Connectionist Temporal Classification

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The Speech Recognition Problem

The input is an audio clip \mathbf{x} , as a sequence of frames:

$$\mathbf{x} = \{\mathbf{x}_1 \dots \mathbf{x}_T\}$$

where each frame at time t, \mathbf{x}_t , consists of weights of G spectrograms:

$$\mathbf{x}_t = [x_{t,1} \dots x_{t,G}]^T$$

We can design a RNN to output \mathbf{y}_t for each input frame \mathbf{x}_t :

$$\mathbf{y} = \{\mathbf{y}_1 \dots \mathbf{y}_T\}$$

where each output \mathbf{y}_t is a probability distribution over an alphabet:

$$\mathbf{y}_t = [y_{t,1} \dots y_{t,K}]^T$$

where $y_{t,k} = P(l_t = k)$, and l_t denotes the letter pronounced at time t.

Now, the problem comes – how can we interpret y as a sequence of letters.

At the first sight, this is straightforward – we just find a path

$$\boldsymbol{\pi} = \{\pi_1 \dots \pi_T\}$$

where $\pi_t \in [1, K]$, by

$$\pi = \arg \max_{\pi} P(\pi|\mathbf{y})$$

where $P(\boldsymbol{\pi}|\mathbf{y})$ could be defined as, say,

$$P(\boldsymbol{\pi}|\mathbf{y}) = \prod_{t=1}^{T} y_{t,\pi_t}$$

or

$$P(\boldsymbol{\pi}|\mathbf{y}) = \prod_{t=1}^{T} y_{t,\pi_t} P(\pi_t | \pi_{t-1})$$

where $P(\pi_t|\pi_{t-1})$ comes from a pre-trained n-gram language model.

However, these are NOT what we need. Imagine that people are saying "a". There could be silence (or blank) before and/or after the pronunciation. So the path π could be

```
aaaaaaaa
aaaaa___
___aaaa
__aaaaa_
```

This does not even consider that the period of silences and pronunciations vary. So the following cases all correspond to "a":

```
aa____
aaa____
_aaaa___
_aaaaaaa
```

This tells that the output we really want is not \mathbf{y} nor $\boldsymbol{\pi}$. Instead, it is some sequence called *label* and denoted by \mathbf{l} :

$$\mathbf{l} = \{l_1 \dots l_S\}$$

where $S \leq T$.

For above example, all those paths correspond to the same label: $l = \{a\}$.

Few more examples help reveal the relationship between path π and labels l. All the following examples correspond to $\mathbf{l} = \{h, e\}$:

hhheeee _heee_ hh__eee hh_eee h_ee_ _h_ee_

Please note that blanks could appear before, between, and after consequent appearances of "h" (and "e").

A little more complex example is that all the following paths correspond to label $l = \{b, e, e\}$:

```
bbbeee_ee
_bb_ee_e
_bbbe_e
except for
_b_eeeeee
bbb_eeee_
```

which correspond to $\mathbf{l} = \{b, e\}$. This example shows the importance of blank in separating consecutive letters.

In summary, the output of speech recognition is not alphabet probability distribution \mathbf{y} or path $\boldsymbol{\pi}$, but label \mathbf{l} . And the CTC approach is all about infer \mathbf{l} from \mathbf{y} , by integrating out $\boldsymbol{\pi}$:

$$P(\mathbf{l}|\mathbf{x}) = \sum_{\boldsymbol{\pi}} P(\mathbf{l}|\boldsymbol{\pi}) P(\boldsymbol{\pi}|\mathbf{x})$$

where

$$P(\mathbf{l}|\boldsymbol{\pi}) = \begin{cases} 1 & \text{if } \boldsymbol{\pi} \text{ matches } \mathbf{l} \\ 0 & \text{otherwise} \end{cases}$$

$$P(\boldsymbol{\pi}|\mathbf{x}) = \prod_{t=1}^{T} y_{t,\pi_t}$$

Dynamic Time Warping

Because the length of \mathbf{y} might differ from (often longer than) \mathbf{l} , so the inference of \mathbf{l} from \mathbf{y} is actually a dynamic time warping problem.

There is a dynamic programming algorithm that can solve this time warping problem. And this algorithm enables us to train the RNN using \mathbf{x} and \mathbf{l} pairs, instead of \mathbf{x} and \mathbf{y} pairs. This is very valuable because there is no need to segment \mathbf{y} and align \mathbf{y} with \mathbf{x} before training.

When we say time warping, we mean that we want to map each frame \mathbf{y}_t to some l_s . The second example above shows that we actually want to make \mathbf{y}_t to either a l_s or a blank, because only if we do so, we have the chance to recognize successive letters like "ff" and "ee" in "coffee", and "ee" in "bee".

Here is a more detailed example about this. Suppose that we have an audio clip of "bee". The most probable path π is

```
___bbeeee____
```

we would like to wrap it to $l = \{b, e, e\}$. It looks like we can map as

```
___bbeeee
\|||//
|||
bee
```

but the truth is that we do not have much information to prevent the algorithm from mapping all e's in π into the first e in l:

```
___bbeeee____
\||///
||
bee
```

And another problem is that to whom should we map those blanks in π ?

