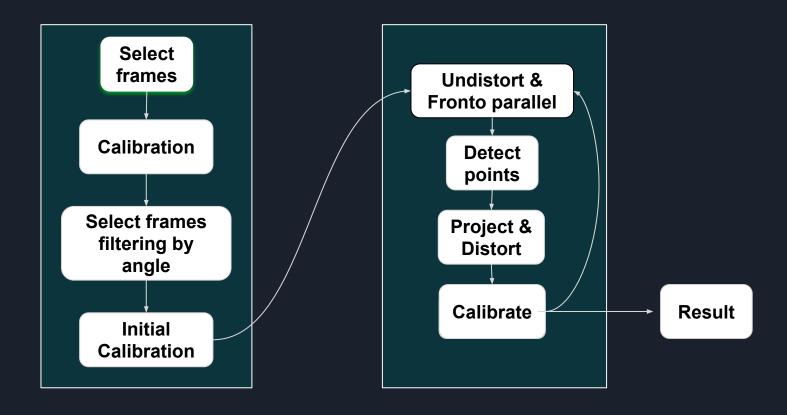
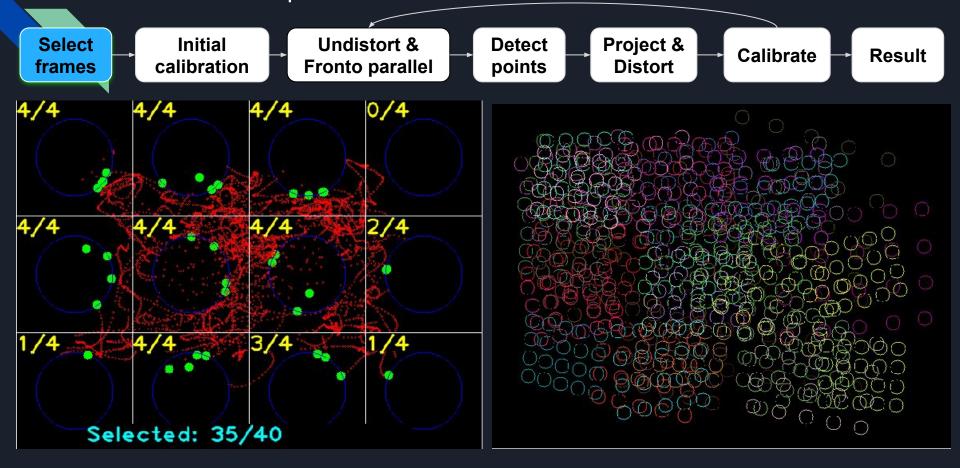


