

Question 1

$$\begin{aligned} \bar{E}_i &= E_1 \cdot \hat{a}_y \cdot e^{-jk_1 \cdot (\sin \theta_i x + \cos \theta_i z)} \\ \bar{E}_r &= E_2 \cdot \hat{a}_y \cdot e^{-jk_1 \cdot (\sin \theta_r x - \cos \theta_r z)} \end{aligned} \left. \vphantom{\begin{aligned} \bar{E}_i &= E_1 \cdot \hat{a}_y \cdot e^{-jk_1 \cdot (\sin \theta_i x + \cos \theta_i z)} \\ \bar{E}_r &= E_2 \cdot \hat{a}_y \cdot e^{-jk_1 \cdot (\sin \theta_r x - \cos \theta_r z)} \end{aligned}} \right\} \text{for } z < 0$$

$$\begin{aligned} \bar{E}_a &= E_3 \cdot \hat{a}_y \cdot e^{-jk_2 \cdot (\sin \theta_a x + \cos \theta_a z)} \\ \bar{E}_b &= E_4 \cdot \hat{a}_y \cdot e^{-jk_2 \cdot (\sin \theta_b x - \cos \theta_b z)} \end{aligned} \left. \vphantom{\begin{aligned} \bar{E}_a &= E_3 \cdot \hat{a}_y \cdot e^{-jk_2 \cdot (\sin \theta_a x + \cos \theta_a z)} \\ \bar{E}_b &= E_4 \cdot \hat{a}_y \cdot e^{-jk_2 \cdot (\sin \theta_b x - \cos \theta_b z)} \end{aligned}} \right\} \text{for } 0 < z < d$$

$$\bar{E}_t = E_5 \cdot \hat{a}_y \cdot e^{-jk_1 \cdot (\sin \theta_t x + \cos \theta_t z)} \left. \vphantom{\bar{E}_t = E_5 \cdot \hat{a}_y \cdot e^{-jk_1 \cdot (\sin \theta_t x + \cos \theta_t z)}} \right\} \text{for } z > d$$

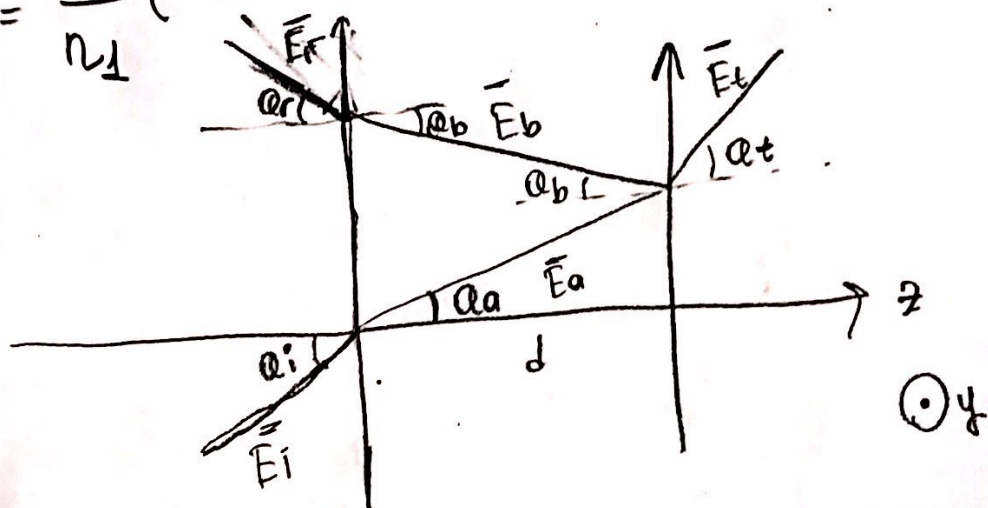
$$\bar{H}_i = \frac{E_1}{\eta_1} (-\cos \theta_i \hat{a}_x + \sin \theta_i \hat{a}_z) e^{-jk_1 \cdot (\sin \theta_i x + \cos \theta_i z)}$$

