

[CSE4152] 고급소프트웨어 실습 I Week 13

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GPGPU(General-Purpose Computing on GPU)



- "General-purpose computing on graphics processing units (GPGPU) is the means of using a graphics processing unit (GPU), which typically handles computation only for computer graphics, to perform computation in applications traditionally handled by the central processing unit(CPU)." (from Wikipedia)
- 최근 그래픽스 프로세서는 massively-parallel streaming processing을 위한 프로세서로서 비약할 만한 성능 향상을 이루었으며, 그러한 추세는 계속될 것으로 예상됨.
 - "A *stream* is simply a set of records that require similar computation. Streams provide SIMD parallelism. *Kernels* are the functions that are applied to each element in the stream." (*from Wikipedia*)
- 최근 GPU의 놀라운 성능 향상으로 인하여 그래픽스 분야의 문제 뿐만 아니라 "compute-intensive data-parallel" 성질을 가지는 **일반 응용** 문제를 해결하는데 유용하게 쓰이고 있음.

NVIDIA Graphics Processing Units



Turing Architecture (2018)

- Chips: TU102, TU104, TU106, TU116, TU117
- Graphics card: GeForce 16/20 series
 - GeForce RTX 2080 Ti with 4,352 CUDA cores (max 13.45 TFLOPS)
- CUDA cores/Ray Tracing cores/Tensor cores
- CUDA Compute Capability: 7.5

Ampere Architecture (2020)

- Chips: GA100, GA102, GA104
- Graphics card: GeForce 30 series
 - GeForce RTX 3090 with **10,496 CUDA cores** (max **35.68 TFLOPS**)
- CUDA cores/Ray Tracing cores/Tensor cores
- CUDA Compute Capability: 8.0/8.6

Supercomputer와 성능 비교: FLOPS (FLoating-point OPerations per Second)



1993	Thinking Machines CM-5/1024	65.5 GFLOPS	DoE-Los Alamos National Laboratory; National Security Agency
	Fujitsu Numerical Wind Tunnel	124.50 GFLOPS	National Aerospace Laboratory, Tokyo, Japan
	Intel Paragon XP/S 140	143.40 GFLOPS	DoE-Sandia National Laboratories, New Mexico, USA
1994	Fujitsu Numerical Wind Tunnel	170.40 GFLOPS	National Aerospace Laboratory, Tokyo, Japan
1996	Hitachi SR2201/1024	220.4 GFLOPS	University of Tokyo, Japan
	Hitachi/Tsukuba CP-PACS/2048	368.2 GFLOPS	Center for Computational Physics, University of Tsukuba, Tsukuba, Japan
1997	Intel ASCI Red/9152	1.338 TFLOPS	DoE-Sandia National Laboratories, New Mexico, USA
1999	Intel ASCI Red/9632	2.3796 TFLOPS	
2000	IBM ASCI White	7.226 TFLOPS	DoE-Lawrence Livermore National Laboratory, California, USA
2002	NEC Earth Simulator	35.86 TFLOPS	Earth Simulator Center, Yokohama, Japan

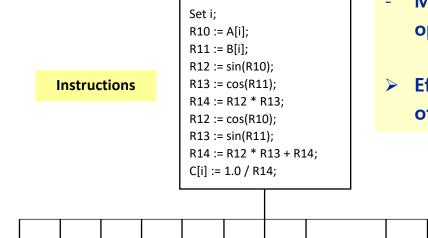
SIMD (Single Instruction, Multiple Data)



