

Model Evaluation

Classification quality metrics, prediction error, cross-validation

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LAMBD A • HSE

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Classification quality metrics

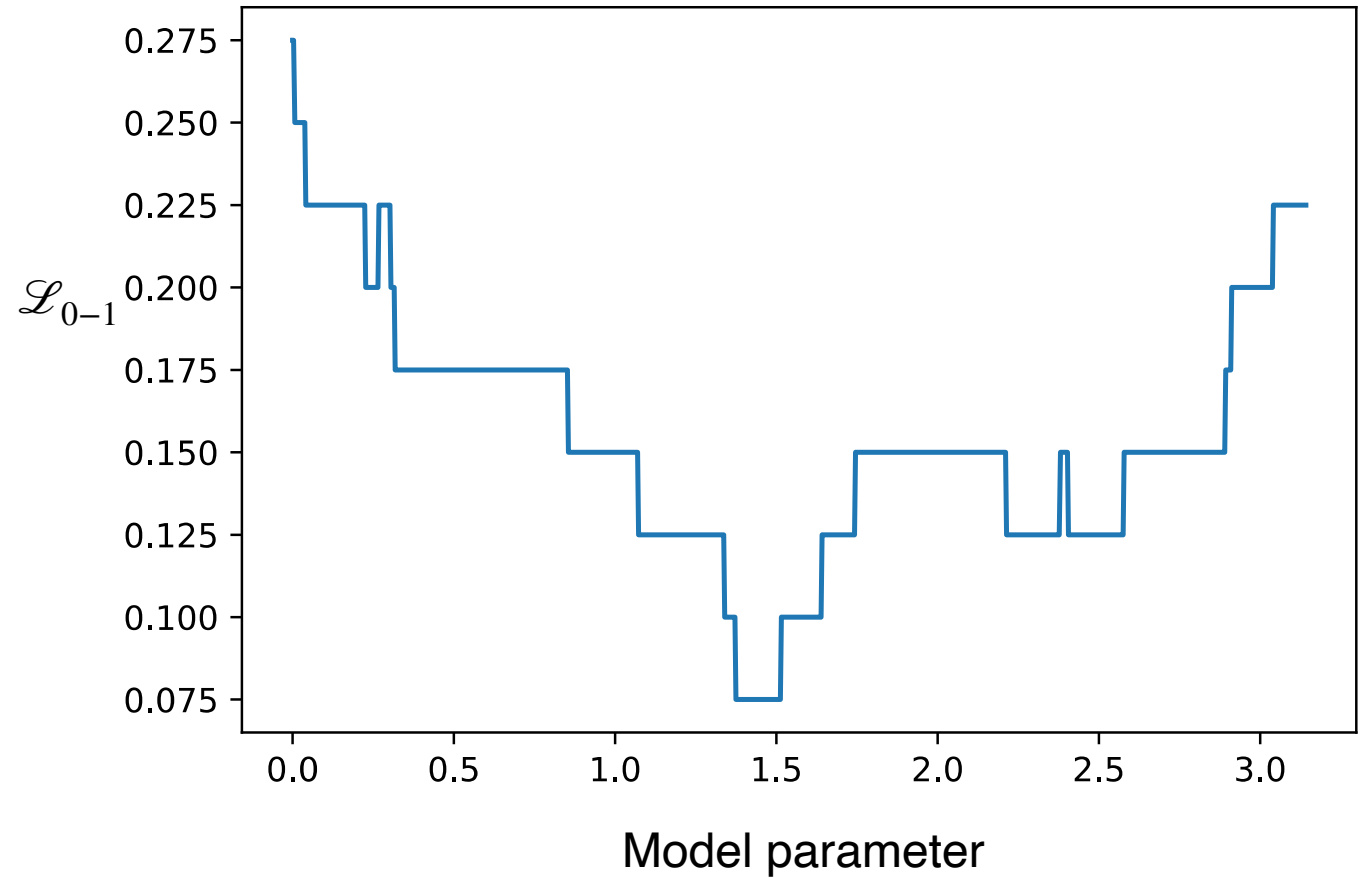


How to evaluate a classifier?

0-1 Loss

- Probability of an error (error rate):

$$\mathcal{L}_{0-1} = \frac{1}{N} \sum_{i=1 \dots N} \mathbb{I}(y_i \neq \hat{y}_i)$$



