

Matrices



Why do they work?

*Screenshot from
Insane Clown Posse - Miracles



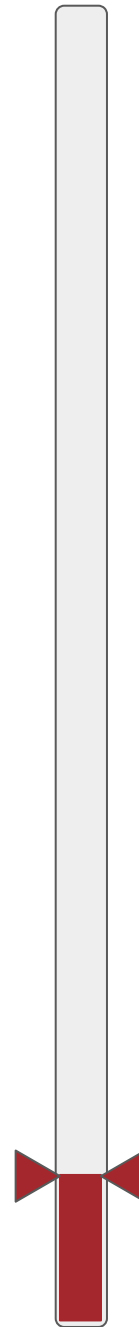
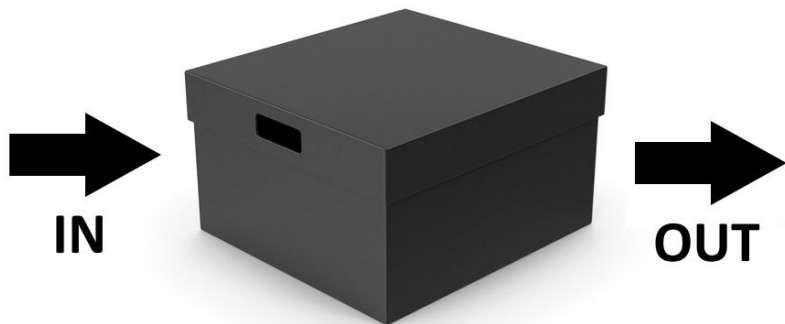
Aw jeez, not this again



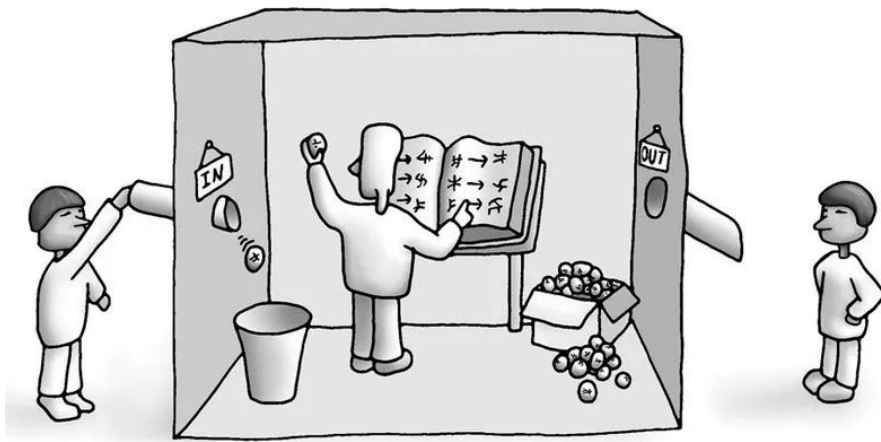
Aw jeez, not this again



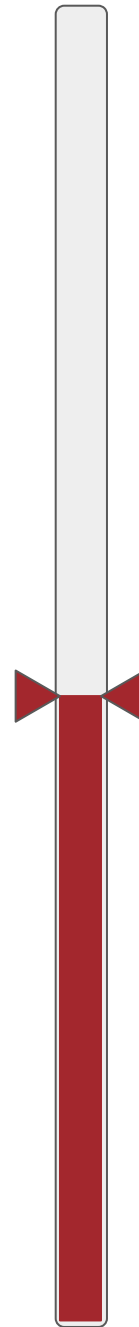
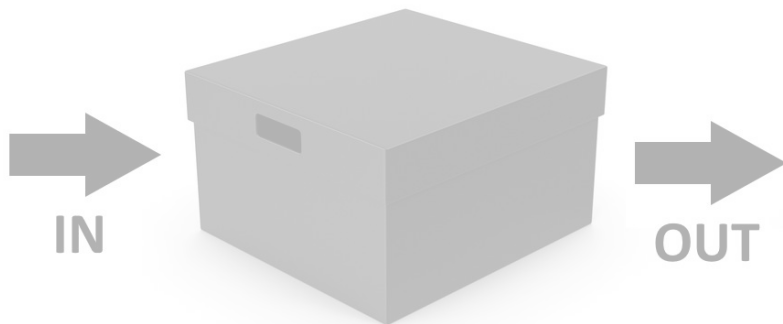
**Oh, really?
Tell me more**



