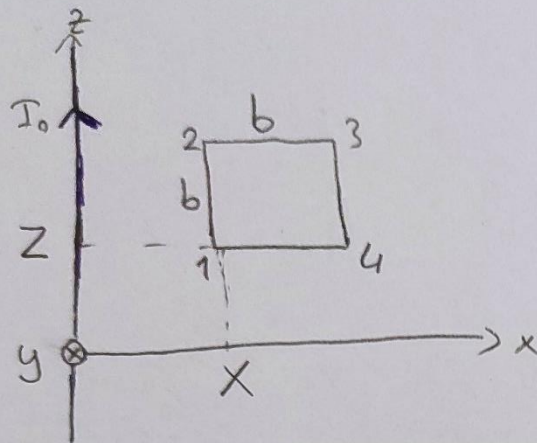


EE303 HW#1 Solution Key

Solution of Problem 1



$$\vec{B} = \hat{a}_\phi \frac{\mu_0 I_0}{2\pi r} \text{ Tesla}$$

here r : distance from z -axis
in \hat{a}_r direction

$$\text{at } y=0 \text{ plane } \vec{B} = \hat{a}_y \frac{\mu_0 I_0}{2\pi x} \text{ T}$$

a) For $\hat{n} = \hat{a}_x$: $V_{ind} = -\frac{\partial \Phi}{\partial t}$ where $\Phi = \int \vec{B} \cdot d\vec{s}$

$$d\vec{s} = \hat{a}_y dx dz$$

$$\Phi = \int_{X(t)}^{X(t)+b} \int_{z_0}^{z_0+b} \frac{\mu_0 I_0}{2\pi x} dz dx = \frac{\mu_0 I_0 b}{2\pi} \ln \left(\frac{X(t)+b}{X(t)} \right) \quad \text{wb}$$

$$V_{ind} = -\frac{d\Phi}{dt} = - \left(\frac{\mu_0 I_0 b}{2\pi} \frac{d}{dt} \left(\ln \left(\frac{X(t)+b}{X(t)} \right) \right) \right)$$

$$\Rightarrow V_{ind} = -\frac{\mu_0 I_0 b}{2\pi} \left(\frac{-b}{X(t)(X(t)+b)} \right) \frac{d(X(t))}{dt}$$

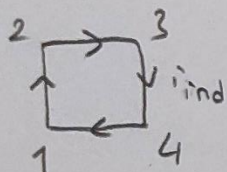
$$X(t) = \underbrace{X(t=0)}_{x_0} + \frac{a_0 t^2}{2} \Rightarrow \frac{d(X(t))}{dt} = a_0 t$$

Then

$$V_{ind} = \frac{\mu_0 I_0 b^2}{2\pi} \frac{a_0 t}{\left(x_0 + \frac{a_0 t^2}{2} \right) \left(x_0 + \frac{a_0 t^2}{2} + b \right)} \text{ Volts}$$

$$i_{\text{ind}} = \frac{V_{\text{ind}}}{R} = \frac{b^2 \mu_0 I}{2\pi R} \frac{a_0 t}{\left(x_0 + \frac{a_0 t^2}{2}\right) \left(x_0 + \frac{a_0 t^2}{2} + b\right)} \quad \text{A}$$

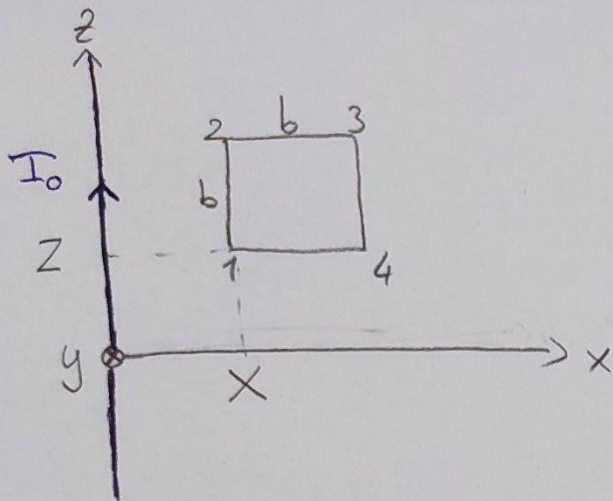
The direction of the induced current can be found by Lenz's Rule. As the square loop moves in $\hat{n} = \hat{a}_x$ direction, Φ (flux) linked by the loop decreases. Therefore, i_{ind} should be in the clockwise direction to support Φ .



b) For $\hat{n} = \hat{a}_z$, there won't be any change in flux as the square loop moves.

