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Wave Equations for \vec{E} and \vec{H} Fields

Assume a simple (i.e. linear + isotropic + homogeneous) medium where ϵ and μ are simple constants.

USE:

Maxwell's Eqns. (M.E.)	{	$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$
		$\vec{\nabla} \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$
		$\vec{\nabla} \cdot \vec{D} = \rho_v$
		$\vec{\nabla} \cdot \vec{B} = 0$
Constitutive Relations for a "simple" medium	{	$\vec{B} = \mu \vec{H}$
		$\vec{D} = \epsilon \vec{E}$

To obtain the wave equation for \vec{E} field, start by computing the curl of both sides of the 1st M.E., i.e. $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$.

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = \vec{\nabla} \times \left(-\frac{\partial \vec{B}}{\partial t} \right) = -\frac{\partial}{\partial t} (\underbrace{\vec{\nabla} \times \vec{B}}_{\mu \vec{H} \rightarrow \text{constant}})$$

$$\underbrace{\vec{\nabla} (\vec{\nabla} \cdot \vec{E})}_{\frac{\rho_v}{\epsilon}} - \nabla^2 \vec{E}$$

$$\Rightarrow \Rightarrow \vec{\nabla} \left(\underbrace{\vec{\nabla} \cdot \frac{\vec{D}}{\epsilon}}_{\text{constant}} \right) - \nabla^2 \vec{E} = -\mu \frac{\partial}{\partial t} \left(\underbrace{\vec{\nabla} \times \vec{H}}_{\vec{J} + \frac{\partial \vec{D}}{\partial t} \rightarrow \epsilon \vec{E}} \right)$$

$$\Rightarrow \vec{\nabla} \left[\frac{1}{\epsilon} (\underbrace{\vec{\nabla} \cdot \vec{D}}_{\rho_v}) \right] - \nabla^2 \vec{E} = -\mu \frac{\partial \vec{J}}{\partial t} - \epsilon \mu \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\vec{\nabla} \left(\frac{\rho_v}{\epsilon} \right) - \nabla^2 \vec{E} = -\mu \frac{\partial \vec{J}}{\partial t} - \epsilon \mu \frac{\partial^2 \vec{E}}{\partial t^2}$$

Reorganize as

$$\nabla^2 \vec{E} - \epsilon \mu \frac{\partial^2 \vec{E}}{\partial t^2} = \mu \frac{\partial \vec{J}}{\partial t} + \vec{\nabla} \left(\frac{\rho_v}{\epsilon} \right)$$

Inhomogeneous (right hand side contains source terms) wave eqn. for \vec{E} field!

where \vec{J} and ρ_v are the vector and scalar type sources of the problem.

Exercise: Repeat the same procedure to obtain the wave equation for \bar{H} field!

(Hint: Start with the 2nd M.E. $\bar{\nabla} \times \bar{H} = \bar{J} + \frac{\partial \bar{D}}{\partial t}$ this time)

Similarly, we can get the wave eqn. for \bar{H} field as

$$\boxed{\nabla^2 \bar{H} - \epsilon\mu \frac{\partial^2 \bar{H}}{\partial t^2} = -\bar{\nabla} \times \bar{J}}$$

Again, this wave eqn. is inhomogeneous as the right hand side contains the source term \bar{J} !

Special Case I: For a [SIMPLE \oplus LOSSLESS \oplus SOURCE FREE] medium.

