

FullyConnectedNets

May 4, 2023

```
[ ]: # this mounts your Google Drive to the Colab VM.
from google.colab import drive
drive.mount('/content/drive', force_remount=True)

# enter the foldername in your Drive where you have saved the unzipped
# assignment folder, e.g. 'CV7062610/assignments/assignment3/'
FOLDERNAME = None
assert FOLDERNAME is not None, "[!] Enter the foldername."

# now that we've mounted your Drive, this ensures that
# the Python interpreter of the Colab VM can load
# python files from within it.
import sys
sys.path.append('/content/drive/My Drive/{}'.format(FOLDERNAME))

# this downloads the CIFAR-10 dataset to your Drive
# if it doesn't already exist.
%cd drive/My\ Drive/$FOLDERNAME/CV7062610/datasets/
!bash get_datasets.sh
%cd /content
```

1 Fully-Connected Neural Nets

In the previous homework you implemented a fully-connected two-layer neural network on CIFAR-10. The implementation was simple but not very modular since the loss and gradient were computed in a single monolithic function. This is manageable for a simple two-layer network, but would become impractical as we move to bigger models. Ideally we want to build networks using a more modular design so that we can implement different layer types in isolation and then snap them together into models with different architectures.

In this exercise we will implement fully-connected networks using a more modular approach. For each layer we will implement a **forward** and a **backward** function. The **forward** function will receive inputs, weights, and other parameters and will return both an output and a **cache** object storing data needed for the backward pass, like this:

```
def layer_forward(x, w):
    """ Receive inputs x and weights w """
    # Do some computations ...
```

```

z = # ... some intermediate value
# Do some more computations ...
out = # the output

cache = (x, w, z, out) # Values we need to compute gradients

return out, cache

```

The backward pass will receive upstream derivatives and the `cache` object, and will return gradients with respect to the inputs and weights, like this:

```

def layer_backward(dout, cache):
    """
    Receive dout (derivative of loss with respect to outputs) and cache,
    and compute derivative with respect to inputs.
    """
    # Unpack cache values
    x, w, z, out = cache

    # Use values in cache to compute derivatives
    dx = # Derivative of loss with respect to x
    dw = # Derivative of loss with respect to w

    return dx, dw

```

After implementing a bunch of layers this way, we will be able to easily combine them to build classifiers with different architectures.

In addition to implementing fully-connected networks of arbitrary depth, (in the second part of the assignment) we will explore different update rules for optimization, and introduce Dropout as a regularizer and Batch/Layer Normalization as a tool to more efficiently optimize deep networks.

```

[2]: # As usual, a bit of setup
from __future__ import print_function
import time
import numpy as np
import matplotlib.pyplot as plt
from CV7062610.classifiers.fc_net import *
from CV7062610.data_utils import get_CIFAR10_data
from CV7062610.gradient_check import eval_numerical_gradient, \
    eval_numerical_gradient_array
from CV7062610.solver import Solver

%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

# for auto-reloading external modules

```

```
# see http://stackoverflow.com/questions/1907993/
↪ autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2

def rel_error(x, y):
    """ returns relative error """
    return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
```

===== You can safely ignore the message below if you are NOT working on ConvolutionalNetworks.ipynb =====

You will need to compile a Cython extension for a portion of this assignment.

The instructions to do this will be given in a section of the notebook below.

There will be an option for Colab users and another for Jupyter (local) users.

[3]: *# Load the (preprocessed) CIFAR10 data.*

```
data = get_CIFAR10_data()
for k, v in list(data.items()):
    print('%s: ' % k, v.shape)
```

```
('X_train: ', (49000, 3, 32, 32))
('y_train: ', (49000,))
('X_val: ', (1000, 3, 32, 32))
('y_val: ', (1000,))
('X_test: ', (1000, 3, 32, 32))
('y_test: ', (1000,))
```

2 Affine layer (fully-connected): forward

Open the file CV7062610/layers.py and implement the `affine_forward` function.

Once you are done you can test your implementation by running the following:

[4]: *# Test the affine_forward function*

```
num_inputs = 2
input_shape = (4, 5, 6)
output_dim = 3

input_size = num_inputs * np.prod(input_shape)
weight_size = output_dim * np.prod(input_shape)

x = np.linspace(-0.1, 0.5, num=input_size).reshape(num_inputs, *input_shape)
```

```

w = np.linspace(-0.2, 0.3, num=weight_size).reshape(np.prod(input_shape),  

↳output_dim)
b = np.linspace(-0.3, 0.1, num=output_dim)

out, _ = affine_forward(x, w, b)
correct_out = np.array([[ 1.49834967,  1.70660132,  1.91485297],
                        [ 3.25553199,  3.5141327,  3.77273342]])

# Compare your output with ours. The error should be around e-9 or less.
print('Testing affine_forward function:')
print('difference: ', rel_error(out, correct_out))

```

Testing affine_forward function:
difference: 9.769849468192957e-10

3 Affine layer: backward

Now implement the `affine_backward` function and test your implementation using numeric gradient checking.

```

[5]: # Test the affine_backward function
np.random.seed(231)
x = np.random.randn(10, 2, 3)
w = np.random.randn(6, 5)
b = np.random.randn(5)
dout = np.random.randn(10, 5)

dx_num = eval_numerical_gradient_array(lambda x: affine_forward(x, w, b)[0], x,  

↳dout)
dw_num = eval_numerical_gradient_array(lambda w: affine_forward(x, w, b)[0], w,  

↳dout)
db_num = eval_numerical_gradient_array(lambda b: affine_forward(x, w, b)[0], b,  

↳dout)

_, cache = affine_forward(x, w, b)
dx, dw, db = affine_backward(dout, cache)

# The error should be around e-10 or less
print('Testing affine_backward function:')
print('dx error: ', rel_error(dx_num, dx))
print('dw error: ', rel_error(dw_num, dw))
print('db error: ', rel_error(db_num, db))

```

Testing affine_backward function:
dx error: 5.399100368651805e-11
dw error: 9.904211865398145e-11
db error: 2.4122867568119087e-11

4 ReLU activation: forward

Implement the forward pass for the ReLU activation function in the `relu_forward` function and test your implementation using the following:

```
[6]: # Test the relu_forward function

x = np.linspace(-0.5, 0.5, num=12).reshape(3, 4)

out, _ = relu_forward(x)
correct_out = np.array([[ 0.,          0.,          0.,          0.],
                        [ 0.,          0.,          0.04545455, 0.13636364],
                        [ 0.22727273, 0.31818182, 0.40909091, 0.5]])

# Compare your output with ours. The error should be on the order of e-8
print('Testing relu_forward function:')
print('difference: ', rel_error(out, correct_out))
```

```
Testing relu_forward function:
difference:  4.999999798022158e-08
```

5 ReLU activation: backward

Now implement the backward pass for the ReLU activation function in the `relu_backward` function and test your implementation using numeric gradient checking:

```
[7]: np.random.seed(231)
x = np.random.randn(10, 10)
dout = np.random.randn(*x.shape)

dx_num = eval_numerical_gradient_array(lambda x: relu_forward(x)[0], x, dout)

_, cache = relu_forward(x)
dx = relu_backward(dout, cache)
# The error should be on the order of e-12
print('Testing relu_backward function:')
print('dx error: ', rel_error(dx_num, dx))
```

```
Testing relu_backward function:
dx error:  3.2756349136310288e-12
```

5.1 Inline Question 1:

We've only asked you to implement ReLU, but there are a number of different activation functions that one could use in neural networks, each with its pros and cons. In particular, an issue commonly seen with activation functions is getting zero (or close to zero) gradient flow during backpropagation. Which of the following activation functions have this problem? If you consider these functions in the one dimensional case, what types of input would lead to this behaviour? 1. Sigmoid 2. ReLU

3. Leaky ReLU

5.2 Answer:

The answer is the Sigmoid activation function. Sigmoid derivative is: $S(x)(1-S(x))$. Therefore, getting input values far from 0 may result in gradients getting closer and closer to zero.

6 “Sandwich” layers

There are some common patterns of layers that are frequently used in neural nets. For example, affine layers are frequently followed by a ReLU nonlinearity. To make these common patterns easy, we define several convenience layers in the file CV7062610/layer_utils.py.

For now take a look at the `affine_relu_forward` and `affine_relu_backward` functions, and run the following to numerically gradient check the backward pass:

```
[8]: from CV7062610.layer_utils import affine_relu_forward, affine_relu_backward
np.random.seed(231)
x = np.random.randn(2, 3, 4)
w = np.random.randn(12, 10)
b = np.random.randn(10)
dout = np.random.randn(2, 10)

out, cache = affine_relu_forward(x, w, b)
dx, dw, db = affine_relu_backward(dout, cache)

dx_num = eval_numerical_gradient_array(lambda x: affine_relu_forward(x, w, b)[0], x, dout)
dw_num = eval_numerical_gradient_array(lambda w: affine_relu_forward(x, w, b)[0], w, dout)
db_num = eval_numerical_gradient_array(lambda b: affine_relu_forward(x, w, b)[0], b, dout)

# Relative error should be around e-10 or less
print('Testing affine_relu_forward and affine_relu_backward:')
print('dx error: ', rel_error(dx_num, dx))
print('dw error: ', rel_error(dw_num, dw))
print('db error: ', rel_error(db_num, db))
```

Testing affine_relu_forward and affine_relu_backward:

```
dx error:  2.299579177309368e-11
dw error:  8.162011105764925e-11
db error:  7.826724021458994e-12
```

7 Loss layers: Softmax

You implemented this loss functions in the last assignment, so we'll give it to you for free here. You should still make sure you understand how it work by looking at the implementations in

CV7062610/layers.py.

You can make sure that the implementations are correct by running the following:

```
[9]: np.random.seed(231)
num_classes, num_inputs = 10, 50
x = 0.001 * np.random.randn(num_inputs, num_classes)
y = np.random.randint(num_classes, size=num_inputs)

dx_num = eval_numerical_gradient(lambda x: softmax_loss(x, y)[0], x,
    verbose=False)
loss, dx = softmax_loss(x, y)

# Test softmax_loss function. Loss should be close to 2.3 and dx error should
    be around e-8
print('\nTesting softmax_loss:')
print('loss: ', loss)
print('dx error: ', rel_error(dx_num, dx))
```

Testing softmax_loss:

loss: 2.302545844500738

dx error: 9.384673161989355e-09

8 Two-layer network

In the previous assignment you implemented a two-layer neural network in a single monolithic class. Now that you have implemented modular versions of the necessary layers, you will reimplement the two layer network using these modular implementations.

Open the file CV7062610 /classifiers/fc_net.py and complete the implementation of the TwoLayerNet class. This class will serve as a model for the other networks you will implement in this assignment, so read through it to make sure you understand the API. You can run the cell below to test your implementation.

```
[10]: np.random.seed(231)
N, D, H, C = 3, 5, 50, 7
X = np.random.randn(N, D)
y = np.random.randint(C, size=N)

std = 1e-3
model = TwoLayerNet(input_dim=D, hidden_dim=H, num_classes=C, weight_scale=std)

print('Testing initialization ... ')
W1_std = abs(model.params['W1'].std() - std)
b1 = model.params['b1']
W2_std = abs(model.params['W2'].std() - std)
b2 = model.params['b2']
```

```

assert W1_std < std / 10, 'First layer weights do not seem right'
assert np.all(b1 == 0), 'First layer biases do not seem right'
assert W2_std < std / 10, 'Second layer weights do not seem right'
assert np.all(b2 == 0), 'Second layer biases do not seem right'

print('Testing test-time forward pass ... ')
model.params['W1'] = np.linspace(-0.7, 0.3, num=D*H).reshape(D, H)
model.params['b1'] = np.linspace(-0.1, 0.9, num=H)
model.params['W2'] = np.linspace(-0.3, 0.4, num=H*C).reshape(H, C)
model.params['b2'] = np.linspace(-0.9, 0.1, num=C)
X = np.linspace(-5.5, 4.5, num=N*D).reshape(D, N).T
scores = model.loss(X)
correct_scores = np.asarray(
    [[11.53165108, 12.2917344, 13.05181771, 13.81190102, 14.57198434, 15.
↪33206765, 16.09215096],
    [12.05769098, 12.74614105, 13.43459113, 14.1230412, 14.81149128, 15.
↪49994135, 16.18839143],
    [12.58373087, 13.20054771, 13.81736455, 14.43418138, 15.05099822, 15.
↪66781506, 16.2846319 ]])
scores_diff = np.abs(scores - correct_scores).sum()
assert scores_diff < 1e-6, 'Problem with test-time forward pass'

print('Testing training loss (no regularization)')
y = np.asarray([0, 5, 1])
loss, grads = model.loss(X, y)
correct_loss = 3.4702243556
assert abs(loss - correct_loss) < 1e-10, 'Problem with training-time loss'

model.reg = 1.0
loss, grads = model.loss(X, y)
correct_loss = 26.5948426952
assert abs(loss - correct_loss) < 1e-10, 'Problem with regularization loss'

# Errors should be around e-7 or less
for reg in [0.0, 0.7]:
    print('Running numeric gradient check with reg = ', reg)
    model.reg = reg
    loss, grads = model.loss(X, y)

    for name in sorted(grads):
        f = lambda _: model.loss(X, y)[0]
        grad_num = eval_numerical_gradient(f, model.params[name], verbose=False)
        print('%s relative error: %.2e' % (name, rel_error(grad_num, grads[name])))

```

Testing initialization ...

Testing test-time forward pass ...

Testing training loss (no regularization)


```

Running numeric gradient check with reg = 0.0
W1 relative error: 1.83e-08
W2 relative error: 3.12e-10
b1 relative error: 9.83e-09
b2 relative error: 4.33e-10
Running numeric gradient check with reg = 0.7
W1 relative error: 2.53e-07
W2 relative error: 2.85e-08
b1 relative error: 1.56e-08
b2 relative error: 7.76e-10

```

9 Solver

In the previous assignment, the logic for training models was coupled to the models themselves. Following a more modular design, for this assignment we have split the logic for training models into a separate class.

