FACIAL EMOTION DETECTION USING CONVOLUTIONAL NEURAL NETWORKS

This project report is submitted for the partial fulfillment of the degree of Bachelor of Science in Computer Science

Submitted By

Tanmoy Das Utsav Saha Soumik Choudhury Reg.No. 1131911400411 Reg.No. 1131911400403 Reg.No. 1131911400408

Under The Guidance Of DR. Rajib Sarkar

Department of Computer Science WEST BENGAL STATE UNIVERSITY KOLKATA - 700126

Declaration

We hereby declare that except where specific reference is made to the work of others, the contents of this dissertation are original and have not been submitted in whole or in part for consideration for any other degree or qualification in this, or any other university. This dissertation is our own work and contains nothing which is the outcome of work done in collaboration with others, except as specified in the text and Acknowledgements.

Tanmoy I	Das
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Utsav Saha

Soumik Choudhury

Reg. No. 1131911400411 Computer Science Department

Reg. No. 1131911400403 **Computer Science** Department

Reg. No. 1131911400408 Computer Science Department West Bengal State University West Bengal State University West Bengal State University

West Bengal State University

Department of Computer Science Barasat, Kolkata – 7000126

CERTIFICATE

This is to certify that the project entitled "Facial Expression Detection" has been prepared according to the regulation of the Degree of Bachelor of Science in Computer Science and the candidates have partially fulfilled the academic session 2019-2022.

> Dr. Rajib Sarkar **Project Supervisor**

Computer Science Department Derozio Memorial College West Bengal State University

Dr. Rajib Sarkar **Head Of Department**

Computer Science Department Derozio Memorial College West Bengal State University

Candidates	
------------	--

Tanmoy Das

Reg. No. 1131911400411 Computer Science Department West Bengal State University West Bengal State University West Bengal State University

Utsav Saha

Reg. No. 1131911400403 Computer Science Department

Soumik Choudhury

Reg. No. 1131911400408 Computer Science Department

West Bengal State University

Department of Computer Science Barasat, Kolkata – 7000126

CERTIFICATE OF APPROVAL

${f T}$ he foregoing project report entitled "Facial Expression Detection " is hereby approved as
a creditable study of B.Sc.(Hons.) subject carried out and presented in a manner
satisfactory to warrant its acceptance as a prerequisite to the degree for which it has
been submitted. It is understood by this approval the undersigned do not necessarily
endorse or accept every statement made, opinion expressed or conclusion drawn therein
but approve the report only for the purpose for which it has been submitted.

Internal Examiner		External Examiner
	Candidates	
Tanmoy Das Reg. No. 1131911400411	Utsav Saha Reg. No. 1131911400403	Soumik Choudhury Reg. No. 1131911400408

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Tanmoy Das Reg. No. 1131911400411

Utsav Saha Reg. No. 1131911400403 Soumik Choudhury Reg. No. 1131911400408

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ABSTRACT

Human emotions are the mental state of feelings and are spontaneous. There is no clear connection between emotions and facial expressions and there is significant variability making facial recognition a challenging research area. Features like Histogram of Oriented Gradient (HOG) and Scale Invariant Feature Transform (SIFT) have been considered for pattern recognition. These features are extracted from images according to manual predefined algorithms. In recent years, Machine Learning (ML) and Neural Networks (NNs) have been used for emotion recognition. In this report, a Convolution Neural Network (CNN) is used to extract features from images to detect emotions. The Python Dlib toolkit is used to identify and extract 64 important landmarks on a face. A CNN model is trained with greyscale images from the FER 2013 dataset to classify expressions into five emotions, namely happy, sad, neutral, fear and angry. To improve the accuracy and avoid over fitting of the model, batch normalization and dropout are used. The best model parameters are determined considering the training results. The test results obtained show that CNN Model is 80% accurate for five emotions (happy, sad, angry, fear, Neutral) and 72% accurate for Seven emotions (happy, sad, angry, neutral, fear, Surprise, Disgust).

CHAPTER 1: INTRODUCTION

 ${\sf F}$ acial emotions are important factors in human communication that help to understand the intentions of others. In general, people infer the emotional state of other people, such as joy, sadness and anger, using facial expressions and vocal tones. Facial expressions are one of the main information channels in interpersonal communication. Therefore, it is natural that facial emotion research has gained a lot of attention over the past decade with applications in perceptual and cognitive sciences. Interest in automatic Facial Emotion Recognition (FER) has also been increasing recently with the rapid development of Artificial Intelligent (AI) techniques. They are now used in many applications and their exposure to humans is increasing. To improve Human Computer Interaction (HCI) and make it more natural, machines must be provided with the capability to understand the surrounding environment, especially the intentions of humans. Machines can capture their environment state through cameras and sensors. In recent years, Deep Learning (DL) algorithms have proven to be very successful in capturing environment states . Emotion detection is necessary for machines to better serve their purpose since they deliver information about the inner state of humans. A machine can use a sequence of facial images with DL techniques to determine human emotions.

