

# LINFO1113 - Cheat Sheet - 2019-2020

## Numbers and Error propagation

- Float32:  $(-1)^{b_{31}} \cdot (1.b_{22} \dots b_0)_2 \cdot 2^{(b_{30} \dots b_{23})_2 - 127}$
- $fl(x) = x(1 + \varepsilon)$  with  $|\varepsilon| \leq 2^{-p}$  with  $p=24$  (53) for float32 (float64)
- $e = |\tilde{x} - x| = |fl(x) - x| \leq 2^{-p+2t}$  ;  $\varepsilon = \frac{|\tilde{x} - x|}{|x|} \leq |fl(x) - x| \leq 2^{-p}$

## Linear Systems ( $Ax = b$ )

- Doolittle:  $A = LU$  with  $L_{ii} = 1$
- Choleski:  $A = LU$  with  $L = U^T$ ;  $L_{jj} = \sqrt{A_{jj} - \sum_{k=1}^{j-1} L_{jk}^2}$ ;  $L_{ij} = (A_{ij} - \sum_{k=1}^{j-1} L_{ik} L_{jk}) / L_{jj}$
- Jacobi:  $X_{k+1} := D^{-1}(b - RX_k)$

## Curve fitting and interpolation

- Lagrange:  $P_n(x) = \sum_i y_i l_i(x)$  with  $l_i(x) = \prod_{j \neq i} \frac{(x - x_j)}{(x_i - x_j)}$
- Newton:  $P_k(x) = a_{n-k} + (x - x_{n-k})P_{k-1}(x)$  with  $a_0 = y_0$ ;  $a_1 = \nabla y_1$ ;  $a_2 = \nabla^2 y_2$ ; ...
- Neville:  $P_k[x_i, \dots, x_{i+k}] = \{(x - x_{i+k})P_{k-1}[x_i, \dots, x_{i+k-1}] + (x_i - x)P_{k-1}[x_{i+1}, \dots, x_{i+k}]\} / (x - x_{i+k})$
- Cubic spine:  $k_{i-1} + 4k_i + k_{i+1} = \frac{6}{h^2}(y_{i-1} - 2y_i + y_{i+1})$   
 $f_{i,i+1}(x) = \frac{k_i}{6} \left[ \frac{(x - x_{i+1})^3}{-h} - (x - x_{i+1})(-h) \right] - \frac{k_{i+1}}{6} \left[ \frac{(x - x_i)^3}{-h} - (x - x_i)(-h) \right] + \frac{y_i(x - x_{i+1}) - y_{i+1}(x - x_i)}{-h}$
- Least-Square:  $S = \sum (y_i - f(x_i))^2$  ;  $\sigma = \sqrt{S/(n - m)}$   
 In the case:  $Y = f(x) = \sum_{i=0}^m a_m x_m = XA \rightarrow S = Y^T Y + A^T X^T X A - 2A^T X^T Y \rightarrow X^T X A = X^T Y$

## Root Search

- RegulaFalsi /Secant:  $x_3 = x_2 - f_2 \frac{(x_2 - x_1)}{(f_2 - f_1)}$  Rider:  $x_4 = x_3 \pm (x_3 - x_1) \frac{f_3}{\sqrt{f_3^2 - f_1 f_2}}$
- Newton-Raphson:  $x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$  or for a system:  $x \leftarrow (x + \Delta x)$  with  $J(x)\Delta x = -f(x)$

## Numerical differentiation

- Be able to derivate first/second (non-)central approximation for  $f'$ ,  $f''$  and associated error
- Richardson: IF  $G = g(h) + E(h)$  with  $E(h) = ch^p$  and  $h_2 = h_1/2$  then  $G = \frac{2^p g(h_1/2) - g(h_1)}{2^p - 1}$

## Numerical Integration

- Newton-Cotes:  $I \approx \sum_{i=0}^n A_i f(x_i)$  with  $A_i = \int_a^b l_i(x) dx$ , trapzoid ( $n=1$ ), simpson 1/3 ( $n=2$ ) 3/8 ( $n=3$ )
- Composite Trapezoidal:  $I = \frac{h}{2} [f(x_0) + 2f(x_1) + \dots + 2f(x_{n-1}) + f(x_n)]$
- Recursive Trapezoidal:  $I_k = \frac{1}{2} I_{k-1} + \frac{H}{2^{k-1}} \sum_{i=1}^{2^{k-2}} f\left(a + \frac{(2i-1)H}{2^{k-1}}\right)$
- Simpson 1/3:  $\frac{h}{3} [f(x_i) + 4f(x_{i+1}) + f(x_{i+2})]$ ; Simpson 3/8:  $\frac{3h}{8} [f(x_0) + 3f(x_1) + 3f(x_2) + f(x_3)]$
- Romberg:  $R_{i,j} = \frac{4^{j-1} R_{i,j-1} - R_{i-1,j-1}}{4^{j-1} - 1}$

## Initial Value Problem

- Euler:  $y(x + h) \approx y(x) + y'(x)h$
- Modified Euler (RK2):  $y(x + h) \approx y(x) + hF\left(x + \frac{h}{2}, y + \frac{h}{2} F(x, y)\right)$
- RK4:  $y(x + h) \approx y(x) + \frac{1}{6}(K_0 + 2K_1 + 2K_2 + K_3)$  with  
 $K_0 = hF(x, y)$ ;  $K_1 = hF\left(x + \frac{h}{2}, y + \frac{K_0}{2}\right)$ ;  $K_2 = hF\left(x + \frac{h}{2}, y + \frac{K_1}{2}\right)$ ;  $K_3 = hF(x + h, y + K_2)$

## Optimization

- Unconstrained:  $F^*(x) = F(x) + \lambda P(x)$  with  $P(x) = \sum_i^M (g_i(x))^2 + \sum_j^N \max(0, h_j(x))^2$
- Golden Search:  $x_1 = b - Rh$ ;  $x_2 = a + Rh$ ;  $R = \frac{-1 + \sqrt{5}}{2}$
- Gradient Descent:  $x \leftarrow x - \eta \nabla f(x)$