



CSC380: Principles of Data Science

Probability Primer 5

Today:

- Expectation
- Variance
- Covariance
- Correlation

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Credit:

- Jason Pacheco,
- Kwang-Sung Jun,
- Chicheng Zhang
- Xincheng yu

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Review: Continuous Probability

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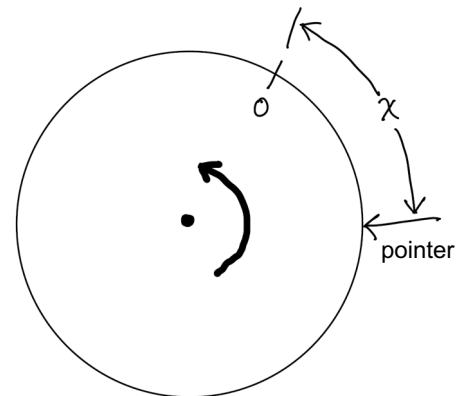
Experiment Spin continuous wheel and measure X displacement from 0

Say the circumference is 1.

Outcome space Ω is all points (real numbers) in $(0,1]$

Question Assuming uniform distribution,
what is $P(X = x)$?

A much better question: What is $P(X \leq x)$.
(that is, that the wheel reached at most x .
Examples $P(X \leq 0.5)$



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Review: Continuous Random Variable

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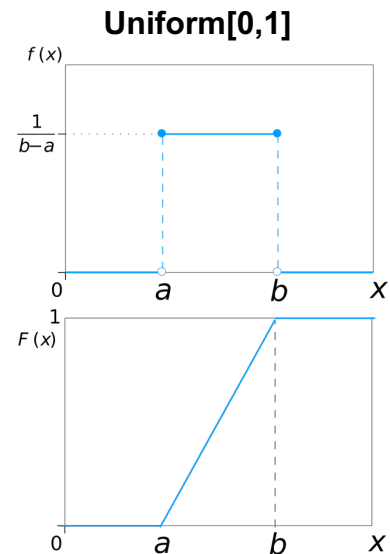
- Probability can be assigned to intervals
- Define CDF: $F(x) := P(X \leq x)$
- Then, PDF: $f(x) := p(X = x) := F'(x)$ // the slope at $F(x)$
- $P(X \in [a, b]) = F(b) - F(a)$ // area under the PDF curve

Another viewpoint

- A continuous distribution is defined by PDF $f(x)$ whose area under the curve is 1
- Then, we can compute $P(X \in [a, b])$ by computing the area under the curve on $[a, b]$.

Note:

$$P(X \in [a, b]) = P(X \in (a, b]) = P(X \in [a, b)) = P(X \in (a, b))$$



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Review: Continuous Random Variable

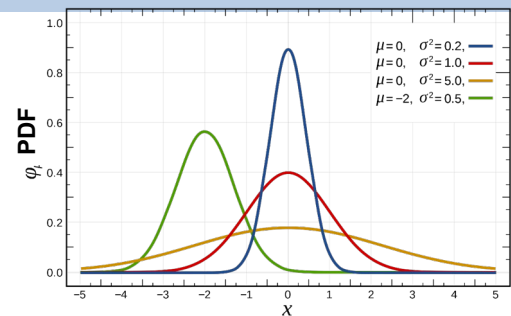
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Gaussian (a.k.a. Normal) distribution with mean (location) μ and variance (scale) σ^2 parameters,

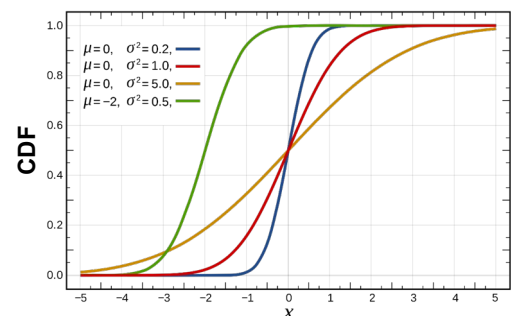
$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$$