- Use as black box
- What but not How



- Know what inside
- Can implement
- Know performance
- How but not Why



No such article



Basics

Conventions

Geometry meaning

3	34	6	1
5	4	2.9	0
2.3	19	0	34
17	3	4.4	5

Basics

Conventions

Geometry meaning

Basics



Conventions



Geometry meaning

X Y Z

← **RUF** - Unity

← **FRU** - Unreal

→ **RUB** - Godot, XNA

→ **RFU** - O3DE, Blender

→ **LUF** - PyTorch3D

→ **RDF** - Vulkan NDC

RUF - Unity

FRU - Unreal

RUB - Godot, XNA

RFU - O3DE, Blender

LUF - PyTorch3D

RDF - Vulkan NDC

RUF - Unity

FRU - Unreal

RUB - Godot, XNA

RFU - O3DE, Blender

LUF - PyTorch3D

RDF - Vulkan NDC

RUF - Unity

FRU - Unreal

RUB - Godot, XNA

RFU - O3DE, Blender

LUF - PyTorch3D

RDF - Vulkan NDC

RUF - Unity

FRU - Unreal

RUB - Godot, XNA

RFU - O3DE, Blender

LUF - PyTorch3D

RDF - Vulkan NDC

RUF - Unity

FRU - Unreal

~~RUB - Godot, XNA~~

RFU - O3DE, Blender

~~LUF - PyTorch3D~~

~~RDF - Vulkan NDC~~



Tim Sweeney 

@TimSweeneyEpic



Sorry y'all I was young and this coordinate system stuff was confusing

← **RUF** - Unity

~~FRU - Unreal~~

~~RUB - Godot, XNA~~

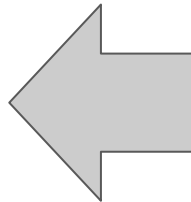
→ **RFU** - O3DE, Blender

~~LUF - PyTorch3D~~

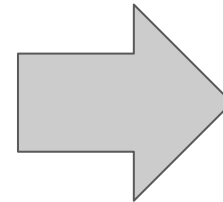
~~RDF - Vulkan NDC~~



RUFF



PERFUME



... X Y Z X Y Z X Y Z ...

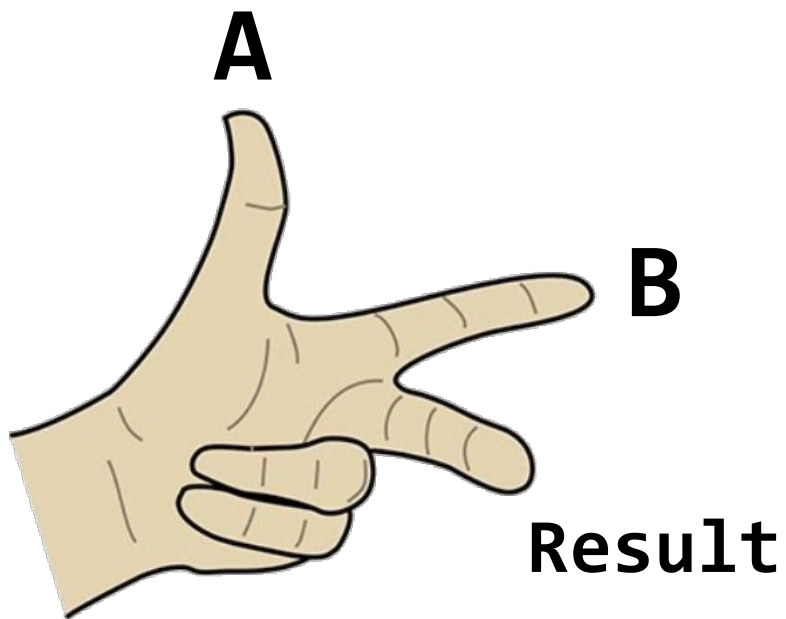
... X Y Z **X_xY** Z X Y Z ...