- linear
+ isotropic
+ homogeneous
- zero conductivity
 $\sigma = 0$
- $\bar{J}_{\text{impressed}} = 0$
 $J_{\text{re}} = 0$
(no impressed sources)

In general, \bar{J} in Maxwell's Equations may have the following form:

$$\bar{J} = \underbrace{\bar{J}_{\text{impressed}}}_{\substack{\text{forced or impressed} \\ \text{current density} \\ \text{which is zero} \\ \text{in source-free} \\ \text{case.}}} + \underbrace{\bar{J}_{\text{conduction}}}_{\substack{\sigma \bar{E}, \text{ which is zero} \\ \text{in lossless case} \\ \text{(i.e. when } \sigma = 0 \text{)}}}$$

In this special case, both components of current density are zero. Hence, set $\bar{J} = 0$ in M.E.s and in wave equations.

$$\Rightarrow \boxed{\nabla^2 \bar{E} - \epsilon\mu \frac{\partial^2 \bar{E}}{\partial t^2} = 0} \quad \text{and} \quad \boxed{\nabla^2 \bar{H} - \epsilon\mu \frac{\partial^2 \bar{H}}{\partial t^2} = 0}$$

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Consider $\boxed{\nabla^2 \bar{F} - \epsilon\mu \frac{\partial^2 \bar{F}}{\partial t^2} = 0}$ for instance

where $\bar{F}(\vec{r}, t) = \hat{a}_x F_x(x, y, z, t) + \hat{a}_y F_y(x, y, z, t) + \hat{a}_z F_z(x, y, z, t)$

in general, in Cartesian coordinate system.

For simplicity, assume $\underline{\bar{F}} = \underline{\hat{a}_x F_x(z, t)}$

Insert this solution to wave eqn. above:

$$\frac{\partial^2}{\partial x^2} [\hat{a}_x F_x(z, t)] + \frac{\partial^2}{\partial y^2} [\hat{a}_x F_x(z, t)] + \frac{\partial^2}{\partial z^2} [\hat{a}_x F_x(z, t)] - \epsilon\mu \frac{\partial^2}{\partial t^2} [\hat{a}_x F_x(z, t)] = 0$$

$$\Rightarrow \boxed{\frac{\partial^2 F_x(z, t)}{\partial z^2} - \epsilon\mu \frac{\partial^2 F_x(z, t)}{\partial t^2} = 0} \quad (a)$$

It can be shown by inspection that the pde (a) has the solutions in the form

$$\left. \begin{array}{c} g_1(z-vt) \\ g_2(z+vt) \end{array} \right\} \text{ where } \boxed{v = \frac{1}{\sqrt{\epsilon\mu}}}$$

and g_1, g_2 are double-differentiable functions with respect to z and t .

Proof: Insert $g_1(z-vt)$, for instance, into pde (a) to see if it is satisfied.

$$\text{Let } s = z - vt \Rightarrow \frac{\partial s}{\partial z} = 1 \quad \text{and} \quad \frac{\partial s}{\partial t} = -v = -\frac{1}{\sqrt{\epsilon\mu}}$$

$$\frac{\partial g_1}{\partial z} = \frac{\partial g_1}{\partial s} \frac{\partial s}{\partial z} = \frac{\partial g_1}{\partial s} \quad (\text{using chain rule in differentiation})$$

and $\frac{\partial^2 g_1}{\partial z^2} = \frac{\partial}{\partial z} \left(\frac{\partial g_1}{\partial z} \right) = \frac{\partial}{\partial z} \left(\frac{\partial g_1}{\partial s} \right) = \frac{\partial}{\partial s} \left(\frac{\partial g_1}{\partial s} \right) \underbrace{\frac{\partial s}{\partial z}}_1$

$$\boxed{\frac{\partial^2 g_1}{\partial z^2} = \frac{\partial^2 g_1}{\partial s^2}} \quad (*)$$

Also,

$$\frac{\partial g_1}{\partial t} = \frac{\partial g_1}{\partial s} \underbrace{\frac{\partial s}{\partial t}}_{-v} = -\frac{1}{\sqrt{\epsilon\mu}} \frac{\partial g_1}{\partial s}$$

and $\frac{\partial^2 g_1}{\partial t^2} = \frac{\partial}{\partial t} \left(-\frac{1}{\sqrt{\epsilon\mu}} \frac{\partial g_1}{\partial s} \right) = \frac{\partial}{\partial s} \left[-\frac{1}{\sqrt{\epsilon\mu}} \frac{\partial g_1}{\partial s} \right] \underbrace{\frac{\partial s}{\partial t}}_{-\frac{1}{\sqrt{\epsilon\mu}}}$

$$\boxed{\frac{\partial^2 g_1}{\partial t^2} = \frac{1}{\mu\epsilon} \frac{\partial^2 g_1}{\partial s^2}} \quad (**)$$