Facial Emotion Recognition

FER typically has four steps. The first is to detect a face in an image and draw a rectangle around it and the next step is to detect landmarks in this face region. The third step is extracting spatial and temporal features from the facial components. The final step is to use a Feature Extraction (FE) classifier and produce the recognition results using the extracted features. Figure 1 shows the FER procedure for an input image where a face region and facial landmarks are detected. Facial landmarks are visually salient points such as the end of a nose, and the ends of eyebrows and the mouth as shown in Figure 2. The pair wise positions of two landmark points or the local texture of a landmark are used as features. Table 1 gives the definitions of 64 primary and secondary landmarks. The spatial and temporal features are extracted from the face and the expression is determined based on one of the facial categories using pattern classifiers. [1]

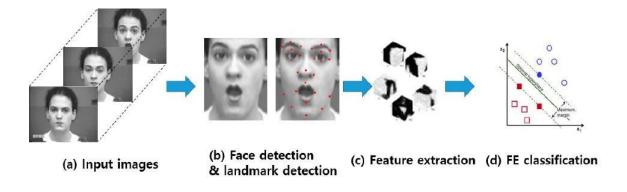


Figure 1 FER Procedure For An Image

Table 1: Definitions of 64 Primary And Secondary Landmarks

Primary landmarks		Secondary landmarks	
Number	Definition	Number	Definition
16	Left eyebrow outer corner	1	Left temple
19	Left eyebrow inner corner	8	Chin tip
22	Right eyebrow inner corner	2-7,9-14	Cheek contours
25	Right eyebrow outer corner	15	Right temple
28	Left eye outer corner	16-19	Left eyebrow contours
30	Left eye inner corner	22-25	Right eyebrow corners
32	Right eye inner corner	29,33	Upper eyelid centers
34	Right eye outer corner	31,35	Lower eyelid centers
41	Nose tip	36,37	Nose saddles
46	Left mouth corner	40,42	Nose peaks (nostrils)
52	Right mouth corner	38-40,42-45	Nose contours
63,64	Eye centers	47-51,53-62	Mouth contours

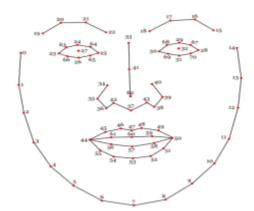


Figure 2: Facial landmarks to be extracted from face

DL based FER approaches greatly reduce the dependence on face-physics based models and other pre-processing techniques by enabling end to end learning directly from the input images. Among DL models, Convolution Neural Networks (CNNs) are the most popular. With a CNN, an input image is filtered through convolution layers to produce a feature map. This map is then input to fully connected layers, and the facial expression is recognized as belonging to a class based on the output of the FE classifier. The dataset used for this model is the Facial Emotion Recognition 2013 (FER 2013) dataset. This is an open source dataset that was created for a project then shared publicly for a Kaggle competition. It consists of 35,000 greyscale size 48×48 face images with various emotion labels. For this project, five emotions are used, namely happy, angry, neutral, sad and fear.

Facial expressions are used by humans to convey mood. Automatic facial expression analysis tools have applications in robotics, medicine, driving assist systems, and lie detection. Recent advances in FER have led to improvements in neuroscience and cognitive science. Further developments in Computer Vision (CV), and ML have made emotion identification

more accurate and accessible. Table 2 gives a summary of FER systems based on DL methods.

Table 2: A summary of FER systems based on DL

Referenc e	Emotions analyzed	Recognition algorithm	Databas e
Hybrid CNN- RNN	(angry, disgust, fear,	Hybrid Recurrent Neural Network (RNN)- CNN framework for propagating information over a sequence Temporal averaging is used for aggregation	EmotiW
Spatio temporal feature representati on	, , ,	Spatial image characteristics of the representative expression state frames are learned using a CNN Temporal characteristics of the spatial feature representation in the first part are learned using a long short term memory model	
Joint fine using		Two different models CNN for temporal appearance features CNN for temporal geometry features from temporal facial landmark points	CK+ MMI
Candide-3	: = :	Candide-3 model in conjunction with a learned objective function for face model fitting RNN for temporal dependencies present in the image sequences during classification	
Multi angle FER	: = :	Extraction of texture patterns and the relevant key features of the facial points CNN to predict labels for the facial expressions	

Al and Machine Learning (ML) are widely employed in many domains. In data mining, they have been used to detect insurance fraud . In clustering based data mining was used to identify patterns in stock market data. ML algorithms have played a significant role in pattern recognition and pattern classification problems such as FER, Electroencephalography (EEG) and spam detection . ML can be used to provide cost-effective, reliable and low computation time FER solutions .

