```cpp
// opcontrol.cpp: Handles the interaction and procedure of opcontrol mode
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#include "../include/main.h"
bool tank     = true;
bool wpressed = false;

void operatorControl() {
  sensors::reset();

  while (isEnabled()) {
    if (tank) {
      drive::tank();
    } else {
      drive::accel::drive();
    }
    if (!wpressed && joystickGetDigital(1, 7, JOY_DOWN)) {
      tank = !tank;
    } else {
      wpressed = joystickGetDigital(1, 7, JOY_DOWN);
    }
    debug::debug();
    delay(50);
  }
}
```