0-1 Loss

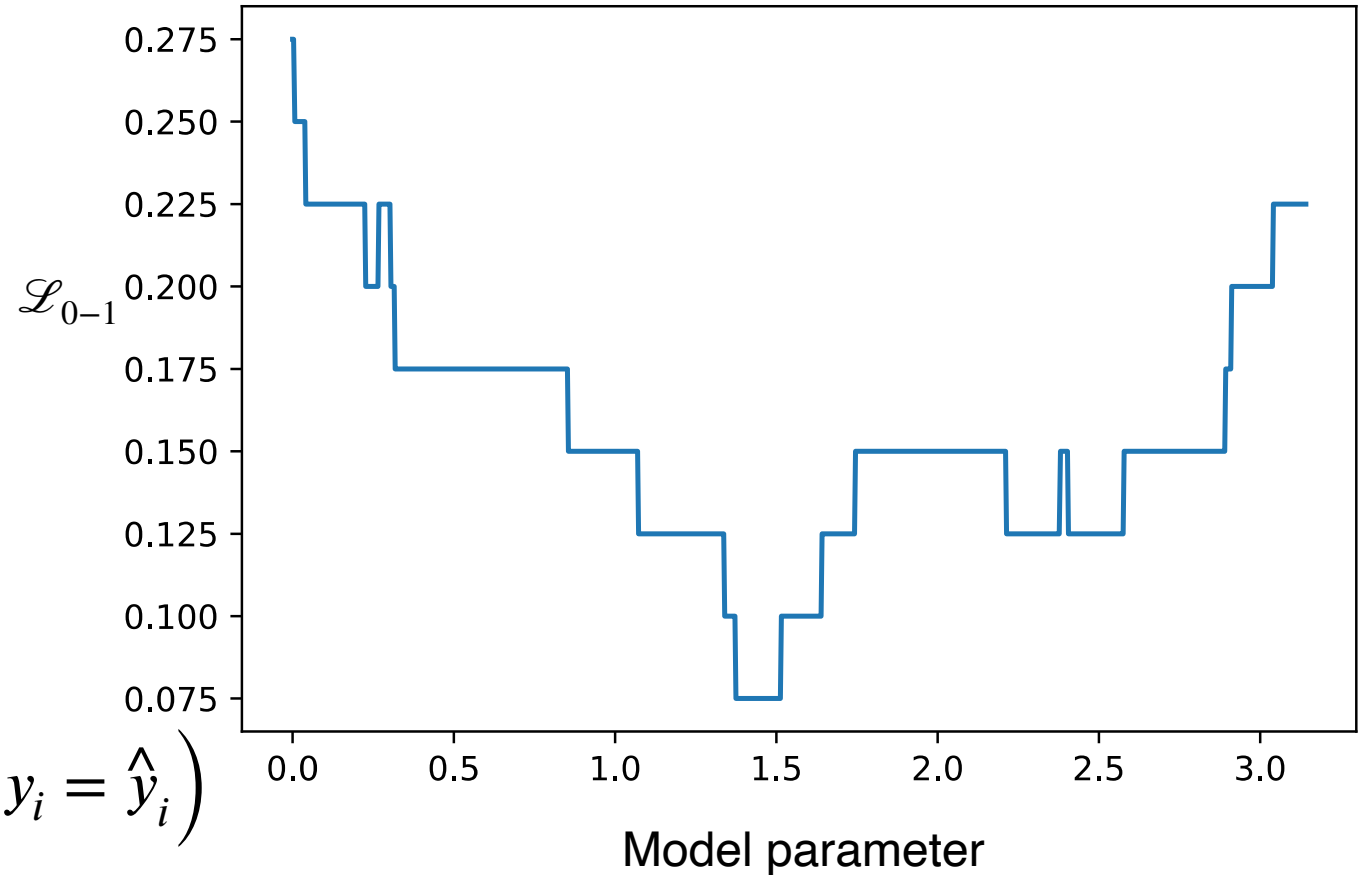
- Probability of an error (error rate):

$$\mathcal{L}_{0-1} = \frac{1}{N} \sum_{i=1 \dots N} \mathbb{I}(y_i \neq \hat{y}_i)$$

- Accuracy:

$$accuracy = 1 - \mathcal{L}_{0-1} = \frac{1}{N} \sum_{i=1 \dots N} \mathbb{I}(y_i = \hat{y}_i)$$

- Not always a good quality measure
 - E.g. when classes are imbalanced



Confusion matrix

		Actual class		
		1	2	...
Pre dict ed clas s	1			...
	2			...
	⋮	⋮	⋮	⋮
				...

n_{ij} – number of objects of class j , that were predicted as class i

Diagonal elements – correct classifications

Off-diagonal elements – incorrect classifications

Binary case

Actual class

+

−

Pred
icted
class

+

TP

(True Positives)

FP

(False Positives)

−

FN

(False Negatives)

TN

(True Negatives)

Binary case

		Actual class	
		+	-
Pred icted class	+	TP (True Positives)	FP (False Positives)
	-	FN (False Negatives)	TN (True Negatives)

$$\text{Accuracy} = \frac{\text{TP} + \text{TN}}{\text{TP} + \text{TN} + \text{FP} + \text{FN}}$$

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True positive rate, TPR $= \frac{\text{TP}}{\text{TP} + \text{FN}}$

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$$\text{Precision} = \frac{\text{TP}}{\text{TP} + \text{FP}}$$

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$$\text{Precision} = \frac{\text{TP}}{\text{TP} + \text{FP}}$$