CHAPTER 2 PROPOSED METHODOLOGY

In this chapter we discussed about our flow chart representation, CNN architecture, our training model, our validation and testing process.

As an input we take a single image or an image sequence or video then we put it into our testing model then the testing model [12] calls the trainer as well as the xml file where the face detecting methodology performed if the methodology gives us a false value then we go again for a valid input and if the methodology gives us True value or in other words if face is detected then we move forward. Now we extract the features of the image or image sequence's 1 frame at a time and applied classification over it, and at a same time we called the PRE BUILD Trainer Model [11] by the trainer programme and check for the validation for the classes 5 or 7 and then shows the prediction and this process continues until the process killed or terminated by the system. You can view the full source code here [13].

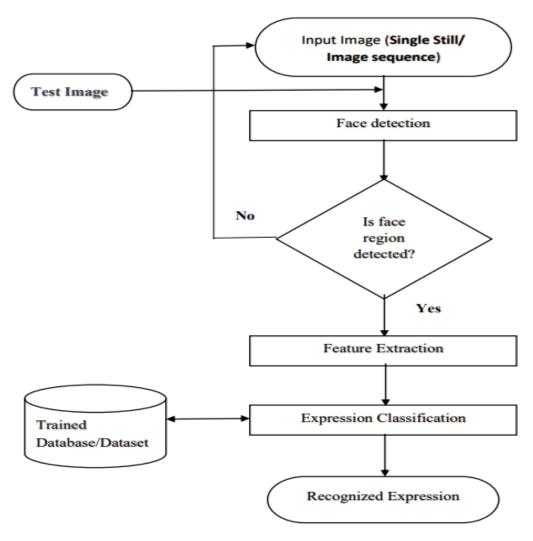


Figure 3: Flow Chart Of Our Testing Model while we have already our pre-generated Trained Model.

The fundamental building block of a NN is a neuron. Figure 4 shows the structure of a neuron. Forward propagation of information through a neuron happens when inputs x1 to xm are multiplied by their corresponding weights and then added together. This result is passed through a nonlinear activation function along with a bias term which shifts the output. The bias is shown as w0 in Figure 4. For an input vector x=x1, x2,..., xm and weight vector w=w1, w2,..., wm, the neuron output is

$$\hat{y} = g(w_0 + \sum_{i=1}^m x_i w_i).$$

The output is between 0 and 1 which makes it suitable for problems with probabilities. The purpose of the activation function is to introduce nonlinearities in the network since most real world data is nonlinear. The use of a nonlinear function also allows NNs to approximate complex functions.

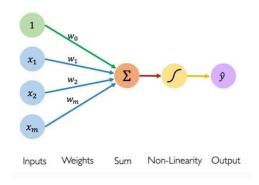


Figure 4: Diagram Of Convolutional Neural Network (CNN)

2.1 Concepts of Deep learning

Neurons can be combined to create a multi output NN. If every input has a connection to every neuron it is called dense or fully connected. Figure 5 shows a dense multi output NN with two neurons. A deep NN has multiple hidden layers stacked on top of each other and every neuron in each hidden layer is connected to a neuron in the previous layer.

A CNN is a DL algorithm which takes an input image, assigns importance (learnable weights and biases) to various aspects/objects in the image and is able to differentiate between images. The pre-processing required in a CNN is much lower than other classification algorithms. Figure 5 shows the CNN operations. The architecture of a CNN is analogous to that of the connectivity pattern of neurons in the human brain and was inspired by the organization of the visual cortex. One role of a CNN is to reduce images into a form which is easier to process without losing features that are critical for good prediction. This is important when designing an architecture which is not only good at learning features but also is scalable to massive datasets. The main CNN operations are convolution, pooling, batch normalization and dropout which are described below. [2-3]

The objective of the convolution operation is to extract high level features such as edges from an input image. The convolution layer functions are as follows.

- •The first convolution layer(s) learns features such as edges, colour, gradient orientation and simple textures.
- •The next convolution layer(s) learns features that are more complex textures and patterns.
- •The last convolution layer(s) learns features such as objects or parts of objects.