Compactly, $X \sim \mathcal{N}(\mu, \sigma^2)$

Probability
Density
function



Cumulative
Distribution
Function



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Outline

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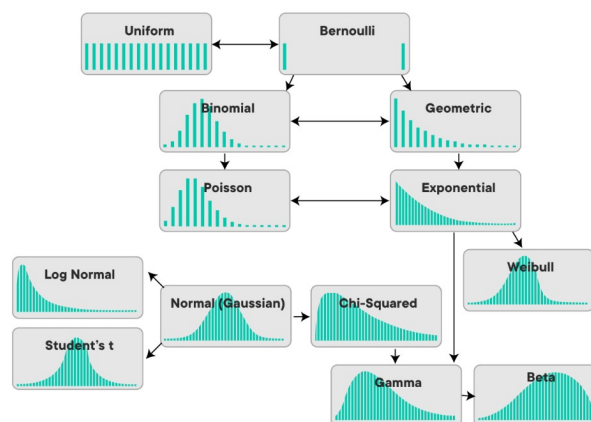
- Expectation
- Variance
- Covariance
- Correlation

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Moments of Random Variables

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Q: How to describe characteristics of different distributions?



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Moments of Random Variables

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Properties of a RV are characterized by its distribution / PMF / PDF
 But there are “summary” numbers capturing important characteristics
 This is called “**moments**”.

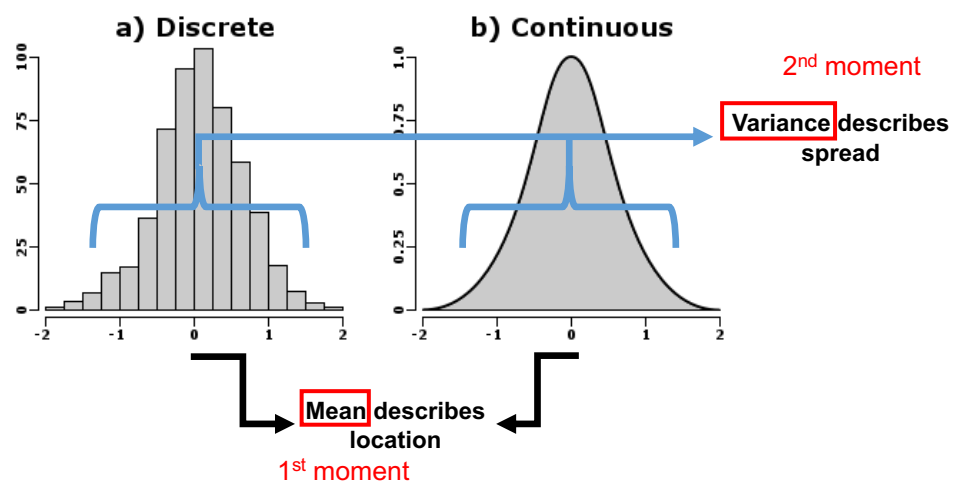
Moment ordinal	Moment			Cumulant	
	Raw	Central	Standardized	Raw	Normalized
1	Mean	0	0	Mean	N/A
2	–	Variance	1	Variance	1

(Wikipedia)

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Moments of Random Variables

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Moments characterize properties of the distribution “shape”

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Expectation

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Expectation: a game-theoretic viewpoint

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- Consider the following game:
 - Flip an unfair coin X with PMF
 - If $X = 1$, you receive \$1
 - If $X = -1$, you lose \$1

outcome	prob.
$X = 1$	0.7
$X = -1$	0.3

- How much are you willing to pay to play the game?
 - As long as you pay $\leq \$0.4$ per game, your wealth will not decrease in the long run
 - 'value of the game' = \$0.4



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Mean = Expectation = Expected Value

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Definition The expectation of a discrete RV X , denoted by $E[X]$, is:

(with PMF)

$$E[X] = \sum_x x \cdot p(X = x)$$

Probability Mass Function

Summation over all values in domain of X

- **Effectively, a weighted average:** each outcome weighted by probability of occurring

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Expected Value

Let X = sum of two dice, probability of S on different values:

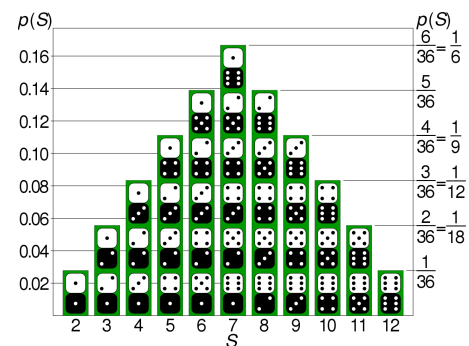
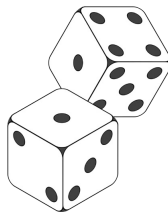
$$P(X = 2) = 1/36$$

$$P(X = 3) = 2/36$$

$$P(X = 4) = 3/36$$

$$\dots$$

$$P(X = 12) = 1/36$$



Q: $E[X]$?

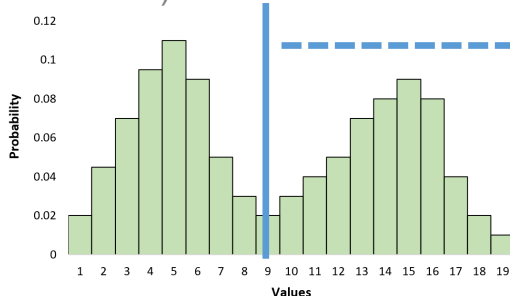
$$2 \cdot \frac{1}{36} + 3 \cdot \frac{2}{36} + \dots + 6 \cdot \frac{5}{36} + 7 \cdot \frac{6}{36} + 8 \cdot \frac{5}{36} + \dots + 12 \cdot \frac{1}{36} = 7$$

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Expected Value

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(discrete RV)



Expected value is not always a high probability event...

...in fact, it may not even be a feasible value...

Example Let X be the outcome of a fair die, then:

$$\mathbf{E}[X] = \frac{1}{6} \cdot (1 + 2 + 3 + 4 + 5 + 6) = 3.5$$

Can't actually roll 3.5

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Expected Value

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Theorem (Linearity of Expectations) For any finite collection of discrete RVs X_1, X_2, \dots, X_N with finite expectations,

$$\mathbf{E} \left[\sum_{i=1}^N X_i \right] = \sum_{i=1}^N \mathbf{E}[X_i]$$

E.g. for two RVs X and Y
 $\mathbf{E}[X + Y] = \mathbf{E}[X] + \mathbf{E}[Y]$

you do not need an independence!

Example Throw two fair dice. What is the expected sum? Let X and Y be the outcome of the first and second die, respectively.

$$\mathbf{E}[X + Y] = \mathbf{E}[X] + \mathbf{E}[Y] = 3.5 + 3.5 = 7$$

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Expected Value

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Proof: $E[X + Y] = E[X] + E[Y]$

$$\sum_{i=1}^3 \sum_{j=1}^2 a_{ij} = \sum_{i=1}^3 (a_{i1} + a_{i2}) = (a_{11} + a_{12}) + (a_{21} + a_{22}) + (a_{31} + a_{32}).$$

$$E[X + Y] = \sum_i \sum_j (i + j) p(X = i, Y = j)$$

Sum is linear operator

$$= \sum_i \sum_j i \cdot p(X = i, Y = j) + \sum_i \sum_j j \cdot p(X = i, Y = j)$$

Sum is linear operator

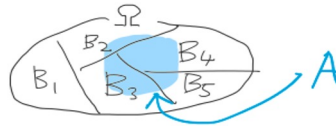
$$= \sum_i i \sum_j p(X = i, Y = j) + \sum_j j \sum_i p(X = i, Y = j)$$

