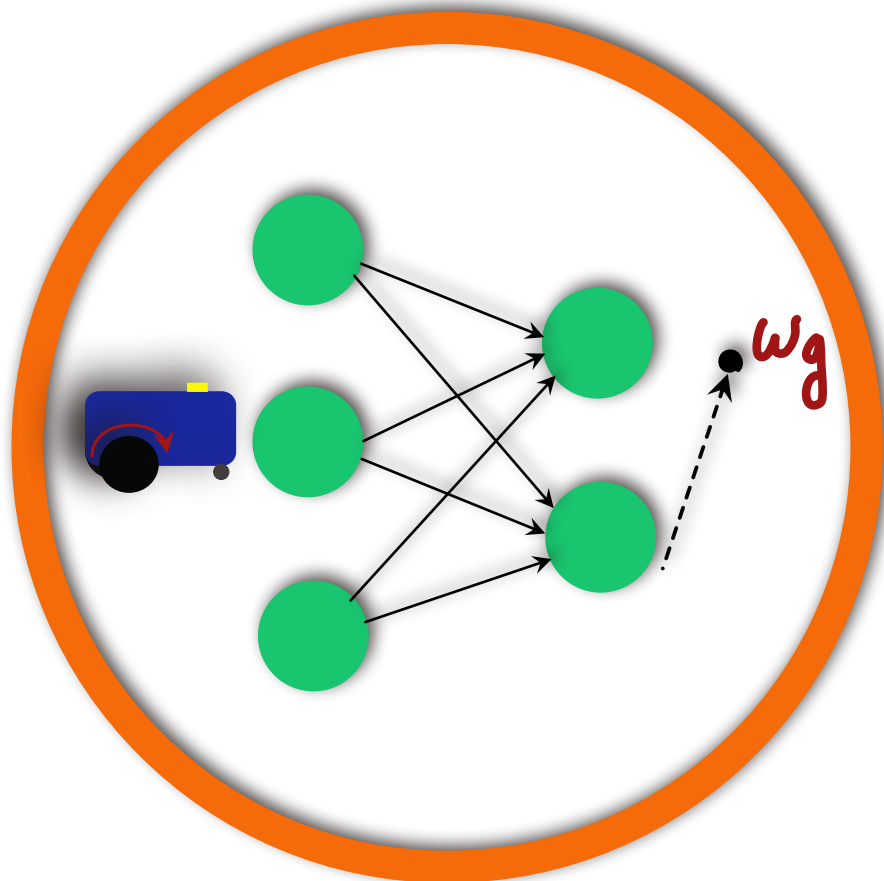


# Move the robot



Forward model



Inverse model