The element involved in carrying out the convolution operation is called the kernel. A kernel filters everything that is not important for the feature map, only focusing on specific information. The filter moves to the right with a certain stride length till it parses the complete width. Then, it goes back to the left of the image with the same stride length and repeats the process until the entire image is traversed.

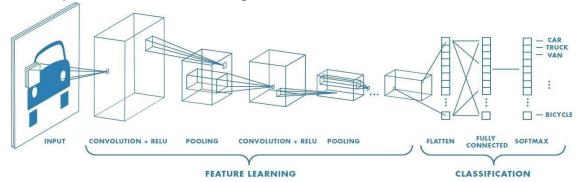


Figure 5: The CNN operations

The filter kernel:

1	0	1
0	1	0
1	0	1

The stride length is chosen as one so the kernel shifts nine times, each time performing a matrix multiplication of the kernel and the portion of the image under it.

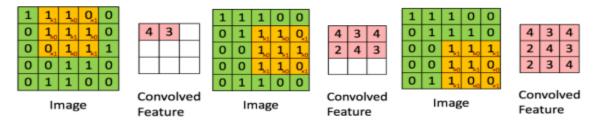


Figure 6: Convolving a 5 × 5 image with a 3 × 3 kernel to get a 3 × 3 convolved feature

The pooling layer reduces the spatial size of a convolved feature. This is done to decrease the computations required to process the data and extract dominant features which are rotation and position invariant. There are two types of pooling, namely max pooling and average pooling. Max pooling returns the maximum value from the portion of the image covered by the kernel, while average pooling returns the average of the corresponding values. Figure 7 shows the outputs obtained by performing max and average pooling on an image.

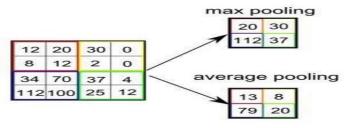


Figure 7: Max and average poling outputs for an image

Neurons in a fully connected layer have connections to all neurons in the previous layer. This layer is found towards the end of a CNN. In this layer, the input from the previous layer is flattened into a one-dimensional vector and an activation function is applied to obtain the output.

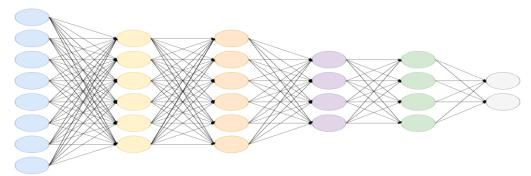


Figure 8: Fully Connected Layer As A Need Of Every Perfect CNN Model

Dropout is used to avoid over fitting. Over fitting in an ML model happens when the training accuracy is much greater than the testing accuracy. Dropout refers to ignoring neurons during training so they are not considered during a particular forward or backward pass leaving a reduced network. These neurons are chosen randomly and an example is shown in Figure 8. The dropout rate is the probability of training a given node in a layer, where 1.0 means no dropout and 0.0 means all outputs from the layer are ignored.

Softmax and Exponential Linear Unit (ELU) are activation functions commonly used in CNNs and are described below. The softmax function is given by

$$\frac{e^{z_i}}{\sum_{j=1}^K e^{z_j}}$$

where the zi are the input values and K is the number of input values. This function converts real numbers into probabilities as it ensures the output values sum to 1 and are in the range 0 to 1. Softmax is used in the fully connected layer of the proposed models so the results can be interpreted as a probability distribution for the five emotions. Figure 3.8 shows the location of the softmax function. The ELU function is

$$\begin{cases} x, if \ x > 0 \\ a(e^x - 1), if \ x \le 0 \end{cases}$$

where x is the input value and α is the slope. This function saturates to a negative value when x is negative and α controls the saturation. This decreases the information passed to the next layer.



Figure 9: Structure of a CNN As we mentioned in our model

ML models can be built and trained easily using a high level Application Programming Interface (API) like Keras. In this report, a sequential CNN model is developed using Tensorflow with the Keras API since it allows a model to be built layer by layer. Tensorflow is an end to end open source platform for ML. It has a flexible collection of tools, libraries and community resources to build and deploy ML applications. Figure 3.9 shows the structure of a CNN where conv. denotes convolution. OUR CNN Model has Seven Phases. [4-6]

2.3 Dataset Preparation:

The FER 2013 dataset is well known and was used in the Kaggle competition. The data must be prepared for input to the CNN because there are some issues with this dataset as discussed below. The input to the model should be an array of numbers, so images must be converted into arrays. [9-10]

Some dataset challenges are given below.