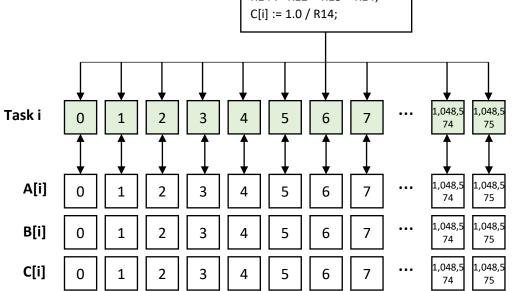
```
#define MAX_N_ELEMENTS 1048576 // pow(2,20)
void combine_two_arrays(float *x, float *y, float *z, int n) {
 int i;
 for (i = 0; i < n; i++) {
  z[i] = 1.0f/(\sin(x[i])*\cos(y[i]) + \cos(x[i])*\sin(y[i]));
                                            동일한 방식의 계산이 서로 다른 데이터에 대하여 반복이 되고 있음.
                                            각 데이터에 대한 계산은 서로 독립적임.
void main(void) {
                                            만약 프로세서가 MAX N ELEMENTS개만큼 있다면, ...
 int n_elements;
 float A[MAX_N_ELEMENTS], B[MAX_N_ELEMENTS], C[MAX_N_ELEMENTS];
 n_elements = MAX_N_ELEMENTS;
 combine_two_arrays(A, B, C, n_elements);
                                                x[i]x
                                                                                                    1,048,
                                                y[i]
                                                                                               1,048,
                                                                                                    1,048,
                                                z[i]
                                                                                               1.048.
                                                                                                    1.048.
                                                                                                     575
```

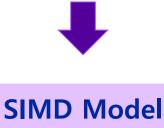
- 동일한 프로그램의 명령어들을 순차적으로 ← Single Instruction Stream
- 서로 다른 데이터 스트림에 대하여 ← Multiple Data
 Stream
- 동기화하면서 수행(run in lockstep)하면서 계산하면,

 $z[i] = 1.0f/(\sin(x[i])*\cos(y[i]) + \cos(x[i])*\sin(y[i]));$



- Multiple processing elements perform the same operation on multiple data points simultaneously.
- Effective graphics/multimedia computations and others.





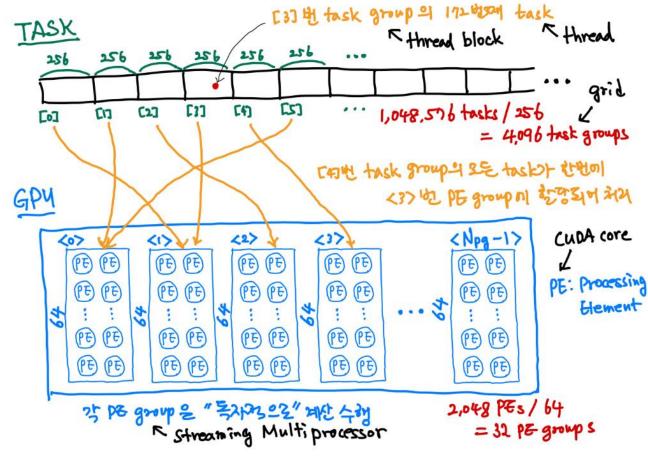
An execution model in parallel computing

