neq j}{\Rightarrow}$

$$E \varepsilon \varepsilon^T = \text{Var } \varepsilon = \sigma^2 I$$

$$\begin{aligned} \text{Var}(\hat{\alpha}) &= R \cdot \sigma^2 I \cdot R^T = \sigma^2 R R^T \\ &= \sigma^2 \underbrace{(B^T B)}_R^{-1} \underbrace{B^T}_R B \underbrace{(B^T B)}_R^{-1} \\ &= \sigma^2 \underbrace{(B^T B)}_{=T}^{-1} = \sigma^2 T^{-1} \end{aligned}$$

$$\text{Var}(\hat{\alpha}_j) = E(\hat{\alpha}_j - \alpha_j)^2 = \sigma^2 (T^{-1})_{jj}$$

$$\text{Cor}(\hat{\alpha}_j, \hat{\alpha}_k) = E(\hat{\alpha}_j - \alpha_j)(\hat{\alpha}_k - \alpha_k) = \sigma^2 (T^{-1})_{jk}$$

### Estimation of $f(x)$

$$\begin{aligned} \hat{f}(x) &= \hat{\alpha}_1 f_1(x) + \dots + \hat{\alpha}_m f_m(x) \\ &= F_x \hat{\alpha} \quad F_x = [f_1(x) \dots f_m(x)] \end{aligned}$$

$$E(\hat{f}(x) - f(x)) = E(F_x \hat{\alpha} - F_x \alpha) =$$

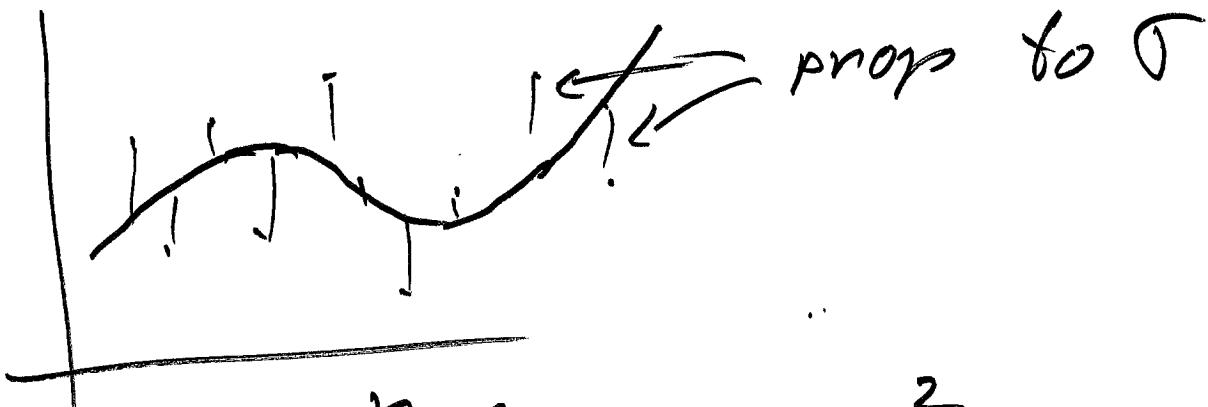
$$\begin{aligned} \hat{f}(x) &= E F_x (\hat{\alpha} - \alpha) = F_x (\underbrace{E \hat{\alpha} - \alpha}_{=0}) = 0 \\ &\text{unbiased est. of } f(x) \end{aligned}$$

$$\begin{aligned}
 \text{Var}(\widehat{f(x)}) &= E(\widehat{f(x)} - f(x))^2 = \\
 &= E\left(F_x \underbrace{(\vec{\alpha} - \alpha)}_{R\varepsilon}\right)^2 = E\left(F_x R \varepsilon \underbrace{(F_x R \varepsilon)^T}_{\substack{\frac{m}{m} \times \frac{n}{n} \\ |n}}\right) \\
 &= E(F_x R \varepsilon \varepsilon^T R^T F_x^T) \\
 &= F_x R \underbrace{E(\varepsilon \varepsilon^T)}_{= \sigma^2 I} \cdot R^T F_x^T = F_x \underbrace{R R^T}_{= T^{-1}} F_x^T \\
 &= \sigma^2 F_x T^{-1} F_x^T
 \end{aligned}$$

$x \rightarrow \underset{*}{\textcircled{*}} \xrightarrow{\text{apply}} f(x), \quad \text{Var}(\widehat{f(x)})$   
 $\widehat{f(x)} = F_x T^{-1} z$   
 $\text{Var}(\widehat{f(x)}) = \sigma^2 F_x T^{-1} F_x^T$

Assumed that  $\sigma^2$  is given.