- i) Imbalance: Imbalance is when one class has many more images than another class. This results in the model being biased towards one class. For example, if there are 2000 images for the happy expression and 500 images for the fear expression, then the model will be biased towards the happy expression. Data augmentation is done to avoid this problem. Data augmentation increases the amount of data using techniques like cropping, padding, and horizontal flipping.
- **ii) Contrast variation:** Some images in the dataset can be too dark and some can be too light. Since images contain visual information, higher contrast images have more information than lower contrast images. A CNN takes images as input, automatically learns image features and classifies the images into output classes. Thus, variations in image contrast affect CNN performance. This problem can be solved by changing the images to focus on the faces.
- **iii)** Intra-class variation: Some images in the dataset are not human faces as there are drawings and animated faces. The features in real and animated faces differ and this creates confusion when the model is extracting landmark features. Model performance will be better if all images in the dataset are human faces so other images should be removed.
- **iv) Occlusion:** Occlusion is when part of the image is covered. This can occur when a hand covers a part of the face such as the right eye or nose. A person wearing sunglasses or a mask also creates occlusion. Table 1 indicates that eyes and noses have primary features which are important to extract and recognize emotions. Thus, occluded images should be removed from the dataset as the model cannot recognize emotions from these images.

The images used for training should be free from the above issues. Thus, manual filtering of the 35,000 images in the FER 2013 dataset was done and 7,074 images from five classes were selected, 966 for angry, 859 for fear, 2477 for happy, 1466 for neutral and 1326 for sad.

We have used different types of python libraries such as, NumPy, OpenCV, Keras, Tensorflow etc.

Numerical Python (NumPy) is an open source Python library used for working with arrays and matrices. An array object in NumPy is called nd.array. CNN inputs are arrays of numbers

and NumPy can be used to convert images into NumPy arrays to easily perform matrix multiplications and other CNN operations.

OpenCV is an open source library for CV, ML and image processing. Images and videos can be processed by OpenCV to identify objects, faces and handwriting. When it is integrated with a library such as Numpy, OpenCV can process array structures for analysis. Mathematical operations are performed on these array structures for pattern recognition.

Tensorflow is an end-to-end open source platform for machine learning. It has a comprehensive, flexible, ecosystem of tools and libraries and community resources that lets researchers push the state-of-the-art in ML and developers easily build and deploy ML Powered applications.

Keras is an API designed for human beings, not machines. Keras follows best practices for reducing cognitive load; it offers consistent & simple APIs, it minimizes the number of user actions required for common use cases .

An image is represented by values (numbers) that correspond to the pixel intensities. The array module in NumPy (nd.array) is used to convert an image into an array and obtain the image attributes. Figure 10 shows an image in the sad class from the FER 2013 dataset converted into a NumPy array. Figure 11 shows the attributes of this image which are 2304 pixels, 2 dimensions and size 48×48 pixels.

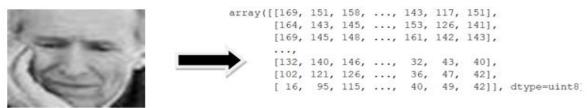


Figure 10: image from the FER dataset converted into array

The library is used to detect facial landmarks. This process consists of two steps, localize the face in an image and detect the facial landmarks. The frontal face detector from is used to detect the face in an image. A rectangle on the face is obtained which is defined by the top left corner and the bottom right corner coordinates. The shape predictor is used to extract the key facial features from an input image. An object called landmarks which has two arguments is passed. The first argument is an image in which faces will be detected and the second specifies the area where the facial landmarks will be obtained. This area is represented by the coordinates of the rectangle. Figure 11 shows the 64 landmarks detected in an image.



Figure 11: Landmarks detect on a face

Image pre-processing are the steps taken to format images before they are used by model training and inference. This includes resizing, orienting, and color corrections etc. Here, we used 'ImageDataGenerator' class from 'Keras' deep learning library for these actions-rotation, shear, rescale, zoom, height_shift, width_shift, horizontal_flip that are applied to all the input sample images.

Training model is used to run the input data through the algorithm to correlate the processed output against the sample output. Specifically for our purpose of work we chose to build and work with a 'CNN' model. Model type is Sequential and the configurations are pretty close to the standard 'VGG16' which is a widely famous CNN model. Within Deep Learning, a Convolution Neural Network or CNN is a type of artificial neural network(An artificial neural network is a computational model that mimics the way nerve cells work in the human brain), which is widely used for image/object recognition and classification. Deep Learning thus recognizes objects in an image by using a CNN. Our model has 7 blocks. In creating first four blocks we have use two convolution layer(conv2D) and a pooling(MaxPooling2D) layer with kernel initializer='he normal' and activation function 'elu' and 0.2 dropout percentage for each. Then the 5th and 6th blocks that are basically used for feature extraction has been created with a dense (or fully connected layer) layer and kernel initializer='he normal' and Activation function 'elu' and 0.5 dropout percentage for each. We also use Flatten() in block 5 to flatten the multi-dimensional input tensors into a single dimension. At last in the last block there is a dense layer with the activation fuction 'softmax', this layer is for the classification and output data. NOTE: In our case we didn't use any special feature extraction or face detection method. Actually both things are done by the CNN model automatically. CNN model for facial expression recognition. After creating or building the model we have to compile it. We use 'adam' optimizer for our work but there are many other optimizers available.

