

```

// init.cpp: Handles the initialization of everything needed, ie. sensors, pid.
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#include "../include/main.h"

extern "C" {
void __libc_init_array();
}

void initializeIO() {
    __libc_init_array();
}

void initialize() {
    motors::slew::init();
    drive::init();
    sensors::init();
    pid::init();
}

```