

Revision: 5.64

Date:2023.11





Features:

Item	Description			
	Chip	M10050		
	Receiver type	GPS L1 C/A, QZSS L1 C/A/S,BDS B1I/B1C, Galileo		
Electrical	receiver type	E1B/C,SBAS L1 C/A: WAAS, EGNOS, MSAS, GAGAN		
Characteristic	Default position system	GPS, BDS, GALILEO		
	Augmentation system	SBAS, QZSS		
	Channel	N/A		
	Tracking & Navigation	-166dBm		
Sensitivity	Reacquisition	-160dBm		
Sensitivity	Cold start	-148dBm		
	Hot Start	-160dBm		
	Horizontal position	2.0m CEP		
	Velocity	0.05m/s		
Accuracy	Dynamic heading	0.3 deg		
	Ti	RMS 30ns		
	Time pulse	99% 60ns		
	Cold start	27s		
Acquisition	Hot start	1s		
	Aided start	1s		
	Baud rate	4800bps - 921600bps,default 38400bps		
	Level	TTL level		
	Protocol	NMEA,UBX		
	NMEA messages	RMC,VTG,GGA,GSA,GSV,GLL		
Data Output	Update rate	0.25Hz-18Hz,default 1Hz		
	FLASH	With FLASH, the configuration can be changed, and the		
	FLASH	power will not be lost		
	Frequency of time pulse			
	signal Altitude	1s, and the high level lasts for 100ms		
Operational		80,000m		
Limits	Velocity	500m/s		
	Dynamics	<4g		
Power	Voltage	DC 3.6V-5.5V, typical: 5.0V		
Consumption	Current	15mA/5.0V		
Physical	Dimension	22*20*6mm		
Specications	Weight	5.3g		
	Connector	1.00mm 4pins connector		
Temperature	Operating	-40 °C ~ +85°C		



	Storage	-40°C ~ +105°C	
		TX LED: blue. The data output, TX LED flashing	
LED	Built-in LED	PPS LED: red. PPS LED not bright when GPS not fixed,	
		flashing when fixed	

Pin Description:

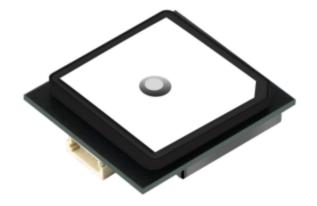


PIN	Name	I/O	Description
1	GND	G	Ground
2	TX	0	Serial Data Output.
3	RX	I	Serial Data Input.
4	VCC	I	DC 3.6V - 5.5V supply input, Typical: 5.0V

Indicator light:

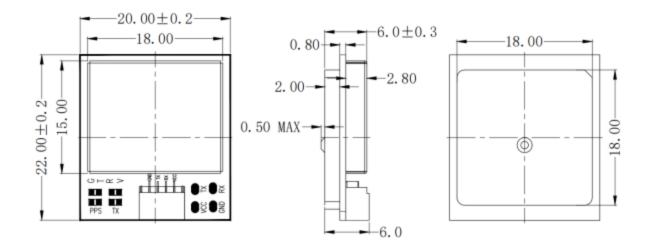
- 1. The blue light, the TX light, and the blue light flashes when power on, indicating that there is data output.
- 2. The red light, the PPS light, does not light up if it is not positioned; after 3D positioning, it starts to flash.

Rear view of the module:





Dimensions:



Data output protocol

Joint Mode Protocol Header - GN GPS Mode Protocol Header-GP GLONASS Mode Protocol Header-GL Beidou mode protocol header - GB or BD

Unlocated:

\$GNRMC,,V,,,,,,,,,N,V*37 \$GNVTG,,,,,,,,,,,,*56 \$GNGGA,,,,,0,00,99.99,,99.99,99.99,99,99,1*33 \$GNGSA,A,1,,,,,,,,,,,99.99,99.99,99,99,3*31 \$GNGSA,A,1,,,,,,,,,,,99.99,99,99,99,99,4*36 \$GNGSA,A,1,,,,,,,,,,,99.99,99,99,99,99,5*37 \$GPGSV,1,1,00,0*65 \$GAGSV,1,1,00,0*74 \$GBGSV,1,1,00,0*77 \$GQGSV,1,1,00,0*64 \$GNGLL,,,,,,V,N*7A

Positioned:

\$GNRMC,054411.00,A,2243.08151,N,11401.10827,E,0.008,,230423,,,A,V*1E \$GNVTG,,T,,M,0.008,N,0.016,K,A*32 \$GNGGA,054411.00,2243.08151,N,11401.10827,E,1,12,0.56,93.2,M,-2.7,M,,*64 \$GNGSA,A,3,30,03,14,06,07,17,01,19,...,1.15,0.56,1.00,1*0D \$GNGSA,A,3,30,13,15,34,27,02,....,1.15,0.56,1.00,3*01 \$GNGSA,A,3,27,28,30,01,02,03,37,38,40,..,1.15,0.56,1.00,4*04 \$GNGSA,A,3,02,07,03,04,....,1.15,0.56,1.00,5*00 \$GPGSV,3,1,12,01,27,034,37,03,44,087,39,06,38,241,42,07,15,180,35,1*64



\$GPGSV,3,2,12,14,78,359,45,17,43,333,38,19,28,303,39,30,34,212,39,1*6C

\$GPGSV,3,3,12,39,29,252,33,40,20,257,40,41,46,237,44,50,60,149,39,1*65

\$GPGSV,1,1,01,11,00,228,,0*5C

\$GAGSV,2,1,06,02,30,136,38,13,23,238,40,15,68,289,42,27,37,324,30,7*7E

\$GAGSV,2,2,06,30,83,091,42,34,41,026,41,7*70

\$GBGSV,3,1,11,01,47,123,36,02,46,234,37,03,63,189,38,04,,,31,1*49

\$GBGSV,3,2,11,05,..34,27,52,351,44,28,24,046,37,30,31,283,40,1*46

\$GBGSV,3,3,11,37,43,178,40,38,70,172,40,40,57,034,39,1*48

\$GQGSV,1,1,04,02,63,125,42,03,59,044,39,04,38,131,38,07,60,149,36,1*6C

\$GNGLL,2243.08151,N,11401.10827,E,054411.00,A,A*71

xxGGA, time, lat, NS, lon, EW, quality, numSV, HDOP, alt, altUnit, sep, sepUnit, diffAge, diffStation*cs
 xxGGA, time, lat, NS, lon, EW, quality, numSV, HDOP, alt, altUnit, sep, sepUnit, diffAge, diffStation*cs
 xxGGA, time, lat, NS, lon, EW, quality, numSV, HDOP, alt, altUnit, sep, sepUnit, diffAge, diffStation*c

Example:

\$GPGGA,092725.00,4717.11399,N,00833.91590,E,1,08,1.01,499.6,M,48.0,M,,*5B

Field	Name	Unit	Format	Example	Description
No.					
0	xxGGA	-	string	\$GPGGA	GGA Message ID (xx = current Talker ID, see
					NMEA Talker IDs table)
1	time	-	hhmmss.ss	092725.00	UTC time, see note on UTC representation
2	lat	-	ddmm.	4717.11399	Latitude (degrees & minutes), see format
			mmmmm		description
3	NS	-	character	N	North/South indicator
4	lon	-	dddmm.	00833.91590	Longitude (degrees & minutes), see format
			mmmmm		description
5	EW	-	character	E	East/West indicator
6	quality	-	digit	1	Quality indicator for position fix, see position
					fix flags description Flags in NMEA 4.10 and
					<u>above</u>
7	numSV	-	numeric	08	Number of satellites used (range: 0-12)
8	HDOP	-	numeric	1.01	Horizontal Dilution of Precision
9	alt	m	numeric	499.6	Altitude above mean sea level
Field	Name	Unit	Format	Example	Description
No.					
10	altUnit	-	character	М	Altitude units: M (meters, fixed field)
11	sep	m	numeric	48.0	Geoid separation: difference between
					ellipsoid
					and mean sea level
12	sepUnit	-	character	М	Geoid separation units: M (meters, fixed
					field)
13	diffAge	s	numeric	-	Age of differential corrections (null when
					DGPS is not used)
14	diffStat	-	numeric	-	ID of station providing differential corrections
	ion				(null when DGPS is not used)



15	cs	-	hexadecim al	*5B	Checksum
16	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed

\$xxGLL,lat,NS,lon,EW,time,status,posMode*cs<CR><LF> Example:

\$GF	PGI	LL,4717.113	64,N,	00833.91565,E	E,092321.00,A,	A*60
Fiel	d	Name	Unit	Format	Example	Desc

