Curved Boundary Conditions in lattice Boltzmann method

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Outline

- Introduction
 - General aspects
 - Motivation
 - Possible approaches
- 2 Problem statement
 - Off-grid populations
 - Interpolated Boundary Conditions
- 3 Summary

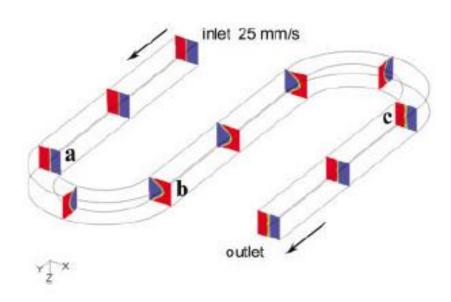
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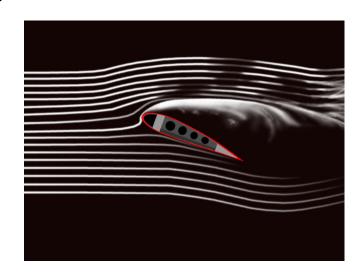
Irregular geometries in fluid flow problems

Most practical fluid flow problems of interest in engineering or science involve:

1) **irregular** domains



2) irregular shaped objects



http://engineeringskills.wikidot.com/concepts#toc27

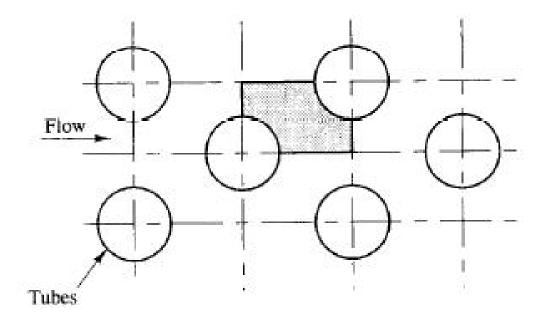
Yamaguchi et al. AIChE, 50(7), 1530 (2004)

Computational Fluid Dynamics: non-orthogonal boundaries

Representing irregular domains in Computational Fluid Dynamics

Example: Flow in a

tube bank

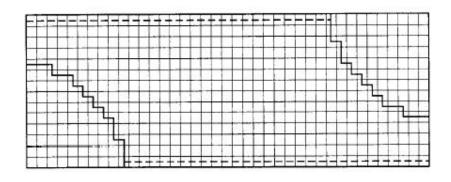


Versteeg & Malalasekera, An Introduction to CFD. Prentice Hall, 1995

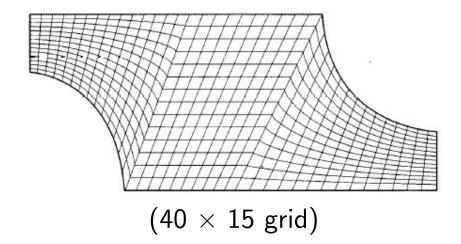
Computational Fluid Dynamics: non-orthogonal boundaries

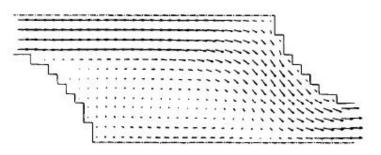
Cartesian grid

Non-orthogonal body-fitted grid

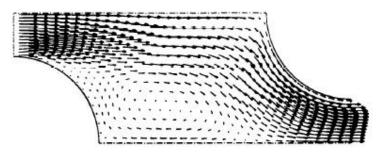


 $(40 \times 15 \text{ grid})$





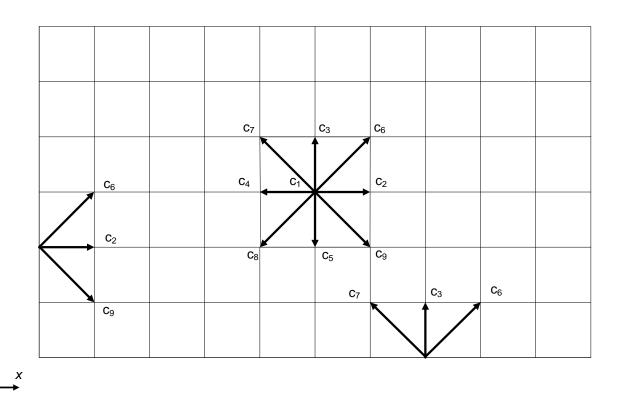
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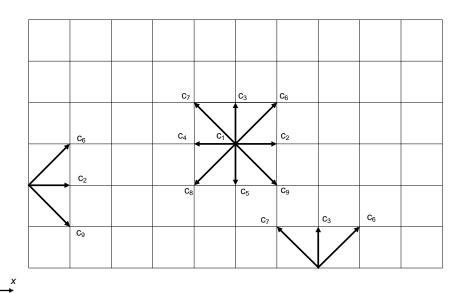
Versteeg & Malalasekera, An Introduction to CFD. Prentice Hall, 1995