Open the file CV7062610/solver.py and read through it to familiarize yourself with the API. After doing so, use a Solver instance to train a TwoLayerNet that achieves at least 45% accuracy on the validation set. If you are doing it correctly this shouldn't take more than 5 epochs of training and more than 5 minutes using vanilla sgd.

```

[11]: model = TwoLayerNet()
      solver = None
      best_val = -1
      #####
      # TODO: Use a Solver instance to train a TwoLayerNet that achieves at least #
      # 50% accuracy on the validation set.                                     #
      #####
      # *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)*****

      solver_data = {
          'X_train': data['X_train'],
          'y_train': data['y_train'],
          'X_val': data['X_val'],
          'y_val': data['y_val'],
      }

      solver = Solver(model, solver_data,
                      update_rule='sgd',
                      optim_config={'learning_rate': 1e-3},
                      lr_decay=0.85,
                      num_epochs=5,
                      batch_size=32,
                      print_every=100
                      )

      solver.train()

```

```
# *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)*****
#####
#                               END OF YOUR CODE                               #
#####
```

```
(Iteration 1 / 7655) loss: 2.305074
(Epoch 0 / 5) train acc: 0.117000; val_acc: 0.100000
(Iteration 101 / 7655) loss: 1.906716
(Iteration 201 / 7655) loss: 1.770236
(Iteration 301 / 7655) loss: 2.050725
(Iteration 401 / 7655) loss: 1.711676
(Iteration 501 / 7655) loss: 1.752242
(Iteration 601 / 7655) loss: 1.889657
(Iteration 701 / 7655) loss: 1.825485
(Iteration 801 / 7655) loss: 2.012939
(Iteration 901 / 7655) loss: 1.630006
(Iteration 1001 / 7655) loss: 1.527262
(Iteration 1101 / 7655) loss: 1.116888
(Iteration 1201 / 7655) loss: 2.034647
(Iteration 1301 / 7655) loss: 1.443752
(Iteration 1401 / 7655) loss: 1.822128
(Iteration 1501 / 7655) loss: 1.234313
(Epoch 1 / 5) train acc: 0.365000; val_acc: 0.391000
(Iteration 1601 / 7655) loss: 1.975240
(Iteration 1701 / 7655) loss: 1.801315
(Iteration 1801 / 7655) loss: 1.482838
(Iteration 1901 / 7655) loss: 1.807896
(Iteration 2001 / 7655) loss: 2.013776
(Iteration 2101 / 7655) loss: 1.513751
(Iteration 2201 / 7655) loss: 1.270315
(Iteration 2301 / 7655) loss: 1.771921
(Iteration 2401 / 7655) loss: 1.731830
(Iteration 2501 / 7655) loss: 1.863763
(Iteration 2601 / 7655) loss: 2.437257
(Iteration 2701 / 7655) loss: 2.114428
(Iteration 2801 / 7655) loss: 1.309577
(Iteration 2901 / 7655) loss: 1.762229
(Iteration 3001 / 7655) loss: 1.562118
(Epoch 2 / 5) train acc: 0.456000; val_acc: 0.446000
(Iteration 3101 / 7655) loss: 1.740869
(Iteration 3201 / 7655) loss: 1.489221
(Iteration 3301 / 7655) loss: 0.952412
(Iteration 3401 / 7655) loss: 2.047188
(Iteration 3501 / 7655) loss: 1.884539
(Iteration 3601 / 7655) loss: 1.412975
(Iteration 3701 / 7655) loss: 1.476068
(Iteration 3801 / 7655) loss: 1.348516
```

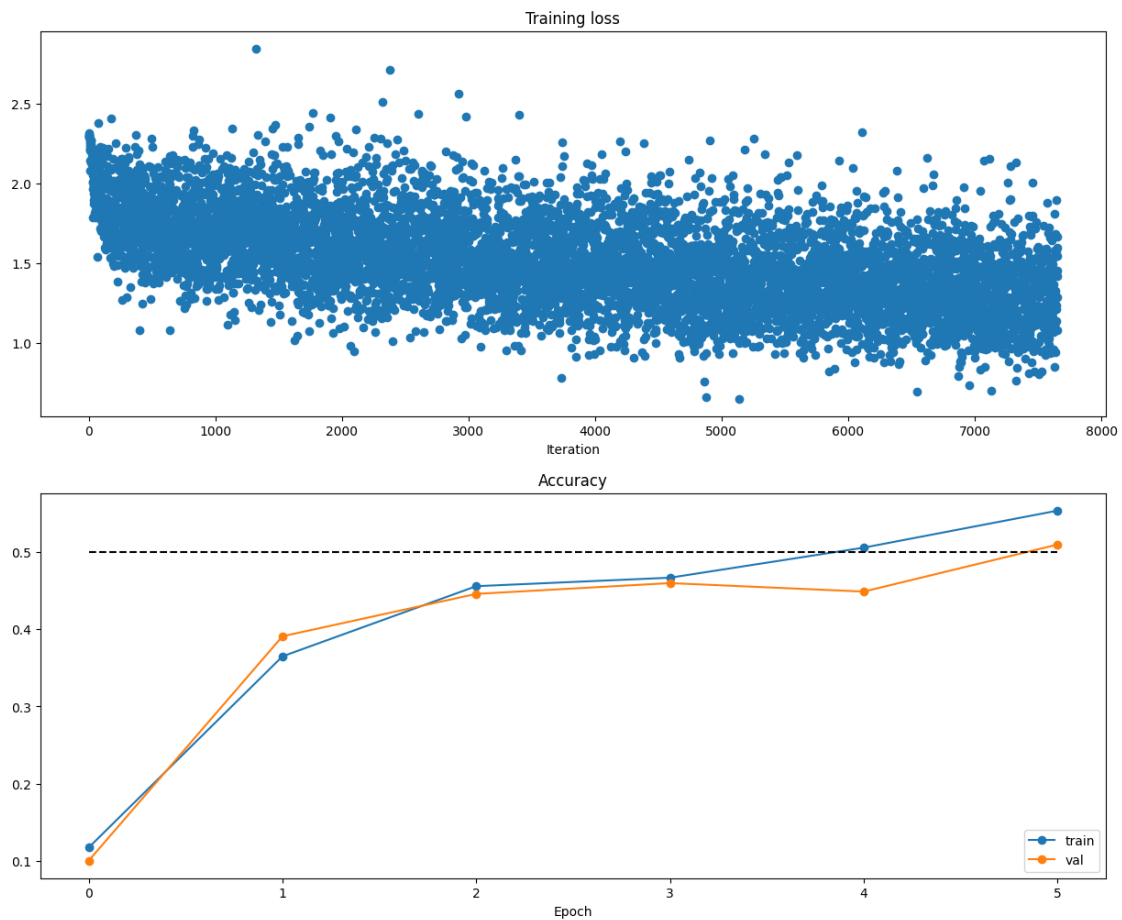
```
(Iteration 3901 / 7655) loss: 1.732564
(Iteration 4001 / 7655) loss: 1.025839
(Iteration 4101 / 7655) loss: 1.136028
(Iteration 4201 / 7655) loss: 1.013832
(Iteration 4301 / 7655) loss: 1.480531
(Iteration 4401 / 7655) loss: 1.042135
(Iteration 4501 / 7655) loss: 1.150540
(Epoch 3 / 5) train acc: 0.467000; val_acc: 0.460000
(Iteration 4601 / 7655) loss: 1.510926
(Iteration 4701 / 7655) loss: 1.516520
(Iteration 4801 / 7655) loss: 1.442728
(Iteration 4901 / 7655) loss: 1.174211
(Iteration 5001 / 7655) loss: 1.073182
(Iteration 5101 / 7655) loss: 1.328942
(Iteration 5201 / 7655) loss: 1.199831
(Iteration 5301 / 7655) loss: 1.283328
(Iteration 5401 / 7655) loss: 1.183562
(Iteration 5501 / 7655) loss: 1.693131
(Iteration 5601 / 7655) loss: 1.663059
(Iteration 5701 / 7655) loss: 1.642291
(Iteration 5801 / 7655) loss: 1.893189
(Iteration 5901 / 7655) loss: 1.646956
(Iteration 6001 / 7655) loss: 1.528532
(Iteration 6101 / 7655) loss: 1.525050
(Epoch 4 / 5) train acc: 0.506000; val_acc: 0.449000
(Iteration 6201 / 7655) loss: 1.332085
(Iteration 6301 / 7655) loss: 1.549609
(Iteration 6401 / 7655) loss: 1.244617
(Iteration 6501 / 7655) loss: 1.077214
(Iteration 6601 / 7655) loss: 1.359196
(Iteration 6701 / 7655) loss: 1.495418
(Iteration 6801 / 7655) loss: 1.478592
(Iteration 6901 / 7655) loss: 1.413427
(Iteration 7001 / 7655) loss: 1.337018
(Iteration 7101 / 7655) loss: 1.430698
(Iteration 7201 / 7655) loss: 1.613953
(Iteration 7301 / 7655) loss: 1.210013
(Iteration 7401 / 7655) loss: 1.427466
(Iteration 7501 / 7655) loss: 1.428936
(Iteration 7601 / 7655) loss: 1.536703
(Epoch 5 / 5) train acc: 0.554000; val_acc: 0.510000
```

```
[12]: # Run this cell to visualize training loss and train / val accuracy
```

```
plt.subplot(2, 1, 1)
plt.title('Training loss')
plt.plot(solver.loss_history, 'o')
```

```
plt.xlabel('Iteration')

plt.subplot(2, 1, 2)
plt.title('Accuracy')
plt.plot(solver.train_acc_history, '-o', label='train')
plt.plot(solver.val_acc_history, '-o', label='val')
plt.plot([0.5] * len(solver.val_acc_history), 'k--')
plt.xlabel('Epoch')
plt.legend(loc='lower right')
plt.gcf().set_size_inches(15, 12)
plt.show()
```



10 Multilayer network

Next you will implement a fully-connected network with an arbitrary number of hidden layers.

Read through the `FullyConnectedNet` class in the file `CV7062610/classifiers/fc_net.py`.

Implement the initialization, the forward pass, and the backward pass. For the moment don't worry

about implementing dropout or batch/layer normalization; we will add those features soon.

10.1 Initial loss and gradient check

As a sanity check, run the following to check the initial loss and to gradient check the network both with and without regularization. Do the initial losses seem reasonable?

For gradient checking, you should expect to see errors around $1e-7$ or less.

```
[22]: np.random.seed(231)
N, D, H1, H2, C = 2, 15, 20, 30, 10
X = np.random.randn(N, D)
y = np.random.randint(C, size=(N,))

for reg in [0, 3.14]:
    print('Running check with reg = ', reg)
    model = FullyConnectedNet([H1, H2], input_dim=D, num_classes=C,
                              reg=reg, weight_scale=5e-2, dtype=np.float64)

    loss, grads = model.loss(X, y)
    print('Initial loss: ', loss)

    # Most of the errors should be on the order of e-7 or smaller.
    # NOTE: It is fine however to see an error for W2 on the order of e-5
    # for the check when reg = 0.0
    for name in sorted(grads):
        f = lambda _: model.loss(X, y)[0]
        grad_num = eval_numerical_gradient(f, model.params[name], verbose=False,
        ↪h=1e-5)
        print('%s relative error: %.2e' % (name, rel_error(grad_num, grads[name])))
```

```
Running check with reg = 0
Initial loss: 2.3004790897684924
W1 relative error: 1.48e-07
W2 relative error: 2.21e-05
W3 relative error: 3.53e-07
b1 relative error: 5.38e-09
b2 relative error: 2.09e-09
b3 relative error: 5.80e-11
Running check with reg = 3.14
Initial loss: 7.052114776533016
W1 relative error: 3.90e-09
W2 relative error: 6.87e-08
W3 relative error: 2.13e-08
b1 relative error: 1.48e-08
b2 relative error: 1.72e-09
b3 relative error: 1.57e-10
```

As another sanity check, make sure you can overfit a small dataset of 50 images. First we will try a