Field	Name	Unit	Format	Example	Description
No.					
0	xxGLL	-	string	\$GPGLL	GLL Message ID (xx = current Talker ID, see
					NMEA Talker IDs table)
1	lat	-	ddmm.	4717.11364	Latitude (degrees & minutes), see format
			mmmmm		description
2	NS	-	character	N	North/South indicator
3	lon	-	dddmm.	00833.91565	Longitude (degrees & minutes), see format
			mmmmm		description
4	EW	-	character	E	East/West indicator
5	time	-	hhmmss.ss	092321.00	UTC time, see note on UTC representation
6	status	-	character	А	Data validity status, see position fix flags
					description
7	posMode	-	character	Α	Positioning mode, see position fix flags
					description (only available in NMEA 2.3 and
					later)
Field	Name	Unit	Format	Example	Description
No.					
8	cs	-	hexadecimal	*60	Checksum
9	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed

\$GPGSA,A,3,23,29,07,08,09,18,26,28,,,,,1.94,1.18,1.54,1*0D

Field	Name	Unit	Format	Example	Description			
No.								
0	xxGSA	-	string	\$GPGSA	GSA Message ID (xx = current Talker ID, see			
					NMEA Talker IDs table)			
1	opMode	-	character	A	Operation mode:			
					M = Manually set to operate in 2D or 3D mode			
					A = Automatically switching between 2D or 3D			
					mode			
2	navMode	-	digit	3	Navigation mode, see position fix flags			
					description			
Start o	Start of repeated block (12 times)							



3 +	svid	-	numeric	29	Satellite number
1*N					
End o	f repeated bl	ock	•		
15	PDOP	-	numeric	1.94	Position dilution of precision
16	HDOP	-	numeric	1.18	Horizontal dilution of precision
17	VDOP	-	numeric	1.54	Vertical dilution of precision
18	systemId	-	numeric	1	NMEA defined GNSS System ID, see Signal Identifiers table (only available in NMEA 4.10 and later)
19	cs	-	hexadecimal	*0D	Checksum
20	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed

\$xxGSV,numMsg,msgNum,numSV{,svid,elv,az,cno},signalld*cs<CR><LF>

Example:

\$GPGSV,3,1,09,09,,,17,10,,,40,12,,,49,13,,,35,1*6F

\$GPGSV,3,2,09,15,,,44,17,,,45,19,,,44,24,,,50,1*64

\$GPGSV,3,3,09,25,,,40,1*6E

\$GPGSV,1,1,03,12,,,42,24,,,47,32,,,37,5*66

\$GAGSV,1,1,00,2*76

Field No.	Name	Unit	Format	Example	Description
0	xxGSV	-	string	\$GPGSV	GSV Message ID (xx = GSV Talker ID, see NMEA Talker IDs table). Talker ID GN shall not be used
1	numMsg	-	digit	3	Number of messages, total number of GSV messages being output (range: 1-9)
2	msgNum	-	digit	1	Number of this message (range: 1-numMsg)
3	numSV	-	numeric	10	Number of known satellites in view regarding both the talker ID and the signalld
Start o	of repeated b	olock	(14 times)	•	·
4 + 4*N	svid	-	numeric	23	Satellite ID
5 + 4*N	elv	deg	numeric	38	Elevation (range: 0-90)
6 + 4*N	az	deg	numeric	230	Azimuth (range: 0-359)
7 + 4*N	cno	dB Hz	numeric	44	Signal strength (C/N0, range: 0-99), null when not tracking
End o	frepeated b	lock	•	•	
Field No.	Name	Unit	Format	Example	Description
5 16	signalld	-	numeric	0	NMEA defined GNSS Signal ID, see Signal Identifiers table (only available in NMEA 4.10



					and later)
6	cs	-	hexadecimal	*7F	Checksum
16					
7	<cr><lf></lf></cr>	}	character	-	Carriage return and line feed
16					

xxRMC, time, status, lat, NS, lon, EW, spd, cog, date, mv, mvEW, posMode, navStatus*cs < CR > < LF > Example:

Field	Name	Unit	Format	Example	Description
No.					
0	xxRMC	-	string	\$GPRMC	RMC Message ID (xx = current Talker ID, see
					NMEA Talker IDs table)
1	time	-	hhmmss.ss	083559.00	UTC time, see note on UTC representation
2	status	-	character	Α	Data validity status, see position fix flags
					description
3	lat	-	ddmm.	4717.11437	Latitude (degrees & minutes), see format
			mmmmm		description
4	NS	-	character	N	North/South indicator
5	lon	-	dddmm.	00833.91522	Longitude (degrees & minutes), see format
			mmmmm		description
6	EW	-	character	E	East/West indicator
7	spd	kno	numeric	0.004	Speed over ground
		ts			
8	cog	deg	numeric	77.52	Course over ground
		ree s			
Field	Name	Unit	Format	Example	Description
No.					
9	date	-	ddmmyy	091202	Date in day, month, year format, see note on
					UTC representation
10	mν	deg	numeric	-	Magnetic variation value. Only supported in
		ree s			ADR 4.10 and later
11	mvEW	-	character	-	Magnetic variation E/W indicator. Only
					supported in ADR 4.10 and later
12	posMode	-	character	A	Mode Indicator, see position fix flags
					description (only available in NMEA 2.3 and
					later)



13	navStatu	-	character	V	Navigational status indicator: V (Equipment is
	s				not providing navigational status information,
					fixed field, only available in NMEA 4.10 and
					ater)
14	cs	-	hexadecimal	*57	Checksum
15	<cr><l< td=""><td>-</td><td>character</td><td>-</td><td>Carriage return and line feed</td></l<></cr>	-	character	-	Carriage return and line feed
	F>				

\$xxVTG, cogt, cogtUnit, cogm, cogmUnit, sogn, sognUnit, sogk, sogkUnit, posMode*cs < CR > < LF >

Example:

Field	Name	Unit	Format	Example	Description			
No.	Valle	, , , , , , , , , , , , , , , , , , ,	Office	Lxample	Description			
0	xxVTG	G - string \$GPVTG VTG Mess:		\$GPVTG	VTG Message ID (xx = current Talker ID, see			
					NMEA Talker IDs table)			
1	cogt	deg	numeric	77.52	Course over ground (true)			
		re e						
		s						
2	cogtUnit	-	character	Course over ground units: T (degrees true,				
					fixed field)			
3	cogm	deg	numeric	-	Course over ground (magnetic). Only			
		re e			supported in ADR 4.10 and above			
		s						
4	cogmUnit	-	character	M	Course over ground units: M (degrees			
					magnetic, fixed field)			
5	sogn kno numeric 0.004		0.004	Speed over ground				
		ts						
6	sognUnit	-	character	N	Speed over ground units: N (knots, fixed field)			
Field	Name	Unit	Format	Example	Description			
No.								
7	sogk	km/	numeric	0.008	Speed over ground			
		h						
8	sogkUnit	-	character	K	Speed over ground units: K (kilometers per			
					hour, fixed field)			
9	posMode	-	character	A	Mode Indicator, see position fix flags			
					description (only available in NMEA 2.3 and			
					later)			
10	cs	-	hexadecimal	*06	Checksum			
11	<cr><lf></lf></cr>	-	character	-	Carriage return and line feed			

Flags in NMEA 4.10 and above

NMEA Message	GLL, RMC	GGA	GLL, VTG	RMC, GNS



Field	status	quality	posMode	posMode			
No position fix (at power-up, after losing satellite lock)	V	0	N	N			
GNSS fix, but user limits exceeded	V	0	N	N			
Dead reckoning fix, but user limits exceeded	V	6	Е	E			
Dead reckoning fix	Α	6	Е	E			
RTK float	Α	5	D	F			
RTK fixed	Α	4	D	R			
2D GNSS fix	Α	1/2	A/D	A/D			
3D GNSS fix	Α	1/2	A/D	A/D			
Combined GNSS/dead reckoning fix	Α	1/2	A/D	A/D			
	See below (1)	See below(2)	See below(3)	See below(3)			

- (1) Possible values for status: V = Data invalid, A = Data valid
- (2) Possible values for quality: 0 = No fix, 1 = Autonomous GNSS fix, 2 = Differential GNSS fix, 4 = RTK fixed, 5 = RTK float, 6 = Estimated/Dead reckoning fix
- (3) Possible values for posMode: N = No fix, E = Estimated/Dead reckoning fix, A = Autonomous GNSS fix, D = Differential GNSS fix, F = RTK float, R = RTK fixed