Law of Total Probability

$$= \sum_i i \cdot p(X = i) + \sum_j j \cdot p(Y = j)$$

By definition of Expectation

$$= E[X] + E[Y]$$



Sum of Summations

$$\sum_{i=1}^n x_i + \sum_{i=1}^n y_i = \sum_{i=1}^n (x_i + y_i)$$

Scaling of Summations

$$\lambda \sum_{i=1}^n x_i = \sum_{i=1}^n \lambda x_i$$

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Expected Value

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Theorem For any random variable X and constant c ,

$$\begin{aligned} E[cX] &= cE[X] \\ E[cX + k] &= cE[X] + k \\ E[k] &= k \end{aligned}$$

Caveat: k has to be a constant, not a random variable!

Example Throw two fair dice twice, X : outcome of 1st die, Y : outcome of 2nd die. The expected sum:

$$\begin{aligned} E[2(X + Y)] &= E[2X] + E[2Y] \\ &= 2E[X] + 2E[Y] \\ &= 2 \cdot 3.5 + 2 \cdot 3.5 = 14 \end{aligned}$$

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Conditional Expected Value

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Definition The conditional expectation of a discrete RV X , given Y is:

$$\mathbf{E}[X \mid Y = y] = \sum_x x p(X = x \mid Y = y) \quad \text{cf. } \mathbf{E}[X] = \sum_x x \cdot p(X = x)$$

Example Roll two fair dice. X_1 : first die outcome, Y : sum of two dice is 5

$$\begin{aligned} \mathbf{E}[X_1 \mid Y = 5] &= \sum_{x=1}^4 x p(X_1 = x \mid Y = 5) && \text{quiz candidate} \\ &= \sum_{x=1}^4 x \frac{p(X_1 = x, Y = 5)}{p(Y = 5)} = \sum_{x=1}^4 x \frac{1/36}{4/36} = \frac{5}{2} \end{aligned}$$

Conditional expectation follows properties of expectation (linearity, etc.)

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Variance

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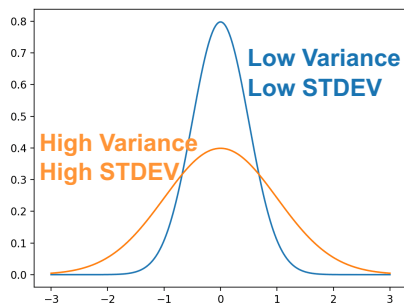
Variance and Standard Deviation

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Definition The variance of a RV X is defined as,

$$\text{Var}[X] = \mathbf{E}[(X - \mathbf{E}[X])^2] = E[(X - \mu)^2], \quad \text{when } \mu = E[X]$$

The standard deviation (STDEV) is $\sigma[X] = \sqrt{\text{Var}[X]}$.



- Describes the “spread” of a distribution
- Describes uncertainty of outcome
- STDEV is in original units (more intuitive), variance is in units²
- Variance is more mathematically useful than STDEV

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Variance

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Example Let X be the outcome of a fair SEVEN-sided die.

The expected value is $E(X) = (1+2+3+4+5+6+7)/7 = 28/7 = 4$

$$\text{Var}[X] = \mathbf{E}[(X - \mathbf{E}[X])^2]$$

The values of $X - E(X)$ are $\{-3, -2, -1, 0, 1, 2, 3\}$

$Y = (X - E(X))^2 = (9, 4, 1, 0, 1, 4, 9)$ ←

$\text{Var}(X) = E(Y) = 9p(Y=9) + 4p(Y=4) + 1p(Y=1) + 0p(Y=0) = 4$

and $\text{STDEV}(X) = \sqrt{4} = 2$

The STDEV is 2, so we should expect outcomes to vary around the mean of 4 by ± 2

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Variance

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Lemma An equivalent form of variance is:

$$E[2XE[X]] = 2E[XE[X]] = 2E[X]E[X]$$

$E[X]$ is a constant

$$\text{Var}[X] = E[X^2] - (E[X])^2$$

Proof

$$E[(X - E[X])^2] = E[X^2 - 2XE[X] + E[X]^2] \quad (\text{Expand it})$$

$$= E[X^2] - 2E[X]E[X] + E[X]^2 \quad (\text{Linearity of expectations})$$

$$= E[X^2] - 2E[X]^2 + E[X]^2 \quad (\text{Algebra})$$

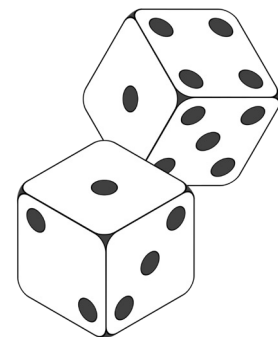
$$= E[X^2] - E[X]^2 \quad (\text{Algebra})$$

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Variance

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Example General form of variance for a fair n-sided fair die,



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Variance

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- If c is a constant, $\text{Var}[cX] = c^2 \text{Var}[X]$
 - Exercise: try to convince yourself why this is true
 - Hint: use $\mathbf{E}[cX] = c\mathbf{E}[X]$

$$\text{Var}[X] = \mathbf{E}[X^2] - (\mathbf{E}[X])^2$$

$$\begin{aligned} \text{Var}[cX] &= \mathbf{E}[(cX)^2] - (\mathbf{E}[cX])^2 \\ &= \mathbf{E}[c^2 X^2] - (c\mathbf{E}[X])^2 \\ &= c^2 \mathbf{E}[X^2] - c^2 \mathbf{E}[X]^2 \\ &= c^2 (\mathbf{E}[X^2] - \mathbf{E}[X]^2) \end{aligned}$$

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Moments of Useful Discrete Distributions

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Bernoulli A.k.a. the **coinflip** distribution on binary RVs $X \in \{0, 1\}$

$$p(X) = \pi^X (1 - \pi)^{(1-X)}$$

$$\text{Var}[X] = \mathbf{E}[X^2] - (\mathbf{E}[X])^2$$

Where π is the probability of **success** (i.e., heads), and also the mean

$$\mathbf{E}[X] = \pi \cdot 1 + (1 - \pi) \cdot 0 = \pi$$

$$\text{Var}[X] = \pi(1 - \pi)$$

$$\mathbf{E}[X^2] = \pi \cdot 1^2 + (1 - \pi) \cdot 0^2 = \pi$$

$$\text{Var}[X] = \pi - \pi^2$$



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Covariance – warm up

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Assume $E[X] = E[Y] = 0$

We define in this case

$$\text{Cov}(X, Y) = E[X \cdot Y] = \sum_i \sum_j x_i \cdot y_j \cdot p(X = x_i, Y = y_j)$$

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Covariance

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Definition The covariance of two RVs X and Y is defined as,

$$\text{Cov}(X, Y) = \mathbf{E}[(X - \mathbf{E}[X])(Y - \mathbf{E}[Y])]$$

Question What is $\text{Cov}(X, X)$?

Answer $\text{Cov}(X, X) = \text{Var}(X)$

In the case of discrete vars

$$\text{Cov}(X, Y) = \sum_i \sum_j (x_i - \mu_x)(y_i - \mu_y) \cdot p(X = x_i, Y = y_i)$$

Where $\mu_x = E(X)$, $\mu_y = E(Y)$

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Covariance

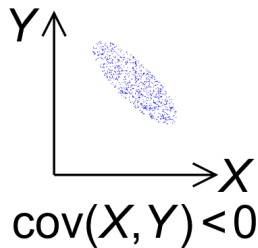
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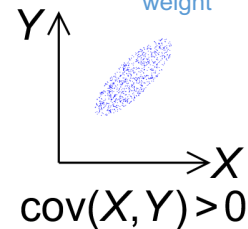
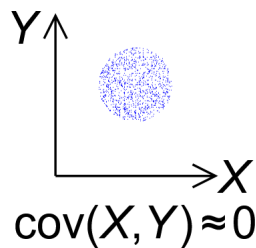
$$\text{Cov}(X, Y) = \mathbf{E}[(X - \mathbf{E}[X])(Y - \mathbf{E}[Y])]$$