Validation Model: We need to fit the model and apply it on the data set in order to get the trained model. In our case, we fit the model with the batch_size of 100 and no of epochs are 50 and also use of three callbacks (earlystop, checkpoint, reduce_lr) with patience of 5 Our model runs till 43 epoch then it early stopped because after the best epoch that is 38 epoch (where the val_loss is improved from 1.06779 to 1.04583) the validation loss or val_loss doesn't improve.

CHAPTER 3

RESULTS AND DISCUSSION

In this chapter, the metrics used to evaluate model performance are defined. Then the best parameter values for each model are determined from the training results. These values are used to evaluate the accuracy and loss for CNN models 1 and 2. The results for these models are then compared and discussed.

Evaluation matrix

Accuracy, loss, precision, recall and F-score are the metrics used to measure model performance. These metrics are defined below.

• Accuracy: Accuracy is given by

$$Accuracy = \frac{Number\ of\ Correct\ Predictions}{Total\ Number\ of\ Predictions}$$

Loss: Categorical cross-entropy is used as the loss function and is given by

$$Loss = -\sum_{c=1}^{m} (y_0 \log(p_{0,c}))$$

where y is a binary indicator (0 or 1), p is the predicted probability and m is the number of classes (happy, sad, neutral, fear, angry)

- Confusion matrix: The confusion matrix provides values for the four combinations of true and predicted values, True Positive (TP), True Negative (TN), False Positive (FP) and False Negative (FN). Precision, recall and F-score are calculated using TP, FP, TN, FN. TP is the correct prediction of an emotion, FP is the incorrect prediction of an emotion, TN is the correct prediction of an incorrect emotion and FN is the incorrect prediction of an incorrect emotion. Consider an image from the happy class. The confusion matrix for this example is shown in Figure 5.1. The red section has the TP value as the happy image is predicted to be happy. The blue section has FP values as the image is predicted to be sad, angry, neutral or fear. The yellow section has TN values as the image is not sad, angry, neutral or fear but the model predicted this. The green section has FN values as the image is not happy but was predicted to be happy.
- Recall: Recall is given by

$$Recall = \frac{TP}{TP + FN}$$

Precision: Precision is given by

$$Precision = \frac{TP}{TP + FP}$$

• F-Score: F-Score is the harmonic mean of recall and precision and is given by

$$F-Score = \frac{2*Recall*Precision}{Recall+Precision}$$

we start from a image of 48x48 then after applying conv2d, activation ,batch normalization at the moment of applying max pooling 2d the image becomes 24x24 then again it goes through some phases when applying max pooling 2d again the image becomes 12x12 and this cycle continues until we reached dropout 3 the image becomes flattened which one we need then applied dense and our activation function softmax