Insert (*) and (**) in (a) to see

$$\underbrace{\frac{\partial^2 g_1(z-vt)}{\partial z^2}}_{\frac{\partial^2 g_1}{\partial s^2}} - \cancel{\mu\epsilon} \underbrace{\frac{\partial^2 g_1(z-vt)}{\partial t^2}}_{\frac{1}{\cancel{\mu\epsilon}} \frac{\partial^2 g_1}{\partial s^2}} = 0 \quad \checkmark \text{ as claimed!}$$

(Validity of the other solution $g_2(z+vt)$ can be proven similarly.)

Some Examples to Wave Solutions

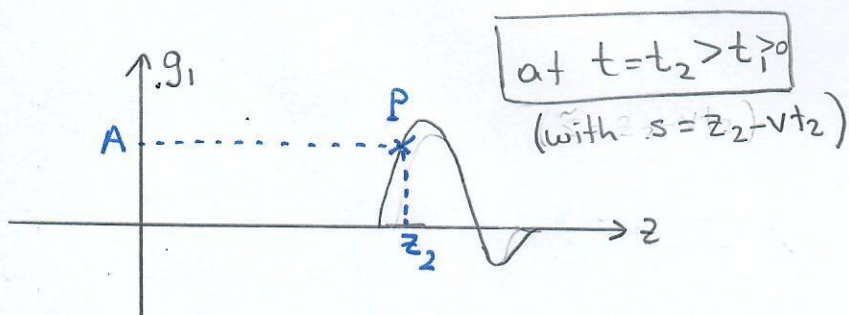
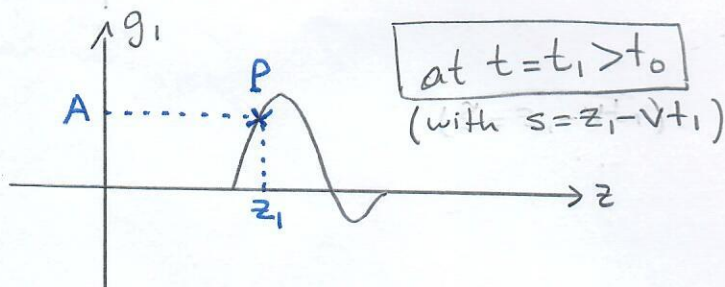
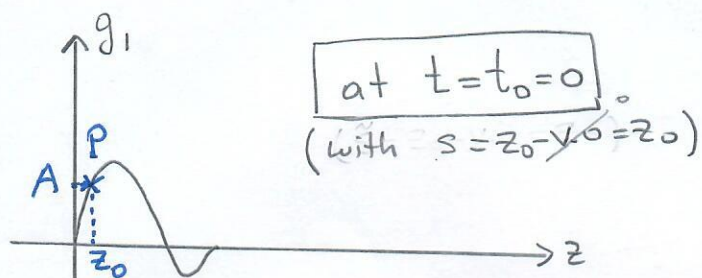
$$K e^{\alpha(z \mp vt)} , K \cos \{ \alpha (z \mp vt) \} , K (z \mp vt)^3 , \text{etc.} \dots$$

where $v = \frac{1}{\sqrt{\mu\epsilon}}$, K and α are some arbitrary constants.

Behavior of Wave Solutions: Traveling Waves

Let's examine the behavior of $g_1(z-vt)$ types of solutions.