three-layer network with 100 units in each hidden layer. In the following cell, tweak the **learning rate** and **weight initialization scale** to overfit and achieve 100% training accuracy within 20 epochs.

```
[49]: # TODO: Use a three-layer Net to overfit 50 training examples by
# tweaking just the learning rate and initialization scale.

num_train = 50
small_data = {
    'X_train': data['X_train'][:num_train],
    'y_train': data['y_train'][:num_train],
    'X_val': data['X_val'],
    'y_val': data['y_val'],
}

##### TODO: find the best lr and wight scale #####
params = {}
learning_rate = [1e-3, 3e-4] # Experiment with this!
weight_scale = [5e-2, 1e-3] # Experiment with this!
#####
for lr in learning_rate:
    for ws in weight_scale:
        model = FullyConnectedNet([100, 100],
                                   weight_scale=ws, dtype=np.float64)
        solver = Solver(model, small_data,
                        print_every=10, num_epochs=20, batch_size=25,
                        update_rule='sgd',
                        optim_config={
                            'learning_rate': lr,
                        })
        solver.train()
        final_acc = solver.train_acc_history[-1]

        params["lr: "+str(lr) + " , ws: " + str(ws)] = final_acc

# Find the best params:
best_acc = 0.0
best_params = None
for k, v in params.items():
    if v > best_acc:
        best_acc = v
        best_params = k

print(params)
print("The best parameters for the Fully Connected network are: " + best_params +
      "\n with final accuracy of: {}".format(best_acc))
```

```
plt.plot(solver.loss_history, 'o')
plt.title('Training loss history')
plt.xlabel('Iteration')
plt.ylabel('Training loss')
plt.show()
```

```
(Iteration 1 / 40) loss: 38.649062
(Epoch 0 / 20) train acc: 0.200000; val_acc: 0.119000
(Epoch 1 / 20) train acc: 0.300000; val_acc: 0.119000
(Epoch 2 / 20) train acc: 0.500000; val_acc: 0.116000
(Epoch 3 / 20) train acc: 0.660000; val_acc: 0.133000
(Epoch 4 / 20) train acc: 0.740000; val_acc: 0.135000
(Epoch 5 / 20) train acc: 0.740000; val_acc: 0.132000
(Iteration 11 / 40) loss: 2.475907
(Epoch 6 / 20) train acc: 0.960000; val_acc: 0.128000
(Epoch 7 / 20) train acc: 0.880000; val_acc: 0.139000
(Epoch 8 / 20) train acc: 1.000000; val_acc: 0.122000
(Epoch 9 / 20) train acc: 1.000000; val_acc: 0.119000
(Epoch 10 / 20) train acc: 1.000000; val_acc: 0.119000
(Iteration 21 / 40) loss: 0.017777
(Epoch 11 / 20) train acc: 1.000000; val_acc: 0.122000
(Epoch 12 / 20) train acc: 1.000000; val_acc: 0.123000
(Epoch 13 / 20) train acc: 1.000000; val_acc: 0.123000
(Epoch 14 / 20) train acc: 1.000000; val_acc: 0.122000
(Epoch 15 / 20) train acc: 1.000000; val_acc: 0.122000
(Iteration 31 / 40) loss: 0.001316
(Epoch 16 / 20) train acc: 1.000000; val_acc: 0.122000
(Epoch 17 / 20) train acc: 1.000000; val_acc: 0.123000
(Epoch 18 / 20) train acc: 1.000000; val_acc: 0.123000
(Epoch 19 / 20) train acc: 1.000000; val_acc: 0.122000
(Epoch 20 / 20) train acc: 1.000000; val_acc: 0.122000
(Iteration 1 / 40) loss: 2.302597
(Epoch 0 / 20) train acc: 0.120000; val_acc: 0.106000
(Epoch 1 / 20) train acc: 0.180000; val_acc: 0.113000
(Epoch 2 / 20) train acc: 0.200000; val_acc: 0.103000
(Epoch 3 / 20) train acc: 0.160000; val_acc: 0.111000
(Epoch 4 / 20) train acc: 0.200000; val_acc: 0.101000
(Epoch 5 / 20) train acc: 0.160000; val_acc: 0.090000
(Iteration 11 / 40) loss: 2.302229
(Epoch 6 / 20) train acc: 0.160000; val_acc: 0.111000
(Epoch 7 / 20) train acc: 0.160000; val_acc: 0.111000
(Epoch 8 / 20) train acc: 0.160000; val_acc: 0.112000
(Epoch 9 / 20) train acc: 0.160000; val_acc: 0.112000
(Epoch 10 / 20) train acc: 0.160000; val_acc: 0.112000
(Iteration 21 / 40) loss: 2.302143
```

```

(Epoch 11 / 20) train acc: 0.160000; val_acc: 0.112000
(Epoch 12 / 20) train acc: 0.160000; val_acc: 0.112000
(Epoch 13 / 20) train acc: 0.160000; val_acc: 0.112000
(Epoch 14 / 20) train acc: 0.160000; val_acc: 0.112000
(Epoch 15 / 20) train acc: 0.160000; val_acc: 0.112000
(Iteration 31 / 40) loss: 2.301931
(Epoch 16 / 20) train acc: 0.160000; val_acc: 0.112000
(Epoch 17 / 20) train acc: 0.160000; val_acc: 0.111000
(Epoch 18 / 20) train acc: 0.160000; val_acc: 0.112000
(Epoch 19 / 20) train acc: 0.160000; val_acc: 0.112000
(Epoch 20 / 20) train acc: 0.160000; val_acc: 0.112000
(Iteration 1 / 40) loss: 25.958445
(Epoch 0 / 20) train acc: 0.340000; val_acc: 0.118000
(Epoch 1 / 20) train acc: 0.260000; val_acc: 0.123000
(Epoch 2 / 20) train acc: 0.300000; val_acc: 0.104000
(Epoch 3 / 20) train acc: 0.340000; val_acc: 0.123000
(Epoch 4 / 20) train acc: 0.440000; val_acc: 0.114000
(Epoch 5 / 20) train acc: 0.520000; val_acc: 0.131000
(Iteration 11 / 40) loss: 3.792293
(Epoch 6 / 20) train acc: 0.560000; val_acc: 0.140000
(Epoch 7 / 20) train acc: 0.680000; val_acc: 0.128000
(Epoch 8 / 20) train acc: 0.720000; val_acc: 0.127000
(Epoch 9 / 20) train acc: 0.880000; val_acc: 0.145000
(Epoch 10 / 20) train acc: 0.900000; val_acc: 0.141000
(Iteration 21 / 40) loss: 0.139161
(Epoch 11 / 20) train acc: 0.920000; val_acc: 0.140000
(Epoch 12 / 20) train acc: 0.920000; val_acc: 0.141000
(Epoch 13 / 20) train acc: 0.940000; val_acc: 0.144000
(Epoch 14 / 20) train acc: 0.960000; val_acc: 0.140000
(Epoch 15 / 20) train acc: 0.960000; val_acc: 0.141000
(Iteration 31 / 40) loss: 0.475656
(Epoch 16 / 20) train acc: 1.000000; val_acc: 0.143000
(Epoch 17 / 20) train acc: 1.000000; val_acc: 0.143000
(Epoch 18 / 20) train acc: 1.000000; val_acc: 0.142000
(Epoch 19 / 20) train acc: 1.000000; val_acc: 0.142000
(Epoch 20 / 20) train acc: 1.000000; val_acc: 0.143000
(Iteration 1 / 40) loss: 2.302544
(Epoch 0 / 20) train acc: 0.180000; val_acc: 0.089000
(Epoch 1 / 20) train acc: 0.160000; val_acc: 0.083000
(Epoch 2 / 20) train acc: 0.140000; val_acc: 0.087000
(Epoch 3 / 20) train acc: 0.180000; val_acc: 0.090000
(Epoch 4 / 20) train acc: 0.160000; val_acc: 0.089000
(Epoch 5 / 20) train acc: 0.160000; val_acc: 0.094000
(Iteration 11 / 40) loss: 2.302524
(Epoch 6 / 20) train acc: 0.140000; val_acc: 0.091000
(Epoch 7 / 20) train acc: 0.200000; val_acc: 0.092000
(Epoch 8 / 20) train acc: 0.160000; val_acc: 0.089000
(Epoch 9 / 20) train acc: 0.200000; val_acc: 0.093000

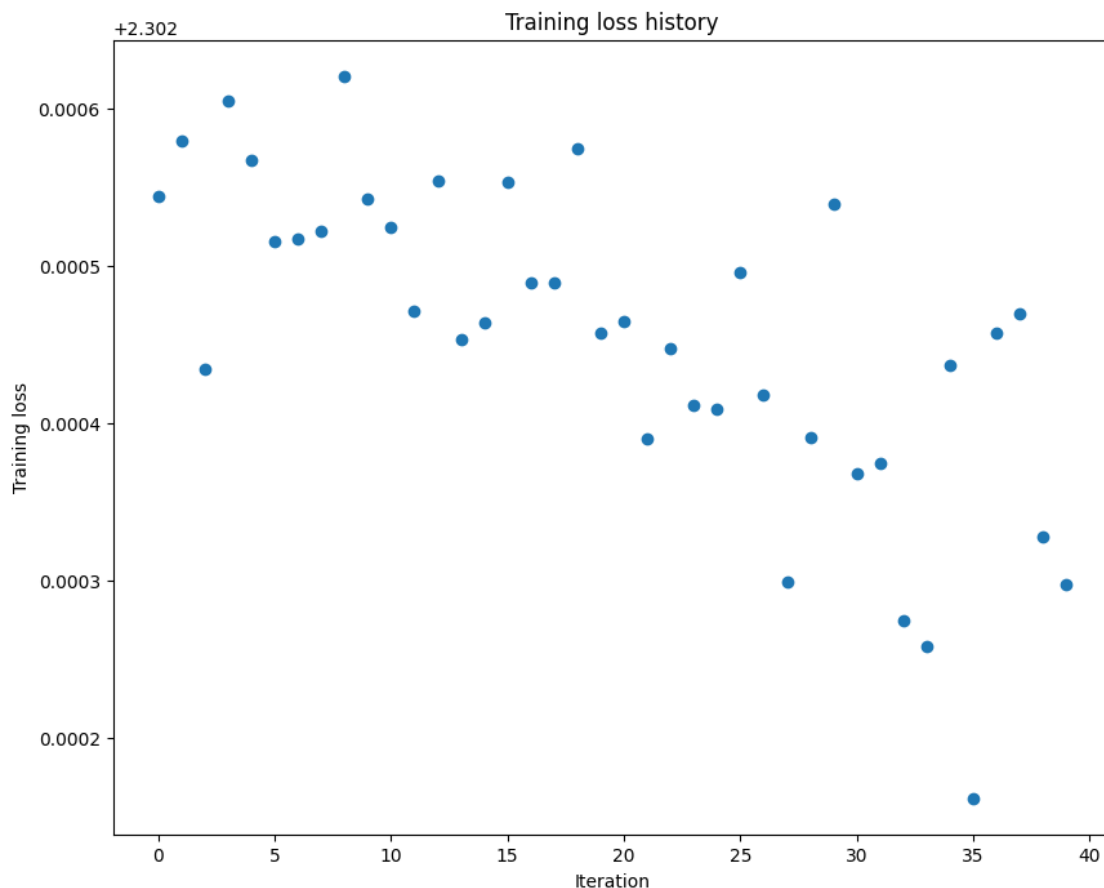
```



```

(Epoch 10 / 20) train acc: 0.200000; val_acc: 0.094000
(Iteration 21 / 40) loss: 2.302465
(Epoch 11 / 20) train acc: 0.200000; val_acc: 0.093000
(Epoch 12 / 20) train acc: 0.200000; val_acc: 0.095000
(Epoch 13 / 20) train acc: 0.200000; val_acc: 0.095000
(Epoch 14 / 20) train acc: 0.200000; val_acc: 0.094000
(Epoch 15 / 20) train acc: 0.200000; val_acc: 0.097000
(Iteration 31 / 40) loss: 2.302368
(Epoch 16 / 20) train acc: 0.180000; val_acc: 0.091000
(Epoch 17 / 20) train acc: 0.180000; val_acc: 0.093000
(Epoch 18 / 20) train acc: 0.180000; val_acc: 0.093000
(Epoch 19 / 20) train acc: 0.180000; val_acc: 0.094000
(Epoch 20 / 20) train acc: 0.200000; val_acc: 0.099000
{'lr: 0.001 , ws: 0.05': 1.0, 'lr: 0.001 , ws: 0.001': 0.16, 'lr: 0.0003 , ws:
0.05': 1.0, 'lr: 0.0003 , ws: 0.001': 0.2}
The best parameters for the Fully Connected network are: lr: 0.001 , ws: 0.05
with final accuracy of: 1.0

```



Now try to use a five-layer network with 100 units on each layer to overfit 50 training examples. Again, you will have to adjust the learning rate and weight initialization scale, but you should be

able to achieve 100% training accuracy within 20 epochs.

```
[51]: # TODO: Use a five-layer Net to overfit 50 training examples by
# tweaking just the learning rate and initialization scale.

num_train = 50
small_data = {
    'X_train': data['X_train'][:num_train],
    'y_train': data['y_train'][:num_train],
    'X_val': data['X_val'],
    'y_val': data['y_val'],
}

##### TODO: find the best lr and wight scale #####
learning_rate = [2e-3, 1e-3, 3e-4] # Experiment with this!
weight_scale = [9e-2, 5e-2] # Experiment with this!
#####
for lr in learning_rate:
    for ws in weight_scale:
        model = FullyConnectedNet([100, 100, 100, 100],
                                   weight_scale=ws, dtype=np.float64)
        solver = Solver(model, small_data,
                        print_every=10, num_epochs=20, batch_size=25,
                        update_rule='sgd',
                        optim_config={
                            'learning_rate': lr,
                        })
        solver.train()
        final_acc = solver.train_acc_history[-1]

        params["lr: " + str(lr) + " , ws: " + str(ws)] = final_acc

# Find the best params:
best_acc = 0.0
best_params = None
for k, v in params.items():
    if v > best_acc:
        best_acc = v
        best_params = k

print(params)
print("The best parameters for the Fully Connected network are: " + best_params_
    ↵ + " with final accuracy of: {}".format(best_acc))

plt.plot(solver.loss_history, 'o')
plt.title('Training loss history')
```

```
plt.xlabel('Iteration')
plt.ylabel('Training loss')
plt.show()
```

```
(Iteration 1 / 40) loss: 86.423960
(Epoch 0 / 20) train acc: 0.140000; val_acc: 0.099000
(Epoch 1 / 20) train acc: 0.140000; val_acc: 0.107000
(Epoch 2 / 20) train acc: 0.360000; val_acc: 0.124000
(Epoch 3 / 20) train acc: 0.500000; val_acc: 0.112000
(Epoch 4 / 20) train acc: 0.620000; val_acc: 0.108000
(Epoch 5 / 20) train acc: 0.720000; val_acc: 0.118000
(Iteration 11 / 40) loss: 5.422583
(Epoch 6 / 20) train acc: 0.920000; val_acc: 0.115000
(Epoch 7 / 20) train acc: 0.940000; val_acc: 0.110000
(Epoch 8 / 20) train acc: 0.980000; val_acc: 0.107000
(Epoch 9 / 20) train acc: 0.980000; val_acc: 0.107000
(Epoch 10 / 20) train acc: 0.980000; val_acc: 0.108000
(Iteration 21 / 40) loss: 0.023062
(Epoch 11 / 20) train acc: 0.980000; val_acc: 0.111000
(Epoch 12 / 20) train acc: 0.980000; val_acc: 0.111000
(Epoch 13 / 20) train acc: 0.980000; val_acc: 0.109000
(Epoch 14 / 20) train acc: 0.980000; val_acc: 0.109000
(Epoch 15 / 20) train acc: 1.000000; val_acc: 0.113000
(Iteration 31 / 40) loss: 0.001425
(Epoch 16 / 20) train acc: 1.000000; val_acc: 0.112000
(Epoch 17 / 20) train acc: 1.000000; val_acc: 0.111000
(Epoch 18 / 20) train acc: 1.000000; val_acc: 0.111000
(Epoch 19 / 20) train acc: 1.000000; val_acc: 0.112000
(Epoch 20 / 20) train acc: 1.000000; val_acc: 0.112000
(Iteration 1 / 40) loss: 3.910568
(Epoch 0 / 20) train acc: 0.200000; val_acc: 0.122000
(Epoch 1 / 20) train acc: 0.260000; val_acc: 0.116000
(Epoch 2 / 20) train acc: 0.300000; val_acc: 0.125000
(Epoch 3 / 20) train acc: 0.520000; val_acc: 0.123000
(Epoch 4 / 20) train acc: 0.580000; val_acc: 0.115000
(Epoch 5 / 20) train acc: 0.680000; val_acc: 0.131000
(Iteration 11 / 40) loss: 0.858628
(Epoch 6 / 20) train acc: 0.740000; val_acc: 0.122000
(Epoch 7 / 20) train acc: 0.840000; val_acc: 0.136000
(Epoch 8 / 20) train acc: 0.880000; val_acc: 0.135000
(Epoch 9 / 20) train acc: 0.940000; val_acc: 0.144000
(Epoch 10 / 20) train acc: 0.940000; val_acc: 0.135000
(Iteration 21 / 40) loss: 0.504102
(Epoch 11 / 20) train acc: 0.940000; val_acc: 0.147000
(Epoch 12 / 20) train acc: 0.960000; val_acc: 0.143000
(Epoch 13 / 20) train acc: 0.960000; val_acc: 0.127000
(Epoch 14 / 20) train acc: 1.000000; val_acc: 0.148000
```