Lattice Boltzmann algorithm consists of...

...stream along links and equilibrate at nodes



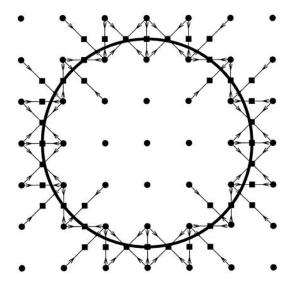
- ⇒ In "stream along links and equilibrate at nodes" philosophy the streaming operation is exact
 - → Advantage: No interpolations are needed → virtually no numerical dissipation is introduced in streaming
 - → **Disadvantage:** Lattice structure, *i.e.* velocity space discretization, constrains the configuration space discretization, *i.e.* the location of spatial nodes is prescribed by lattice



Conclusion:

Because the lattice Boltzmann method is an "on-grid" scheme it is restricted to **uniform cartesian grids**

Are we limited to the stepwise representation of irregular shapes?



Ladd & Verbeg 2001, J. Stat. Phys. 104, 1191-1251

The fact is...

...if we intend to represent non-orthogonal shapes we have to use numerical approximations (e.g. interpolations) somewhere

Two different approaches:

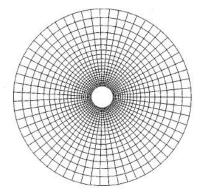
- Interpolate: Everywhere
- Preserve: Boundary scheme
- Non-orthogonal body-fitted grids

- Interpolate: Boundary scheme
- Preserve: Everywhere
- Interpolated boundary conditions

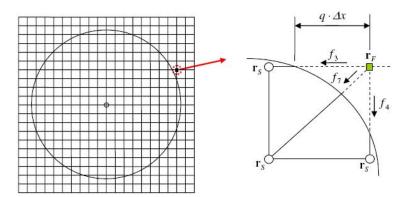
Example: Flow domain containing a solid circle represented through each approach:

Non-orthogonal body-fitted grids





He & Doolen 1997, Phys. Rev. E 56, 434

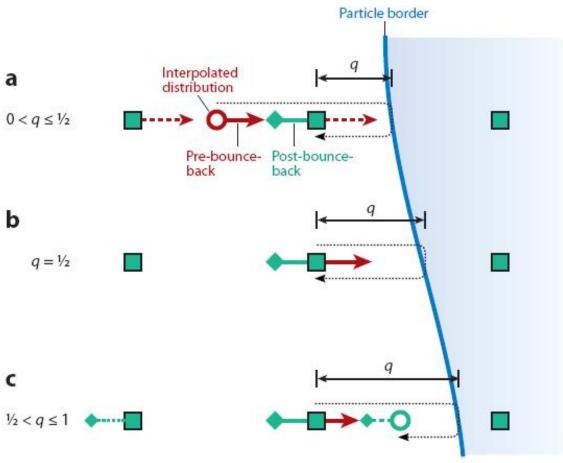


Kao & Yang 2008, J. Comp. Phys. 227, 5671-5690

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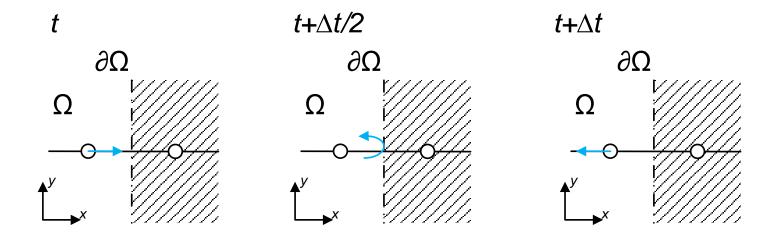
Example:



Aidun & Clausen 2010, Annu. Rev. Fluid Mech. 42, 439-472

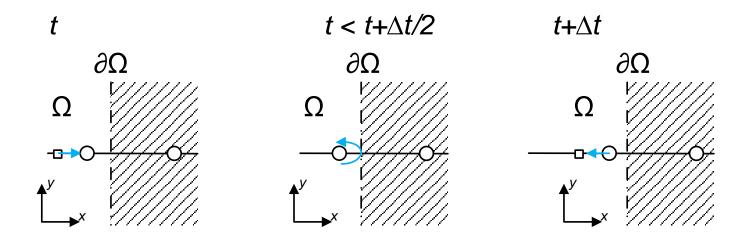
Remember: When the wall is half-way

- On-grid population at time t is propagated
- Bounces-back at the wall
- Returns to the same **on-grid** location at time $t + \Delta t$

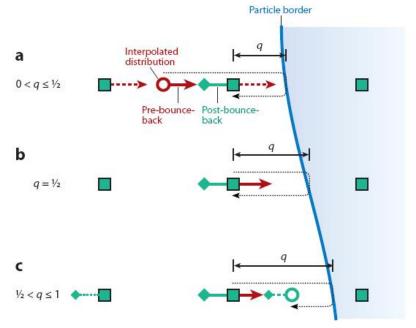


However: When the wall is **NOT** half-way

- Construct off-grid population at time t from where is propagated
- Bounces-back at the wall
- ullet Returns to an **on-grid** location at time $t+\Delta t$



Coming back to the example:



Aidun & Clausen 2010, Annu. Rev. Fluid Mech. 42, 439-472

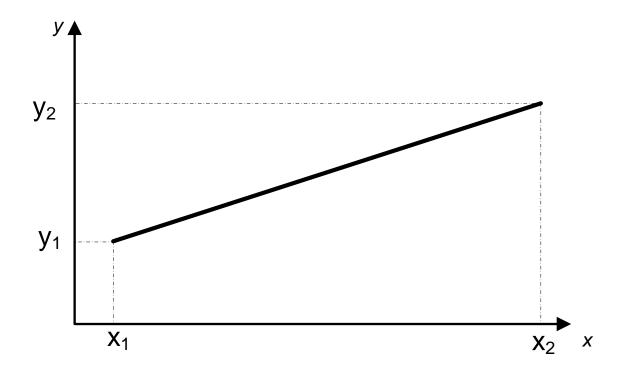
Idea of interpolating the boundary condition:

Reconstruct the **off-grid** population by interpolating the known **on-grid** data

Linear interpolation

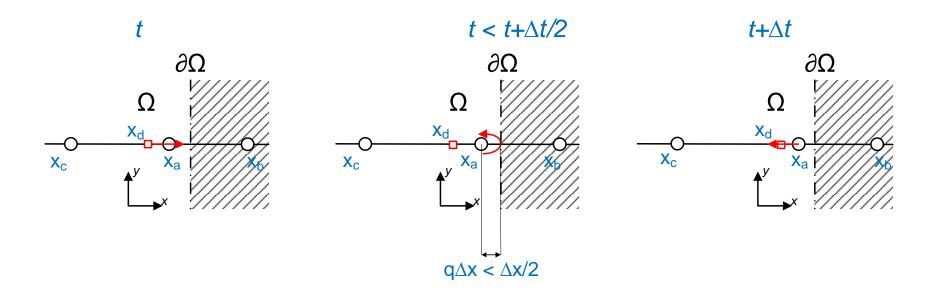
Recall the linear equation formula

$$y = \left(\frac{y_2 - y_1}{x_2 - x_1}\right) (x - x_1) + y_1$$



Linear interpolation

- Use linear interpolation based on known populations:
 - \rightarrow known: $\tilde{f}_R(\mathbf{x}_a,t)$
 - \rightarrow known: $\tilde{f}_R(\mathbf{x}_c,t)$
 - ightarrow unknown: $ilde{f}_R(\mathbf{x}_d,t)$

