•	Appl	ly the	B DBSCAN	
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algorithm to the given

data points and

Create the clusters with

minPts = 4 and

• epsilon ( $\epsilon$ ) = 1.9.

#### Data Points:

.

Use Eucladian distance and calculate the distance between each points.

Distance(
$$A(x_1, y_1), B(x_2, y_2)$$
) =  $\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$ 



D1. /2 7\					minPts =	4 and	epsilon (	ε) = 1.9					
P1: (3, 7)		P1	P2	Р3	P4	P5	P6	P7	P8	P9	P10	P11	P12
P2: (4, 6)	P1	0											
P3: (5, 5)	P2	1.41	0										
P4: (6, 4)	Р3	2.83	1.41	0									
P5: (7, 3)	P4	4.24	2.83	1.41	0								
P6: (6, 2)	P5	5.66	4.24	2.83	1.41	0							
P7: (7, 2)	P6	5.83	4.47	3.16	2.00	1.41	0						
P8: (8, 4)	P7	6.40	5.00	3.61	2.24	1.00	1.00	0					
	P8	5.83	4.47	3.16	2.00	1.41	2.83	2.24	0				
P9: (3, 3)	P9	4.00	3.16	2.83	3.16	4.00	3.16	4.12	5.10	0			
P10: (2, 6)	P10	1.41	2.00	3.16	4.47	5.83	5.66	6.40	6.32	3.16	0		
P11: (3, 5)	P11	2.00	1.41	2.00	3.16	4.47	4.24	5.00	5.10	2.00	1.41	0	
P12: (2, 4)	P12	3.16	2.83	3.16	4.00	5.10	4.47	5.39	6.00	1.41	2.00	1.41	0

minPts = 4 and epsilon ( $\epsilon$ ) = 1.9 $^{\vee}$								P1: P2, P10					
	PY	P2	Р3	P4	P5	P6	P7	P8	P9	P10	P11	P12	P1. P2, P10
P1	0												P2: P1, P3, P11
P2	1.41	0											P3: P2, P4
P3 🗸	2.83	1.41	0										P4: P3, P5
P4	4.24	2.83	1.41	0									P5: P4, P6, P7, P8
P5	5.66	4.24	2.83	1.41	0								P6: P5, P7
P6	5.83	4.47	3.16	2.00	1.41	0							P7: P5, P6
P7	6.40	5.00	3.61	2.24	1.00	1.00	0						P8: P5
P8	5.83	4.47	3.16	2.00	1.41	2.83	2.24	0					Po. P3
P9	4.00	3.16	2.83	3.16	4.00	3.16	4.12	5.10	0				P9: P12
P10	1.41	2.00	3.16	4.47	5.83	5.66	6.40	6.32	3.16	0			P10: P1, P11
P11	2.00	1.41	2.00	3.16	4.47	4.24	5.00	5.10	2.00	1.41	0		P11: P2, P10, P1
P12	3.16	2.83	3.16	4.00	5.10	4.47	5.39	6.00	1.41	2.00	1.41	0	P12: P9, P11

P1: P2, P10

P2: P1, P3, P11

P3: P2, P4

P4: P3, P5

P5: P4, P6, P7, P8

P6: P5, P7

P7: P5, P6

P8: P5

P9: P12

P10: P1, P11

P11: P2, P10, P12

P12: P9, P11

minPts = 4 and epsilon ( $\epsilon$ ) = 1.9

Point	Sta	atus
P1	Noise	
P2	Core	
Р3	Noise	
P4	Noise	
P5	Core	
P6	Noise	
P7	Noise	
P8	Noise	
P9	Noise	
P10	Noise	
P11	Core	
P12	Noise	