$$\bar{H}_r = \frac{E_2}{\eta_1} (\cos \theta_r \hat{a}_x + \sin \theta_r \hat{a}_z) e^{-jk_1 \cdot (\sin \theta_r x - \cos \theta_r z)}$$

$$\bar{H}_a = \frac{E_3}{\eta_2} (-\cos \theta_a \hat{a}_x + \sin \theta_a \hat{a}_z) e^{-jk_2 \cdot (\sin \theta_a x + \cos \theta_a z)}$$

$$\bar{H}_b = \frac{E_4}{\eta_2} (\cos \theta_b \hat{a}_x + \sin \theta_b \hat{a}_z) e^{-jk_2 \cdot (\sin \theta_b x - \cos \theta_b z)}$$

$$\bar{H}_t = \frac{E_5}{\eta_1} (-\cos \theta_t \hat{a}_x + \sin \theta_t \hat{a}_z) e^{-jk_1 \cdot (\sin \theta_t x + \cos \theta_t z)}$$



For $z=0$

$$d' = d \cdot (\tan \theta_a + \tan \theta_b)$$

$$\textcircled{1} E_{\text{tang}}^{(1)} = E_{\text{tang}}^{(2)} \quad |_{z=0}$$

$$E_1 \cdot e^{-jk_1 \sin \theta_i \cdot x} + E_2 \cdot e^{-jk_1 \sin \theta_r (x+d')} = E_a \cdot e^{-jk_2 \sin \theta_a x} + E_b \cdot e^{-jk_2 \sin \theta_b (x+d')}$$

$\theta_a = \theta_b \Rightarrow$ we show this in the next part

and $k_1 \sin \theta_i = k_2 \sin \theta_a$

$\theta_i = \theta_r$

$$E_1 + E_2 \cdot e^{-jk_1 \sin \theta_r \cdot d'} = E_3 + E_4 \cdot e^{-jk_2 \sin \theta_b \cdot d'}$$

For $z=d$

$$\textcircled{2} E_{\text{tang}}^{(1)} = E_{\text{tang}}^{(2)} \quad |_{z=d}$$

$$E_3 \cdot e^{-jk_2 [\sin \theta_a \cdot (x+d \cdot \tan \theta_a) + \cos \theta_a \cdot d]} +$$

$$E_4 \cdot e^{-jk_2 [\sin \theta_b (x+d \tan \theta_a) - \cos \theta_b \cdot d]}$$

$$= E_5 \cdot e^{-jk_1 [\sin \theta_t (x+d \tan \theta_a) + \cos \theta_t \cdot d]}$$

$$E_3 \cdot e^{-jk_2 \cos \theta_a \cdot d} + E_4 \cdot e^{+jk_2 \cos \theta_b \cdot d}$$

$$= E_5 \cdot e^{-jk_1 \cos \theta_t \cdot d}$$

$$\left. \begin{aligned} \sin \theta_a \cdot k_2 &= \sin \theta_b \cdot k_2 \\ &= \sin \theta_t \cdot k_1 \\ &(\text{for all } x) \\ &\Downarrow \\ \theta_a &= \theta_b \end{aligned} \right\}$$

$\theta_t = \theta_i \Rightarrow$ does not depend on d
(in question $\theta_e = \theta_i$)

Final results

$\theta_a = \theta_b \quad \sin \theta_a \cdot k_2 = \sin \theta_i \cdot k_1$

$\theta_t = \theta_i$

$\theta_r = \theta_i$

For $z=0$

$$\textcircled{1} H_{\text{tang}}^{(1)} = H_{\text{tang}}^{(2)}$$

$$-\frac{E_1}{n_1} \cos \alpha_i + \frac{E_2}{n_1} \cos \alpha_i \cdot e^{-jk_1 \sin \alpha_i d'} = -\frac{E_3}{n_2} \cos \alpha_a + \frac{E_4}{n_2} \cos \alpha_a \cdot e^{jk_2 \sin \alpha_b d'}$$