Measures the linear relationship between X and Y

Example: height vs weight



Negative relationship



Positive relationship

If we are given a set of points $\{(x_1, y_1) \dots (x_n, y_n)\}$ and pick from with uniform probability $1/n$, then

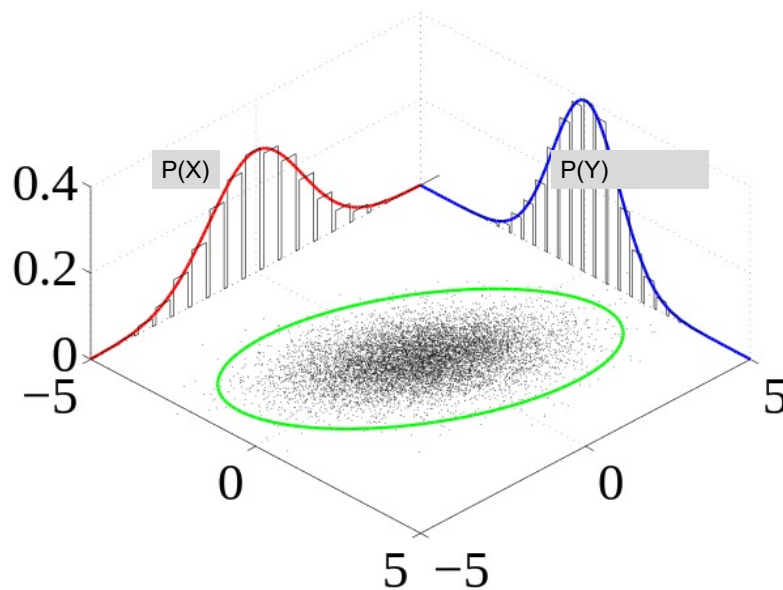
$$\text{cov}(X, Y) = \frac{1}{n} \sum_{i=1}^n (x_i - E(X))(y_i - E(Y)).$$

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Joint Probability Mass distribution $p(X, Y)$

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• Credit: Wiki



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Properties

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Credit: wikipedia

$$\text{cov}(X, a) = 0$$

$$\text{cov}(X, X) = \text{var}(X)$$

$$\text{cov}(X, Y) = \text{cov}(Y, X)$$

$$\text{cov}(aX, bY) = ab \text{ cov}(X, Y)$$

$$\text{cov}(X + a, Y + b) = \text{cov}(X, Y)$$

$$|\text{cov}(X, Y)| \leq \sqrt{\sigma^2(X)\sigma^2(Y)}$$

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Covariance

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- A shortcut to compute covariance.
- $\text{Cov}(X, Y) = E[(X - E[X])(Y - E[Y])]$

$$= E[XY - X \cdot E[Y] - Y \cdot E[X] + E[X]E[Y]]$$

$$= E[XY] - E[X]E[Y] - E[Y]E[X] + E[X]E[Y]$$

$$= E[XY] - E[X]E[Y]$$
- Safety check: $\text{Cov}(X, X) = E[XX] - E[X]E[X] = \text{Var}(X)$

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Covariance

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Lemma For any two RVs X and Y ,

$$\text{Var}[X] = \mathbf{E}[(X - \mathbf{E}[X])^2]$$

$$\text{Var}[X + Y] = \text{Var}[X] + \text{Var}[Y] + 2\text{Cov}(X, Y)$$

=> variance is not a linear operator.

