```cpp
// gyro.hpp: Gyro utilities that provide ease of access to the robot's rotation
// and manipulation of this rotation
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//
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#pragma once
#include "pid.hpp"

namespace gyro {
  class drive {
    public:
      sensors::gyro_t* gyro;
      int heading;

  };

  /** TaskHandle for the gyro heading task */
  extern TaskHandle handle;
} // namespace gyro
```