Authors: Raúl Romaní Flores Paul Alonzo Quio Añamuro Jose Jaita Aguilar

### Iterative process for camera calibration





Select frames

Initial calibration

Undistort & Fronto parallel

Detect points

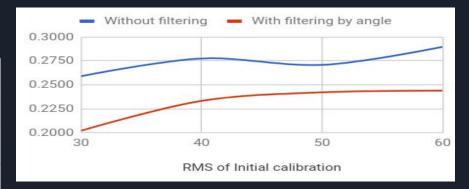
Project & Distort

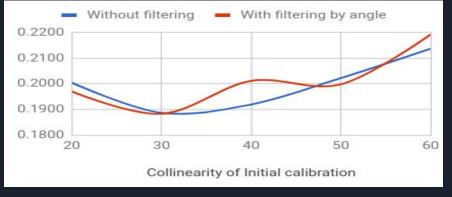
Calibrate

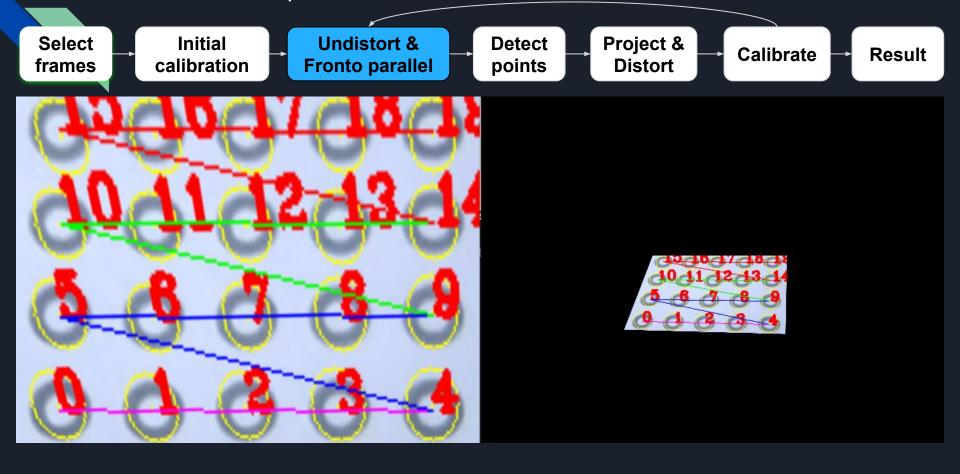
Result

# Filter by angle

Initial calibration										
RMS/Samples	20	30	40	50	60					
Without filtering	0.2590	0.2776	0.2709	0.2898	0.2890					
With filtering by angle	0.2020	0.2333	0.2421	0.2439	0.2684					
Initial calibration										
Collinearity/Samples	20	30	40	50	60					
Without filtering	0.2004	0.1886	0.1919	0.2021	0.2136					
With filtering by angle	0.1969	0.1883	0.2011	0.1997	0.2191					







Select frames

Initial calibration

Undistort & Fronto parallel

Detect points

Project & Distort

Calibrate

Result

1.- fitEllipse

2.- Center of mass

	Rings - Average					Rings - Center of mass					
Samples	20	30	40	50	60	20	30	40	50	60	
Rms	0.194	0.190	0.234	0.219	0.251	0.193	0.189	0.234	0.227	0.250	
fx	844.143	832.426	823.290	819.639	811.885	844.570	829.719	823.771	799.462	812.651	
fy	838.616	826.569	818.583	813.977	807.060	838.924	824.023	819.144	796.585	807.890	
cx	328.923	311.706	304.667	299.790	298.915	329.150	312.364	305.356	294.199	298.840	
су	241.277	237.382	244.639	259.618	259.824	241.039	237.254	243.683	255.140	260.558	
Collinearity	0.197	0.188	0.201	0.200	0.219	0.197	0.188	0.201	0.207	0.216	
Collinearity undistorted		0.078	0.079	0.088	0.089	0.075	0.073	0.076	0.086	0.087	