Proof $\text{Var}[X + Y] = \mathbf{E}[(X + Y - \mathbf{E}[X + Y])^2]$

(Linearity of expt.) $= \mathbf{E}[(X + Y - \mathbf{E}[X] - \mathbf{E}[Y])^2]$

(Distributive property) $= \mathbf{E}[(X - \mathbf{E}[X])^2 + (Y - \mathbf{E}[Y])^2 + 2(X - \mathbf{E}[X])(Y - \mathbf{E}[Y])]$

(Linearity of expt.) $= \mathbf{E}[(X - \mathbf{E}[X])^2] + \mathbf{E}[(Y - \mathbf{E}[Y])^2] + 2\mathbf{E}[(X - \mathbf{E}[X])(Y - \mathbf{E}[Y])]$

(Definition of Var / Cov) $= \text{Var}[X] + \text{Var}[Y] + 2\text{Cov}(X, Y)$

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Covariance

$$\text{Cov}(X, Y) = E[XY] - E[X]E[Y]$$



Person_1	1	1
Person_2	3	0
Person_3	-1	-1
Expectation	$E[A]$	$E[B]$

$$\begin{bmatrix} \text{Cov}(A, A) & \text{Cov}(A, B) \\ \text{Cov}(B, A) & \text{Cov}(B, B) \end{bmatrix} = \begin{bmatrix} \text{Var}(A) & \\ & \text{Var}(B) \end{bmatrix}$$

$$E[A] = \frac{1}{3} \cdot 1 + \frac{1}{3} \cdot 3 + \frac{1}{3} \cdot (-1) = 1, \quad E[B] = 0$$

$$\begin{aligned} \text{Cov}(A, B) &= \text{Cov}(B, A) \\ &= E[AB] - E[A]E[B] \\ &= E[AB] - 0 \\ &= \frac{1}{3} \cdot 1 + \frac{1}{3} \cdot 0 + \frac{1}{3} \cdot 1 = \frac{2}{3} \end{aligned}$$

$$\begin{aligned} \text{Cov}(A, A) &= E[A^2] - (E[A])^2 \\ &= \left(\frac{1}{3} \cdot 1 + \frac{1}{3} \cdot 9 + \frac{1}{3} \cdot 1 \right) - 1 \\ &= \frac{8}{3} \end{aligned}$$

$$\begin{aligned} \text{Cov}(B, B) &= E[B^2] - (E[B])^2 \\ &= \left(\frac{1}{3} \cdot 1 + \frac{1}{3} \cdot 0 + \frac{1}{3} \cdot 1 \right) - 0 \\ &= \frac{2}{3} \end{aligned}$$

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Correlation

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Definition The correlation of two RVs X and Y is given by,

$$\text{Corr}(X, Y) = \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y} \quad \text{where} \quad \sigma_X = \sqrt{\text{Var}(X)}$$

Normalized version of covariance!

⇒ Always between -1 and 1

Useful when you are interested in how X and Y are related, independent of the individual variability.

⇒ $\text{Cov}(cX, dY) \neq \text{Cov}(X, Y)$ **but** $\text{Corr}(cX, dY) = \text{Corr}(X, Y)$

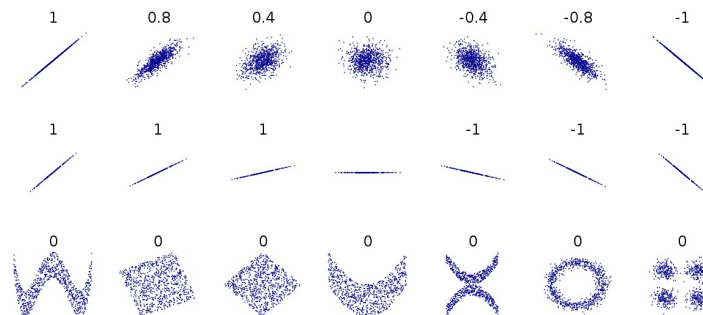
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Correlation

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Like covariance, only expresses linear relationships!

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