```
%% 1.1.a
syms theta big omega i a e f small omega
first matrix rotation = [cos(big omega) sin(big omega) 0;-sin(big omega) cos(big omega) ✓
0;0 0 1];
second matrix rotation = [1 \ 0 \ 0; 0 \ \cos(i) \ \sin(i); 0 \ -\sin(i) \ \cos(i)];
third matrix rotation = [\cos(\text{theta}) \sin(\text{theta}) 0; -\sin(\text{theta}) \cos(\text{theta}) 0; 0 0 1];
DCM_ECI_to_LVLH = third_matrix_rotation * second_matrix_rotation * \( \mathbf{L} \)
first matrix rotation;
DCM_LVLH_to_ECI = DCM_ECI_to_LVLH.';
%% 1.1.b
syms theta big_omega i a e f small_omega
first matrix rotation = [cos(big omega) sin(big omega) 0;-sin(big omega) cos(big omega) ✓
0;0 0 1];
second matrix rotation = [1 \ 0 \ 0; 0 \ \cos(i) \ \sin(i); 0 \ -\sin(i) \ \cos(i)];
third matrix rotation = [\cos(small omega + f) \sin(small omega + f) 0; -\sin(small omega + <math>\checkmark
f) cos(small omega + f) 0;0 0 1];
DCM ECI to LVLH = third matrix rotation * second matrix rotation *\checkmark
first matrix rotation;
DCM LVLH to ECI = DCM ECI to LVLH.';
r = a*(1-e^2)/(1+e*cos(f));
r LVLH = [r;0;0];
r ECI = DCM_LVLH_to_ECI * r_LVLH;
r dot ECI = diff(r ECI,f);
%% 1.2.c
mu = 3.98603e5;
[a,e,i,small omega, big omega,f] = kepler orbital elements([2.5 -6.6 1.059]*10.^3, [3.8\checkmark
0.40885 - 6.422], mu)
%% 1.2.d
syms big omega i a e f small omega mu v f(f) r f(f)
first matrix rotation = [cos(big omega) sin(big omega) 0;-sin(big omega) cos(big omega) ✓
second matrix rotation = [1 \ 0 \ 0; 0 \ \cos(i) \ \sin(i); 0 \ -\sin(i) \ \cos(i)];
f) cos(small omega + f) 0;0 0 1];
DCM ECI to LVLH = third matrix rotation * second matrix rotation *\checkmark
first matrix rotation;
DCM LVLH to ECI = DCM ECI to LVLH.';
r = a*(1-e^2)/(1+e*cos(f));
r LVLH = [r;0;0];
r ECI = DCM LVLH_to_ECI * r_LVLH;
r dot ECI wrt f = diff(r ECI,f);
f dot = (sqrt(mu)*(1+e*cos(f))^2)/(a*(1-e^2))^(3/2);
r dot ECI wrt time = r dot ECI wrt f .* f dot;
a = 12e3; % [km]
```

```
e = 0.345; % [-]
i = 60*pi/180; % [rad]
small omega = 20*pi/180; % [rad]
big omega = 110*pi/180; % [rad]
mu = 3.986e5; % [km^3/s^2]
number of rotaions = 10;
number_of_points = 3000;
values for f = linspace(0, 2*pi*number of rotaions, number of points);
rs = zeros(3,length(values for f));
vs = zeros(3, length(values for f));
as = zeros(1,length(values_for_f));
es = zeros(1,length(values for f));
is = zeros(1,length(values_for_f));
small omegas = zeros(1,length(values for f));
big omegas = zeros(1,length(values for f));
fs = zeros(1,length(values for f));
v f(f) = subs(r dot ECI wrt time);
r f(f) = subs(r ECI);
for j = 1:length(values for f)
    f = values for f(j);
    rs(:,j) = r f(f);
    vs(:,j) = v f(f);
    [as(j), es(j), is(j), small omegas(j), big omegas(j), fs(j)] = kepler orbital elements \checkmark
(rs(:,j), vs(:,j), mu);
    %function [a,e,i,small omega, big omega,f] = kepler orbital elements(r vector, ✓
v vector, mu)
    j
end
perigee = r_f(0);
apogee = r f(180*pi/180);
ascending node = r f(2*pi-small omega);
응응
fig1 = figure ("Name", "3D figure of the orbit trajectory along with the Earth ✓
drawing", 'Position', [100 100 900 500]);
% axis equal
hold all