(Epoch 15 / 20) train acc: 0.980000; val_acc: 0.145000
(Iteration 31 / 40) loss: 0.343263
(Epoch 16 / 20) train acc: 0.980000; val_acc: 0.140000
(Epoch 17 / 20) train acc: 1.000000; val_acc: 0.141000
(Epoch 18 / 20) train acc: 0.980000; val_acc: 0.138000
(Epoch 19 / 20) train acc: 1.000000; val_acc: 0.138000
(Epoch 20 / 20) train acc: 1.000000; val_acc: 0.144000
(Iteration 1 / 40) loss: 42.764636
(Epoch 0 / 20) train acc: 0.240000; val_acc: 0.124000
(Epoch 1 / 20) train acc: 0.320000; val_acc: 0.092000
(Epoch 2 / 20) train acc: 0.260000; val_acc: 0.129000
(Epoch 3 / 20) train acc: 0.640000; val_acc: 0.120000
(Epoch 4 / 20) train acc: 0.820000; val_acc: 0.114000
(Epoch 5 / 20) train acc: 0.920000; val_acc: 0.110000
(Iteration 11 / 40) loss: 0.013287
(Epoch 6 / 20) train acc: 0.940000; val_acc: 0.107000
(Epoch 7 / 20) train acc: 0.920000; val_acc: 0.120000
(Epoch 8 / 20) train acc: 0.940000; val_acc: 0.108000
(Epoch 9 / 20) train acc: 0.980000; val_acc: 0.105000
(Epoch 10 / 20) train acc: 1.000000; val_acc: 0.112000
(Iteration 21 / 40) loss: 0.001341
(Epoch 11 / 20) train acc: 1.000000; val_acc: 0.110000
(Epoch 12 / 20) train acc: 1.000000; val_acc: 0.111000
(Epoch 13 / 20) train acc: 1.000000; val_acc: 0.111000
(Epoch 14 / 20) train acc: 1.000000; val_acc: 0.111000
(Epoch 15 / 20) train acc: 1.000000; val_acc: 0.111000
(Iteration 31 / 40) loss: 0.000444
(Epoch 16 / 20) train acc: 1.000000; val_acc: 0.111000
(Epoch 17 / 20) train acc: 1.000000; val_acc: 0.111000
(Epoch 18 / 20) train acc: 1.000000; val_acc: 0.111000
(Epoch 19 / 20) train acc: 1.000000; val_acc: 0.111000
(Epoch 20 / 20) train acc: 1.000000; val_acc: 0.111000
(Iteration 1 / 40) loss: 3.873925
(Epoch 0 / 20) train acc: 0.120000; val_acc: 0.099000
(Epoch 1 / 20) train acc: 0.200000; val_acc: 0.098000
(Epoch 2 / 20) train acc: 0.300000; val_acc: 0.104000
(Epoch 3 / 20) train acc: 0.380000; val_acc: 0.096000
(Epoch 4 / 20) train acc: 0.420000; val_acc: 0.111000
(Epoch 5 / 20) train acc: 0.460000; val_acc: 0.120000
(Iteration 11 / 40) loss: 1.445205
(Epoch 6 / 20) train acc: 0.540000; val_acc: 0.125000
(Epoch 7 / 20) train acc: 0.620000; val_acc: 0.116000
(Epoch 8 / 20) train acc: 0.640000; val_acc: 0.119000
(Epoch 9 / 20) train acc: 0.740000; val_acc: 0.115000
(Epoch 10 / 20) train acc: 0.740000; val_acc: 0.131000
(Iteration 21 / 40) loss: 1.426182
(Epoch 11 / 20) train acc: 0.840000; val_acc: 0.117000
(Epoch 12 / 20) train acc: 0.820000; val_acc: 0.126000

```

(Epoch 13 / 20) train acc: 0.820000; val_acc: 0.140000
(Epoch 14 / 20) train acc: 0.860000; val_acc: 0.126000
(Epoch 15 / 20) train acc: 0.860000; val_acc: 0.128000
(Iteration 31 / 40) loss: 0.713464
(Epoch 16 / 20) train acc: 0.900000; val_acc: 0.121000
(Epoch 17 / 20) train acc: 0.900000; val_acc: 0.122000
(Epoch 18 / 20) train acc: 0.940000; val_acc: 0.124000
(Epoch 19 / 20) train acc: 0.940000; val_acc: 0.129000
(Epoch 20 / 20) train acc: 0.940000; val_acc: 0.128000
(Iteration 1 / 40) loss: 73.035041
(Epoch 0 / 20) train acc: 0.160000; val_acc: 0.105000
(Epoch 1 / 20) train acc: 0.180000; val_acc: 0.112000
(Epoch 2 / 20) train acc: 0.280000; val_acc: 0.109000
(Epoch 3 / 20) train acc: 0.400000; val_acc: 0.109000
(Epoch 4 / 20) train acc: 0.520000; val_acc: 0.104000
(Epoch 5 / 20) train acc: 0.600000; val_acc: 0.107000
(Iteration 11 / 40) loss: 4.919066
(Epoch 6 / 20) train acc: 0.700000; val_acc: 0.105000
(Epoch 7 / 20) train acc: 0.780000; val_acc: 0.107000
(Epoch 8 / 20) train acc: 0.820000; val_acc: 0.107000
(Epoch 9 / 20) train acc: 0.900000; val_acc: 0.107000
(Epoch 10 / 20) train acc: 0.940000; val_acc: 0.114000
(Iteration 21 / 40) loss: 0.326023
(Epoch 11 / 20) train acc: 0.880000; val_acc: 0.113000
(Epoch 12 / 20) train acc: 0.980000; val_acc: 0.115000
(Epoch 13 / 20) train acc: 1.000000; val_acc: 0.111000
(Epoch 14 / 20) train acc: 1.000000; val_acc: 0.110000
(Epoch 15 / 20) train acc: 1.000000; val_acc: 0.110000
(Iteration 31 / 40) loss: 0.006697
(Epoch 16 / 20) train acc: 1.000000; val_acc: 0.110000
(Epoch 17 / 20) train acc: 1.000000; val_acc: 0.109000
(Epoch 18 / 20) train acc: 1.000000; val_acc: 0.109000
(Epoch 19 / 20) train acc: 1.000000; val_acc: 0.109000
(Epoch 20 / 20) train acc: 1.000000; val_acc: 0.112000
(Iteration 1 / 40) loss: 3.535646
(Epoch 0 / 20) train acc: 0.220000; val_acc: 0.121000
(Epoch 1 / 20) train acc: 0.180000; val_acc: 0.117000
(Epoch 2 / 20) train acc: 0.180000; val_acc: 0.117000
(Epoch 3 / 20) train acc: 0.180000; val_acc: 0.117000
(Epoch 4 / 20) train acc: 0.260000; val_acc: 0.112000
(Epoch 5 / 20) train acc: 0.280000; val_acc: 0.112000
(Iteration 11 / 40) loss: 2.601043
(Epoch 6 / 20) train acc: 0.300000; val_acc: 0.107000
(Epoch 7 / 20) train acc: 0.360000; val_acc: 0.107000
(Epoch 8 / 20) train acc: 0.400000; val_acc: 0.107000
(Epoch 9 / 20) train acc: 0.420000; val_acc: 0.107000
(Epoch 10 / 20) train acc: 0.480000; val_acc: 0.111000
(Iteration 21 / 40) loss: 2.028721

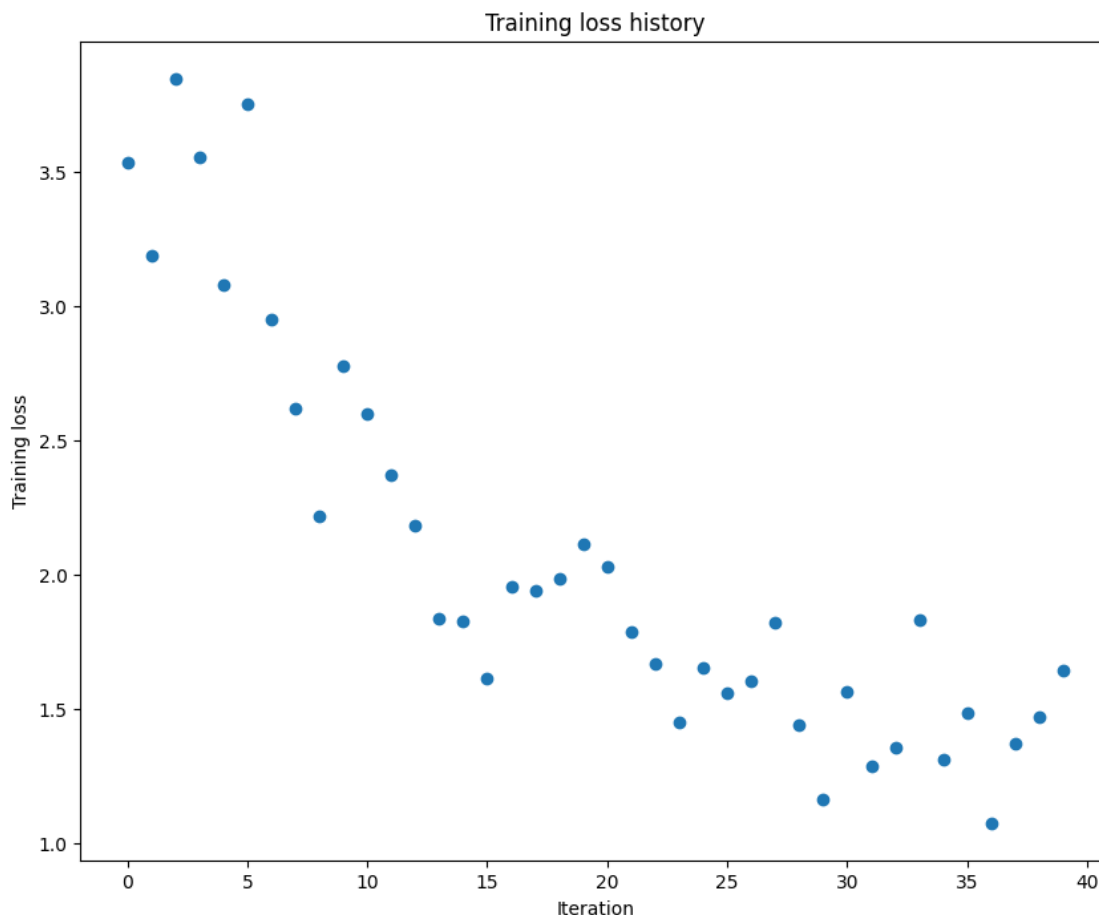
```

```

(Epoch 11 / 20) train acc: 0.500000; val_acc: 0.109000
(Epoch 12 / 20) train acc: 0.520000; val_acc: 0.107000
(Epoch 13 / 20) train acc: 0.500000; val_acc: 0.105000
(Epoch 14 / 20) train acc: 0.520000; val_acc: 0.103000
(Epoch 15 / 20) train acc: 0.540000; val_acc: 0.102000
(Iteration 31 / 40) loss: 1.564983
(Epoch 16 / 20) train acc: 0.620000; val_acc: 0.105000
(Epoch 17 / 20) train acc: 0.620000; val_acc: 0.106000
(Epoch 18 / 20) train acc: 0.640000; val_acc: 0.109000
(Epoch 19 / 20) train acc: 0.640000; val_acc: 0.111000
(Epoch 20 / 20) train acc: 0.620000; val_acc: 0.112000
{'lr: 0.001 , ws: 0.05': 0.94, 'lr: 0.001 , ws: 0.001': 0.16, 'lr: 0.0003 , ws:
0.05': 0.62, 'lr: 0.0003 , ws: 0.001': 0.2, 'lr: 0.002 , ws: 0.09': 1.0, 'lr:
0.002 , ws: 0.05': 1.0, 'lr: 0.001 , ws: 0.09': 1.0, 'lr: 0.0003 , ws: 0.09':
1.0}

```

The best parameters for the Fully Connected network are: lr: 0.002 , ws: 0.09 with final accuracy of: 1.0



10.2 Inline Question 2:

Did you notice anything about the comparative difficulty of training the three-layer net vs training the five layer net? In particular, based on your experience, which network seemed more sensitive to the initialization scale? Why do you think that is the case?

10.3 Answer:

Base on our experience and knowledge, the five-layer network is more sensitive to the initialization scale. The deeper the network, the lower the impact of the gradients upon the first layers as the gradients are getting smaller and smaller during the back-propagation process (close to 0 numbers when reaching the first layers). Therefore, the init values of the weights have a high impact on the first layers when the network is deeper.