$$\text{Recall} = \frac{\text{TP}}{\text{TP} + \text{FN}}$$

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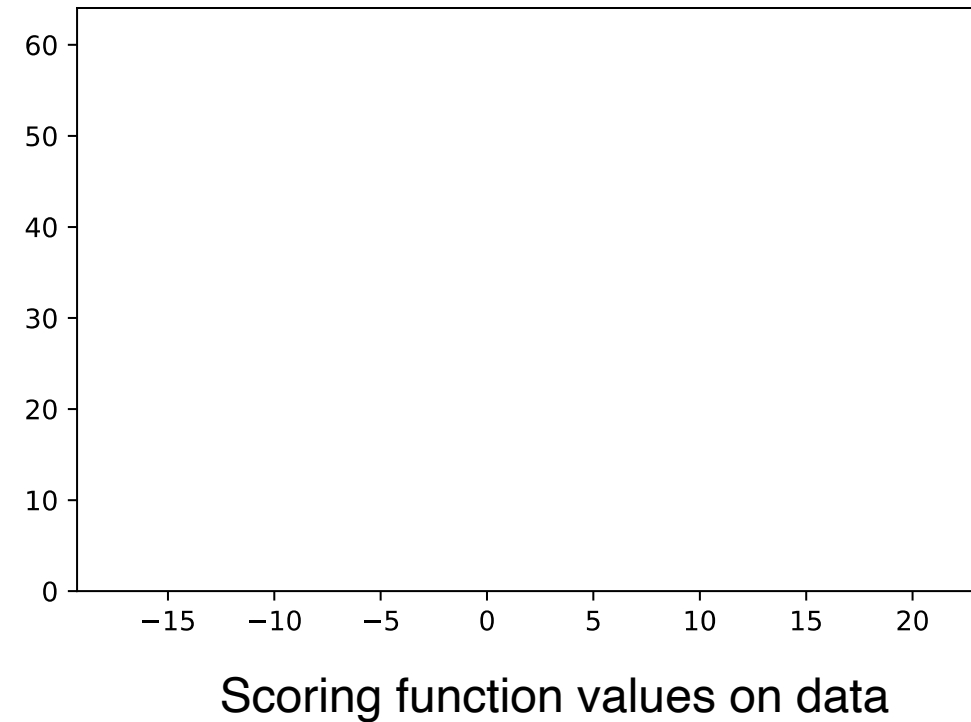
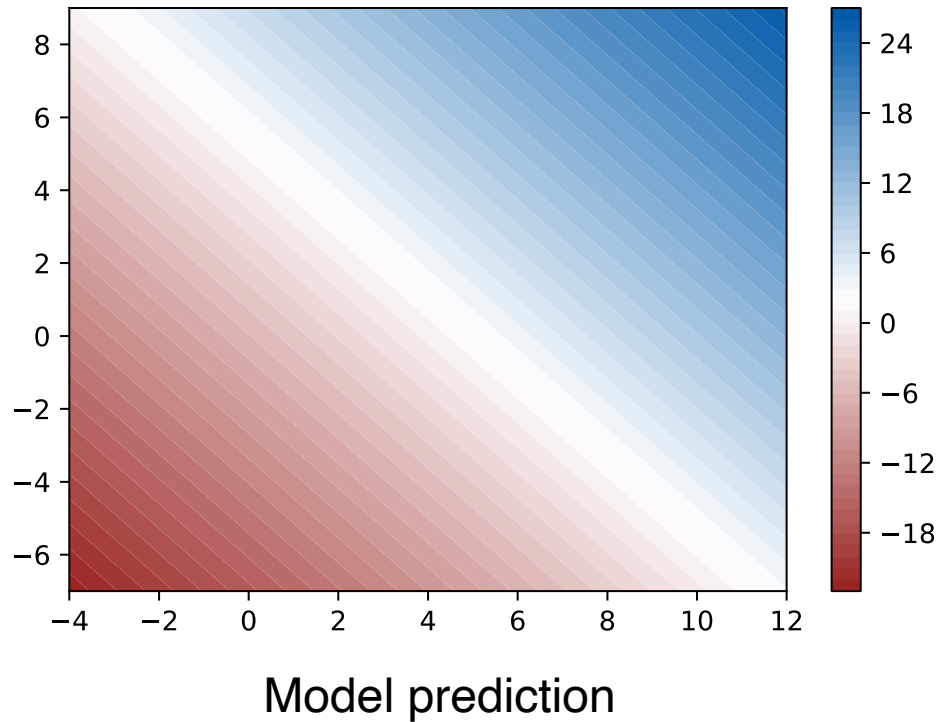
$$\text{Precision} = \frac{\text{TP}}{\text{TP} + \text{FP}}$$

$$\text{Recall} = \frac{\text{TP}}{\text{TP} + \text{FN}}$$

$$F_1\text{-score} = \frac{2 \cdot \text{Precision} \cdot \text{Recall}}{\text{Precision} + \text{Recall}}$$

