

Computational Fluid Dynamics

HW1

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1 Inviscid Burgers Equation

The Inviscid Burgers equation, in conservation law form, is given by:

$$\frac{\partial u}{\partial t} + \frac{\partial F}{\partial x} = 0 \quad F = F(u) = \frac{u^2}{2} \quad (1)$$

In non-conservation law form, is given by:

$$\frac{\partial u}{\partial t} + A \frac{\partial u}{\partial x} = 0 \quad A = \frac{\partial F}{\partial u} = u \quad (2)$$

The equation is obtained by neglecting the viscous term from the viscous Burger equation.

1.1 Boundary and Initial Conditions

$$\begin{aligned} u_{(x=0,t)} &= 1.0 \\ u_{(x=1,t)} &= u_1 \\ u_{(x,t=0)} &= 1 - (1 - u_1) \cdot x \end{aligned} \quad (3)$$

1.2 First Order Roe Method ($u_1 = 0.0$)

Roe scheme is based on the solution of the linear problem:

$$\frac{\partial u}{\partial t} + \bar{A} \frac{\partial u}{\partial x} = 0 \quad (4)$$

Where \bar{A} is a constant matrix that is dependent on local conditions. The matrix is constructed in a way to guarantee unifrom validity across discontinuities:

1. For any u_i, u_{i+1} :

$$F_{i+1} - F_i = \bar{A} \cdot (u_{i+1} - u_i)$$

2. When $u = u_i = u_{i+1}$ then:

$$\bar{A}_{(u_i, u_{i+1})} = \bar{A}_{(u, u)} = \frac{\partial F}{\partial u} = u$$

In case of the Burgers equation, the matrix \bar{A} is a scalar, namely, $\bar{A} = \bar{u}$. The equation becomes:

$$\frac{\partial u}{\partial t} + \bar{u} \frac{\partial u}{\partial x} = 0 \quad (5)$$

The value of \bar{u} for the cell face between i and $i+1$ is determined from the first conditions:

$$\bar{u} = \bar{u}_{i+\frac{1}{2}} = \frac{F_{i+1} - F_i}{u_{i+1} - u_i} = \frac{\frac{1}{2}u_{i+1}^2 - \frac{1}{2}u_i^2}{u_{i+1} - u_i} = \quad (6)$$

1.3 Second Order Roe ($u_1 = 0.5$)

1.3.1 With Limiters

1.3.2 Without Limiters

2 Generalized Burgers Equation