If  $\sigma^2$  is not given.  
need to estimate it.



$$Q(\hat{\alpha}) = \sum_{i=1}^n (y_i - f_{\hat{\alpha}}(x_i))^2$$

$$\mathbb{E} Q(\hat{\alpha}) = (n-m) \sigma^2 \text{ (Later)}$$

$$\hat{\sigma}^2 = \frac{Q(\hat{\alpha})}{n-m} \quad \begin{matrix} \text{- Unbiased est} \\ \text{of } \sigma^2 \end{matrix}$$

$$\begin{aligned} Q(\hat{\alpha}) &= \|y - B\hat{\alpha}\|^2 = \|y\|^2 - \|B(B^T B)^{-1} B^T y\|^2 \\ &= \|y\|^2 - \|B\hat{\alpha}\|^2 \\ &= \underbrace{\sum_{i=1}^n y_i^2}_{= V} - \underbrace{(B\hat{\alpha})^T B \hat{\alpha}}_{= T} \quad |n \\ &= V - \hat{\alpha}^T \underbrace{B^T B}_{= T} \hat{\alpha} \end{aligned}$$

$$Q(\hat{a}) = V - \hat{a}^T T \hat{a} \quad \hat{a} = T^{-1} z$$

$$= V - z^T \underbrace{T^{-1} T T^{-1} z}_{= T^{-1}} = T^{-1}$$

$$= V - z^T T^{-1} z$$

$$V = \sum_{i=1}^n y_i^2 = \sum_{i=1}^n v_i$$

$$\hat{\sigma}^2 = \frac{V - z^T T^{-1} z}{n - m}$$

need to add  $V$  and  $n$   
to can. info.

Can info:  $(T, z, V, n)$

$$m \square_m | m \bullet \bullet$$

$$\begin{bmatrix} (x_1, y_1) \\ \vdots \\ (x_n, y_n) \end{bmatrix} \mapsto (T, z, v, \nu)$$

apply  $\oplus$

$$\begin{aligned} \hat{\alpha} &= T^{-1} z \\ \text{Var}(\hat{\alpha}) &= \hat{\sigma}^2 T^{-1} \\ \hat{\sigma}^2 &= \frac{V - z^T T^{-1} z}{n-m} \\ x \rightarrow \oplus &\Rightarrow \text{Var}(f(\hat{\alpha})) = \hat{\sigma}^2 F_x T^{-1} F_x^T \\ f(\hat{\alpha}) &= F_x T^{-1} z \end{aligned}$$

$$\begin{aligned} (T, z, v, \nu) \oplus (T', z', v', \nu') &= \\ = (T + T', z + z', v + v', \nu + \nu') \end{aligned}$$

Simple lin. regression  
as a particular case.

$$f(x) = \alpha + \beta x = F_x q$$

$$= \underbrace{\begin{bmatrix} 1 & x \end{bmatrix}}_F \begin{bmatrix} q \\ \beta \end{bmatrix}$$

$\sigma^2$  is known - (for simplicity.)

$$(x_i, y_i)_{i=1, n} \mapsto (n, X, Y, Z, U)$$

$$X = \sum_i x_i, \quad Y = \sum_i y_i, \quad Z = \sum_i x_i y_i$$

$$U = \sum_i x_i^2$$

In gen. case can. Inv.:  $(T, Z)$

$$T = \sum_{i=1}^n F_i^T F_i, \quad F_i = \begin{bmatrix} 1 & x_i \end{bmatrix}$$

$$= \sum_{i=1}^n \begin{bmatrix} 1 \\ x_i \end{bmatrix}^T \begin{bmatrix} 1 & x_i \end{bmatrix} = \sum_{i=1}^n \begin{bmatrix} 1 & x_i \\ x_i & x_i^2 \end{bmatrix}$$

$$= \begin{bmatrix} \sum_i 1 & \sum_i x_i \\ \sum_i x_i & \sum_i x_i^2 \end{bmatrix} = \begin{bmatrix} n & X \\ X & U \end{bmatrix}$$

$$Z = \sum_i y_i, \quad F_i^T = \sum_{i=1}^n y_i \begin{bmatrix} 1 \\ x_i \end{bmatrix} = \begin{bmatrix} \sum_i y_i \\ \sum_i y_i x_i \end{bmatrix} = \begin{bmatrix} Y \\ Z \end{bmatrix}$$

$$\begin{bmatrix} \hat{\alpha} \\ \hat{\beta} \end{bmatrix} = T^{-1} \bar{z} = \begin{bmatrix} n & x \\ x & u \end{bmatrix}^{-1} \begin{bmatrix} y \\ z \end{bmatrix}$$

$$= \frac{1}{nu - x^2} \begin{bmatrix} u & -x \\ -x & n \end{bmatrix} \begin{bmatrix} y \\ z \end{bmatrix}$$

