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## Weekly report

### 1 *My Objectives this week*

- Completing Simulation for 2 robots infinite friction algorithm
- Upgrading firmware in windows
- Running go to the light on kilobots

### 2 *My Accomplishments this week*

#### 2.1 *Kilobots*

- I finally found how to change kilobots' firmware, I did that for the controller and 31 kilobots, I can now program them.
- I tried the go to the light program, but it needs some calibration to work. So I am making the code and calibration right now to see if it works or not.
- Now even with mac we can program the kilobots. (So I removed windows on my machine)

#### 2.2 *Algorithms*

- I wrote a draft function that gives the right answer in some cases. But our simulator doesn't work properly and sees errors, I have to fix that to see the result properly but the right path is there. Code is submitted to the github.

### 3 *My Plan for next week*

- Correcting errors in simulations and apply it to both directions(x,y)
- Completing code for kilobots.
- Start working with Arduino and programming the light bulbs.

#### 3.1 *Meeting with Dr. Becker*

- Unfortunately I have filled a wrong form for my QE. And it seems that I have to fill another form for my PhD committee too. I would appreciate if we could discuss about these forms.