11 Train a good model!

Train the best fully-connected model that you can on CIFAR-10, storing your best model in the `best_model` variable. We require you to get at least 40% accuracy on the validation set using a fully-connected net. Using `sgd` this shouldn't take more than 5 minuts per traing over 10 epochs.

If you are careful it should be possible to get accuracies above 55%, but we don't require it for this part and won't assign extra credit for doing so. Later in the assignment we will ask you to train the best convolutional network that you can on CIFAR-10, and we would prefer that you spend your effort working on convolutional nets rather than fully-connected nets.

```
[83]: best_model = None
best_val = 0.0
#####
# TODO: Train the best FullyConnectedNet that you can on CIFAR-10. You might #
# find batch/layer normalization and dropout useful. Store your best model in #
# the best_model variable. #
#####
# *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)*****

learning_rate = [8e-3, 2e-3, 3e-4] # Experiment with this!
weight_scale = [1e-3] # Experiment with this!
#####

for lr in learning_rate:
    for ws in weight_scale:
        model = FullyConnectedNet([128, 64],
                                   reg=2e-4, weight_scale=ws, dtype=np.float64)
        solver = Solver(model, data,
                        print_every=100, num_epochs=10, batch_size=128,
                        update_rule='sgd', lr_decay=0.95,
                        optim_config={
                            'learning_rate': lr,
                        })
        )
```

```

solver.train()
final_acc = solver.best_val_acc
if final_acc > best_val:
    best_model = model
    best_val = final_acc

params["lr: "+str(lr) + " , ws: " + str(ws)] = final_acc

# Find the best params:
best_acc = 0.0
best_params = None
for k, v in params.items():
    if v > best_acc and v != 1.0:
        best_acc = v
        best_params = k

print(params)
print("The best parameters for the Fully Connected network are: " + best_params +
    ↵ " with final accuracy of: {}".format(best_acc))

# *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)*****
#####
#                               END OF YOUR CODE                               #
#####

```

```

(Iteration 1 / 3820) loss: 2.302625
(Epoch 0 / 10) train acc: 0.100000; val_acc: 0.083000
(Iteration 101 / 3820) loss: 2.302240
(Iteration 201 / 3820) loss: 2.134155
(Iteration 301 / 3820) loss: 2.048813
(Epoch 1 / 10) train acc: 0.310000; val_acc: 0.319000
(Iteration 401 / 3820) loss: 1.913194
(Iteration 501 / 3820) loss: 1.672669
(Iteration 601 / 3820) loss: 1.607035
(Iteration 701 / 3820) loss: 1.651024
(Epoch 2 / 10) train acc: 0.447000; val_acc: 0.421000
(Iteration 801 / 3820) loss: 1.422403
(Iteration 901 / 3820) loss: 1.432800
(Iteration 1001 / 3820) loss: 1.649794
(Iteration 1101 / 3820) loss: 1.277607
(Epoch 3 / 10) train acc: 0.444000; val_acc: 0.465000
(Iteration 1201 / 3820) loss: 1.487024
(Iteration 1301 / 3820) loss: 1.390112
(Iteration 1401 / 3820) loss: 1.234184
(Iteration 1501 / 3820) loss: 1.543321
(Epoch 4 / 10) train acc: 0.495000; val_acc: 0.487000
(Iteration 1601 / 3820) loss: 1.236471

```


(Iteration 1701 / 3820) loss: 1.379473
(Iteration 1801 / 3820) loss: 1.334375
(Iteration 1901 / 3820) loss: 1.359218
(Epoch 5 / 10) train acc: 0.540000; val_acc: 0.498000
(Iteration 2001 / 3820) loss: 1.305458
(Iteration 2101 / 3820) loss: 1.161497
(Iteration 2201 / 3820) loss: 1.144237
(Epoch 6 / 10) train acc: 0.560000; val_acc: 0.517000
(Iteration 2301 / 3820) loss: 1.424186
(Iteration 2401 / 3820) loss: 1.171445
(Iteration 2501 / 3820) loss: 1.254960
(Iteration 2601 / 3820) loss: 1.306727
(Epoch 7 / 10) train acc: 0.571000; val_acc: 0.504000
(Iteration 2701 / 3820) loss: 1.165392
(Iteration 2801 / 3820) loss: 1.220496
(Iteration 2901 / 3820) loss: 1.153854
(Iteration 3001 / 3820) loss: 1.199957
(Epoch 8 / 10) train acc: 0.576000; val_acc: 0.509000
(Iteration 3101 / 3820) loss: 1.003538
(Iteration 3201 / 3820) loss: 1.175862
(Iteration 3301 / 3820) loss: 1.057444
(Iteration 3401 / 3820) loss: 1.434331
(Epoch 9 / 10) train acc: 0.631000; val_acc: 0.511000
(Iteration 3501 / 3820) loss: 1.218813
(Iteration 3601 / 3820) loss: 1.139238
(Iteration 3701 / 3820) loss: 1.077057
(Iteration 3801 / 3820) loss: 1.229851
(Epoch 10 / 10) train acc: 0.616000; val_acc: 0.528000
(Iteration 1 / 3820) loss: 2.302613
(Epoch 0 / 10) train acc: 0.124000; val_acc: 0.116000
(Iteration 101 / 3820) loss: 2.302594
(Iteration 201 / 3820) loss: 2.302518
(Iteration 301 / 3820) loss: 2.302322
(Epoch 1 / 10) train acc: 0.144000; val_acc: 0.127000
(Iteration 401 / 3820) loss: 2.302103
(Iteration 501 / 3820) loss: 2.300690
(Iteration 601 / 3820) loss: 2.278128
(Iteration 701 / 3820) loss: 2.191463
(Epoch 2 / 10) train acc: 0.155000; val_acc: 0.188000
(Iteration 801 / 3820) loss: 2.247182
(Iteration 901 / 3820) loss: 2.041864
(Iteration 1001 / 3820) loss: 2.068740
(Iteration 1101 / 3820) loss: 2.045697
(Epoch 3 / 10) train acc: 0.228000; val_acc: 0.236000
(Iteration 1201 / 3820) loss: 2.044906
(Iteration 1301 / 3820) loss: 1.840467
(Iteration 1401 / 3820) loss: 1.796288
(Iteration 1501 / 3820) loss: 1.767176

(Epoch 4 / 10) train acc: 0.311000; val_acc: 0.329000
(Iteration 1601 / 3820) loss: 1.808248
(Iteration 1701 / 3820) loss: 1.690034
(Iteration 1801 / 3820) loss: 1.776386
(Iteration 1901 / 3820) loss: 1.735800
(Epoch 5 / 10) train acc: 0.400000; val_acc: 0.376000
(Iteration 2001 / 3820) loss: 1.703823
(Iteration 2101 / 3820) loss: 1.835719
(Iteration 2201 / 3820) loss: 1.751448
(Epoch 6 / 10) train acc: 0.418000; val_acc: 0.410000
(Iteration 2301 / 3820) loss: 1.682841
(Iteration 2401 / 3820) loss: 1.566697
(Iteration 2501 / 3820) loss: 1.643503
(Iteration 2601 / 3820) loss: 1.537148
(Epoch 7 / 10) train acc: 0.436000; val_acc: 0.452000
(Iteration 2701 / 3820) loss: 1.466290
(Iteration 2801 / 3820) loss: 1.506314
(Iteration 2901 / 3820) loss: 1.562014
(Iteration 3001 / 3820) loss: 1.460708
(Epoch 8 / 10) train acc: 0.478000; val_acc: 0.454000
(Iteration 3101 / 3820) loss: 1.376837
(Iteration 3201 / 3820) loss: 1.405625
(Iteration 3301 / 3820) loss: 1.352558
(Iteration 3401 / 3820) loss: 1.275685
(Epoch 9 / 10) train acc: 0.504000; val_acc: 0.480000
(Iteration 3501 / 3820) loss: 1.325787
(Iteration 3601 / 3820) loss: 1.615433
(Iteration 3701 / 3820) loss: 1.332268
(Iteration 3801 / 3820) loss: 1.531903
(Epoch 10 / 10) train acc: 0.509000; val_acc: 0.491000
(Iteration 1 / 3820) loss: 2.302634
(Epoch 0 / 10) train acc: 0.087000; val_acc: 0.080000
(Iteration 101 / 3820) loss: 2.302625
(Iteration 201 / 3820) loss: 2.302599
(Iteration 301 / 3820) loss: 2.302567
(Epoch 1 / 10) train acc: 0.109000; val_acc: 0.118000
(Iteration 401 / 3820) loss: 2.302597
(Iteration 501 / 3820) loss: 2.302613
(Iteration 601 / 3820) loss: 2.302590
(Iteration 701 / 3820) loss: 2.302573
(Epoch 2 / 10) train acc: 0.145000; val_acc: 0.134000
(Iteration 801 / 3820) loss: 2.302568
(Iteration 901 / 3820) loss: 2.302577
(Iteration 1001 / 3820) loss: 2.302547
(Iteration 1101 / 3820) loss: 2.302502
(Epoch 3 / 10) train acc: 0.116000; val_acc: 0.121000
(Iteration 1201 / 3820) loss: 2.302564
(Iteration 1301 / 3820) loss: 2.302561

```

(Iteration 1401 / 3820) loss: 2.302462
(Iteration 1501 / 3820) loss: 2.302474
(Epoch 4 / 10) train acc: 0.152000; val_acc: 0.149000
(Iteration 1601 / 3820) loss: 2.302511
(Iteration 1701 / 3820) loss: 2.302410
(Iteration 1801 / 3820) loss: 2.302396
(Iteration 1901 / 3820) loss: 2.302414
(Epoch 5 / 10) train acc: 0.140000; val_acc: 0.150000
(Iteration 2001 / 3820) loss: 2.302432
(Iteration 2101 / 3820) loss: 2.302378
(Iteration 2201 / 3820) loss: 2.302249
(Epoch 6 / 10) train acc: 0.185000; val_acc: 0.173000
(Iteration 2301 / 3820) loss: 2.302298
(Iteration 2401 / 3820) loss: 2.302249
(Iteration 2501 / 3820) loss: 2.302354
(Iteration 2601 / 3820) loss: 2.302239
(Epoch 7 / 10) train acc: 0.169000; val_acc: 0.181000
(Iteration 2701 / 3820) loss: 2.302341
(Iteration 2801 / 3820) loss: 2.301925
(Iteration 2901 / 3820) loss: 2.301855
(Iteration 3001 / 3820) loss: 2.302007
(Epoch 8 / 10) train acc: 0.168000; val_acc: 0.160000
(Iteration 3101 / 3820) loss: 2.301149
(Iteration 3201 / 3820) loss: 2.301848
(Iteration 3301 / 3820) loss: 2.301163
(Iteration 3401 / 3820) loss: 2.301239
(Epoch 9 / 10) train acc: 0.171000; val_acc: 0.149000
(Iteration 3501 / 3820) loss: 2.300052
(Iteration 3601 / 3820) loss: 2.300413
(Iteration 3701 / 3820) loss: 2.300091
(Iteration 3801 / 3820) loss: 2.298889
(Epoch 10 / 10) train acc: 0.160000; val_acc: 0.156000
{'lr: 0.001 , ws: 0.05': 0.385, 'lr: 0.001 , ws: 0.001': 0.16, 'lr: 0.0003 , ws:
0.05': 0.324, 'lr: 0.0003 , ws: 0.001': 0.181, 'lr: 0.002 , ws: 0.09': 1.0, 'lr:
0.002 , ws: 0.05': 0.398, 'lr: 0.001 , ws: 0.09': 1.0, 'lr: 0.0003 , ws: 0.09':
1.0, 'lr: 0.0001 , ws: 0.05': 0.277, 'lr: 0.002 , ws: 0.07': 0.327, 'lr: 0.001 ,
ws: 0.07': 0.306, 'lr: 0.0003 , ws: 0.07': 0.293, 'lr: 0.008 , ws: 0.07': 0.233,
'lr: 0.008 , ws: 0.05': 0.388, 'lr: 0.008 , ws: 0.001': 0.528, 'lr: 0.002 , ws:
0.001': 0.491}
The best parameters for the Fully Connected network are: lr: 0.008 , ws: 0.001
with final accuracy of: 0.528

```

12 Test your model!

Run your best model on the validation and test sets. You should achieve above 50% accuracy on the validation set.

```
[84]: y_test_pred = np.argmax(best_model.loss(data['X_test']), axis=1)
      y_val_pred = np.argmax(best_model.loss(data['X_val']), axis=1)
      print('Validation set accuracy: ', (y_val_pred == data['y_val']).mean())
      print('Test set accuracy: ', (y_test_pred == data['y_test']).mean())
```

Validation set accuracy: 0.528

Test set accuracy: 0.519

```
[ ]:
```

Convolutional Networks

May 4, 2023

```
[11]: # this mounts your Google Drive to the Colab VM.
from google.colab import drive
drive.mount('/content/drive', force_remount=True)

# enter the foldername in your Drive where you have saved the unzipped
# assignment folder, e.g. 'CV7062610/assignments/assignment3/'
FOLDERNAME = None
assert FOLDERNAME is not None, "[!] Enter the foldername."

# now that we've mounted your Drive, this ensures that
# the Python interpreter of the Colab VM can load
# python files from within it.
import sys
sys.path.append('/content/drive/My Drive/{}'.format(FOLDERNAME))

# this downloads the CIFAR-10 dataset to your Drive
# if it doesn't already exist.
%cd drive/My\ Drive/$FOLDERNAME/CV7062610/datasets/
!bash get_datasets.sh
%cd /content
```

```
-----
ModuleNotFoundError                                Traceback (most recent call last)
Cell In[11], line 2
      1 # this mounts your Google Drive to the Colab VM.
----> 2 from google.colab import drive
      3 drive.mount('/content/drive', force_remount=True)
      5 # enter the foldername in your Drive where you have saved the unzipped
      6 # assignment folder, e.g. 'CV7062610/assignments/assignment3/'

ModuleNotFoundError: No module named 'google.colab'
```

1 Convolutional Networks

So far we have worked with deep fully-connected networks, using them to explore different optimization strategies and network architectures. Fully-connected networks are a good testbed for

experimentation because they are very computationally efficient, but in practice all state-of-the-art results use convolutional networks instead.