... X Y Z **$X \times Y = Z$** X Y Z ...

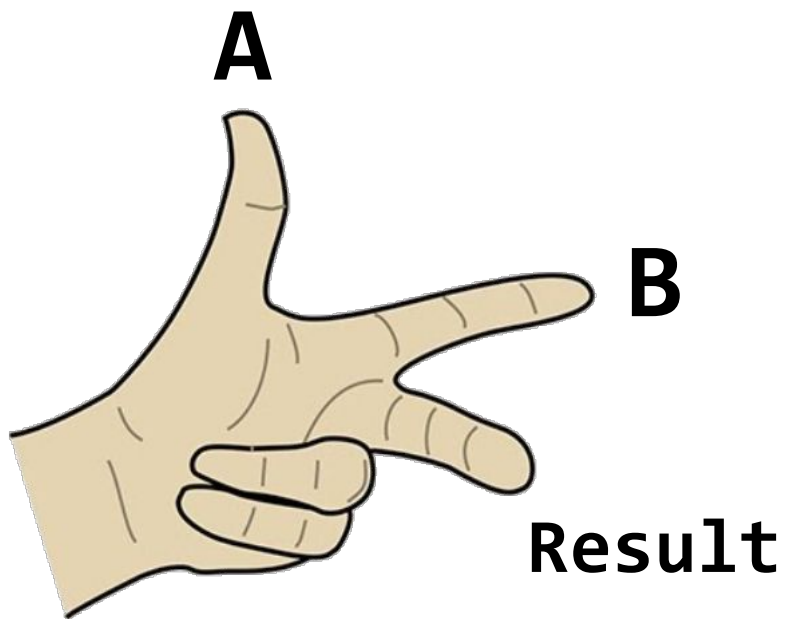
... X Y Z X **$Y \times Z = X$** Y Z ...

... X Y Z X Y **$Z \times X = Y$** Z ...

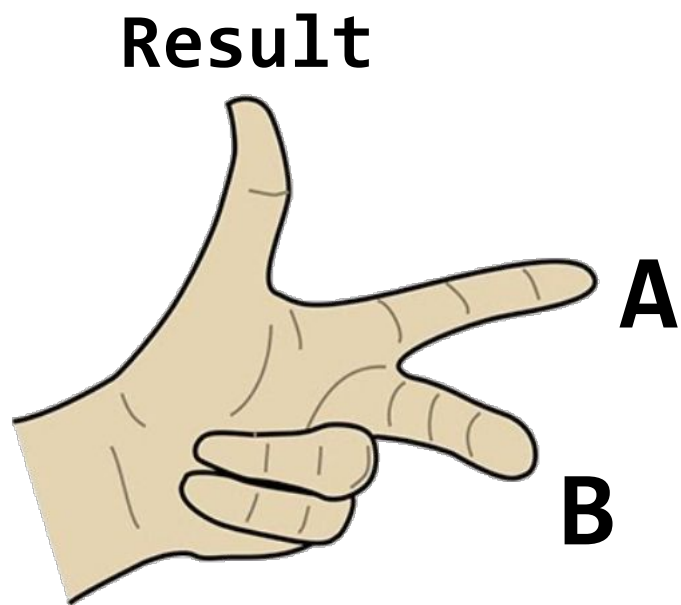
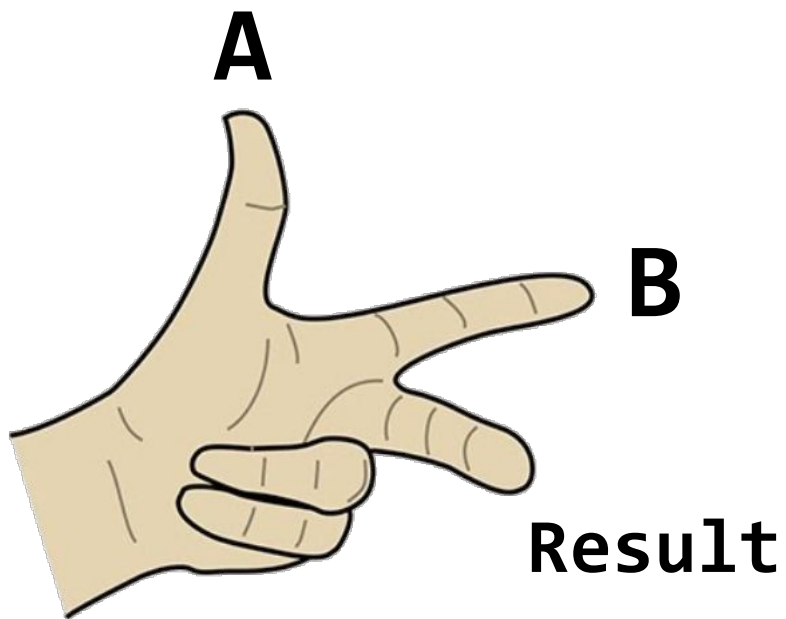
... X Y Z X Y **$Z \times X = Y$** Z ...