$$\text{Thus, } V_{\text{ind}} = -\frac{d\Phi}{dt} = 0 \text{ Volt, } i_{\text{ind}} = \frac{V_{\text{ind}}}{R} = 0 \text{ A}$$

Alternative Solution of Problem 1



$$V_{ind} = \oint_C \vec{v} \times \vec{B} \cdot d\vec{l}$$

C: The closed contour of the square loop

$$C = C_{12} + C_{23} + C_{34} + C_{41} \quad \text{then for}$$

$$C_{12} : d\vec{l} = \hat{a}_z dz$$

$$C_{23} : d\vec{l} = \hat{a}_x dx$$

$$C_{34} : d\vec{l} = \hat{a}_z dz$$

$$C_{41} : d\vec{l} = \hat{a}_x dx$$

$$a) \quad \hat{n} = \hat{a}_x \Rightarrow (\vec{v} \times \vec{B}) \cdot d\vec{l} = 0 \quad \text{for } C_{23} \text{ and } C_{41}$$

$$\left(\hat{a}_y \perp \hat{a}_x \right)$$

$$\Rightarrow V_{ind} = \int_{C_{12}} \vec{v} \times \vec{B} \cdot (\hat{a}_z dz) + \int_{C_{34}} \vec{v} \times \vec{B} \cdot (\hat{a}_z dz)$$

$$\vec{B} = \hat{a}_y \frac{\mu_0 I_0}{2\pi x} \quad \text{Tesla at } y=0 \text{ plane}$$

$$\vec{v} = \hat{a}_x \omega_0 t$$

$$\Rightarrow V_{ind} = \int_{z_0}^{z_0+b} (\hat{a}_x a_0 t) \times \left(\hat{a}_y \frac{\mu_0 I_0}{2\pi X(t)} \right) \cdot (\hat{a}_z dz) + \int_{z_0+b}^{z_0} (\hat{a}_x a_0 t) \times \left(\hat{a}_y \frac{\mu_0 I_0}{2\pi (X(t)+b)} \right) \cdot (\hat{a}_z dz)$$

$$\Rightarrow V_{ind} = \frac{\mu_0 I_0 a_0 t b^2}{2\pi X(t) (X(t)+b)} \quad \text{Volts}$$

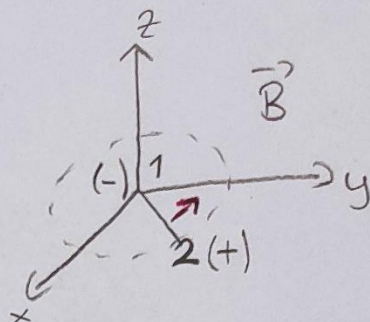
$$X(t) = X(t=0) + \frac{a_0 t^2}{2} = x_0 + \frac{a_0 t^2}{2}$$

$$\Rightarrow V_{ind} = \frac{\mu_0 I_0 a_0 t b^2}{2\pi} \frac{1}{\left(x_0 + \frac{a_0 t^2}{2}\right) \left(x_0 + \frac{a_0 t^2}{2} + b\right)} \quad \text{Volts}$$

↳ The same as the result of 1st solution

Solution of Problem 2

a) $\vec{B} = B_0 \hat{a}_z$ Tesla



$$V_{ind} = \int \vec{v} \times \vec{B} \cdot d\vec{l}$$

$$\vec{v} = |\vec{v}| \hat{a}_\phi$$

$$d\vec{l} = \hat{a}_r dr$$

N revolutions in 1 min (60 sec)
 $\Rightarrow \frac{N}{60}$ revolutions in 1 sec

At each revolution, the rotational distance taken $= 2\pi r$
(where r is the distance of an arbitrary point on the conducting rod to the origin.)

\Rightarrow With $\frac{N}{60}$ revolutions/sec, the distance taken in 1 sec $= 2\pi r \left(\frac{N}{60}\right)$ m

$$\Rightarrow \boxed{\vec{v} = \frac{2\pi r N}{60} \hat{a}_\phi \text{ m/s}}$$

the definition of velocity in m/s

$$V_{21} = \int_0^L \left(\hat{a}_\phi \frac{2\pi r N}{60} \right) \times \left(\hat{a}_z B_0 \right) \cdot \left(\hat{a}_r dr \right)$$

$$\hat{a}_\phi \times \hat{a}_z = \hat{a}_r \quad \text{and} \quad \hat{a}_r \cdot \hat{a}_r = 1$$

$$\Rightarrow V_{21} = \frac{2\pi N B_0}{60} \int_0^L r dr = \frac{2\pi N B_0}{60} \left(\frac{r^2}{2} \Big|_0^L \right)$$

$$\boxed{V_{21} = \frac{\pi N B_0 L^2}{60} \text{ Volts}}$$

b) $V_{ind} = \int \vec{v} \times \vec{B} \cdot d\vec{l}$ However, this time $\vec{v} \times \vec{B} = 0$

$$(\hat{a}_\phi \times \hat{a}_\phi = 0)$$

$$\Rightarrow \boxed{V_{21} = 0 \text{ V}}$$

Solution of Problem 3.