First you will implement several layer types that are used in convolutional networks. You will then use these layers to train a convolutional network on the CIFAR-10 dataset.

```
[2]: # As usual, a bit of setup
import numpy as np
import matplotlib.pyplot as plt
from CV7062610.classifiers.cnn import *
from CV7062610.data_utils import get_CIFAR10_data
from CV7062610.gradient_check import eval_numerical_gradient_array, \
    eval_numerical_gradient
from CV7062610.layers import *
from CV7062610.fast_layers import *
from CV7062610.solver import Solver

%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

# for auto-reloading external modules
# see http://stackoverflow.com/questions/1907993/
# autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2

def rel_error(x, y):
    """ returns relative error """
    return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
```

===== You can safely ignore the message below if you are NOT working on ConvolutionalNetworks.ipynb =====

You will need to compile a Cython extension for a portion of this assignment.

The instructions to do this will be given in a section of the notebook below.

There will be an option for Colab users and another for Jupyter (local) users.

```
[3]: # Load the (preprocessed) CIFAR10 data.

data = get_CIFAR10_data()
for k, v in data.items():
    print('%s: ' % k, v.shape)
```

X_train: (49000, 3, 32, 32)

```
y_train: (49000,)
X_val: (1000, 3, 32, 32)
y_val: (1000,)
X_test: (1000, 3, 32, 32)
y_test: (1000,)
```

2 Convolution: Naive forward pass

The core of a convolutional network is the convolution operation. In the file `CV7062610/layers.py`, implement the forward pass for the convolution layer in the function `conv_forward_naive`.

You don't have to worry too much about efficiency at this point; just write the code in whatever way you find most clear.

You can test your implementation by running the following:

```
[4]: x_shape = (2, 3, 4, 4)
     w_shape = (3, 3, 4, 4)
     x = np.linspace(-0.1, 0.5, num=np.prod(x_shape)).reshape(x_shape)
     w = np.linspace(-0.2, 0.3, num=np.prod(w_shape)).reshape(w_shape)
     b = np.linspace(-0.1, 0.2, num=3)

     conv_param = {'stride': 2, 'pad': 1}
     out, _ = conv_forward_naive(x, w, b, conv_param)
     correct_out = np.array([[[[-0.08759809, -0.10987781],
                               [-0.18387192, -0.2109216 ]],
                             [[ 0.21027089,  0.21661097],
                              [ 0.22847626,  0.23004637]],
                             [[ 0.50813986,  0.54309974],
                              [ 0.64082444,  0.67101435]]],
                             [[[-0.98053589, -1.03143541],
                               [-1.19128892, -1.24695841]],
                              [[ 0.69108355,  0.66880383],
                               [ 0.59480972,  0.56776003]],
                              [[ 2.36270298,  2.36904306],
                               [ 2.38090835,  2.38247847]]]])])

     # Compare your output to ours; difference should be around e-8
     print('Testing conv_forward_naive')
     print('difference: ', rel_error(out, correct_out))
```

```
Testing conv_forward_naive
difference:  2.2121476417505994e-08
```

3 Aside: Image processing via convolutions

As fun way to both check your implementation and gain a better understanding of the type of operation that convolutional layers can perform, we will set up an input containing two images and

manually set up filters that perform common image processing operations (grayscale conversion and edge detection). The convolution forward pass will apply these operations to each of the input images. We can then visualize the results as a sanity check.

3.1 Colab Users Only

Please execute the below cell to copy two cat images to the Colab VM.

```
[ ]: # Colab users only!
%mkdir -p CV7062610/notebook_images
%cd drive/My\ Drive/$FOLDERNAME/CV7062610
%cp -r notebook_images/ /content/CV7062610/
%cd /content/

[5]: from imageio import imread
from PIL import Image

kitten = imread('CV7062610/notebook_images/kitten.jpg')
puppy = imread('CV7062610/notebook_images/puppy.jpg')
# kitten is wide, and puppy is already square
d = kitten.shape[1] - kitten.shape[0]
kitten_cropped = kitten[:, d//2:-d//2, :]

img_size = 200 # Make this smaller if it runs too slow
resized_puppy = np.array(Image.fromarray(puppy).resize((img_size, img_size)))
resized_kitten = np.array(Image.fromarray(kitten_cropped).resize((img_size,
    img_size)))
x = np.zeros((2, 3, img_size, img_size))
x[0, :, :, :] = resized_puppy.transpose((2, 0, 1))
x[1, :, :, :] = resized_kitten.transpose((2, 0, 1))

# Set up a convolutional weights holding 2 filters, each 3x3
w = np.zeros((2, 3, 3, 3))

# The first filter converts the image to grayscale.
# Set up the red, green, and blue channels of the filter.
w[0, 0, :, :] = [[0, 0, 0], [0, 0.3, 0], [0, 0, 0]]
w[0, 1, :, :] = [[0, 0, 0], [0, 0.6, 0], [0, 0, 0]]
w[0, 2, :, :] = [[0, 0, 0], [0, 0.1, 0], [0, 0, 0]]

# Second filter detects horizontal edges in the blue channel.
w[1, 2, :, :] = [[1, 2, 1], [0, 0, 0], [-1, -2, -1]]

# Vector of biases. We don't need any bias for the grayscale
# filter, but for the edge detection filter we want to add 128
# to each output so that nothing is negative.
b = np.array([0, 128])
```



```

# Compute the result of convolving each input in x with each filter in w,
# offsetting by b, and storing the results in out.
out, _ = conv_forward_naive(x, w, b, {'stride': 1, 'pad': 1})

def imshow_no_ax(img, normalize=True):
    """ Tiny helper to show images as uint8 and remove axis labels """
    if normalize:
        img_max, img_min = np.max(img), np.min(img)
        img = 255.0 * (img - img_min) / (img_max - img_min)
    plt.imshow(img.astype('uint8'))
    plt.gca().axis('off')

# Show the original images and the results of the conv operation
plt.subplot(2, 3, 1)
imshow_no_ax(puppy, normalize=False)
plt.title('Original image')
plt.subplot(2, 3, 2)
imshow_no_ax(out[0, 0])
plt.title('Grayscale')
plt.subplot(2, 3, 3)
imshow_no_ax(out[0, 1])
plt.title('Edges')
plt.subplot(2, 3, 4)
imshow_no_ax(kitten_cropped, normalize=False)
plt.subplot(2, 3, 5)
imshow_no_ax(out[1, 0])
plt.subplot(2, 3, 6)
imshow_no_ax(out[1, 1])
plt.show()

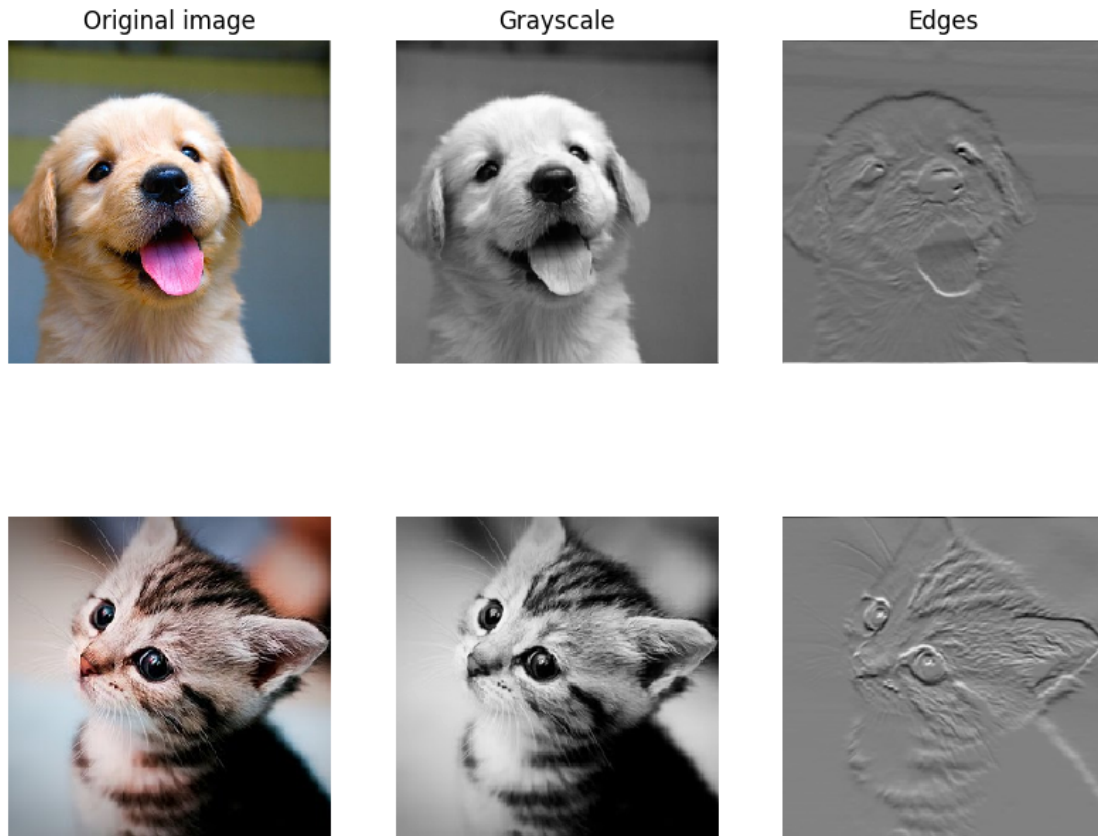
```

/tmp/ipykernel_79265/2599499143.py:4: DeprecationWarning: Starting with ImageIO v3 the behavior of this function will switch to that of iio.v3.imread. To keep the current behavior (and make this warning disappear) use `import imageio.v2 as imageio` or call `imageio.v2.imread` directly.

```
kitten = imread('CV7062610/notebook_images/kitten.jpg')
```

/tmp/ipykernel_79265/2599499143.py:5: DeprecationWarning: Starting with ImageIO v3 the behavior of this function will switch to that of iio.v3.imread. To keep the current behavior (and make this warning disappear) use `import imageio.v2 as imageio` or call `imageio.v2.imread` directly.

```
puppy = imread('CV7062610/notebook_images/puppy.jpg')
```



4 Convolution: Naive backward pass

Implement the backward pass for the convolution operation in the function `conv_backward_naive` in the file `CV7062610/layers.py`. Again, you don't need to worry too much about computational efficiency.

When you are done, run the following to check your backward pass with a numeric gradient check.

```
[6]: np.random.seed(231)
x = np.random.randn(4, 3, 5, 5)
w = np.random.randn(2, 3, 3, 3)
b = np.random.randn(2,)
dout = np.random.randn(4, 2, 5, 5)
conv_param = {'stride': 1, 'pad': 1}

dx_num = eval_numerical_gradient_array(lambda x: conv_forward_naive(x, w, b,
    ↪conv_param)[0], x, dout)
dw_num = eval_numerical_gradient_array(lambda w: conv_forward_naive(x, w, b,
    ↪conv_param)[0], w, dout)
```

```

db_num = eval_numerical_gradient_array(lambda b: conv_forward_naive(x, w, b,
↪conv_param)[0], b, dout)

out, cache = conv_forward_naive(x, w, b, conv_param)
dx, dw, db = conv_backward_naive(dout, cache)

# Your errors should be around e-8 or less.
print('Testing conv_backward_naive function')
print('dx error: ', rel_error(dx, dx_num))
print('dw error: ', rel_error(dw, dw_num))
print('db error: ', rel_error(db, db_num))

```

```

Testing conv_backward_naive function
dx error:  1.159803161159293e-08
dw error:  2.2471230668641297e-10
db error:  3.37264006649648e-11

```

5 Max-Pooling: Naive forward

Implement the forward pass for the max-pooling operation in the function `max_pool_forward_naive` in the file `CV7062610/layers.py`. Again, don't worry too much about computational efficiency.

Check your implementation by running the following:

```

[11]: x_shape = (2, 3, 4, 4)
x = np.linspace(-0.3, 0.4, num=np.prod(x_shape)).reshape(x_shape)
pool_param = {'pool_width': 2, 'pool_height': 2, 'stride': 2}

out, _ = max_pool_forward_naive(x, pool_param)

correct_out = np.array([[[[-0.26315789, -0.24842105],
                           [-0.20421053, -0.18947368]],
                          [[-0.14526316, -0.13052632],
                           [-0.08631579, -0.07157895]],
                          [[-0.02736842, -0.01263158],
                           [ 0.03157895,  0.04631579]]],
                        [[[ 0.09052632,  0.10526316],
                           [ 0.14947368,  0.16421053]],
                          [[ 0.20842105,  0.22315789],
                           [ 0.26736842,  0.28210526]],
                          [[ 0.32631579,  0.34105263],
                           [ 0.38526316,  0.4          ]]]])

# Compare your output with ours. Difference should be on the order of e-8.
print('Testing max_pool_forward_naive function:')
print('difference: ', rel_error(out, correct_out))

```

Testing max_pool_forward_naive function:
difference: 4.166665157267834e-08

6 Max-Pooling: Naive backward

Implement the backward pass for the max-pooling operation in the function max_pool_backward_naive in the file CV7062610/layers.py. You don't need to worry about computational efficiency.

Check your implementation with numeric gradient checking by running the following:

```
[12]: np.random.seed(231)
x = np.random.randn(3, 2, 8, 8)
dout = np.random.randn(3, 2, 4, 4)
pool_param = {'pool_height': 2, 'pool_width': 2, 'stride': 2}

dx_num = eval_numerical_gradient_array(lambda x: max_pool_forward_naive(x,
    pool_param)[0], x, dout)

out, cache = max_pool_forward_naive(x, pool_param)
dx = max_pool_backward_naive(dout, cache)

# Your error should be on the order of e-12
print('Testing max_pool_backward_naive function:')
print('dx error: ', rel_error(dx, dx_num))
```

Testing max_pool_backward_naive function:
dx error: 3.27562514223145e-12

7 Fast layers

Making convolution and pooling layers fast can be challenging. To spare you the pain, we've provided fast implementations of the forward and backward passes for convolution and pooling layers in the file CV7062610/fast_layers.py.

