

Robot



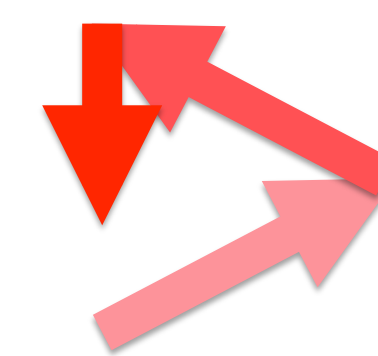
Goal



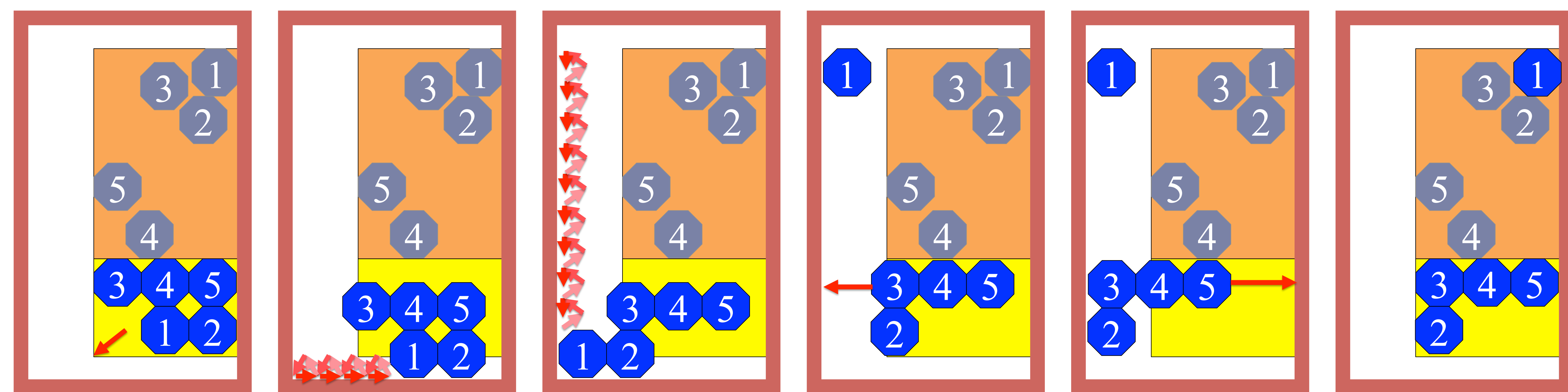
Move



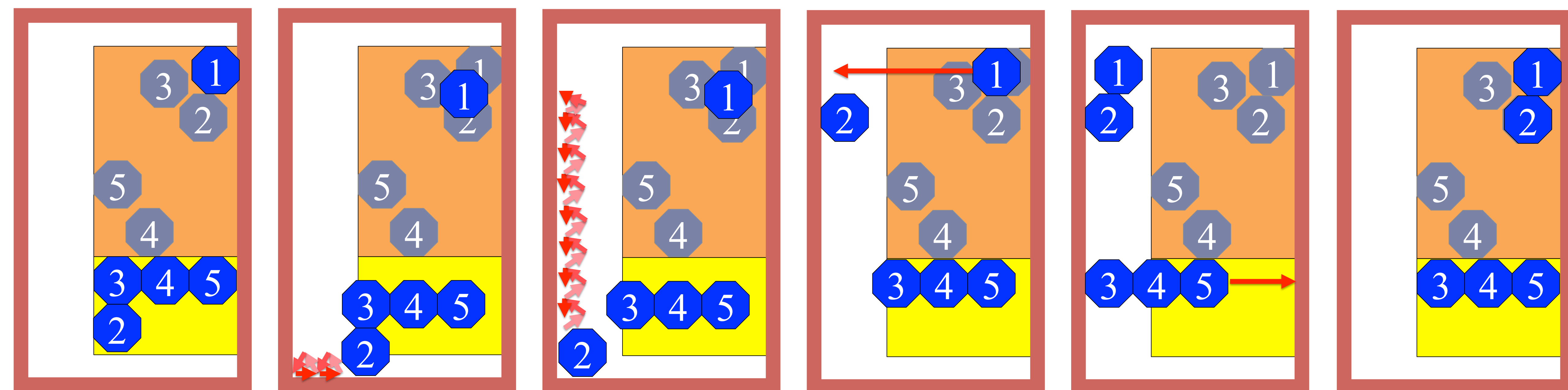
DriftMove



$k=1$



$k=2$



⋮

$k=5$