For $z=d$

$$\textcircled{2} \frac{E_3}{n_2} \cos \alpha_a \cdot e^{-jk_2 \cos \alpha_a d} + \frac{E_4}{n_2} \cos \alpha_b \cdot e^{+jk_2 \cos \alpha_b d}$$

$$= -\frac{E_5}{n_1} \cos \alpha_t \cdot e^{-jk_1 \cos \alpha_t d}$$

$$A = \begin{bmatrix} -e^{-jk_1 \sin \alpha_i d'} & 1 & 1 & e^{-jk_2 \sin \alpha_b d'} & 0 \\ 0 & e^{-jk_2 \cos \alpha_a d} & e^{jk_2 \cos \alpha_b d} & -e^{jk_1 \cos \alpha_t d} & 0 \\ \frac{1}{n_1} \cos \alpha_i e^{-jk_1 \sin \alpha_i d'} & \frac{1}{n_2} \cos \alpha_a & -\frac{1}{n_2} \cos \alpha_b \cdot e^{jk_2 \sin \alpha_b d'} & 0 & 0 \\ 0 & -\frac{1}{n_2} \cos \alpha_a \cdot e^{-jk_2 \cos \alpha_a d} & \frac{1}{n_2} \cos \alpha_b \cdot e^{jk_2 \cos \alpha_b d} & \frac{1}{n_1} \cos \alpha_t \cdot e^{jk_1 \cos \alpha_t d} & 0 \end{bmatrix}$$

$$\begin{bmatrix} E_2 \\ E_3 \\ E_4 \\ E_5 \end{bmatrix} = E_1 \cdot A^{-1} \begin{bmatrix} 1 \\ 0 \\ \frac{1}{n_1} \cos \alpha_i \\ 0 \end{bmatrix}$$

$$A \begin{bmatrix} E_2 \\ E_3 \\ E_4 \\ E_5 \end{bmatrix} = E_1 \begin{bmatrix} 1 \\ 0 \\ \frac{1}{n_1} \cos \alpha_i \\ 0 \end{bmatrix} \Rightarrow$$

Find E_2, E_3, E_4, E_5 in terms of E_1
Then calculate H_2, H_3, H_4, H_5

$$P_{av} = \frac{1}{2} \operatorname{Re} \{ \bar{E}_1 \times H^* \}$$

Question 2

$$\sin \theta_c = \sqrt{\frac{\mu_2 \epsilon_2}{\mu_1 \epsilon_1}} = \frac{\sqrt{3}}{2}$$

$$\sin^2 \theta_B = \frac{1 - (\mu_2 \epsilon_1 / \mu_1 \epsilon_2)}{1 - (\epsilon_1 / \epsilon_2)^2} = \frac{1}{4}$$

$$\bar{P}_{av}^r = \Gamma^2 \bar{P}_{av}^i \quad \text{and} \quad \bar{P}_{av}^t = \bar{P}_{av}^i + \bar{P}_{av}^r$$

$$\left(\frac{n_2 - n_1}{n_2 + n_1} \right)^2, \quad n_1 = \sqrt{\frac{\mu_1}{\epsilon_1}}, \quad n_2 = \sqrt{\frac{\mu_2}{\epsilon_2}}$$

$$4\mu_2 \epsilon_2 = 3\mu_1 \epsilon_1 \quad (1)$$

$$3 - \frac{4\mu_2 \epsilon_1}{\mu_1 \epsilon_2} = \frac{\epsilon_1^2}{\epsilon_2^2} \quad (2)$$

$$3\epsilon_2^2 - 4\mu_2 \epsilon_1 \epsilon_2^2 = \mu_1 \epsilon_2 \epsilon_1^2 \quad (1) \text{ and } (2)$$

$$3\epsilon_2^2 - 3\mu_1 \epsilon_1^2 \epsilon_2 = \mu_1 \epsilon_2 \epsilon_1^2$$

$$3\epsilon_2^2 = 4\mu_1 \epsilon_1^2 \epsilon_2 \Rightarrow 3\epsilon_2 = 4\mu_1 \epsilon_1^2 \quad (3)$$

