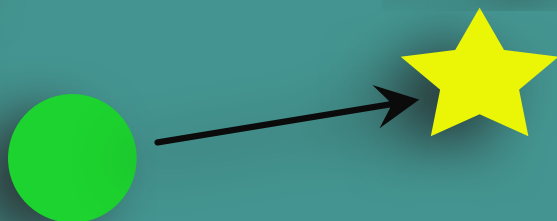


**Movable
obstacle**

A goal



**Static
obstacle**



LIDAR

The robot