conv2d (Conv2D)	(None, 48, 48, 32)	320
activation (Activation)	(None, 48, 48, 32)	0
batch_normalization	(BatchNo (None, 48, 48, 32)	128
conv2d_1 (Conv2D)	(None, 48, 48, 32)	9248
activation_1 (Activation)	(None, 48, 48, 32)	0
patch_normalization_1	(Batch (None, 48, 48, 32)	128
max pooling2d	(MaxPooling2D) (None, 24, 24, 32)	0
dropout (Dropout)	(None, 24, 24, 32)	0
conv2d_2 (Conv2D)	(None, 24, 24, 64)	18496
activation_2 (Activation)	(None, 24, 24, 64)	0
patch_normalization_2	(Batch (None, 24, 24, 64)	256
onv2d_3 (Conv2D)	(None, 24, 24, 64)	36928
activation_3 (Activation)	(None, 24, 24, 64)	0
patch_normalization_3	(Batch (None, 24, 24, 64)	256
max pooling2d 1	(MaxPooling2 (None, 12, 12, 64)	0
dropout_1 (Dropout)	(None, 12, 12, 64)	0
onv2d_4 (Conv2D)	(None, 12, 12, 128)	73856
activation 4 (Activation)	(None, 12, 12, 128)	0
patch_normalization_4	(Batch (None, 12, 12, 128)	512
onv2d_5 (Conv2D)	(None, 12, 12, 128)	147584
activation_5 (Activation)	(None, 12, 12, 128)	0
patch_normalization_5	(Batch (None, 12, 12, 128)	512
max_pooling2d_2	(MaxPooling2 (None, 6, 6, 128)	0
dropout_2 (Dropout)	(None, 6, 6, 128)	0
conv2d_6 (Conv2D)	(None, 6, 6, 256)	295168
activation_6 (Activation)	(None, 6, 6, 256)	0
patch_normalization_6	(Batch (None, 6, 6, 256)	1024
conv2d_7 (Conv2D)	(None, 6, 6, 256)	590080
ctivation_7 (Activation)	(None, 6, 6, 256)	0
patch_normalization_7	(Batch (None, 6, 6, 256)	1024
max_pooling2d_3	(MaxPooling2 (None, 3, 3, 256)	0
dropout_3 (Dropout)	(None, 3, 3, 256)	0
latten (Flatten)	(None, 2304)	0
lense (Dense)	(None, 64)	147520
ctivation_8 (Activation)	(None, 64)	0
patch_normalization_8	(Batch (None, 64)	256
dropout_4 (Dropout)	(None, 64)	0
lense_1 (Dense)	(None, 64)	4160
activation_9 (Activation)	(None, 64)	0
patch_normalization_9	(Batch (None, 64)	256
lropout_5 (Dropout)	(None, 64)	0
dense_2 (Dense)	(None, 5)	325
activation_10 (Activation)	(None, 5)	0

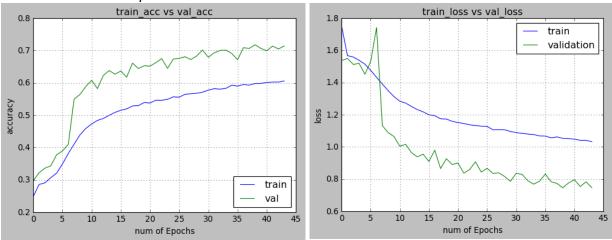
Non-trainable params: 2,176

Training (Model):Model only trained till epoch 83. Then it early stopped according to the call-backs mentioned in methodology because the validation loss (val_loss) didn't improve after epoch 78 (best epoch), rather the loss kept increasing in the following epochs.

Hence, the model early stopped the training process to avoid over fitting.

Maximum accuracy: 0.6642 (82nd epoch)
Minimum loss: 1.1945 (82nd epoch)
Validation accuracy: 0.7925 (81st epoch)
Minimum validation loss: 1.0458 (78th epoch)

Two Random Plot Graphs Are Shown Bellow:



Random Train accuracy VS Validation Accuracy

Random Train Loss VS Validation Loss

Figure 12: Random Graphs

The accuracy of our project is somewhat low because of some problems which we face during our work process like not enough resources during the project work we didn't have enough time to improve our code, limitation of data in our project our data (pictures) were limited, we tried to detect seven emotion but there was not enough pictures for seven emotion and the pictures were not evenly spread among the emotion so some emotion did not had enough pictures to train & the quality of

data, we used FER 2013 data set but in that set the quality of the data was too low which affected our training of the model, and also inconsistency of FER 2013 dataset was a big problem, like in the dataset there were a few pictures which are corrupted some pictures misplaced during sorting. Also, this is our first time working on a project based on Artificial Neural Network and hence we lacked experience on this work. If we were able to overcome these problems we may have had better accuracy.

It is important to remember that there is no specific formula to build a neural network that can guarantee to work properly fine. Different problems would require different network architectures and a lot of trail and errors to produce desirable validation accuracy. This is the reason why neural nets are often perceived as "Black box algorithms."

We need to improve in specific areas like-

- Number (weights etc.) and configuration of convolution layers.
- Number and configuration of dense layers.
- Dropout percentage in both dense and convolution layers.
- Better optimization in compiling the model.
- Using of some special feature extraction and face detection methods.

But due to lack of highly configured system we could not go deeper into dense neural network as the system gets very slow and we will try to improve in these areas in future. We would also like to train more databases into the system to make the model more and more accurate but again resources become a hindrance in the path.

Having examined techniques to cope with expression variation, in future it may be investigated in more depth about the face classification problem and optimal fusion of colour and depth information. Further study can be laid down in the direction of allele of gene matching to the geometric factors of the facial expressions.