A solution other than to map π to \mathbf{l} is to map π to \mathbf{l}' , which is constructed by inserting blanks before, after, and into \mathbf{l} . For the above example, we have

$$\mathbf{l}' = \{, b, e, e, e, \}$$

and the warping could work as:

```
___bbeeee____
\\||/|||///
|| ||| /
_b_e_e_
```

An a little more special case could be that π does not contain leading blanks. In this case, it is reasonable to map the first frame to "b", instead of the leading "__", of 1':

```
bbbeeee____
||////////
||||| /
_b_e_e_
```

A similar edge case is that π does not have padding blanks, therefore no frame should be mapped to the padding blank of l'. These two cases are what we need to care about in designing the algorithm that computes the map from π to l'.

The Forward-Backward Algorithm

Here we derive the dynamic programming algorithm for computing $P(\mathbf{l}'|\mathbf{x})$, which, is notably equivalent to $P(\mathbf{l}|\mathbf{x})$, because \mathbf{l}' is constructed to be unique for the given \mathbf{l} .

The above time warping example shows that π_T could be mapped to either $l'_{|I'|}$, the padding blank of I', or $l'_{|I'|-1}$, which, according to the construction rule of I', is the last element of I. So we have:

$$P(\mathbf{l}'|\mathbf{x}) = P(\mathbf{l}', \pi_T = l'_{|\mathbf{l}'|}|\mathbf{x}) + P(\mathbf{l}', \pi_T = l'_{|\mathbf{l}'|-1}|\mathbf{x})$$

We can generalize $P(\mathbf{l}', \pi_T = l'_{|\mathbf{l}'|}|\mathbf{x})$ and $P(\mathbf{l}', \pi_T = l'_{|\mathbf{l}'|-1}|\mathbf{x})$ to be

$$\alpha(t,s) = P(\mathbf{l'}_{1:s}, \pi_t = l'_s | \mathbf{x})$$

SO

$$P(\mathbf{l}'|\mathbf{x}) = \alpha(T, |\mathbf{l}'|) + \alpha(T, |\mathbf{l}'| - 1)$$

Above time warping example also shows that π_1 could be mapped to either l'_1 , the leading blank of \mathbf{l}' , or l'_2 , the first element of \mathbf{l} . So we have

$$\alpha(1,1) = y_{1,_}$$
 $\alpha(1,2) = y_{1,l_1}$
 $\alpha(1,s) = 0, \forall s > 2$

Here let us take an example. Suppose that $\mathbf{l}' = \{_, h, _, e, _\}$ and a \mathbf{y} (which, for the simplicity, is illustrated as a sequence of subscripts). It is reasonable to map π_1 to l'_1 , the leading blank of \mathbf{l}' , if $\arg\max_k y_{1,k} = "_"$:

Then we think a step further – mapping π_2 , or more generally, π_s . Roughly, it is reasonable to map π_t to

```
1. where \pi_{t-1} was mapped to, denoted by l'_{s(t-1)},
```

- 2. the element next to $l'_{s(t-1)}$, denoted by $l'_{s(t-1)+1}$, or
- 3. $l'_{s(t-1)+2}$, if $l'_{s(t-1)+1} =$

Among these, case 3 is reasonable in case that we want to skip that blank $l'_{s(t-1)+1} =$ "_". An example is that when we want to map $\pi = \{h, h, h, h, e, e, e\}$ to $\mathbf{l'} = \{_, h, _, e, _\}$ – it is not mandatory to map any π_t to any blank in $\mathbf{l'}$, in order to recognize the word "he".

hhhheee \|//|// | / _h_e_

But case 3 is not reasonable when $l'_{s(t-1)+2} = l'_{s(t-1)}$. In this case, we should not skip that blank. For example, to recognize the word "bee", we have $\mathbf{l'} = \{_, b, _, e, _, e, _\}$. In these case, if we skip over the blank between the two es in $\mathbf{l'}$, we would misunderstand the double-e as a single e. In the example below, even if frame (\mathbf{y}_5) sounds more like e than blank, we want to map it to $l'_5 =$ "_", so to recognize the word "bee".

```
bbbeeeee
\|||||//
|/|||
_b_e_e_
```

Summarizing above three cases, we get the following generalization rule for $\alpha(t,s)$:

$$\alpha(t,s) = \begin{cases} y_{t,l_s'} \sum_{i=s-1}^s \alpha(t-1,i) & \text{if } l_s' = _ \text{ or } l_s' = l_{s-2}' \\ y_{t,l_s'} \sum_{i=s-2}^s \alpha(t-1,i) & \text{otherwise} \end{cases}$$

This general rule shows that, to compute $\alpha(t,s)$, we need $\alpha(t-1,s)$, $\alpha(t-1,s-1)$ and $\alpha(t-1,s-2)$. Some of these values are obviously zero. The following figure from Alex Graves' Ph.D. thesis helps us understand in particular which are zeros.

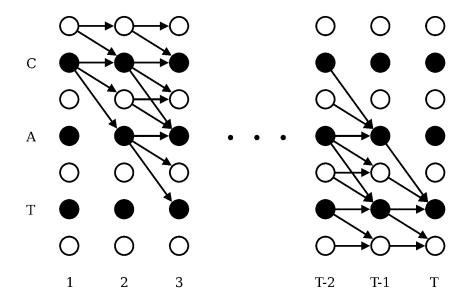


Figure 1: The search space of the forward-backward algorithm

Quiz

1. Please illustrate the search space of the forward-backward algorithm given $\mathbf{l} = \{b, e, e\}$, like Alex Graves illustrates the case of $\mathbf{l} = \{c, a, t\}$ with Figure 7.2 in his Ph.D. thesis.