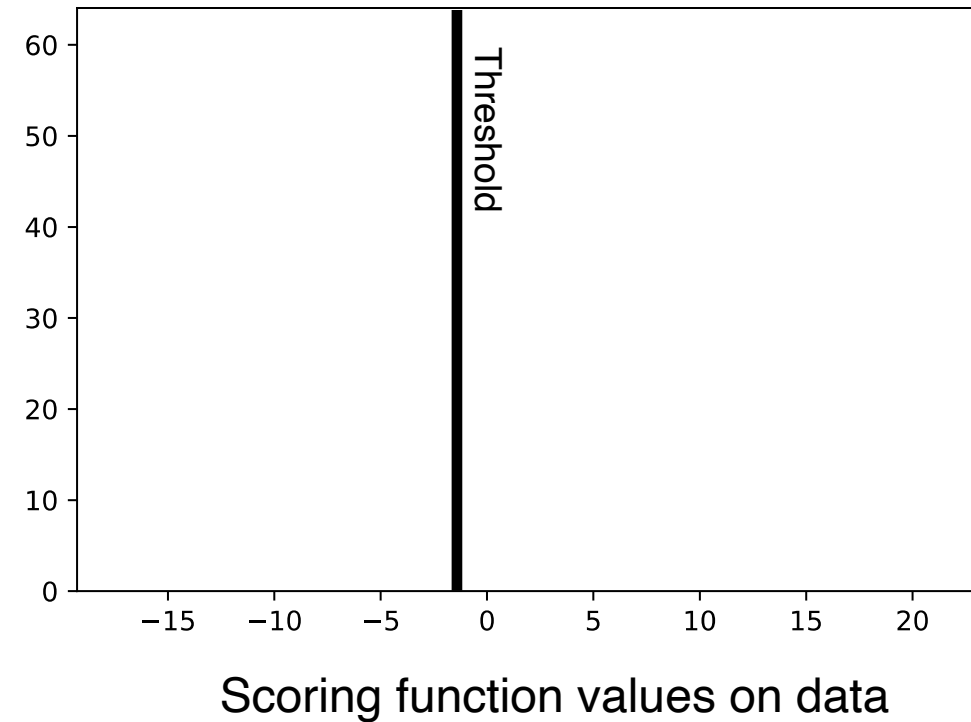
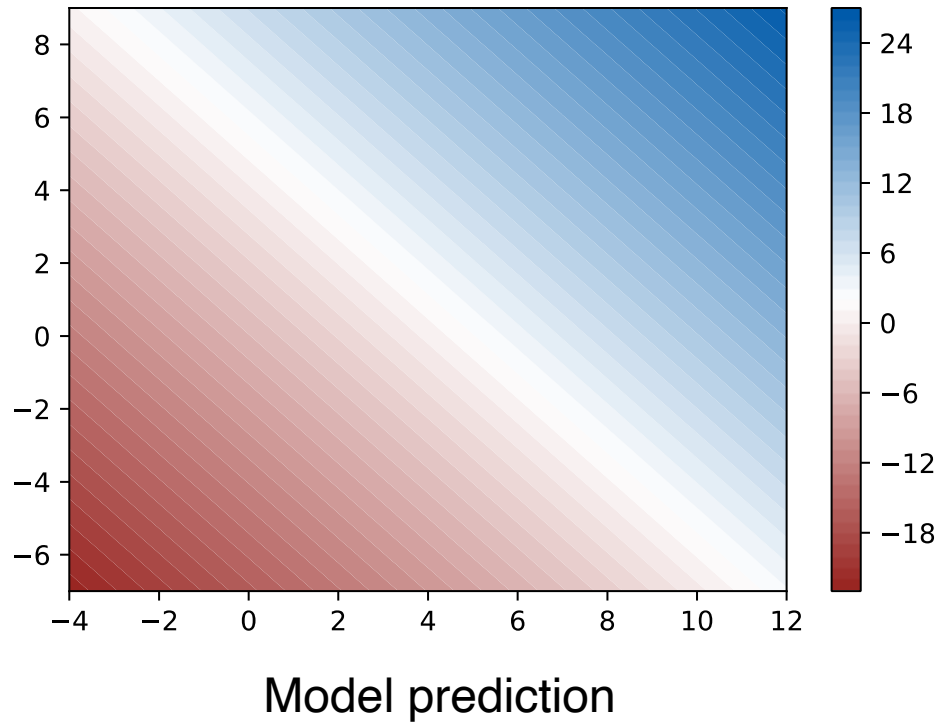
Continuous predictions

- ▶ Many classification algorithms work with continuous scoring functions
 - E.g. log odds in Logistic Regression, or scoring function of an SVM model