earth sphere
plot3(rs(1,:),rs(2,:),rs(3,:), "LineWidth", 2, "Color", "#D95319")
plot3(perigee(1), perigee(2), perigee(3), "hexagram", "LineWidth", 2, "Color", ✓
"#0072BD")
plot3(apogee(1), apogee(2), apogee(3), "hexagram", "LineWidth", 2, "Color", "#77AC30")
plot3(ascending node(1), ascending node(2), ascending node(3), "hexagram", "LineWidth", ✓
2, "Color", "#4DBEEE")
xlabel('X [km]')
ylabel('Y [km]')
zlabel('Z [km]')
```

```
grid on
grid minor
title("3D figure of the orbit trajectory aloog with the Earth drawing")
subtitle("Almog Dobrescu 214254252")
legend({'The Earth','The orbit','perigee','apogee','ascending node'},'FontSize',11

✓
,'Location','southeast')
%exportgraphics(fig1, 'grap1.png', 'Resolution', 1200);
응응
fig2 = figure ("Name", "The position components in the ECI frames as functions of the \checkmark
true anomaly", 'Position', [300 100 900 500]);
% axis equal
hold all
plot(values for f, rs(1,:), "LineWidth", 1.5, "Color", "#0072BD")
plot(values for f, rs(2,:), "LineWidth", 1.5, "Color", "#77AC30")
plot(values for f, rs(3,:), "LineWidth", 1.5, "Color", "#D95319")
xlabel('f [rad]')
ylabel('Magnitude [km]')
grid on
grid minor
title ("The position components in the ECI frames as functions of the true anomaly")
subtitle("Almog Dobrescu 214254252")
legend(('X','Y','Z'),'FontSize',11 ,'Location','southeast')
%exportgraphics(fig2, 'grap2.png','Resolution',1200);
응응
fig3 = figure ("Name", "The velocity components in the ECI frames as functions of the \checkmark
true anomaly", 'Position', [300 100 900 500]);
% axis equal
hold all
plot(values for f, vs(1,:), "LineWidth", 1.5, "Color", "#0072BD")
plot(values for f, vs(2,:), "LineWidth", 1.5, "Color", "#77AC30")
plot(values for f, vs(3,:), "LineWidth", 1.5, "Color", "#D95319")
xlabel('f [rad]')
ylabel('Magnitude [km/sec]')
grid on
grid minor
title ("The velocity components in the ECI frames as functions of the true anomaly")
subtitle("Almog Dobrescu 214254252")
legend({'X dot','Y dot','Z dot'},'FontSize',11 ,'Location','southeast')
%exportgraphics(fig3, 'grap3.png','Resolution',1200);
```

```
응응
fig4 = figure ("Name", "The velocity components in the ECI frames as functions of the \checkmark
true anomaly", 'Position', [300 100 900 500]);
% axis equal
hold all
plot(values for f, as.*10^-3, "LineWidth", 1.5, "Color", "#0072BD")
plot(values for f, es, "LineWidth", 1.5, "Color", "#D95319")
plot(values for f, is, "LineWidth", 1.5, "Color", "#EDB120")
plot(values_for_f, small_omegas,'--', "LineWidth", 1.5, "Color", "#00FF00")
plot(values for f, big omegas, "LineWidth", 1.5, "Color", "#77AC30")
plot(values_for_f, fs, "LineWidth", 1.5, "Color", "#4DBEEE")
xlabel('f [rad]')
ylabel('Magnitude [-]')
grid on
grid minor
title ("The velocity components in the ECI frames as functions of the true anomaly")
subtitle("Almog Dobrescu 214254252")
legend({'calculated a [10^3 km]', 'calculated e [-]', 'calculated i [rad]', 'calculated

✓
small omega [rad]','calculated big omega [rad]','calculated f [rad]'},'FontSize',11\(\m'\)
,'Location','northeast')
%exportgraphics(fig4, 'grap4.png', 'Resolution', 1200);
```