Select frames

Initial calibration

Undistort & Fronto parallel

Detect points

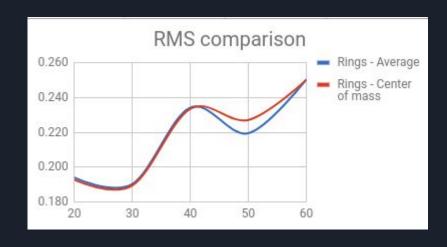
Project & Distort

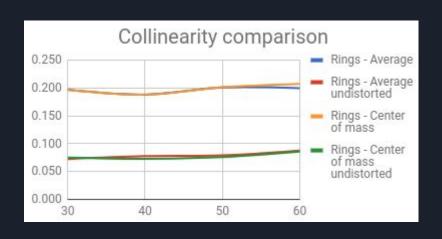
Calibrate

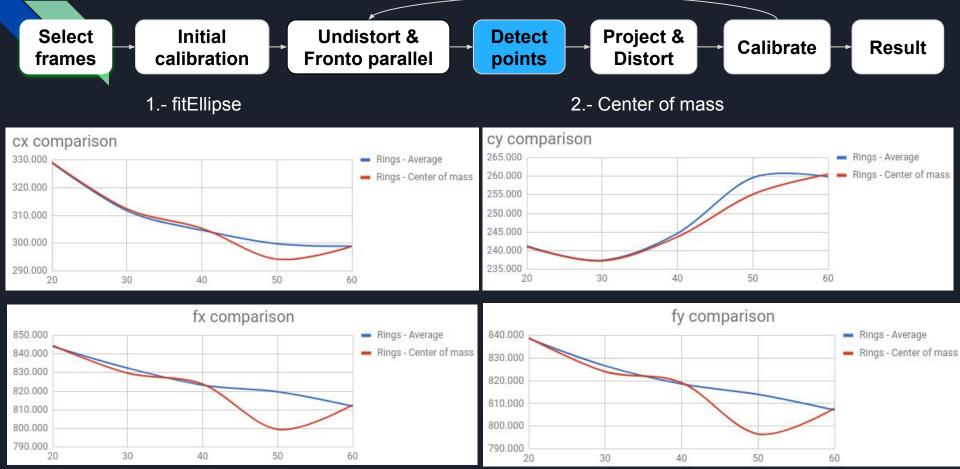
Result

1.- fitEllipse

#### 2.- Center of mass







Select frames

Initial calibration

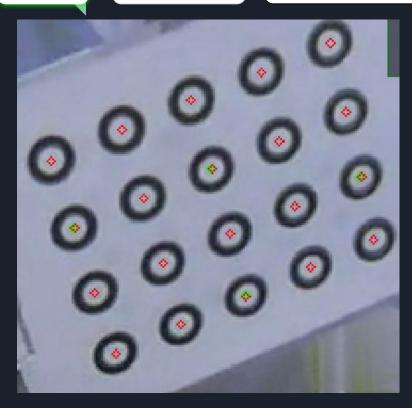
Undistort & Fronto parallel

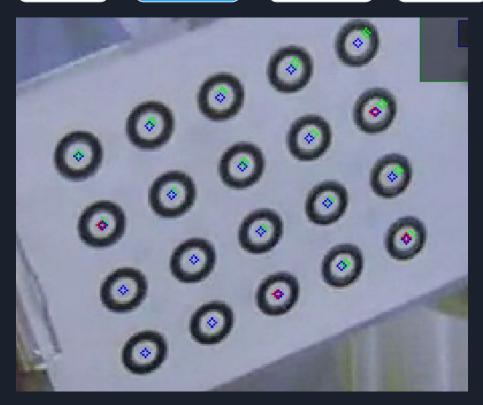
Detect points

Project & Distort

Calibrate

Result





Select frames

Initial calibration

Undistort & Fronto parallel

Detect points

Project & Distort

Calibrate

Result

# Refinement comparison

	Rings - Refinement - Avg					Rings - Refinement - Blend				
Samples	20	30	40	50	60	20	30	40	50	60
Rms	0.194	0.190	0.234	0.219	0.251	0.195	0.192	0.235	0.220	0.251
fx	844.143	832.426	823.290	819.639	811.885	845.748	829.826	823.726	819.288	812.192
fy	838.616	826.569	818.583	813.977	807.060	840.082	824.040	819.035	813.653	807.466
сх	328.923	311.706	304.667	299.790	298.915	329.338	312.016	304.019	299.733	298.165
су	241.277	237.382	244.639	259.618	259.824	241.683	238.191	244.391	259.171	259.310
Collinearity	0.197	0.188	0.201	0.200	0.219	0.197	0.188	0.201	0.200	0.219
Collinearity undistorted	0.073	0.078	0.079	0.088	0.089	0.075	0.077	0.078	0.086	0.089

Select frames

Initial calibration

Undistort & Fronto parallel

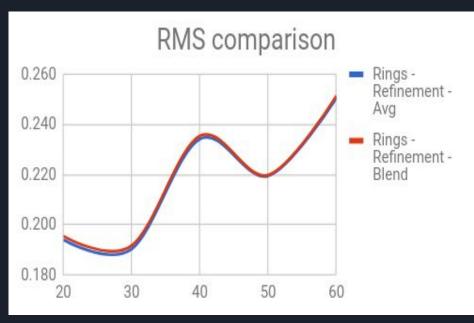
Detect points

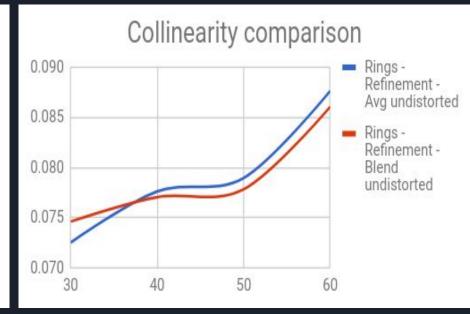
Project & Distort

Calibrate

Result

#### Refinement comparison





Select Initial Calibration Undistort & Detect Project & Distort Calibrate Result

# Refinement using ideal points

	Rings - Average					Rings - Center of mass				
Samples	20	30	40	50	60	20	30	40	50	60
Rms	0.144	0.146	0.200	0.192	0.194	0.173	0.170	0.206	0.205	0.208
fx	831.698	829.754	818.353	819.020	827.578	837.996	841.098	822.289	819.604	827.559
fy	826.859	823.600	813.559	813.132	821.988	833.216	835.851	818.738	816.035	822.820
сх	321.502	311.597	317.957	311.591	303.610	309.248	316.610	305.148	309.821	303.397
су	257.509	247.419	252.088	254.260	254.331	246.846	248.250	231.453	233.980	245.119
Collinearity	0.190	0.184	0.191	0.189	0.200	0.191	0.184	0.186	0.185	0.198
Collinearity undistorted	0.083	0.077	0.083	0.082	0.089	0.069	0.070	0.081	0.083	0.078