Use (1) and (3)

$$4 \cdot \mu_2 \cdot \frac{4\mu_1 \epsilon_1^2}{3} = 3\mu_1 \epsilon_1 \Rightarrow \boxed{\mu_2 \epsilon_1 = 9/16}$$

$$\frac{\mu_2}{\mu_1} = a, \quad \frac{\epsilon_2}{\epsilon_1} = b$$

$$(1) \sqrt{a \cdot b} = \sqrt{\frac{3}{4}} \Rightarrow b = \sqrt{\frac{2}{3}}, \quad a = \frac{3\sqrt{3}}{4\sqrt{2}} = \frac{\mu_2}{\mu_1}$$

$$(2) \frac{1 - a/b}{1 - (1/b)^2} = \frac{1}{4} \Rightarrow \boxed{\frac{\epsilon_2}{\epsilon_1} = \sqrt{\frac{2}{3}}}$$

$$\frac{b^2 - ab}{b^2 - 1} = \frac{1}{4}$$

$$4b^2 - 3 = b^2 - 1 \Rightarrow 3b^2 = 2 \Rightarrow b^2 = \frac{2}{3} = \frac{\epsilon_2^2}{\epsilon_1^2}$$

$$\frac{\mu_2 \epsilon_1}{\mu_1 \epsilon_2} = \frac{3\sqrt{3}}{4\sqrt{2}} \cdot \frac{\sqrt{3}}{\sqrt{2}} = \frac{9}{8}$$

$$\boxed{\mu_1 \epsilon_2 = 1/2}$$

$$\sin^2 \theta_B = \frac{1}{4} = \frac{1 - (9/16 / \mu_1 \epsilon_2)}{1 - (1/2)^2}$$

$$\Rightarrow \frac{1}{4} = \frac{1 - 3/16}{1 - 1/4} = \frac{1 - 3/16}{3/4}$$

$$\Gamma^2 = \frac{\mu_1/\epsilon_1 + \mu_2/\epsilon_2 - 2\sqrt{\frac{\mu_1\mu_2}{\epsilon_1\epsilon_2}}}{\mu_1/\epsilon_1 + \mu_2/\epsilon_2 + 2\sqrt{\frac{\mu_1\mu_2}{\epsilon_1\epsilon_2}}}$$

$$= \frac{\mu_1\epsilon_2 + \mu_2\epsilon_1 - 2\sqrt{\mu_1\epsilon_1\mu_2\epsilon_2}}{\mu_1\epsilon_2 + \mu_2\epsilon_1 + 2\sqrt{\mu_1\epsilon_1\mu_2\epsilon_2}}$$

$$= \frac{1/2 + 9/16 - 2\sqrt{9/32}}{1/2 + 9/16 + 2\sqrt{9/32}} \approx \boxed{8,7 \cdot 10^{-4}}$$

$$P_{av}^r = \Gamma^2 P_{av}^i$$

$$P_{av}^t = (1 - \Gamma^2) P_{av}^i$$

Q3. From coursebook page 343.

radius: a distance: D medium parameters: ϵ, μ

$$C = \frac{\pi \cdot \epsilon}{\cosh^{-1}(D/2a)} \left(\frac{F}{m} \right)$$

$$L = \frac{\mu}{\pi} \cosh^{-1}\left(\frac{D}{2a}\right) \left(\frac{H}{m} \right)$$

$$G = \frac{\pi \sigma}{\cosh^{-1}(D/2a)} \left(\frac{S}{m} \right)$$

$$R = \frac{1}{\pi a} \sqrt{\frac{\pi \mu \nu_c}{\sigma \epsilon}} \left(\frac{\Omega}{m} \right)$$