개략적인 GPU 처리 구조

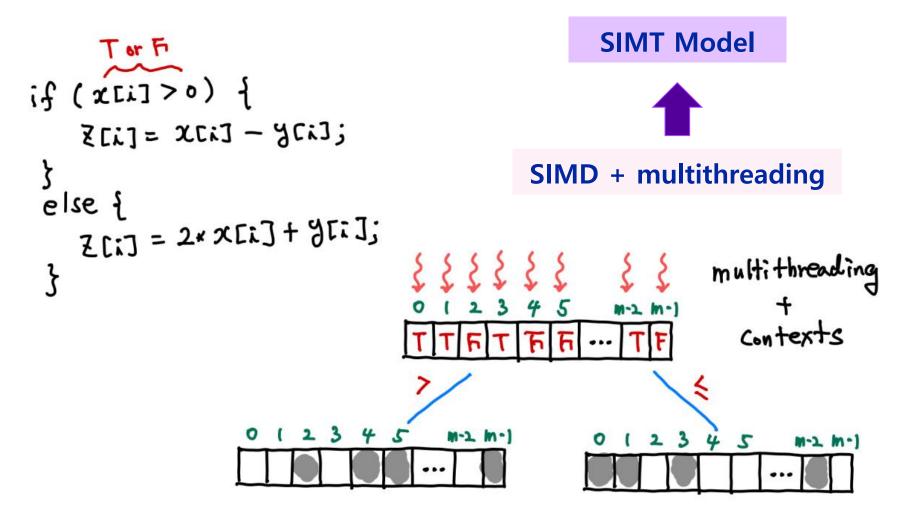


- 관찰 1: 항상 필요한 데이터 스트림 개수만큼 processing element(PE)가 존재할까?
 - 현재 GPU는 현재 수백~수 천개 정도의 PE 제공

(일반적으로) TASK 개수 >> PE 개수



- 관찰 2: 항상 프로그램이 단순한 control flow만으로 구성되어 있을까?
 - 만약 if-문장이 있다면,



NVIDIA Turing TU102 GPU



- ✓ 6 Graphics Processing Clusters(GPCs)
- ✓ 6 Texture Processing
 Clusters(TPCs) / GPC
- √ 36 TPCs
- ✓ 2 Streaming Multiprocessors(SMs) / TPC → 72 SMs
- ✓ 64 **CUDA Cores** / SM → 4,608 CUDA Cores
- ✓ 1 RT Core / SM → 72 RT Cores
- √ 8 Tensor Cores / SM → 576
 Tensor Cores
- √ 4 texture units / SM → 288
 texture units
- ✓ 12 memory controllers
- ✓ 8 ROP units / MC → 96 ROP units
- ✓ 512 KB of **L2 cache** / MC → 6144 KB of L2 cache

NVIDIA Turing GPU Architecture: Graphics Reinvented (2018)

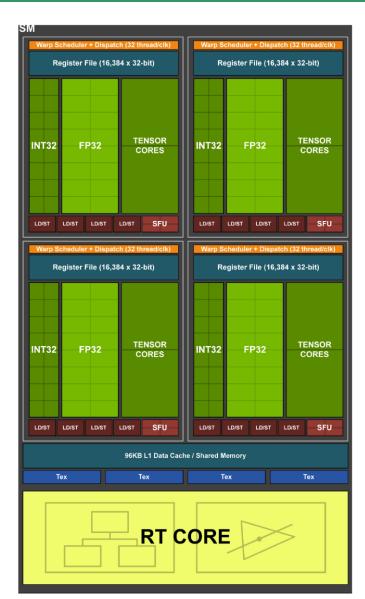


TU102/TU104/TU106 Streaming Multiprocessor (SM)

NVIDIA Turing GPU Architecture: Graphics Reinvented (2018)

Each SM includes

- 64 FP32 Cores / 64 INT32 Cores / 2 FP64 Cores
 - Supports concurrent execution of FP32 and INT32 operations.
- 8 mixed-precision Tensor Cores / 1 RT core
- Each SM is partitioned into four processing blocks each with,
 - 16 FP32 Cores / 16 INT32 Cores (2 cycles per warp)
 - 2 Tensor Cores
 - 1 warp scheduler
 - 1 L0 instruction cache
 - 1 64 KB register file: 16,384 x 32-bit
- The four blocks shares a combined 96 KB L1 data cache/shared memory:
 - 64 KB of graphics shader RAM + 32 KB for texture cache
 - 32 KB shared memory + 64 KB L1 cache
 - 64 KB shared memory + 32 KB L1 cache



APIs for GPU Programming



- OpenGL (Open Graphics Library):
 Vertex/Geometry/Fragment/Compute Shaders
 - OpenGL ES (Open Graphics Library for Embedded System)
 - http://www.khronos.org
- Vulkan / Direct X
 - http://www.khronos.org / http://www.microsoft.com/windows/directx/
- Metal
 - https://developer.apple.com/documentation/metal
- CUDA (Compute Unified Device Architecture)
 - http://www.nvidia.com/object/cuda_home.html
- OpenCL (Open Computing Language)
 - http://www.khronos.org/opencl/