➤ Testing (Model):

Testing samples: 7,178

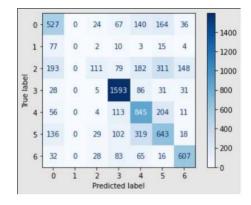


Figure 13: Random Confusion Matrix



Figure 15: Multiple sample images with their redictions

Output:
Single test_sample picture-



Prediction: Sad

Figure 14: Output Sample Image

In this set of predicted output pictures, there are some pictures that are not correctly predicted. Specially four pictures that present in [1. first column-second row, 2. fourth column-third row, 3. first column-fourth row, 4. Fifth column-forth row] are predicted wrong since our model accuracy is somewhat low.

1st image is belongs to angry class but predicted as happy.

2nd image is belongs to disgust class but predicted as sad.

3rd image is belongs to surprise class but predicted as angry.

4th image is belongs to angry class but predicted as surprise.

All other images are predicted correctly. In the case, the model predicts incorrectly, the correct label is often the second most likely emotion. (Based on the predicted scores)

Internal Layers Representation



Figure 16.1: con2d Internal Layer.



Figure 16.3: batch_normalization Internal Layer.



Figure 16.5: activation_1 Internal Layer



Figure 16.7: max_pooling2d Internal Layer

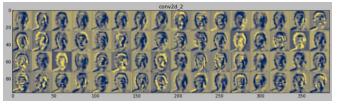


Figure 16.9: conv2d_2 batch_normalization Internal Layer.

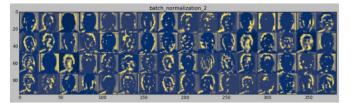


Figure 16.11: batch_normalization_2 Internal Layer



Figure 16.2: activation Internal Layer.

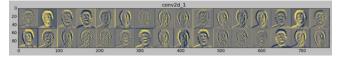


Figure 16.4: conv2d_1 Internal Layer



Figure 16.6: batch_normalization_1 Internal Layer

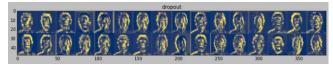


Figure 16.8: dropout Internal Layer

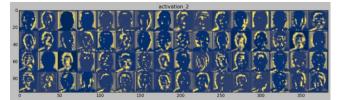


Figure 16.10: activation_2 Internal Layer.

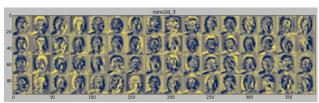


Figure 16.12: conv2d_3 Internal Layer.

CONCLUSION

The facial expression recognition system presented in this project work contributes a resilient face recognition model based on the mapping of behavioural characteristics with the physiological biometric characteristics. The physiological characteristics of the human face with relevance to various expressions such as happiness, sadness, fear, anger, surprise and disgust are associated with geometrical structures which restored as base matching template for the recognition system. The behavioural aspect of this system relates the attitude behind different expressions as property base. This project work also promises a new direction of research in the field of asymmetric biometric cryptosystems which is highly desirable in order to get rid of passwords and smart cards completely. This paper proposes a new framework for facial expression recognition using an attention convolution network. We believe attention to special regions is important for detecting facial expressions, which can enable neural networks with less than 10 layers to compete with (and even outperform) much deeper networks in emotion recognition. We also provide an extensive experimental analysis of our work on four popular facial expression recognition databases and show some promising results. Additionally, we deployed a visualization method to highlight the salient regions of face images that are the most crucial parts thereof for detecting different facial expressions.

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[10]MMA FACIAL EXPRESSION Dataset:

https://www.kaggle.com/datasets/mahmoudima/mma-facial-expression

[11] Trainer Model Link:

https://github.com/AlphaTanmoy/Facial-Expression-etection/blob/main/Trainer Model.py

[12] Testing Model Link:

https://github.com/AlphaTanmoy/Facial-Expression-etection/blob/main/Testing Model.py

[13] Project Source Code Link:

https://github.com/AlphaTanmoy/Facial-Expression-Detection

Appendix 1:

ABBREVATIONS

HOG Histogram of Oriented Gradient
SIFT Scale Invariant Feature Transform

ML Machine Learning
NN Neural Network

CNN Convolution Neural Network

FER 2013 Facial Emotion Recognition 2013 Dataset

FER Facial Emotion Recognition

AI Artificial Intelligence

DL Deep Learning

EEG Electroencephalograph

HCI Human Computer Interaction

FE Feature Extraction
CV Computer Vision

RNN Recurrent Neural Network

MMOD Maximum Margin Object Detection

NumPy Numerical Python ELU Exponential Linear Unit

API Application Programming Interface

TP True PositiveFP False PositiveFN False NegativeTN True Negative

ANN Artificial Neural Network

LR Learning Rate

RNN Recurrent Neural Network