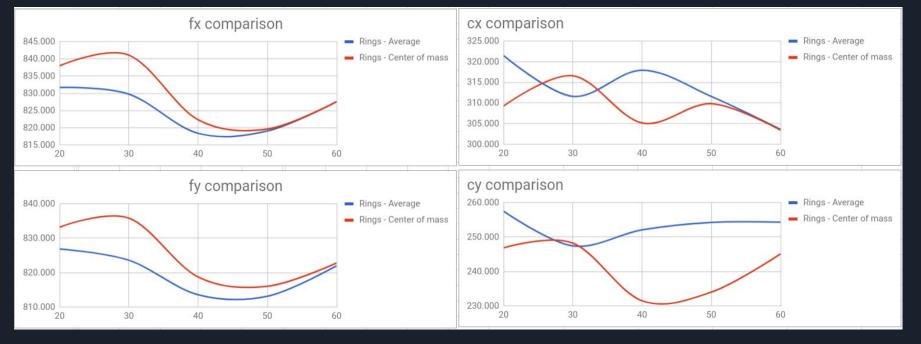


# Refinement using ideal points





# Refinement using ideal points



Select frames

Initial calibration

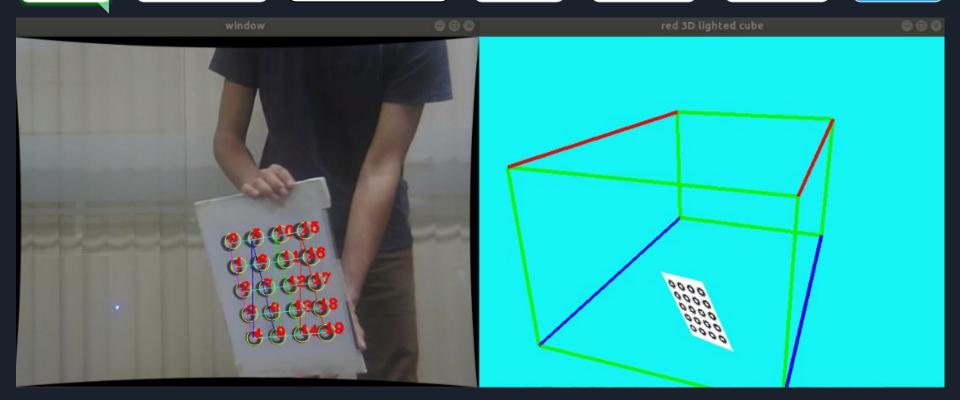
Undistort & Fronto parallel

Detect points

Project & Distort

Calibrate

Result



Select frames

Initial calibration

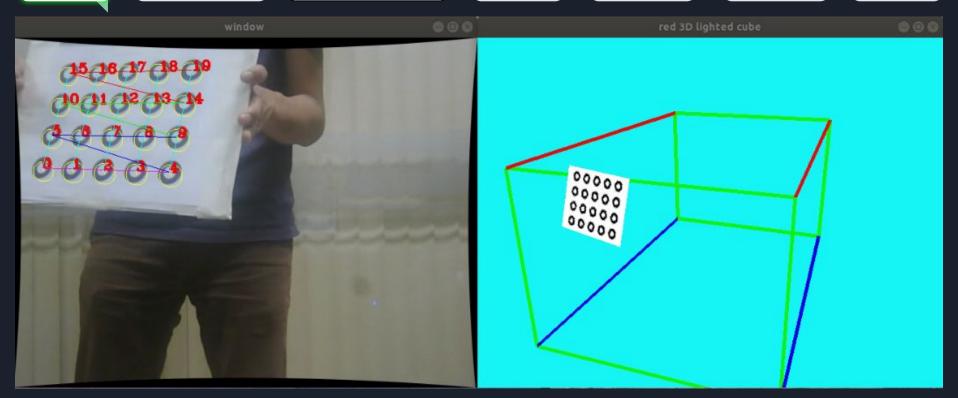
Undistort & Fronto parallel

Detect points

Project & Distort

Calibrate

Result



Select frames

Initial calibration

Undistort & Fronto parallel

Detect points

Project & Distort

Calibrate

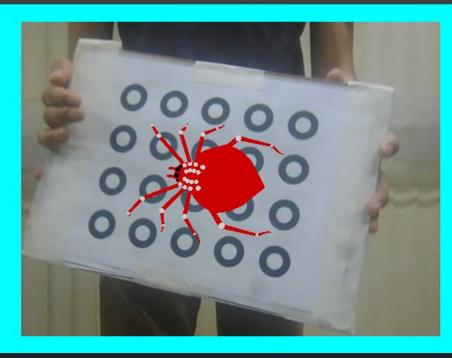
Result

red 3D lighted cube



red 3D lighted cube







# Thank you