CUDA Implementation of Example Code

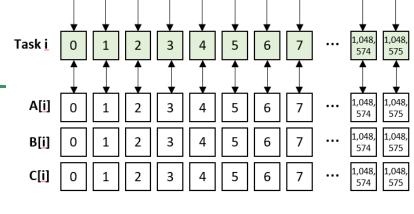


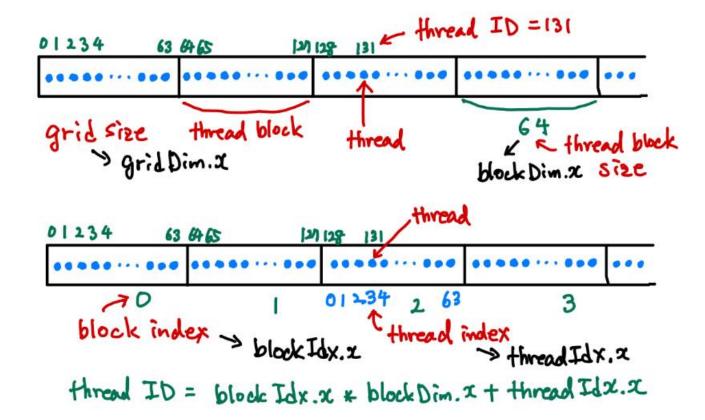
```
#define MAX_N_ELEMENTS 1048576 // pow(2,20)
void combine_two_arrays(float *x, float *y, float *z, int n) {
 int i;
 for (i = 0; i < n; i++) {
  z[i] = 1.0f/(\sin(x[i])*\cos(y[i]) + \cos(x[i])*\sin(y[i]));
                                            동일한 방식의 계산이 서로 다른 데이터에 대하여 반복이 되고 있음.
                                            각 데이터에 대한 계산은 서로 독립적임.
void main(void) {
                                            만약 프로세서가 MAX N ELEMENTS개만큼 있다면, ...
 int n_elements;
 float A[MAX_N_ELEMENTS], B[MAX_N_ELEMENTS], C[MAX_N_ELEMENTS];
 n_elements = MAX_N_ELEMENTS;
                                               x[i]
                                                                                                   1,048,
 combine_two_arrays(A, B, C, n_elements);
                                               y[i]
                                                                                              1,048,
                                                                                                   1,048,
                                               z[i]
                                                                                                   1.048.
                                                                                                   575
```

Tasks and CUDA Threads Taski 0

One dimension

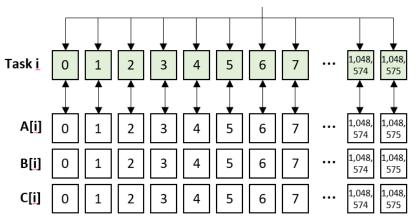
```
for (i = 0; i < n; i++) {
  z[i] = 1.0f/(sin(x[i])*cos(y[i]) + cos(x[i])*sin(y[i]));
}</pre>
```







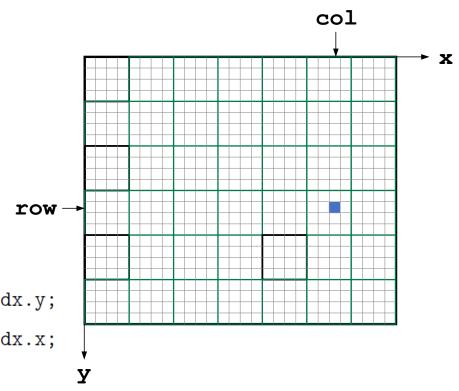
Two dimension



```
gridDim = (7, 6)
blockDim = (4, 4)
blockIdx = (5, 3)
threadIdx = (2, 1)
```

```
int row = blockDim.y*blockIdx.y + threadIdx.y;
int col = blockDim.x*blockIdx.x + threadIdx.x;
int id = gridDim.x*blockDim.x*row + col;
```

```
for (i = 0; i < n; i++) {
  z[i] = 1.0f/(sin(x[i])*cos(y[i]) + cos(x[i])*sin(y[i]));
}</pre>
```