$$= \frac{1}{nu - x^2} \begin{bmatrix} uy - xz \\ -xy + nz \end{bmatrix}$$

$$\hat{\alpha} = \frac{uy - xz}{nu - x^2}$$

$$\hat{\beta} = \frac{nz - xy}{nu - x^2} = \frac{z - \frac{xy}{n}}{u - \frac{x^2}{n}}$$

$$\text{Var} \begin{pmatrix} \hat{\alpha} \\ \hat{\beta} \end{pmatrix} = \sigma^2 T^{-1} = \frac{\sigma^2}{nu - x^2} \begin{bmatrix} u & -x \\ -x & n \end{bmatrix}$$

$$\text{Var } \hat{\alpha} = \frac{\sigma^2 u}{nu - x^2}$$

$$\text{Var } \hat{\beta} = \frac{\sigma^2 n}{nu - x^2}$$

$$\hat{f}(x) = \hat{\alpha} + \hat{\beta}x \quad -\text{unbiased est of } f(x)$$

$$\text{Var}(\hat{f}(x)) = \sigma^2 F_x T^{-1} F_x^T$$

$$= \sigma^2 [1 \ x] \frac{1}{nU - x^2} \begin{bmatrix} U & -x \\ -x & n \end{bmatrix} \begin{bmatrix} 1 \\ x \end{bmatrix}$$

$$= \frac{\sigma^2}{nU - x^2} [1 \ x] \begin{bmatrix} U & -x \\ -x & n \end{bmatrix} \begin{bmatrix} 1 \\ x \end{bmatrix}$$

-----

$$[U - xX - x + nx]$$

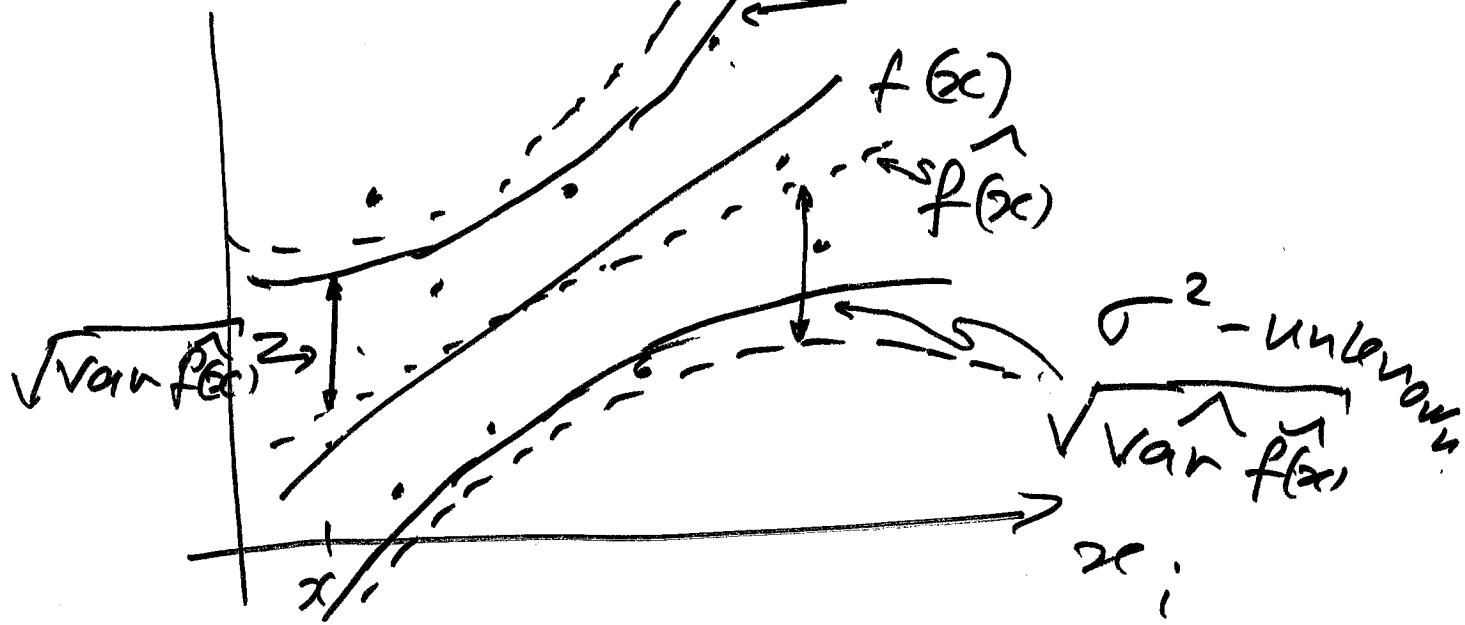
$$= \frac{\sigma^2}{nU - x^2} (U - xX - x + nx) \\ \underbrace{- \frac{x^2}{n} + \frac{x^2}{n}}$$

$$= \frac{\sigma^2}{nU - x^2} \left( U - \frac{x^2}{n} + \frac{x^2}{n} - 2x + nx \right)$$

$$= \sigma^2 \left( \frac{1}{n} + \frac{(x - \bar{x})^2}{U - \frac{x^2}{n}} \right)$$