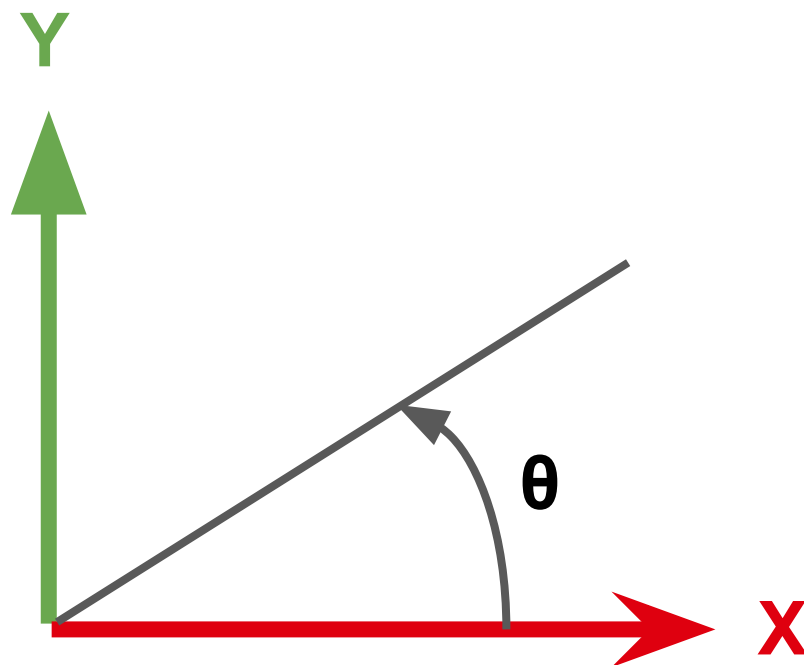
... X Y Z X $Y = Z \times X = Y$ Z ...

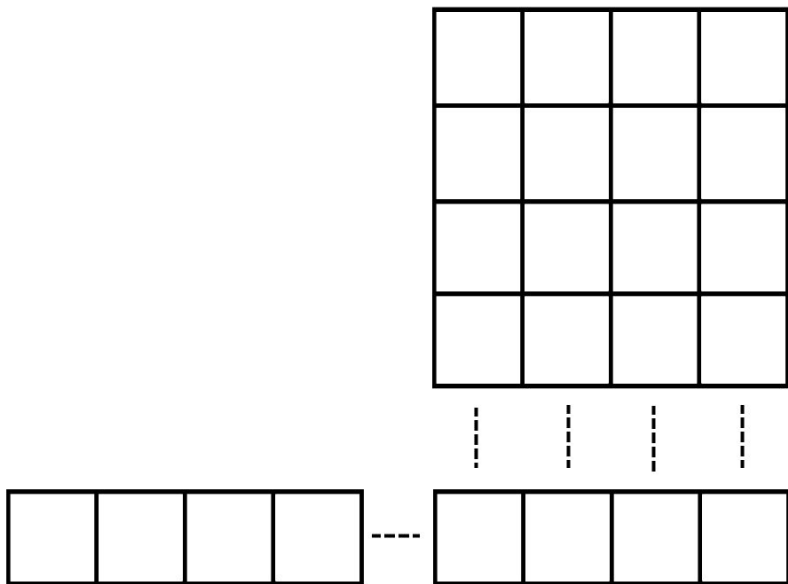


... X Y Z X **$Y = Z \times X = Y$** Z ...