CUDA Kernel

```
for (i = 0; i < n; i++) {
  z[i] = 1.0f/(sin(x[i])*cos(y[i]) + cos(x[i])*sin(y[i]));
}</pre>
```

```
_global_ void CombineTwoArrraysKernel(Array A, Array B, Array C) {
 int row = blockDim.y*blockIdx.y + threadIdx.y;
                                                     Host: CPU
 int col = blockDim.x*blockIdx.x + threadIdx.x;
                                                     Device: GPU
 int id = gridDim.x*blockDim.x*row + col;
                                                     Kernel: the function that runs
                                                             on the device
 C.elements[id] = 1.0f / (sin(A.elements[id])*cos(B.elements[id])
                           + cos(A.elements[id])*sin(B.elements[id])); col
                                                                                   X
Task i
                                                 row-
 A[i]
 B[i]
 C[i]
```

CUDA Host Code



```
int main(void) {
                                                                  #define MAX_N_ELEMENTS 1048576 // pow(2, 20)
                                                                 int BLOCK_SIZE:
 Array A, B, C;
                                                                 typedef struct {
 // Assume that MAX_N_ELEMENTS is a multiple of 1,024.
                                                                      int width;
 A.width = B.width = C.width = 1024;
                                                                      int height;
 A.height = B.height = C.height = MAX_N_ELEMENTS/1024;
                                                                      float *elements;
 BLOCK_SIZE = 16;
                                                                  } Array;
 A.elements = (float *) malloc(sizeof(float)*MAX_N_ELEMENTS);
 B.elements = (float *) malloc(sizeof(float)*MAX_N_ELEMENTS);
 C.elements = (float *) malloc(sizeof(float)*MAX_N_ELEMENTS);
 generate_random_float_array(A.elements, MAX_N_ELEMENTS);
 generate_random_float_array(B.elements, MAX_N_ELEMENTS);
 combine_two_arrays(A, B, C);
```



```
void combine_two_arrays(const Array A, const Array B, Array C) {
 Array d_A, d_B, d_C;
 size_t size;
 d_A.width = A.width; d_A.height = A.height;
 size = A.width * A.height * sizeof(float);
                                                 Memory allocation
                                                 on the device memory
 cudaMalloc(&d_A.elements, size);
 cudaMemcpy(d_A.elements, A.elements, size, cudaMemcpyHostToDevice);
                                                           Memory transfer
 d_B.width = B.width; d_B.height = B.height;
                                                             from the host memory
                                                             to the device memory
 size = B.width * B.height * sizeof(float);
 cudaMalloc(&d_B.elements, size);
 cudaMemcpy(d_B.elements, B.elements, size, cudaMemcpyHostToDevice);
 d_C.width = C.width; d_C.height = C.height;
 size = C.width * C.height * sizeof(float);
 cudaMalloc(&d_C.elements, size);
```



```
// Assume that width and height are multiples of BLOCK_SIZE.
                                                               Execution of the kernel
dim3 dimBlock(BLOCK_SIZE, BLOCK_SIZE);
dim3 dimGrid(A.width/dimBlock.x, A.height/dimBlock.y);
CombineTwoArrraysKernel <<< dimGrid, dimBlock >>> (d_A, d_B, d_C);
cudaMemcpy(C.elements, d_C.elements, size, cudaMemcpyDeviceToHost);
cudaFree(d_A.elements);
cudaFree(d_B.elements);
                                                                             col
                          qridDim = (7, 6)
cudaFree(d_C.elements);
                          blockDim = (4, 4)
                          blockIdx = (5, 3)
                          threadIdx = (2, 1)
                                                     row-
// Assume that MAX_N_ELEMENTS is a multiple of 1,024.
A.width = B.width = C.width = 1024;
A.height = B.height = C.height = MAX_N_ELEMENTS/1024;
BLOCK_SIZE = 16;
                                                          У
```