2) Maxwell's Equations:

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$
$$\vec{\nabla} \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$
$$\vec{\nabla} \cdot \vec{D} = \rho_v$$
$$\vec{\nabla} \cdot \vec{B} = 0$$

Constitutive relations:

$$\vec{B} = \mu \vec{H}$$
$$\vec{D} = \epsilon \vec{E}$$

Assuming a simple medium, ϵ and μ are constants.

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{H}) = \vec{\nabla} \times \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right)$$

↓

Taking the curl of $\vec{\nabla} \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{H}) = \vec{\nabla} (\vec{\nabla} \cdot \vec{H}) - \nabla^2 \vec{H}$$

Since $\vec{\nabla} \cdot \vec{B} = 0$, $\vec{\nabla} \cdot \vec{H} = 0 \Rightarrow \vec{\nabla} \times (\vec{\nabla} \times \vec{H}) = -\nabla^2 \vec{H}$

Then, $-\nabla^2 \vec{H} = \vec{\nabla} \times \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) = \vec{\nabla} \times \vec{J} + \frac{\partial}{\partial t} (\vec{\nabla} \times \vec{D})$

$$\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{D}) = \frac{\partial}{\partial t} (\epsilon \vec{\nabla} \times \vec{E}) = \epsilon \frac{\partial}{\partial t} (\vec{\nabla} \times \vec{E}) = \epsilon \frac{\partial}{\partial t} \left(-\frac{\partial \vec{B}}{\partial t} \right)$$

$$\Rightarrow \frac{\partial}{\partial t} (\vec{\nabla} \times \vec{D}) = -\epsilon \frac{\partial^2 \vec{B}}{\partial t^2} = -\epsilon \mu \frac{\partial^2 \vec{H}}{\partial t^2} \quad (\text{using } \vec{B} = \mu \vec{H})$$

$$\Rightarrow -\nabla^2 \vec{H} = \vec{\nabla} \times \vec{J} - \epsilon \mu \frac{\partial^2 \vec{H}}{\partial t^2}$$

which can be written also

$$\Leftrightarrow \boxed{\nabla^2 \vec{H} - \epsilon \mu \frac{\partial^2 \vec{H}}{\partial t^2} = -\vec{\nabla} \times \vec{J}}$$

$$b) \vec{\nabla} \cdot \vec{B} = 0$$

a vector field

using the null identity $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{V}) = 0$

$$\boxed{\vec{B} = \vec{\nabla} \times \vec{A}}, \text{ so that } \vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0 \text{ is satisfied}$$

\vec{A} : Vector potential function

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}, \quad \vec{B} = \vec{\nabla} \times \vec{A} \Rightarrow \vec{\nabla} \times \vec{E} = -\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{A})$$

$$\vec{\nabla} \times \vec{E} = -\vec{\nabla} \times \left(\frac{\partial \vec{A}}{\partial t} \right) \Rightarrow \vec{\nabla} \times \vec{E} + \vec{\nabla} \times \left(\frac{\partial \vec{A}}{\partial t} \right) = 0$$

$$\vec{\nabla} \times \left(\vec{E} + \frac{\partial \vec{A}}{\partial t} \right) = 0$$

a scalar field

Using the null identity $\vec{\nabla} \times (\vec{\nabla} S) = 0$,

$$\vec{E} + \frac{\partial \vec{A}}{\partial t} = -\nabla \Phi$$

Φ : Scalar potential function

$$\boxed{\nabla \Phi = - \left(\vec{E} + \frac{\partial \vec{A}}{\partial t} \right)}$$

c) $\vec{B} = \vec{\nabla} \times \vec{A}$ (the curl of vector potential function)

$$\vec{E} = -\vec{\nabla}\phi - \frac{\partial \vec{A}}{\partial t}$$

(For static problems, $\frac{d}{dt} = 0$, $\vec{E} = -\vec{\nabla}\phi$)