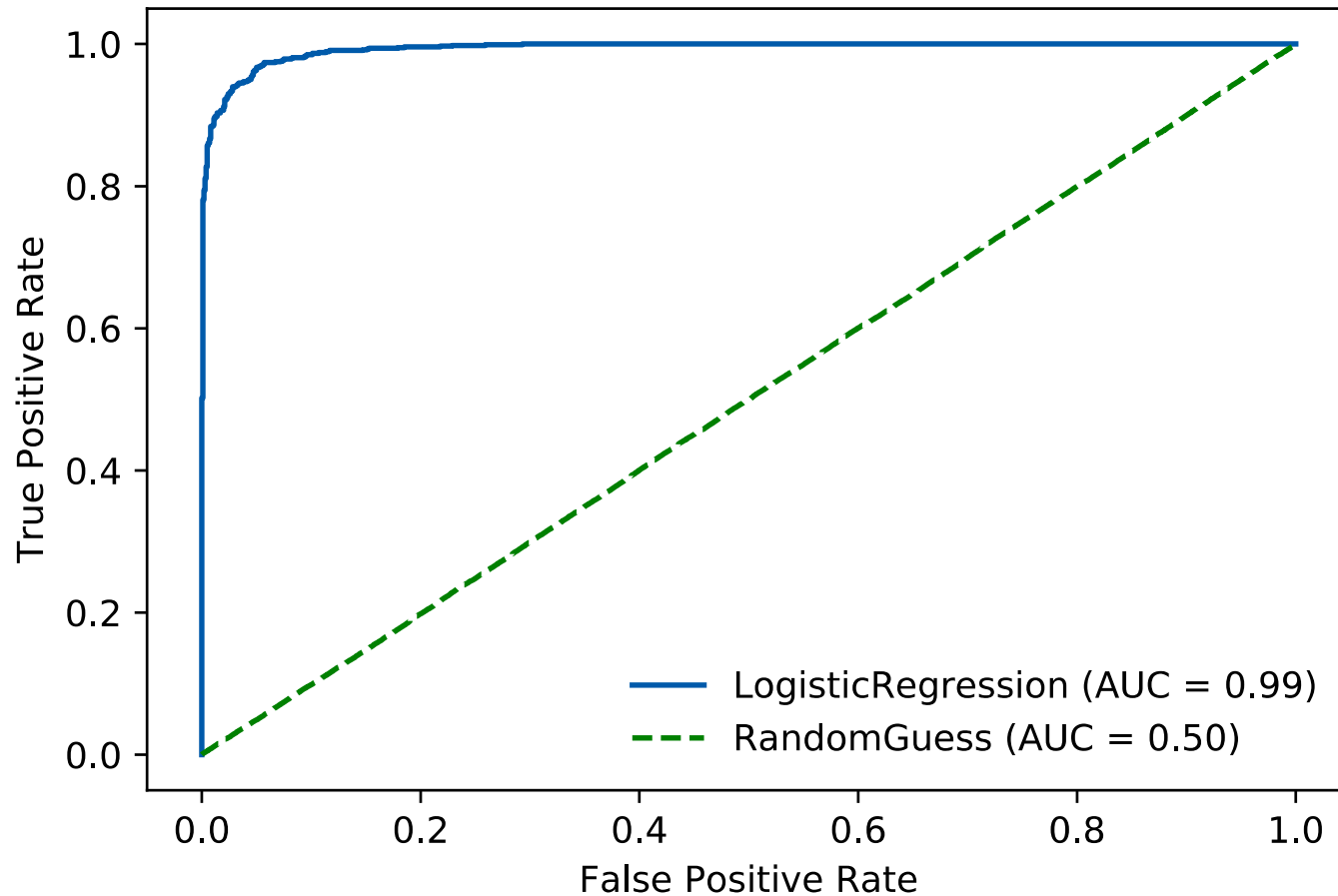
Continuous predictions

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ROC-curve

Receiver operating characteristic = TPR as a function of FPR



History [\[edit \]](#)

The ROC curve was first used during [World War II](#) for the analysis of [radar signals](#) before it was employed in [signal detection theory](#).^[45] Following the [attack on Pearl Harbor](#) in 1941, the United States army began new research to increase the prediction of correctly detected Japanese aircraft from their radar signals. For these purposes they measured the ability of a radar receiver operator to make these important distinctions, which was called the Receiver Operating Characteristic.^[46]

https://en.wikipedia.org/wiki/Receiver_operating_characteristic

Nice demo: <http://arogozhnikov.github.io/2015/10/05/roc-curve.html>

ROC AUC probabilistic interpretation

ROC AUC = area under the ROC curve

For the population distribution:

$$P(x, y), \quad x \in \mathbb{R}^d, \quad y \in \{0, 1\}$$

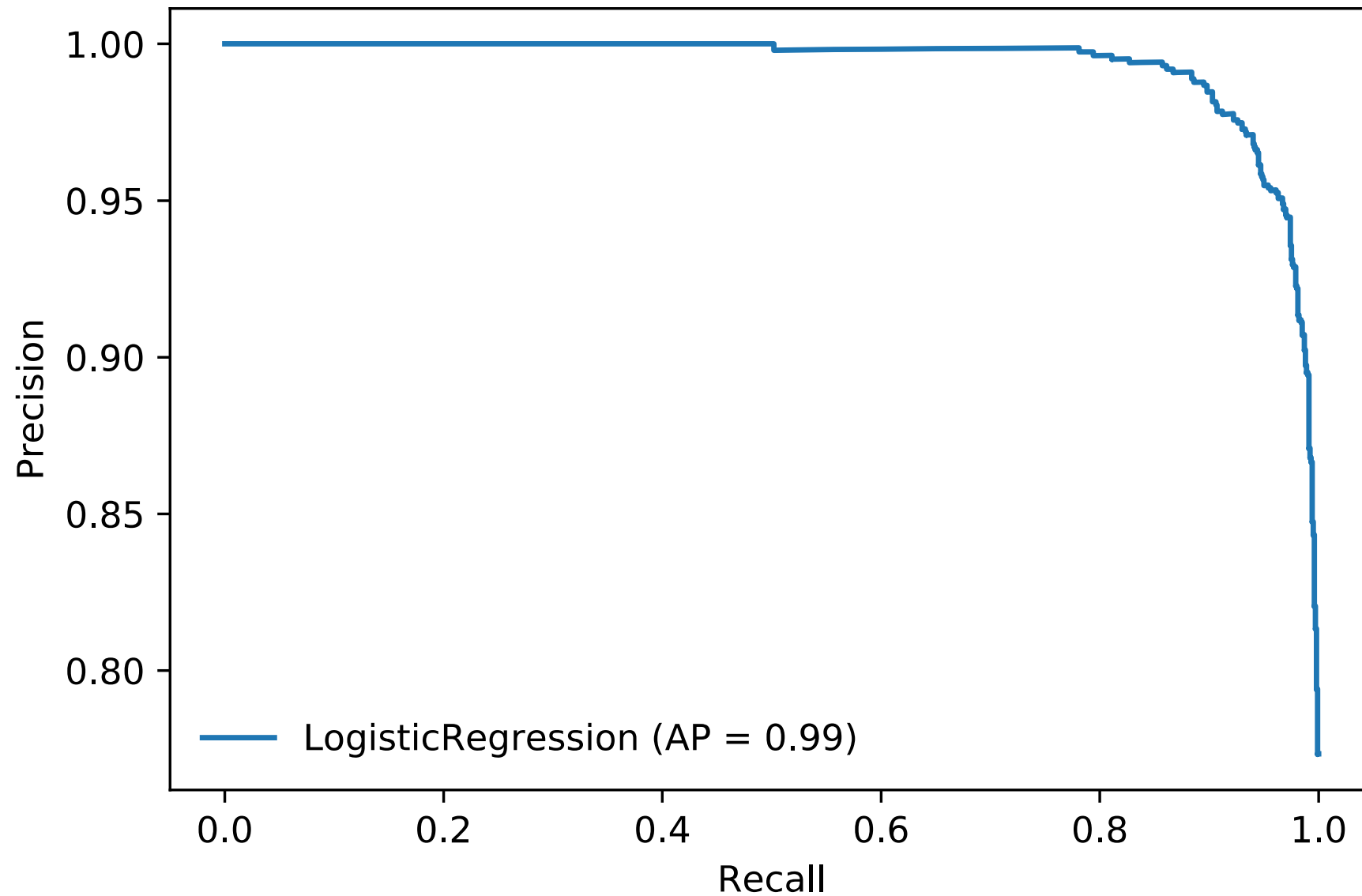
$$\hat{f}(x): \mathbb{R}^d \rightarrow \mathbb{R} \quad - \text{classifier scoring function}$$