The fast convolution implementation depends on a Cython extension; to compile it either execute the local development cell (option A) if you are developing locally, or the Colab cell (option B) if you are running this assignment in Colab.

Very Important, Please Read. For **both** option A and B, you have to **restart** the notebook after compiling the cython extension. In Colab, please save the notebook File -> Save, then click Runtime -> Restart Runtime -> Yes. This will restart the kernel which means local variables will be lost. Just re-execute the cells from top to bottom and skip the cell below as you only need to run it once for the compilation step.

7.1 Option A: Colab

Execute the cell below only only **ONCE**.

```
[14]: %cd drive/My\ Drive/$FOLDERNAME/CV7062610/  
!python setup.py build_ext --inplace
```

```
[Errno 2] No such file or directory: 'drive/My Drive/$FOLDERNAME/CV7062610/'  
/home/alon/Documents/Computer_Vision/CS231n/assignment2  
/bin/bash: line 1: python: command not found
```

The API for the fast versions of the convolution and pooling layers is exactly the same as the naive versions that you implemented above: the forward pass receives data, weights, and parameters and produces outputs and a cache object; the backward pass receives upstream derivatives and the cache object and produces gradients with respect to the data and weights.

NOTE: The fast implementation for pooling will only perform optimally if the pooling regions are non-overlapping and tile the input. If these conditions are not met then the fast pooling implementation will not be much faster than the naive implementation.

You can compare the performance of the naive and fast versions of these layers by running the following:

```
[17]: # Rel errors should be around e-9 or less  
from CV7062610.fast_layers import conv_forward_fast, conv_backward_fast  
from time import time  
np.random.seed(231)  
x = np.random.randn(100, 3, 31, 31)  
w = np.random.randn(25, 3, 3, 3)  
b = np.random.randn(25,)  
dout = np.random.randn(100, 25, 16, 16)  
conv_param = {'stride': 2, 'pad': 1}  
  
t0 = time()  
out_naive, cache_naive = conv_forward_naive(x, w, b, conv_param)  
t1 = time()  
out_fast, cache_fast = conv_forward_fast(x, w, b, conv_param)  
t2 = time()  
  
print('Testing conv_forward_fast:')  
print('Naive: %fs' % (t1 - t0))  
print('Fast: %fs' % (t2 - t1))  
print('Speedup: %fx' % ((t1 - t0) / (t2 - t1)))  
print('Difference: ', rel_error(out_naive, out_fast))  
  
t0 = time()  
dx_naive, dw_naive, db_naive = conv_backward_naive(dout, cache_naive)  
t1 = time()  
dx_fast, dw_fast, db_fast = conv_backward_fast(dout, cache_fast)  
t2 = time()
```

```

print('\nTesting conv_backward_fast:')
print('Naive: %fs' % (t1 - t0))
print('Fast: %fs' % (t2 - t1))
print('Speedup: %fx' % ((t1 - t0) / (t2 - t1)))
print('dx difference: ', rel_error(dx_naive, dx_fast))
print('dw difference: ', rel_error(dw_naive, dw_fast))
print('db difference: ', rel_error(db_naive, db_fast))

```

```

Testing conv_forward_fast:
Naive: 2.016620s
Fast: 0.005313s
Speedup: 379.535000x
Difference: 1.970563140655889e-11

```

```

Testing conv_backward_fast:
Naive: 0.132157s
Fast: 0.004988s
Speedup: 26.496415x
dx difference: 2.0126604132612724e-11
dw difference: 1.9286070076381466e-13
db difference: 0.0

```

```

[15]: # Relative errors should be close to 0.0
from CV7062610.fast_layers import max_pool_forward_fast, max_pool_backward_fast
np.random.seed(231)
x = np.random.randn(100, 3, 32, 32)
dout = np.random.randn(100, 3, 16, 16)
pool_param = {'pool_height': 2, 'pool_width': 2, 'stride': 2}

t0 = time()
out_naive, cache_naive = max_pool_forward_naive(x, pool_param)
t1 = time()
out_fast, cache_fast = max_pool_forward_fast(x, pool_param)
t2 = time()

print('Testing pool_forward_fast:')
print('Naive: %fs' % (t1 - t0))
print('fast: %fs' % (t2 - t1))
print('speedup: %fx' % ((t1 - t0) / (t2 - t1)))
print('difference: ', rel_error(out_naive, out_fast))

t0 = time()
dx_naive = max_pool_backward_naive(dout, cache_naive)
t1 = time()
dx_fast = max_pool_backward_fast(dout, cache_fast)
t2 = time()

```

```

print('\nTesting pool_backward_fast:')
print('Naive: %fs' % (t1 - t0))
print('fast: %fs' % (t2 - t1))
print('speedup: %fx' % ((t1 - t0) / (t2 - t1)))
print('dx difference: ', rel_error(dx_naive, dx_fast))

```

Testing pool_forward_fast:

```

Naive: 0.102880s
fast: 0.002982s
speedup: 34.495883x
difference: 0.0

```

Testing pool_backward_fast:

```

Naive: 0.320316s
fast: 0.008308s
speedup: 38.554309x
dx difference: 0.0

```

8 Convolutional “sandwich” layers

Previously we introduced the concept of “sandwich” layers that combine multiple operations into commonly used patterns. In the file CV7062610/layer_utils.py you will find sandwich layers that implement a few commonly used patterns for convolutional networks. Run the cells below to sanity check they’re working.

```

[18]: from CV7062610.layer_utils import conv_relu_pool_forward,
      ↪ conv_relu_pool_backward
np.random.seed(231)
x = np.random.randn(2, 3, 16, 16)
w = np.random.randn(3, 3, 3, 3)
b = np.random.randn(3,)
dout = np.random.randn(2, 3, 8, 8)
conv_param = {'stride': 1, 'pad': 1}
pool_param = {'pool_height': 2, 'pool_width': 2, 'stride': 2}

out, cache = conv_relu_pool_forward(x, w, b, conv_param, pool_param)
dx, dw, db = conv_relu_pool_backward(dout, cache)

dx_num = eval_numerical_gradient_array(lambda x: conv_relu_pool_forward(x, w,
      ↪ b, conv_param, pool_param)[0], x, dout)
dw_num = eval_numerical_gradient_array(lambda w: conv_relu_pool_forward(x, w,
      ↪ b, conv_param, pool_param)[0], w, dout)
db_num = eval_numerical_gradient_array(lambda b: conv_relu_pool_forward(x, w,
      ↪ b, conv_param, pool_param)[0], b, dout)

# Relative errors should be around e-8 or less

```

```

print('Testing conv_relu_pool')
print('dx error: ', rel_error(dx_num, dx))
print('dw error: ', rel_error(dw_num, dw))
print('db error: ', rel_error(db_num, db))

```

```

Testing conv_relu_pool
dx error: 9.591132621921372e-09
dw error: 5.802391137330214e-09
db error: 1.0146343411762047e-09

```

```

[19]: from CV7062610.layer_utils import conv_relu_forward, conv_relu_backward
np.random.seed(231)
x = np.random.randn(2, 3, 8, 8)
w = np.random.randn(3, 3, 3, 3)
b = np.random.randn(3,)
dout = np.random.randn(2, 3, 8, 8)
conv_param = {'stride': 1, 'pad': 1}

out, cache = conv_relu_forward(x, w, b, conv_param)
dx, dw, db = conv_relu_backward(dout, cache)

dx_num = eval_numerical_gradient_array(lambda x: conv_relu_forward(x, w, b,
    ↪conv_param)[0], x, dout)
dw_num = eval_numerical_gradient_array(lambda w: conv_relu_forward(x, w, b,
    ↪conv_param)[0], w, dout)
db_num = eval_numerical_gradient_array(lambda b: conv_relu_forward(x, w, b,
    ↪conv_param)[0], b, dout)

# Relative errors should be around e-8 or less
print('Testing conv_relu:')
print('dx error: ', rel_error(dx_num, dx))
print('dw error: ', rel_error(dw_num, dw))
print('db error: ', rel_error(db_num, db))

```

```

Testing conv_relu:
dx error: 1.5218619980349303e-09
dw error: 2.702022646099404e-10
db error: 1.451272393591721e-10

```

9 Three-layer ConvNet

Now that you have implemented all the necessary layers, we can put them together into a simple convolutional network.

Open the file `CV7062610/classifiers/cnn.py` and complete the implementation of the `ThreeLayerConvNet` class. Remember you can use the `fast/sandwich` layers (already imported for you) in your implementation. Run the following cells to help you debug:

9.1 Sanity check loss

After you build a new network, one of the first things you should do is sanity check the loss. When we use the softmax loss, we expect the loss for random weights (and no regularization) to be about $\log(C)$ for C classes. When we add regularization the loss should go up slightly.

```
[36]: model = ThreeLayerConvNet()

N = 50
X = np.random.randn(N, 3, 32, 32)
y = np.random.randint(10, size=N)

loss, grads = model.loss(X, y)
print('Initial loss (no regularization): ', loss)

model.reg = 0.5
loss, grads = model.loss(X, y)
print('Initial loss (with regularization): ', loss)
```

```
Initial loss (no regularization): 2.302584690350579
Initial loss (with regularization): 2.5092338379067423
```

9.2 Gradient check

After the loss looks reasonable, use numeric gradient checking to make sure that your backward pass is correct. When you use numeric gradient checking you should use a small amount of artificial data and a small number of neurons at each layer. Note: correct implementations may still have relative errors up to the order of e^{-2} .

```
[37]: num_inputs = 2
input_dim = (3, 16, 16)
reg = 0.0
num_classes = 10
np.random.seed(231)
X = np.random.randn(num_inputs, *input_dim)
y = np.random.randint(num_classes, size=num_inputs)

model = ThreeLayerConvNet(num_filters=3, filter_size=3,
                           input_dim=input_dim, hidden_dim=7,
                           dtype=np.float64)

loss, grads = model.loss(X, y)
# Errors should be small, but correct implementations may have
# relative errors up to the order of e-2
for param_name in sorted(grads):
    f = lambda _: model.loss(X, y)[0]
    param_grad_num = eval_numerical_gradient(f, model.params[param_name],
    ↪ verbose=False, h=1e-6)
    e = rel_error(param_grad_num, grads[param_name])
```

```
print('%s max relative error: %e' % (param_name, rel_error(param_grad_num,
↪grads[param_name])))
```

```
W1 max relative error: 1.380104e-04
W2 max relative error: 1.822723e-02
W3 max relative error: 3.064049e-04
b1 max relative error: 3.477652e-05
b2 max relative error: 2.516375e-03
b3 max relative error: 7.945660e-10
```

9.3 Overfit small data

A nice trick is to train your model with just a few training samples. You should be able to overfit small datasets, which will result in very high training accuracy and comparatively low validation accuracy.

```
[39]: np.random.seed(231)

num_train = 100
small_data = {
    'X_train': data['X_train'][:num_train],
    'y_train': data['y_train'][:num_train],
    'X_val': data['X_val'],
    'y_val': data['y_val'],
}

model = ThreeLayerConvNet(weight_scale=1e-2)

solver = Solver(model, small_data,
                 num_epochs=35, batch_size=50,
                 update_rule='sgd',
                 optim_config={
                     'learning_rate': 1e-3,
                 },
                 verbose=True, print_every=1)
solver.train()

(Iteration 1 / 70) loss: 2.414060
(Epoch 0 / 35) train acc: 0.140000; val_acc: 0.076000
(Iteration 2 / 70) loss: 2.388208
(Epoch 1 / 35) train acc: 0.130000; val_acc: 0.075000
(Iteration 3 / 70) loss: 2.286111
(Iteration 4 / 70) loss: 2.280937
(Epoch 2 / 35) train acc: 0.190000; val_acc: 0.095000
(Iteration 5 / 70) loss: 2.156452
(Iteration 6 / 70) loss: 2.121301
(Epoch 3 / 35) train acc: 0.220000; val_acc: 0.102000
(Iteration 7 / 70) loss: 2.082505
```

(Iteration 8 / 70) loss: 2.132747
(Epoch 4 / 35) train acc: 0.240000; val_acc: 0.113000
(Iteration 9 / 70) loss: 1.974502
(Iteration 10 / 70) loss: 2.234853
(Epoch 5 / 35) train acc: 0.270000; val_acc: 0.115000
(Iteration 11 / 70) loss: 2.062134
(Iteration 12 / 70) loss: 1.967815
(Epoch 6 / 35) train acc: 0.270000; val_acc: 0.115000
(Iteration 13 / 70) loss: 2.151717
(Iteration 14 / 70) loss: 1.962033
(Epoch 7 / 35) train acc: 0.330000; val_acc: 0.131000
(Iteration 15 / 70) loss: 1.905878
(Iteration 16 / 70) loss: 1.981501
(Epoch 8 / 35) train acc: 0.420000; val_acc: 0.144000
(Iteration 17 / 70) loss: 2.000987
(Iteration 18 / 70) loss: 1.943681
(Epoch 9 / 35) train acc: 0.420000; val_acc: 0.137000
(Iteration 19 / 70) loss: 1.894658
(Iteration 20 / 70) loss: 1.798240
(Epoch 10 / 35) train acc: 0.390000; val_acc: 0.137000
(Iteration 21 / 70) loss: 1.930483
(Iteration 22 / 70) loss: 1.848953
(Epoch 11 / 35) train acc: 0.460000; val_acc: 0.160000
(Iteration 23 / 70) loss: 1.733071
(Iteration 24 / 70) loss: 1.833933
(Epoch 12 / 35) train acc: 0.520000; val_acc: 0.167000
(Iteration 25 / 70) loss: 1.759339
(Iteration 26 / 70) loss: 1.707899
(Epoch 13 / 35) train acc: 0.530000; val_acc: 0.171000
(Iteration 27 / 70) loss: 1.668286
(Iteration 28 / 70) loss: 1.632742
(Epoch 14 / 35) train acc: 0.510000; val_acc: 0.173000
(Iteration 29 / 70) loss: 1.493473
(Iteration 30 / 70) loss: 1.852287
(Epoch 15 / 35) train acc: 0.590000; val_acc: 0.177000
(Iteration 31 / 70) loss: 1.544719
(Iteration 32 / 70) loss: 1.445474
(Epoch 16 / 35) train acc: 0.620000; val_acc: 0.167000
(Iteration 33 / 70) loss: 1.438357
(Iteration 34 / 70) loss: 1.558215
(Epoch 17 / 35) train acc: 0.550000; val_acc: 0.181000
(Iteration 35 / 70) loss: 1.457353
(Iteration 36 / 70) loss: 1.430685
(Epoch 18 / 35) train acc: 0.640000; val_acc: 0.177000
(Iteration 37 / 70) loss: 1.417343
(Iteration 38 / 70) loss: 1.224349
(Epoch 19 / 35) train acc: 0.560000; val_acc: 0.182000
(Iteration 39 / 70) loss: 1.358695