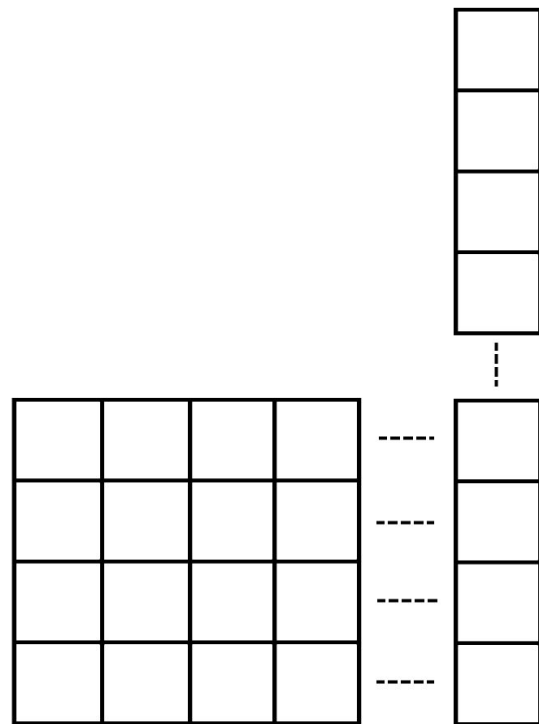
... X Y **$Z = X \Rightarrow Y$** Z X Y Z ...