ROC AUC also equals the probability that

$$P\left[\hat{f}(x_0) < \hat{f}(x_1)\right]$$

for x_0 sampled from $P(x \mid y = 0)$, and x_1 sampled from $P(x \mid y = 1)$

Precision-recall curve



Prediction error
vs
expected prediction error



Two scenarios

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- Trained a model $\hat{f}_\tau(x)$ on a particular dataset τ
- Want to know, how well this particular $\hat{f}_\tau(x)$ will perform on new data

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 - Chose a particular algorithm $\mathcal{A}: \tau \rightarrow \hat{f}_\tau$, for a particular problem – defined by the unknown population distribution $P(x, y)$
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$$\text{Err}_\tau = \mathbb{E}_{x,y} \left[L\left(y, \hat{f}_\tau(x)\right) \right]$$

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- Want to know, how well this algorithm performs on this problem
- **Expected prediction error:**

$$\text{Err} = \mathbb{E}_{x,y,\tau} \left[L\left(y, \hat{f}_\tau(x)\right) \right] = \mathbb{E}_\tau [\text{Err}_\tau]$$

Splitting to train and test



What kind of error do we estimate here?

Splitting to train and test



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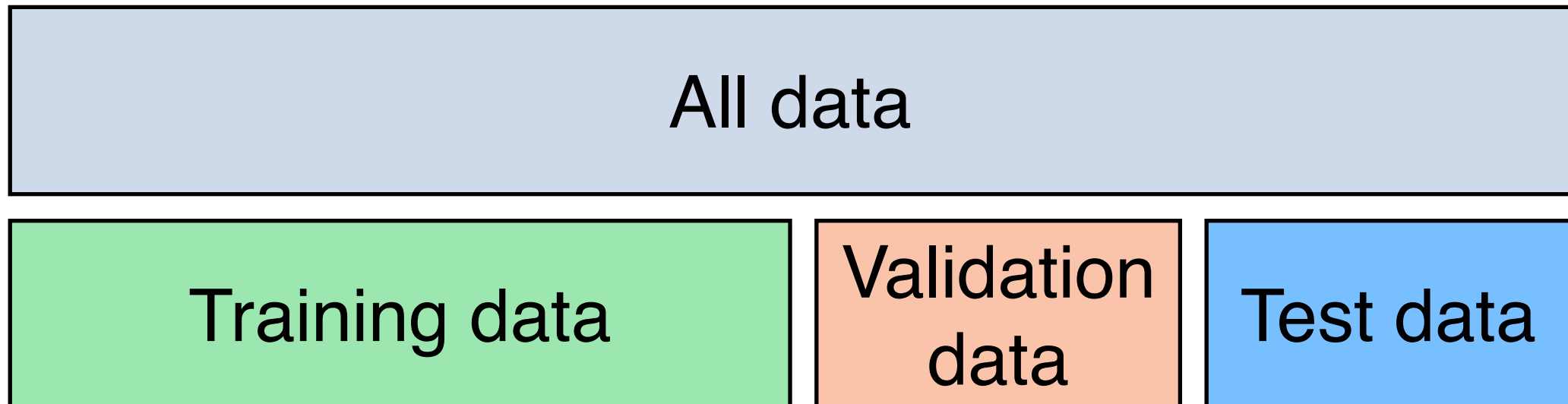
How to estimate its variance?

Splitting to train, validation and test

- ▶ When we do model selection, we use the left-out data to estimate the prediction error and minimize it (e.g., wrt the hyperparameters)
- ▶ May 'overfit to test', so the resulting minimized error is not a good estimate of the prediction error