Call the argument of the function as $\boxed{s = z - vt}$. Plot an arbitrary g_1 function versus distance (z) at different time (t) instants as follows:



Choose an arbitrary point P on the curve. Coordinates of this particular point P

are $\tilde{s} = z_0 - v \cdot 0 = z_0$
 (z_0, A) at $t=t_0=0$
 (z_1, A) at $t=t_1$
 (z_2, A) at $t=t_2$

Note that the value of the argument must remain the same as we keep tracking the same point P of the curve. In other words,

for P $\boxed{s = \tilde{s} = z_0 - v \underset{t_0=0}{(0)} = z_1 - v t_1 = z_2 - v t_2 = \dots}$

Because:

As long as the value of argument (s) remains constant at $s = \tilde{s}$ (for point P) at different combinations of distance (z) and time (t) variables, we keep reading the same functional value $g_1(\tilde{s}) = A$.

More generally, $\tilde{s} = z - vt$ for point P where $\tilde{s} = \text{constant}$

Compute total derivatives of both sides

$$d(\tilde{s}) = d(z - vt)$$

as \tilde{s} is a constant

$$\leftarrow 0$$

$$dz - d(vt)$$

where $v = \frac{1}{\sqrt{\mu\epsilon}}$ is a constant

$$\Rightarrow 0 = dz - v dt$$

$$\Rightarrow \boxed{\frac{dz}{dt} = v = \frac{1}{\sqrt{\mu\epsilon}}}$$

Here, $\frac{dz}{dt}$ is a velocity term by definition.

(*) Therefore, $v = \frac{1}{\sqrt{\mu\epsilon}}$ is the "velocity of propagation" of point P along the z-axis. as time passes.

(*) The same discussion can be repeated for all other points of the wave form $g_1(z - vt) \Rightarrow$ The complete wave solution g_1 moves in (+z) direction with velocity

$$\boxed{v = \frac{1}{\sqrt{\mu\epsilon}}} \text{ as time increases preserving its shape.}$$

(*) Note that we need to use the condition

$$\boxed{s = z \mp vt = \text{constant}}$$

to explain traveling wave behavior.

For $g_1(z - vt)$ (Forward traveling wave)

$$\boxed{z - vt = \text{constant}} \Rightarrow \boxed{\frac{dz}{dt} = v}$$

As time (t) increases, distance (z) must also increase to keep the value of $(z - vt)$ constant.

For $g_2(z + vt)$ (Backward traveling wave)

$$\boxed{z + vt = \text{constant}} \Rightarrow \boxed{\frac{dz}{dt} = -v}$$

As t increases, z must decrease (because of the (+) sign in between) to keep the value of $(z + vt)$ constant.

$\Rightarrow g_2(z + vt)$ travels in (-z) direction

⊗ Check the unit of $\frac{1}{\sqrt{\epsilon\mu}} = v$!

$$\left. \begin{aligned} \mu &\leftrightarrow \frac{\text{Henry}}{\text{meter}} \equiv \frac{(\text{Weber/Amp})}{\text{meter}} \\ \epsilon &\leftrightarrow \frac{\text{Farad}}{\text{meter}} \equiv \frac{(\text{Coulomb/Volt})}{\text{meter}} \end{aligned} \right\} \mu\epsilon \leftrightarrow \frac{\frac{(\text{Volt})(\text{sec})}{\text{meter}} \frac{(\text{Amp})(\text{sec})}{\text{meter}}}{\text{m}^2 (\text{Amp})(\text{Volt})} = \frac{(\text{sec})^2}{\text{m}^2}$$

$$\boxed{\frac{1}{\sqrt{\mu\epsilon}} \leftrightarrow \frac{1}{\sqrt{\frac{\text{sec}^2}{\text{m}^2}}} = \left(\frac{\text{m}}{\text{sec}}\right) = \text{unit of velocity indeed!}}$$

(Remember $v_{\text{ind}} = -\frac{\partial \phi}{\partial t}$)

$$C = \frac{dq}{dt}$$

⊗ In vacuum, $v = \frac{1}{\sqrt{\epsilon_0\mu_0}} = 3 \times 10^8 \text{ m/sec}$: velocity of light in vacuum.