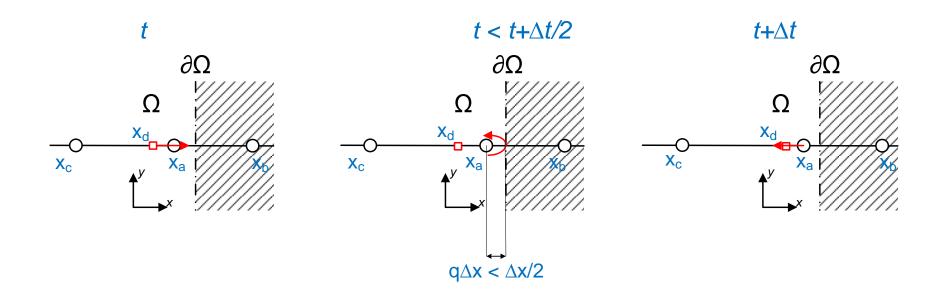


Note:
$$\|\mathbf{x}_c - \mathbf{x}_a\| = \|\mathbf{x}_a - \mathbf{x}_b\| = \Delta \mathbf{x}$$

Linear interpolation: Exercise

Question:

Compute $\tilde{f}_R(\mathbf{x}_d,t)$ through linear interpolation of $\tilde{f}_R(\mathbf{x}_a,t)$ and $\tilde{f}_R(\mathbf{x}_c,t)$



Note:
$$\|\mathbf{x}_c - \mathbf{x}_a\| = \|\mathbf{x}_a - \mathbf{x}_b\| = \Delta \mathbf{x}$$

Linear interpolation: Exercise

Question:

Compute $\tilde{f}_R(\mathbf{x}_d,t)$ through linear interpolation of $\tilde{f}_R(\mathbf{x}_a,t)$ and $\tilde{f}_R(\mathbf{x}_c,t)$

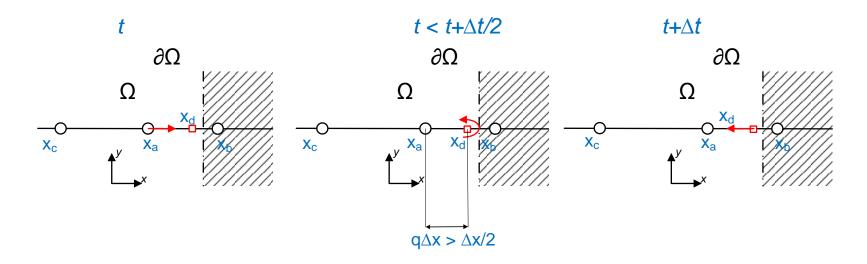
Solution:

$$\tilde{f}_R(\mathbf{x}_d, t) = (1 - 2q)\tilde{f}_R(\mathbf{x}_c, t) + 2q\tilde{f}_R(\mathbf{x}_a, t)$$

that yields:

$$f_L(\mathbf{x}_a, t + \Delta t) = \tilde{f}_R(\mathbf{x}_d, t)$$

When the wall is beyond the half-way location, i.e. $q>\frac{1}{2}$, the previous procedure leads to an extrapolation instead of an interpolation scheme

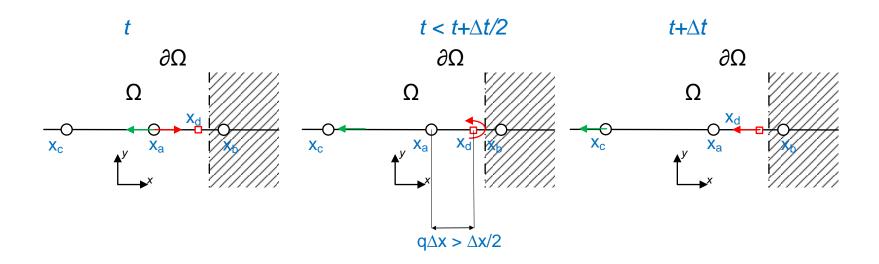


Solution:

Interpolate the post-streaming populations

• From the time evolution sketch of the populations we observe:

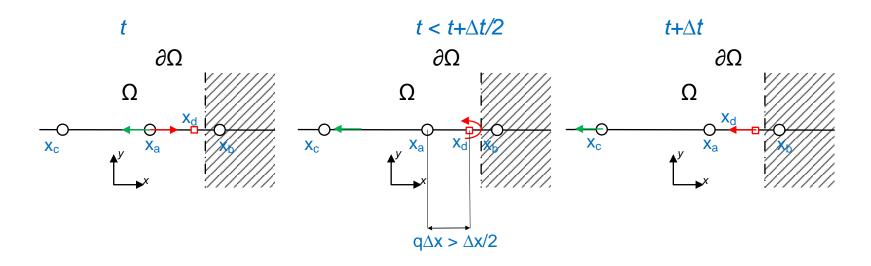
- \rightarrow known: $f_L(\mathbf{x}_d, t + \Delta t) = \tilde{f}_R(\mathbf{x}_a, t)$
- \rightarrow known: $f_L(\mathbf{x}_c, t + \Delta t) = \tilde{f}_L(\mathbf{x}_a, t)$
- \rightarrow unknown: $f_L(\mathbf{x}_a, t + \Delta t)$



Linear interpolation: Exercise

Question:

Compute $f_L(\mathbf{x}_a, t + \Delta t)$ through linear interpolation of $f_L(\mathbf{x}_d, t + \Delta t)$ and $f_L(\mathbf{x}_c, t + \Delta t)$



Note:
$$\|\mathbf{x}_c - \mathbf{x}_a\| = \|\mathbf{x}_a - \mathbf{x}_b\| = \Delta \mathbf{x}$$

Linear interpolation: Exercise

Question:

Compute
$$f_L(\mathbf{x}_a, t + \Delta t)$$
 through linear interpolation of $f_L(\mathbf{x}_d, t + \Delta t)$ and $f_L(\mathbf{x}_c, t + \Delta t)$

Solution:

$$f_L(\mathbf{x}_a, t + \Delta t) = \left(\frac{2q-1}{2q}\right) f_L(\mathbf{x}_d, t + \Delta t) + \frac{1}{2q} f_L(\mathbf{x}_d, t + \Delta t)$$

or

$$f_L(\mathbf{x}_a, t + \Delta t) = \left(\frac{2q-1}{2q}\right) \tilde{f}_R(\mathbf{x}_a, t) + \frac{1}{2q} \tilde{f}_L(\mathbf{x}_a, t)$$

Linear interpolation: 2D lattices

Linear interpolation bounceback:

•
$$q < \frac{1}{2}$$

$$f_{\bar{\alpha}}(\mathbf{x}, t + \Delta t) = 2q\tilde{f}_{\alpha}(\mathbf{x}, t) + (1 - 2q)\tilde{f}_{\alpha}(\mathbf{x} - \mathbf{c}\Delta t, t)$$

$$q \ge \frac{1}{2}$$

$$f_{\bar{\alpha}}(\mathbf{x}, t + \Delta t) = \frac{1}{2q} \tilde{f}_{\alpha}(\mathbf{x}, t) + \left(\frac{2q-1}{2q}\right) \tilde{f}_{\bar{\alpha}}(\mathbf{x}, t)$$

Quadratic interpolation: 2D lattices

Quadratic interpolation bounceback:

• $q < \frac{1}{2}$

$$f_{\bar{\alpha}}(\mathbf{x}, t + \Delta t) = q(2q + 1)\tilde{f}_{\alpha}(\mathbf{x}, t)$$
$$+(1 + 2q)(1 - 2q)\tilde{f}_{\alpha}(\mathbf{x} - \mathbf{c}\Delta t, t) - q(1 - 2q)\tilde{f}_{\alpha}(\mathbf{x} - 2\mathbf{c}\Delta t, t)$$

• $q \ge \frac{1}{2}$

$$f_{\bar{\alpha}}(\mathbf{x}, t + \Delta t) = \frac{1}{q(2q+1)} \tilde{f}_{\alpha}(\mathbf{x}, t) + \frac{2q-1}{q} \tilde{f}_{\bar{\alpha}}(\mathbf{x}, t) + \frac{1-2q}{q} \tilde{f}_{\bar{\alpha}}(\mathbf{x} - \mathbf{c}\Delta t, t)$$

Exercise IV

Exercise IV:

Flow around circular cylinder

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Curved boundary conditions in LBM

- LBM uses cartesian uniform grids
- Non-orthogonal shapes require numerical approximations, e.g. interpolations
- In order to preserve the advantages of LBM it is preferable to only interpolate the solution at boundary
- Bounceback provides a good framework to extend to curved boundaries through interpolations