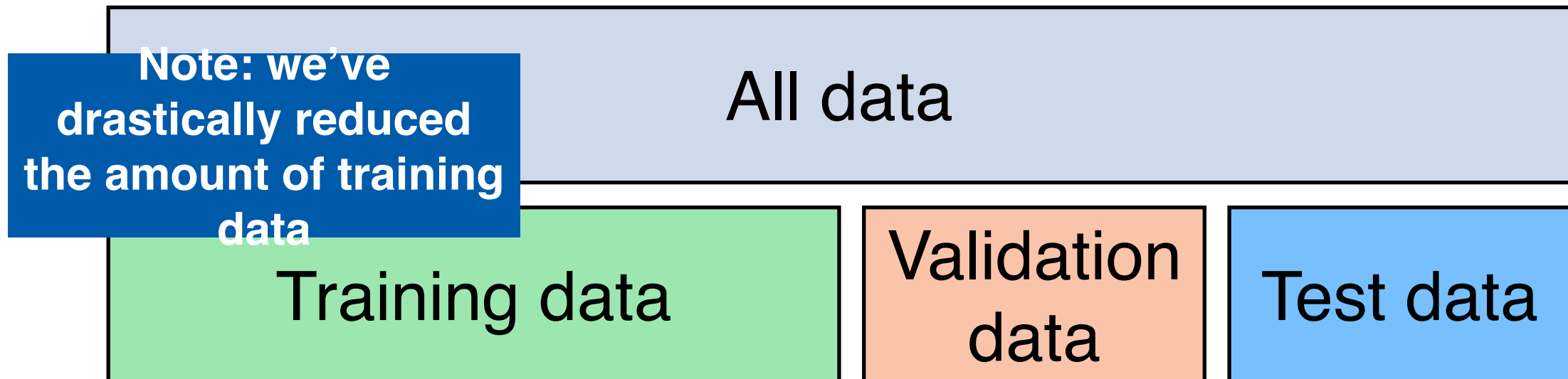
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Cross-validation



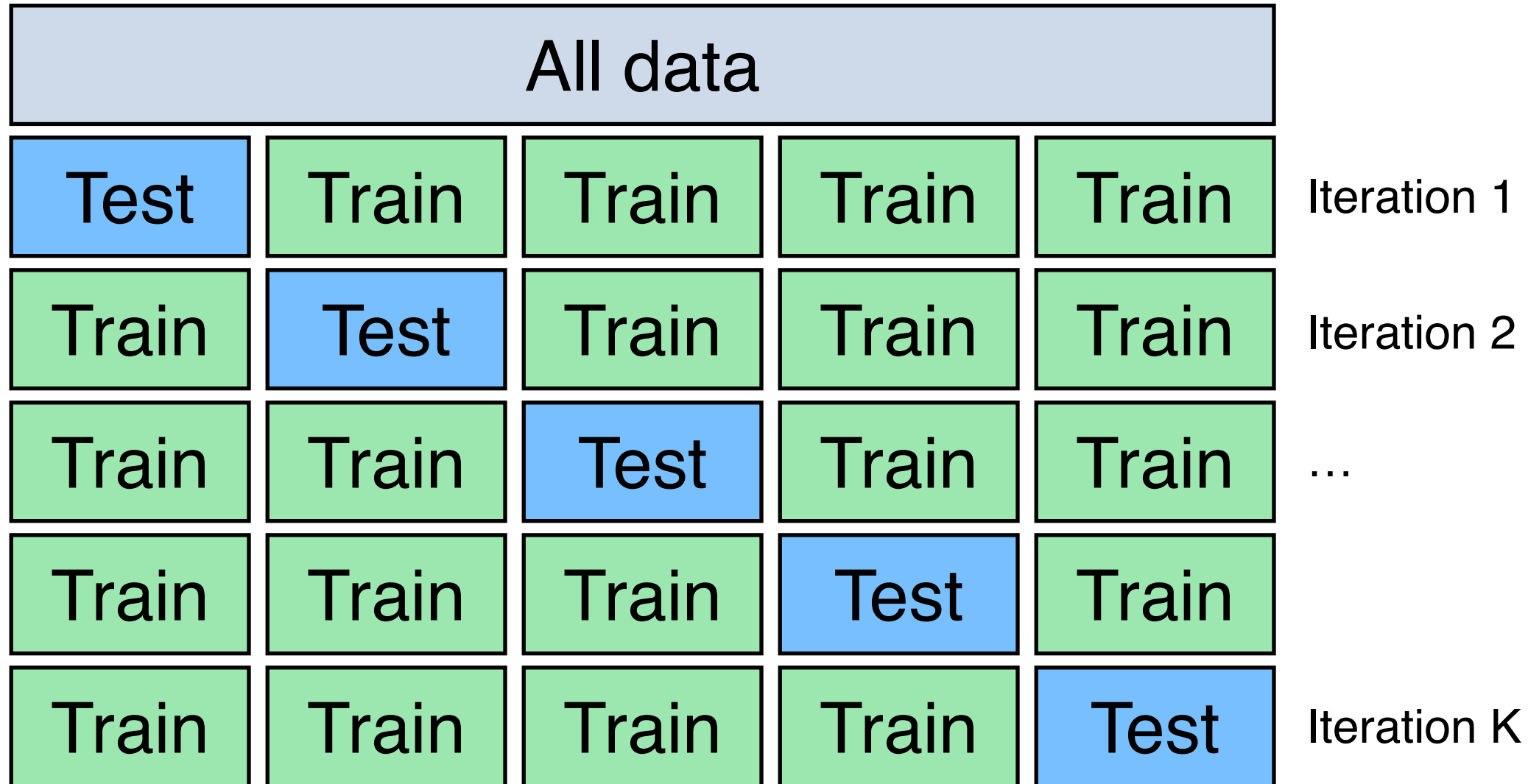
How to estimate the expected prediction error?

$$\text{Err} = \mathbb{E}_{x,y,\tau} \left[L\left(y, \hat{f}_{\tau}(x)\right) \right] = \mathbb{E}_{\tau} [\text{Err}_{\tau}]$$

