Locking Mechanisms

1. TEST and SET

Test-and-set is a type of locking mechanism that uses a single atomic operation to test the value of a lock variable and set it to a new value. The lock variable can have only two possible values, either locked or unlocked. This mechanism ensures that only one process or thread can acquire the lock at a time, preventing race conditions and other synchronization issues.

Implementation

Code

```
import threading
tas lock = threading.Lock()
locked = False
counter = 0
def critical section():
    global counter
    # Simulate some work
    for i in range(5):
        counter += 1
def tas_acquire(thread_id):
    global locked
    while True:
        with tas_lock:
            if not locked:
                locked = True
                print(f"Thread {thread id} acquired the lock")
                return
            else:
                print(f"Thread {thread_id} is waiting for the lock")
def tas release(thread id):
    global locked
    with tas_lock:
        locked = False
```

```
print(f"Thread {thread id} released the lock")
def worker(thread id):
   tas_acquire(thread_id)
    print(f"Thread {thread_id} entered the critical section")
    critical_section()
    print(f"Thread {thread id} exited the critical section")
    tas release(thread id)
# Start multiple threads to execute the worker function
threads = []
for i in range(3):
   t = threading.Thread(target=worker, args=(i,))
    threads.append(t)
for t in threads:
   t.start()
for t in threads:
   t.join()
print("Counter value:", counter)
```

Output

```
Shafei@shafei:~/lockingMechnanisms$ python3 testAndSet.py

Thread 0 acquired the lock
Thread 0 entered the critical section
Thread 0 released the lock
Thread 1 acquired the lock
Thread 1 entered the critical section
Thread 1 exited the critical section
Thread 1 released the lock
Thread 2 exited the lock
Thread 2 acquired the lock
Thread 2 entered the critical section
Thread 2 released the lock
Thread 2 released the lock
Counter value: 15
```

2. WAIT and SIGNAL

WAIT and SIGNAL are two fundamental operations in process synchronization. The WAIT operation causes a process to block or wait until a certain condition is true. The SIGNAL operation is used to wake up a waiting process when the condition it is waiting for becomes true. This mechanism is often used in conjunction with a shared variable or semaphore to coordinate the activities of multiple processes or threads.

Implementation

Code

```
import threading
lock = threading.Lock()
condition = threading.Condition(lock)
def critical section():
    print(f"Entered critical section for thread {threading.get_ident()}")
    # do some critical work here
    print(f"Exiting critical section for thread {threading.get_ident()}")
def wait and signal(counter):
   with condition:
        condition.wait()
        critical_section()
        counter += 1
        print(f"Thread {threading.get ident()} finished. Counter: {counter}")
        condition.notify()
# create three counters
counters = [0, 0, 0]
# create three threads
threads = []
for i in range(3):
    t = threading.Thread(target=wait and signal, args=(counters[i],))
   threads.append(t)
# start all threads
for t in threads:
   t.start()
# signal all threads to wake up
with condition:
    condition.notify_all()
```

Output

```
shafei@shafei:~/lockingMechnanisms$ python3 waitAndSignal.py

Entered critical section for thread 139980092253760
Exiting critical section for thread 139980092253760
Thread 139980092253760 finished. Counter: 1
Entered critical section for thread 139980083861056
Exiting critical section for thread 139980083861056
Thread 139980083861056 finished. Counter: 1
Entered critical section for thread 139980075468352
Exiting critical section for thread 139980075468352
Thread 139980075468352 finished. Counter: 1
```

3. SEMAPHORES

A semaphore is a variable that is used to control access to a shared resource in a concurrent system. Semaphores can be used to enforce mutual exclusion, to control access to a shared resource, or to coordinate the activities of multiple processes or threads. Semaphores can be implemented using either binary or counting variables. A binary semaphore can only have two values, 0 and 1, while a counting semaphore can have a range of values.

Implementation

Code

```
import threading

def Semaphore(value=1):
    mutex = threading.Lock()
    sem = threading.Condition(mutex)
    count = value

def acquire():
    nonlocal count
    with sem:
    while count == 0:
        print(f"{threading.current_thread().name} is waiting for semaphore")
        sem.wait()
    count -= 1
        print(f"{threading.current_thread().name} acquired semaphore")
```

```
def release():
        nonlocal count
        with sem:
            count += 1
            print(f"{threading.current_thread().name} released semaphore")
            sem.notify()
   return acquire, release
# Example usage
acquire, release = Semaphore()
def worker():
   acquire()
   print(f"{threading.current_thread().name} in critical section")
   # Do some work
   release()
   print(f"{threading.current_thread().name} released critical section")
threads = []
for i in range(5):
   thread = threading.Thread(target=worker, name=f"Worker {i}")
   threads.append(thread)
   thread.start()
for thread in threads:
   thread.join()
```

Output

```
shafei@shafei:~/lockingMechnanisms$ python3 semaphore.py
Worker 0 acquired semaphore
Worker 0 in critical section
Worker 0 released semaphore
Worker 0 released critical section
Worker 1 acquired semaphore
Worker 1 in critical section
Worker 1 released semaphore
Worker 1 released critical section
Worker 2 acquired semaphore
Worker 2 in critical section
Worker 2 released semaphore
Worker 2 released critical section
Worker 3 acquired semaphore
Worker 3 in critical section
Worker 3 released semaphore
Worker 3 released critical section
Worker 4 acquired semaphore
Worker 4 in critical section
Worker 4 released semaphore
Worker 4 released critical section
```