

# ArduinoSignalFilteringLibrary

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## 1 Class Index

### 1.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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## 2 Class Documentation

### 2.1 SignalFilter Class Reference

#### Public Member Functions

- [SignalFilter](#) ()  
*SignalFilter - Library to Filter Sensor Data using digital filters Available filters: Chebyshev & Bessel low pass filter (1st & 2nd order)*
- void [begin](#) ()  
*Begin function: set default filter options.*
- void [setFilter](#) (char filter)  
*setFilter(char filter): Select filter: 'c' -> Chebyshev, 'b' -> Bessel*
- void [setOrder](#) (int order)  
*selectOrder(int order): Select filter order (1 or 2)*
- int [run](#) (int data)  
*filter: Runs the actual filter: input=rawdata, output=filtered data*

#### 2.1.1 Constructor & Destructor Documentation

##### 2.1.1.1 SignalFilter::SignalFilter ( )

[SignalFilter](#) - Library to Filter Sensor Data using digital filters Available filters: Chebyshev & Bessel low pass filter (1st & 2nd order)

Constructor

### 2.1.2 Member Function Documentation

#### 2.1.2.1 void SignalFilter::begin ( )

Begin function: set default filter options.

#### 2.1.2.2 int SignalFilter::run ( int *data* )

filter: Runs the actual filter: input=rawdata, output=filtered data

#### 2.1.2.3 void SignalFilter::setFilter ( char *filter* )

[setFilter\(char filter\)](#): Select filter: 'c' -> Chebyshev, 'b' -> Bessel

#### 2.1.2.4 void SignalFilter::setOrder ( int *order* )

selectOrder(int order): Select filter order (1 or 2)

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