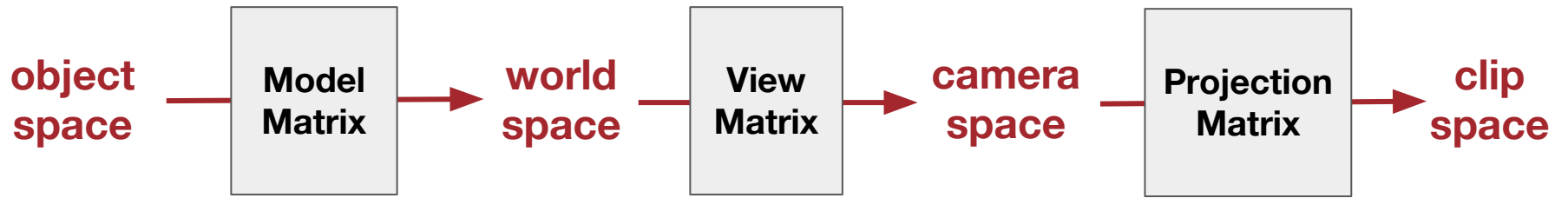


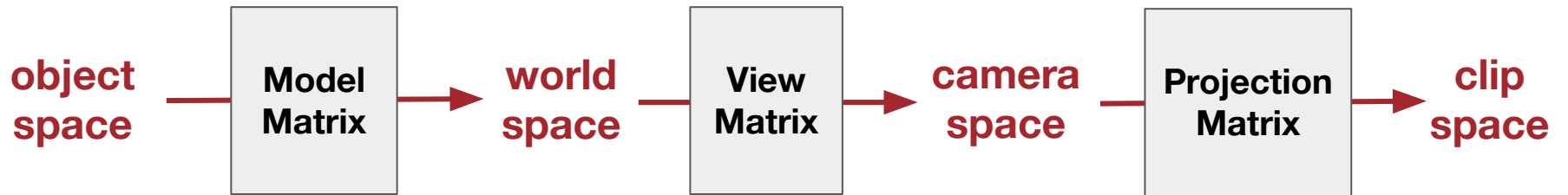
Row-vector

vs

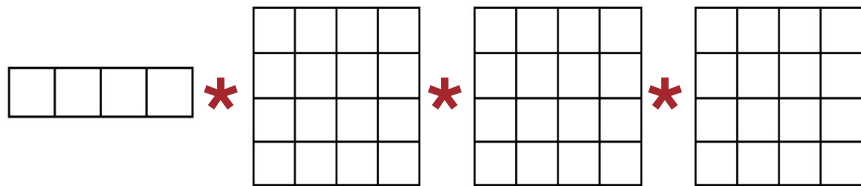


Column-vector

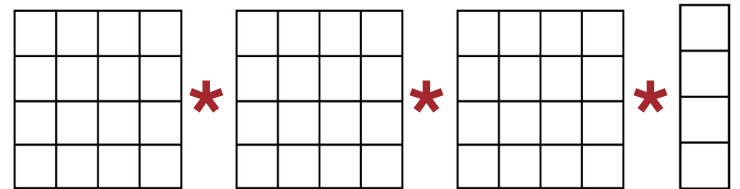


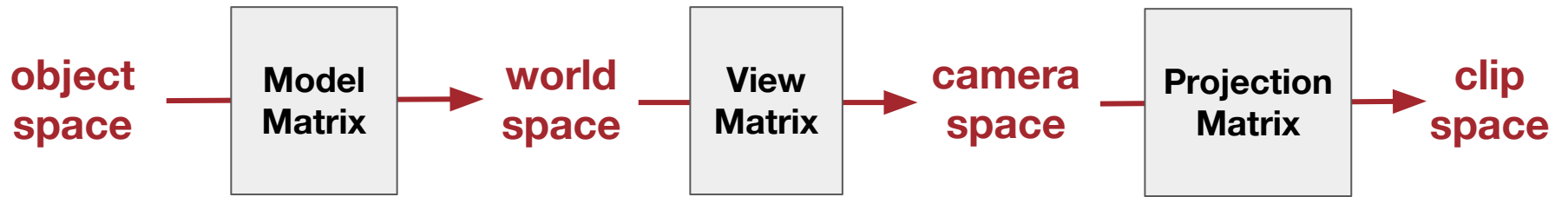


$$X * M * V * P$$



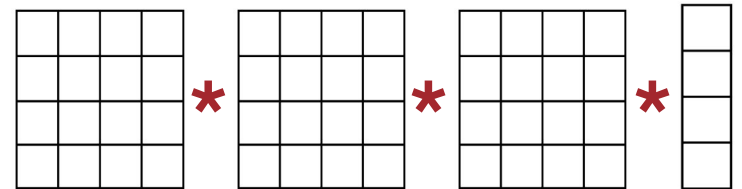
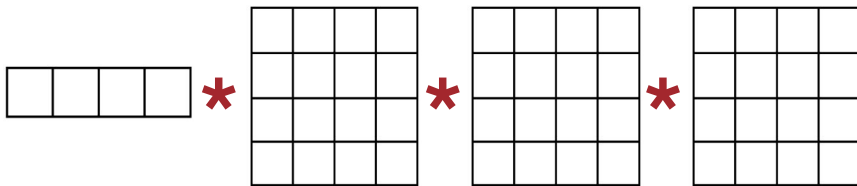
$$P * V * M * X$$





$$x * M * V * P$$

$$P(V(M(x)))$$



Row-vector == row-major

Column-vector == column-major

Row-vector

for

Column-major

column-major



**English is
row major.**

English is
row major.

```
float m11, m12, m13, m14;  
float m21, m22, m23, m24;  
float m31, m32, m33, m34;  
float m41, m42, m43, m44;
```

```
float Matrix[4][4] = {  
    { 1, 0, 0, 0 },  
    { 0, 1, 0, 0 },  
    { 0, 0, 1, 0 },  
    { 0, 0, 0, 1 }  
};  
  
Matrix[3][2];
```


English is
row major.

```
float m11, m12, m13, m14;  
float m21, m22, m23, m24;  
float m31, m32, m33, m34;  
float m41, m42, m43, m44;
```

```
float Matrix[4][4] = {  
    { 1, 0, 0, 0 },  
    { 0, 1, 0, 0 },  
    { 0, 0, 1, 0 },  
    { 0, 0, 0, 1 }  
};  
  
Matrix[3][2];
```

C o l u m n
i s a l s o
c o n v i n i e n t .
m a j o r
v e r y

Basics

Conventions

Geometry meaning

What's next?

Interactive guide to homogeneous coordinates

https://wordsandbuttons.online/interactive_guide_to_homogeneous_coordinates.html

by Oleksandr Kaleniuk

Let's remove Quaternions from every 3D Engine

<https://marctenbosch.com/quaternions/>

by Marc ten Bosch