P1: P2, P10

P2: P1, P3, P11

P3: P2, P4

P4: P3, P5

P5: P4, P6, P7, P8

P6: P5, P7

P7: P5, P6

P8: P5

P9: P12

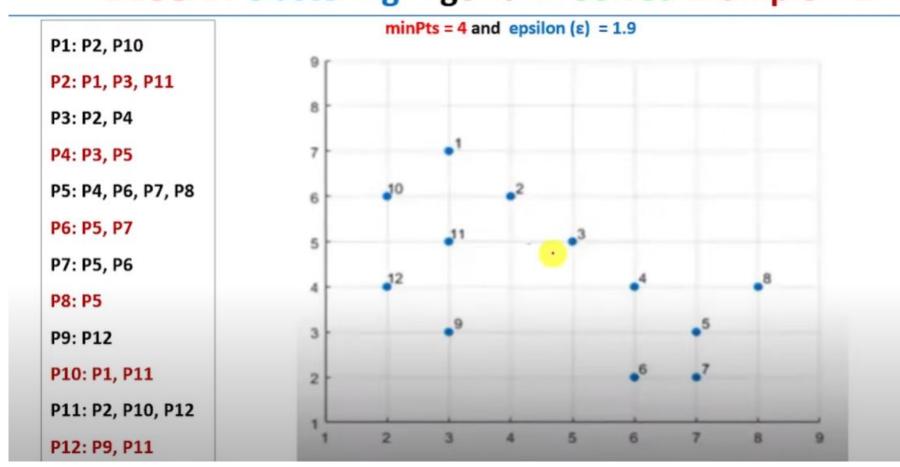
P10: P1, P11

P11: P2, P10, P12

P12: P9, P11

minPts = 4 and epsilon ( $\epsilon$ ) = 1.9

Point	Sta	tus
P1	Noise	Border
P2	Core	
Р3	Noise	Border
P4	Noise	Border
P5	Core	
P6	Noise	Border
P7	Noise	Border
P8	Noise	Border
P9	Noise	
P10	Noise	Border
P11	Core	
P12	Noise	Border



P1: P2, P10

P2: P1, P3, P11

P3: P2, P4

P4: P3, P5

P5: P4, P6, P7, P8

P6: P5, P7

P7: P5, P6

P8: P5

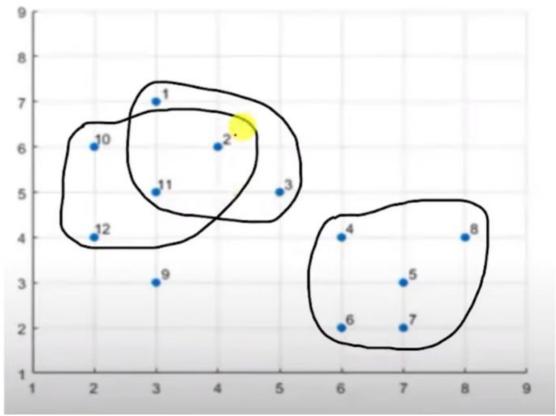
P9: P12

P10: P1, P11

P11: P2, P10, P12

P12: P9, P11





Apply the DBSCAN algorithm with similarity threshold of 0.8 (using the similarity matrix) to the given data points and MinPts>=2 (Minimum required points in a cluster) what are core, border and noise (outliers) in the set of points given in table.

	P1	P2	Р3	P4	P5
P1	1.00	0.10	0.41	0.55	0.35
P2	0.10	1.00	0.64	0.47	0.98
Р3	0.41	0.64	1.00	0.44	0.85
P4	0.55	0.47	0.44	1.00	0.76
P5	0.35	0.98	0.85	0.76	1.00

minPts = 2 and Similarity Index = 0.8

	P1	P2	Р3	P4	P5
P1	1.00	0.10	0.41	0.55	0.35
P2	0.10	1.00	0.64	0.47	0.98
Р3	0.41	0.64	1.00	0.44	0.85
P4	0.55	0.47	0.44	1.00	0.76
P5	0.35	0.98	0.85	0.76	1.00

#### minPts = 2 and Similarity Index = 0.8

	P1	P2	Р3	P4	P5
P1	1.00	0.10	0.41	0.55	0.35
P2	0.10	1.00	0.64	0.47	0.98
Р3	0.41	0.64	1.00	0.44	0.85
P4	0.55	0.47	0.44	1.00	0.76
P5	0.35	0.98	0.85	0.76	1.00

P1: -

P2: P5

P3: P5

P4: -

P5: P2, P3

#### minPts = 2 and Similarity Index = 0.8

	P1	P2	Р3	P4	P5
P1	1.00	0.10	0.41	0.55	0.35
P2	0.10	1.00	0.64	0.47	0.98
Р3	0.41	0.64	1.00	0.44	0.85
P4	0.55	0.47	0.44	1.00	0.76
P5	0.35	0.98	0.85	0.76	1.00

	Point	Stat		
P1: -	P1	Noise	Ī	
P2: P5	P2	Core		
P3: P5	Р3	Core		
P4: -	P4	Noise		
P5: P2, P3	P5	Core		

No Border Points in the given dataset 🧓

# Density-Based Spatial Clustering of Applications with Noise(DBSCAN)