# Comments on HW2, Prob 2.

choose  $(\alpha, \beta)$  /  $\sigma^2$ -known



$$(x_i, y_i) \quad y_i = \alpha + \beta x_i + \varepsilon_i$$

$$\text{can. info.} \Rightarrow \begin{matrix} \hat{f}(x) \\ \text{var } \hat{f}(x) \end{matrix}$$

### Estimation problems.

$$y_1 = x + \varepsilon_1, \quad x - \text{unknown}$$

$$y_2 = x + \varepsilon_2 \quad \varepsilon_i - \text{i.i.d.}$$

$$\mathbb{E} \varepsilon_i = 0 \quad \mathbb{E} \varepsilon_i^2 = \sigma^2$$

$\hat{x}_1 = \frac{y_1 + y_2}{2}$  - unbiased est  
of  $x$ .

$$\hat{x} = \frac{1}{3}y_1 + \frac{2}{3}y_2$$

$$\hat{x} = \alpha y_1 + \beta y_2 \quad \text{if } \alpha + \beta = 1$$

$\Rightarrow$  unbiased

$$\begin{aligned} \mathbb{E} \hat{x} &= \mathbb{E}(\alpha(x + \varepsilon_1) + \beta(x + \varepsilon_2)) \\ &= \underbrace{(\alpha + \beta)x}_{=1} + \alpha \underbrace{\mathbb{E} \varepsilon_1}_{=0} + \beta \underbrace{\mathbb{E} \varepsilon_2}_{=0} = x \end{aligned}$$

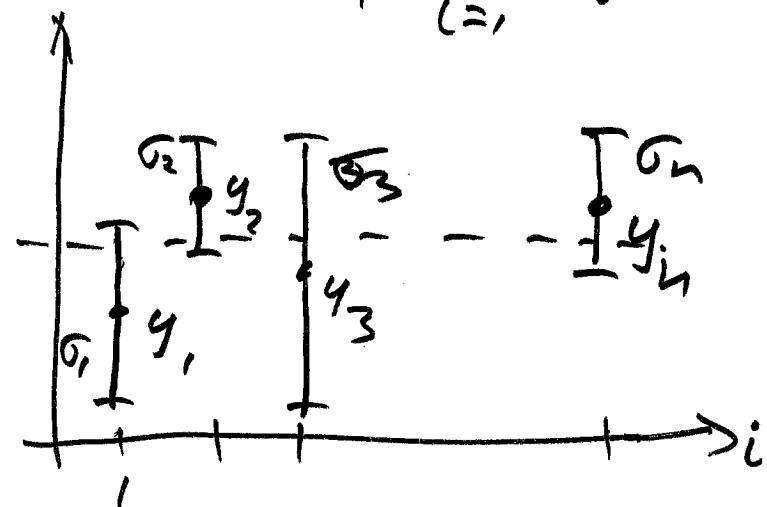
$$y_i = x + \varepsilon_i \quad i=1, \dots, n$$

$$(y_1, \sigma_1^2)$$

$$(y_2, \sigma_2^2)$$

!

$$(y_n, \sigma_n^2)$$



$$\hat{x} = \sum_{i=1}^n \alpha_i y_i \quad \text{want } \hat{x} - \text{unbiased est of } x$$

$$\Rightarrow \sum_{i=1}^n \alpha_i = 1$$

$$\begin{aligned} E \hat{x} &= E \sum_{i=1}^n \alpha_i (x + \varepsilon_i) = \underbrace{\sum_{i=1}^n \alpha_i x}_{=x} + \underbrace{\sum_{i=1}^n \alpha_i E \varepsilon_i}_{=0} \\ &= x \end{aligned}$$

$$\text{Choose } \alpha_i \sim \frac{1}{\sigma_i^2} \Rightarrow \alpha_i = \frac{c}{\sigma_i^2}$$

$$\begin{aligned} \text{Unif} \Rightarrow 1 &= \sum_i \alpha_i = \sum_i \frac{c}{\sigma_i^2} = c \cdot \sum \frac{1}{\sigma_i^2} \\ \Rightarrow c &= \frac{1}{\sum \frac{1}{\sigma_i^2}} \quad \alpha_i = \frac{1}{\sigma_i^2 \sum \frac{1}{\sigma_i^2}} \end{aligned}$$