```cpp
// init.cpp: Handles the initialization of everything needed, ie. sensors, pid.
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#include "../include/main.h"

extern "C" {
void __libc_init_array();
}

void initializeIO() { __libc_init_array(); }

void initialize() {
  motors::slew::init();
  drive::init();
  sensors::init();
  pid::init();
}
```