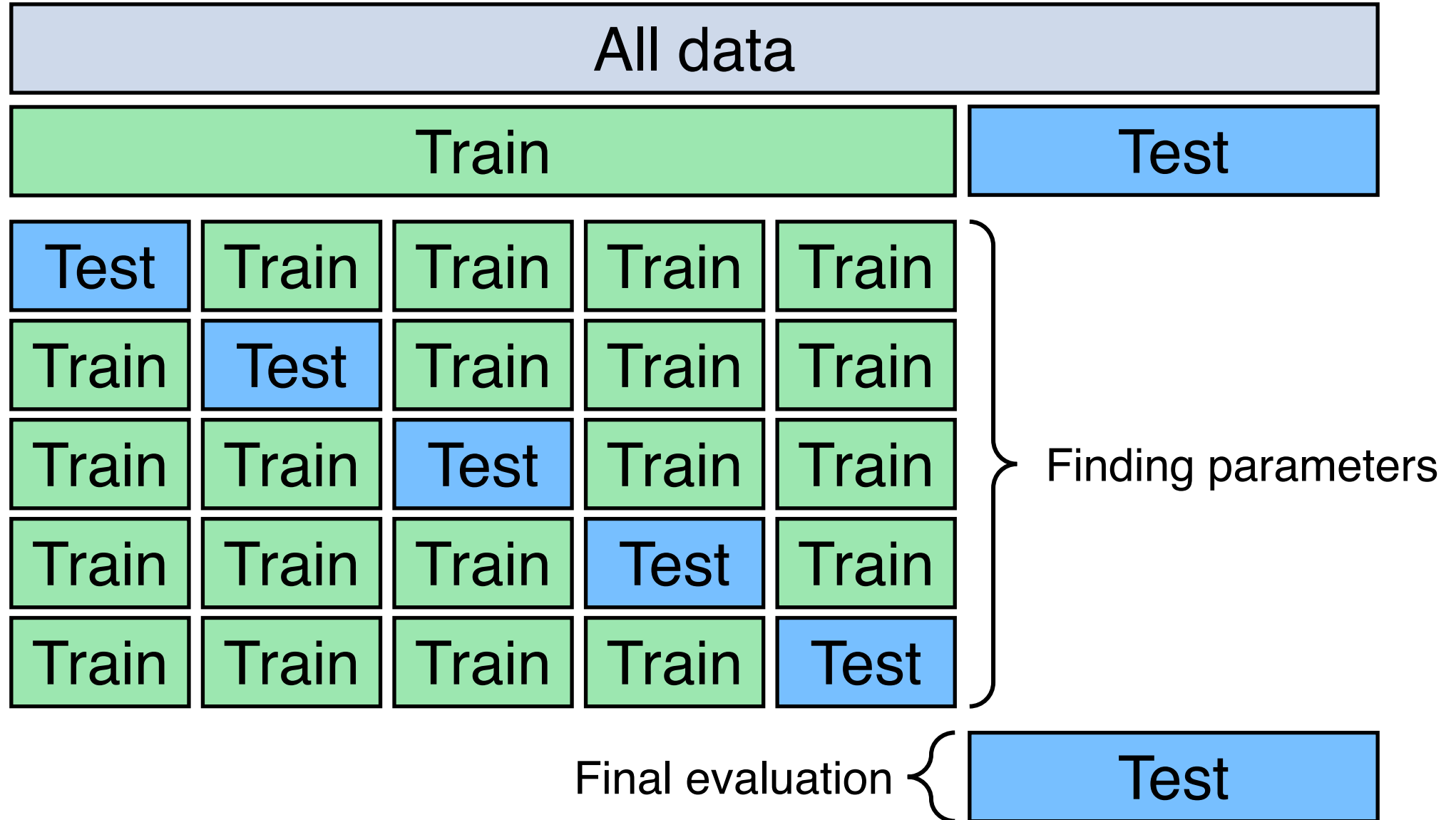
We can't just sample new training sets!
(unless there's **really** a lot of data available to us)

Note: Err_{τ} is by itself an estimate of Err ,
but since it's just a single observation we
know nothing about its variance

K-fold cross-validation



Hyperparameter tuning



K-fold cross-validation

- ▶ Note: K-fold CV estimate of the expected prediction error is unbiased
- ▶ Though the variance estimate is biased!

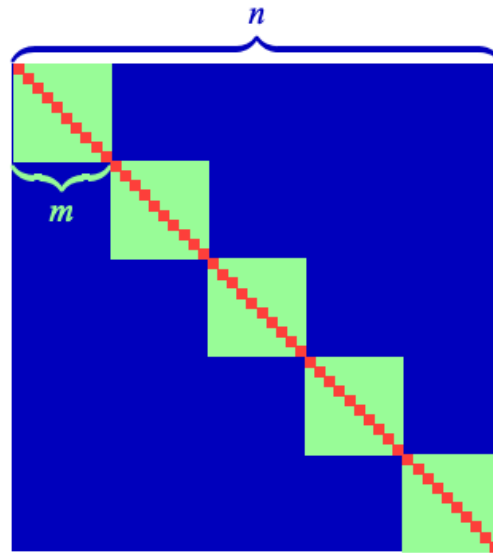


Figure 2: Structure of the covariance matrix.

- ▶ For more details see: <https://www.jmlr.org/papers/v5/grandvalet04a.html>

Thank you!



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