In other natural media: $\mu = \mu_0 \mu_r$, $\epsilon = \epsilon_0 \epsilon_r$
($\mu_r \geq 1$) ($\epsilon_r \geq 1$)

$$v = \frac{1}{\sqrt{\mu\epsilon}} = \frac{1}{\sqrt{\mu_0\epsilon_0} \sqrt{\mu_r\epsilon_r}} = \frac{c}{\sqrt{\mu_r\epsilon_r}} < c$$

(as $\mu_r \geq 1$, $\epsilon_r \geq 1$)

⊗ The argument $(z \pm vt)$ of traveling waves can be expressed in a different but equivalent way:

$$g(z-vt) = g(\underbrace{-v(t - \frac{z}{v})}_{\text{a constant}}) \equiv f(t - \frac{z}{v}) \text{ for instance.}$$

$g(z-vt)$ } forward waves
 $f(t - \frac{z}{v})$ } traveling in
 (+z) direction
 as time progresses
 with velocity

$g(z+vt)$ } backward waves
 $f(t + \frac{z}{v})$ } traveling in
 (-z) direction
 as time progresses.

Special Case II : For a [SIMPLE \oplus LOSSY \oplus SOURCE FREE] medium.

$$\downarrow \quad \bar{J}_{\text{impressed}} = 0 \\ \sigma \neq 0 \quad \bar{P}_v = 0$$

As being different from the special case I, now we have $\sigma \neq 0$ in the lossy medium.

$$\sigma \neq 0 \Rightarrow \bar{J} = \underbrace{\bar{J}_{\text{impressed}}}_{0 \text{ as the medium is source-free}} + \underbrace{\bar{J}_{\text{conduction}}}_{\sigma \bar{E} \neq 0} \Rightarrow \boxed{\bar{J} = \sigma \bar{E}}$$

must be inserted in general expressions!

For instance, $\bar{\nabla} \times \bar{H} = \bar{J} + \frac{\partial \bar{D}}{\partial t} = \sigma \bar{E} + \frac{\partial \bar{D}}{\partial t}$ in this case.
(Generalized Ampere's Law)

Using the general inhomogeneous wave equations with $\begin{cases} \bar{P}_v = 0 \\ \bar{J} = \sigma \bar{E} \end{cases}$

$$\nabla^2 \bar{E} - \mu \epsilon \frac{\partial^2 \bar{E}}{\partial t^2} = \mu \frac{\partial \bar{J}}{\partial t} + \bar{\nabla} \left(\frac{\bar{P}_v}{\epsilon} \right)$$

$$\nabla^2 \bar{E} - \mu \epsilon \frac{\partial^2 \bar{E}}{\partial t^2} = \mu \frac{\partial}{\partial t} (\sigma \bar{E}) = \mu \sigma \frac{\partial \bar{E}}{\partial t}$$

or,

$$\boxed{\nabla^2 \bar{E} - \mu \sigma \frac{\partial \bar{E}}{\partial t} - \mu \epsilon \frac{\partial^2 \bar{E}}{\partial t^2} = 0}$$

for \bar{E}

$$\nabla^2 \bar{H} - \mu \epsilon \frac{\partial^2 \bar{H}}{\partial t^2} = -\bar{\nabla} \times \bar{J}$$

$$\begin{aligned} \nabla^2 \bar{H} - \mu \epsilon \frac{\partial^2 \bar{H}}{\partial t^2} &= -\bar{\nabla} \times (\sigma \bar{E}) \\ &= -\sigma \underbrace{\bar{\nabla} \times \bar{E}}_{-\frac{\partial \bar{B}}{\partial t} \rightarrow \mu \bar{H}} \\ &= \sigma \mu \frac{\partial \bar{H}}{\partial t} \end{aligned}$$

$$\boxed{\nabla^2 \bar{H} - \mu \sigma \frac{\partial \bar{H}}{\partial t} - \mu \epsilon \frac{\partial^2 \bar{H}}{\partial t^2} = 0}$$

Partial differential equations describing
propagation in a simple, source-free but