(Iteration 40 / 70) loss: 1.459283
(Epoch 20 / 35) train acc: 0.620000; val_acc: 0.171000
(Iteration 41 / 70) loss: 1.324597
(Iteration 42 / 70) loss: 1.141805
(Epoch 21 / 35) train acc: 0.710000; val_acc: 0.176000
(Iteration 43 / 70) loss: 1.251012
(Iteration 44 / 70) loss: 1.255930
(Epoch 22 / 35) train acc: 0.740000; val_acc: 0.183000
(Iteration 45 / 70) loss: 1.265682
(Iteration 46 / 70) loss: 1.241632
(Epoch 23 / 35) train acc: 0.800000; val_acc: 0.182000
(Iteration 47 / 70) loss: 1.088461
(Iteration 48 / 70) loss: 1.286929
(Epoch 24 / 35) train acc: 0.790000; val_acc: 0.187000
(Iteration 49 / 70) loss: 1.043943
(Iteration 50 / 70) loss: 1.232451
(Epoch 25 / 35) train acc: 0.830000; val_acc: 0.186000
(Iteration 51 / 70) loss: 1.166305
(Iteration 52 / 70) loss: 0.992921
(Epoch 26 / 35) train acc: 0.810000; val_acc: 0.183000
(Iteration 53 / 70) loss: 1.027397
(Iteration 54 / 70) loss: 1.034611
(Epoch 27 / 35) train acc: 0.870000; val_acc: 0.191000
(Iteration 55 / 70) loss: 1.074365
(Iteration 56 / 70) loss: 0.884611
(Epoch 28 / 35) train acc: 0.790000; val_acc: 0.180000
(Iteration 57 / 70) loss: 1.045844
(Iteration 58 / 70) loss: 0.771730
(Epoch 29 / 35) train acc: 0.850000; val_acc: 0.188000
(Iteration 59 / 70) loss: 0.964063
(Iteration 60 / 70) loss: 0.919592
(Epoch 30 / 35) train acc: 0.840000; val_acc: 0.190000
(Iteration 61 / 70) loss: 0.898468
(Iteration 62 / 70) loss: 0.837345
(Epoch 31 / 35) train acc: 0.890000; val_acc: 0.194000
(Iteration 63 / 70) loss: 0.866577
(Iteration 64 / 70) loss: 0.730397
(Epoch 32 / 35) train acc: 0.850000; val_acc: 0.188000
(Iteration 65 / 70) loss: 0.562069
(Iteration 66 / 70) loss: 0.911381
(Epoch 33 / 35) train acc: 0.910000; val_acc: 0.179000
(Iteration 67 / 70) loss: 0.662602
(Iteration 68 / 70) loss: 0.702882
(Epoch 34 / 35) train acc: 0.920000; val_acc: 0.182000
(Iteration 69 / 70) loss: 0.514115
(Iteration 70 / 70) loss: 0.786051
(Epoch 35 / 35) train acc: 0.900000; val_acc: 0.200000

```
[40]: # Print final training accuracy
print(
    "Small data training accuracy:",
    solver.check_accuracy(small_data['X_train'], small_data['y_train'])
)
```

Small data training accuracy: 0.9

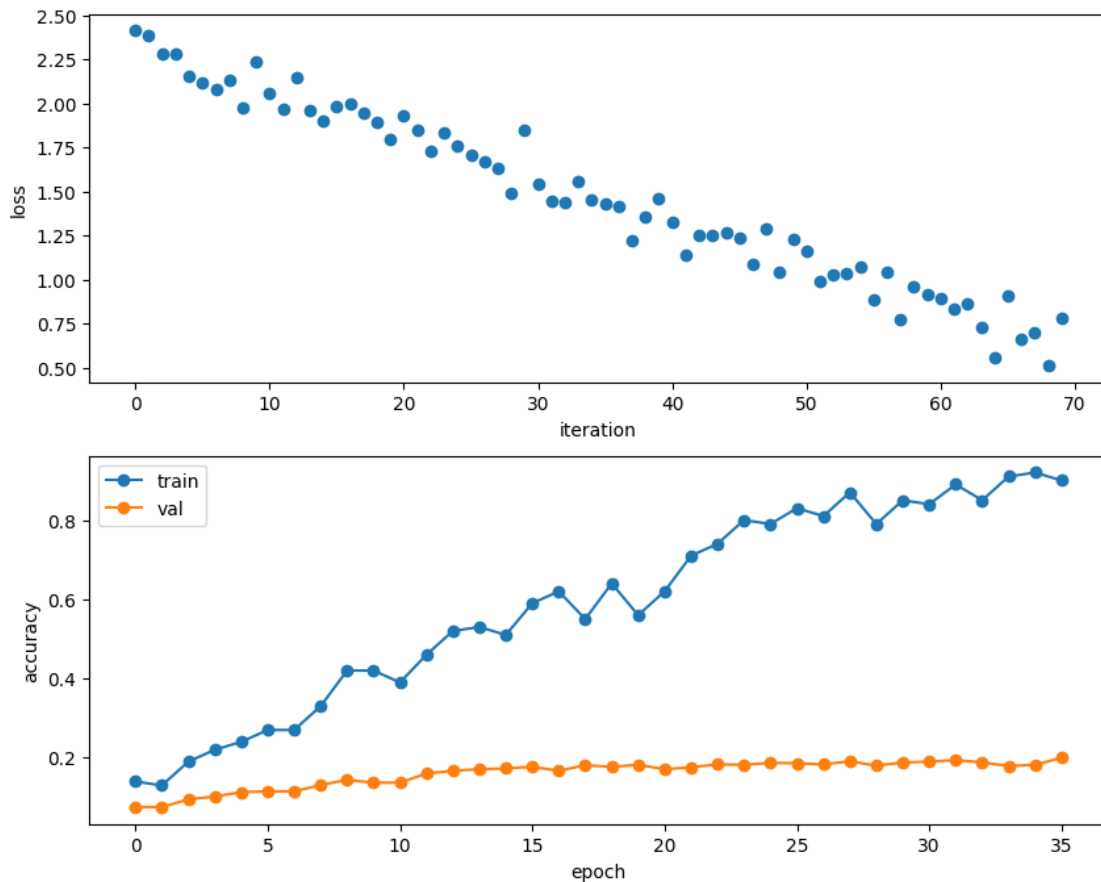
```
[41]: # Print final validation accuracy
print(
    "Small data validation accuracy:",
    solver.check_accuracy(small_data['X_val'], small_data['y_val'])
)
```

Small data validation accuracy: 0.2

Plotting the loss, training accuracy, and validation accuracy should show clear overfitting:

```
[42]: plt.subplot(2, 1, 1)
plt.plot(solver.loss_history, 'o')
plt.xlabel('iteration')
plt.ylabel('loss')

plt.subplot(2, 1, 2)
plt.plot(solver.train_acc_history, '-o')
plt.plot(solver.val_acc_history, '-o')
plt.legend(['train', 'val'], loc='upper left')
plt.xlabel('epoch')
plt.ylabel('accuracy')
plt.show()
```



9.4 Train the net

By training the three-layer convolutional network for one epoch, you should achieve greater than 30% accuracy on the training set with `sgd`, it should take 6 minutes. In the next part when we will learn other optimization techniques we will get better accuracy in the same amount of time:

```
[43]: model = ThreeLayerConvNet(weight_scale=0.001, hidden_dim=500, reg=0.001)

solver = Solver(model, data,
                num_epochs=1, batch_size=50,
                update_rule='sgd',
                optim_config={
                    'learning_rate': 1e-3,
                },
                verbose=True, print_every=20)
solver.train()
```

```
(Iteration 1 / 980) loss: 2.304876
```

```
(Epoch 0 / 1) train acc: 0.083000; val_acc: 0.086000
```

```
(Iteration 21 / 980) loss: 2.304521
```

(Iteration 41 / 980) loss: 2.304424
(Iteration 61 / 980) loss: 2.304157
(Iteration 81 / 980) loss: 2.304181
(Iteration 101 / 980) loss: 2.303648
(Iteration 121 / 980) loss: 2.302706
(Iteration 141 / 980) loss: 2.303352
(Iteration 161 / 980) loss: 2.301611
(Iteration 181 / 980) loss: 2.298818
(Iteration 201 / 980) loss: 2.293071
(Iteration 221 / 980) loss: 2.285592
(Iteration 241 / 980) loss: 2.272385
(Iteration 261 / 980) loss: 2.244782
(Iteration 281 / 980) loss: 2.208467
(Iteration 301 / 980) loss: 2.050966
(Iteration 321 / 980) loss: 2.058296
(Iteration 341 / 980) loss: 2.258100
(Iteration 361 / 980) loss: 2.037670
(Iteration 381 / 980) loss: 1.991332
(Iteration 401 / 980) loss: 1.982192
(Iteration 421 / 980) loss: 1.943203
(Iteration 441 / 980) loss: 2.018387
(Iteration 461 / 980) loss: 2.059734
(Iteration 481 / 980) loss: 1.910822
(Iteration 501 / 980) loss: 1.942802
(Iteration 521 / 980) loss: 1.786348
(Iteration 541 / 980) loss: 2.038088
(Iteration 561 / 980) loss: 1.912679
(Iteration 581 / 980) loss: 1.921920
(Iteration 601 / 980) loss: 1.987053
(Iteration 621 / 980) loss: 1.979135
(Iteration 641 / 980) loss: 1.866771
(Iteration 661 / 980) loss: 1.710859
(Iteration 681 / 980) loss: 2.107062
(Iteration 701 / 980) loss: 1.754281
(Iteration 721 / 980) loss: 1.917319
(Iteration 741 / 980) loss: 2.004374
(Iteration 761 / 980) loss: 1.546441
(Iteration 781 / 980) loss: 1.817538
(Iteration 801 / 980) loss: 1.697297
(Iteration 821 / 980) loss: 1.391700
(Iteration 841 / 980) loss: 1.776255
(Iteration 861 / 980) loss: 1.777225
(Iteration 881 / 980) loss: 1.706812
(Iteration 901 / 980) loss: 1.600886
(Iteration 921 / 980) loss: 1.496853
(Iteration 941 / 980) loss: 1.674209
(Iteration 961 / 980) loss: 1.514064
(Epoch 1 / 1) train acc: 0.402000; val_acc: 0.417000

```
[44]: # Print final training accuracy
print(
    "Full data training accuracy:",
    solver.check_accuracy(small_data['X_train'], small_data['y_train'])
)
```

Full data training accuracy: 0.34

```
[45]: # Print final validation accuracy
print(
    "Full data validation accuracy:",
    solver.check_accuracy(data['X_val'], data['y_val'])
)
```

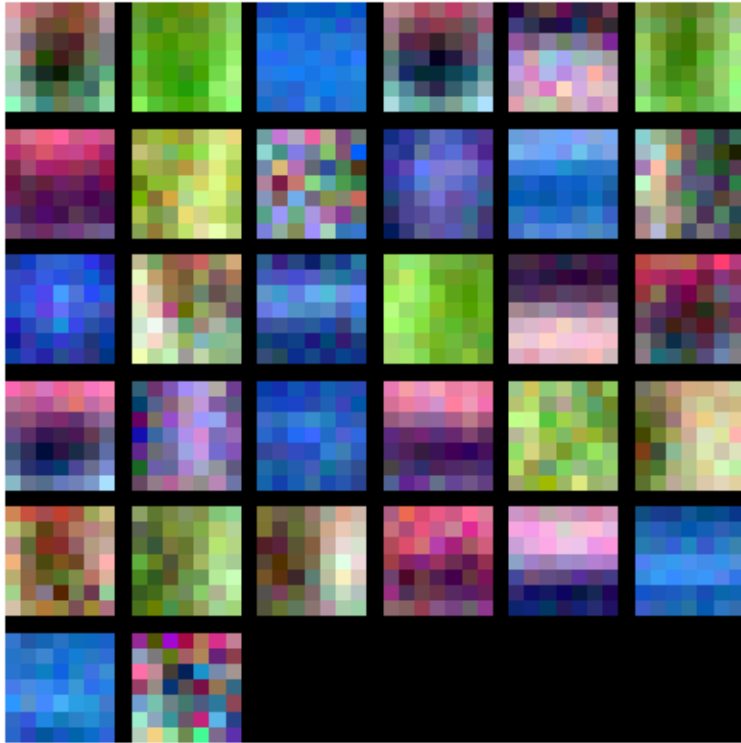
Full data validation accuracy: 0.417

9.5 Visualize Filters

You can visualize the first-layer convolutional filters from the trained network by running the following:

```
[46]: from CV7062610.vis_utils import visualize_grid

grid = visualize_grid(model.params['W1'].transpose(0, 2, 3, 1))
plt.imshow(grid.astype('uint8'))
plt.axis('off')
plt.gcf().set_size_inches(5, 5)
plt.show()
```

[]: