**CSC3060 AIDA – Assignment 3**

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# Introduction

The purpose of this assignment is to use machine learning in order to build classifiers for image data, using data from the previous assignment as well as a large sample of unseen data. This report will detail the observations and accuracy of various predictor models such as logistic regression, k-nearest neighbour and decision trees using predetermined features from the data.

# Section 1

The primary focus of this section is to use logistic regression on the feature data from assignment 2 to build classifiers for living and non-living objects. From the results of the fitted models, we will be looking at the accuracy over the data to determine which individual or combined features might be useful in correctly classifying a given object.

## Section 1.1 – Logistic Regression using the Verticalness feature

Upon loading the feature data into the script, I discovered that for the purpose of this task, I needed to classify each of the observations as either “living” or “non-living”. So, I wrote a function that iterated through each observation, evaluating the value of the ‘label’ column. If the value of the label was one of the living things (banana, cherry, flower, pear) then the classification for that observation would be 1. Likewise, for those observations which had labels belonging to non-living things (envelope, golfclub, pencil, wineglass), the classification would be 0. These classifications were made under the assumption that living things were represented by a value of 1 and non-living things by a value of 0.

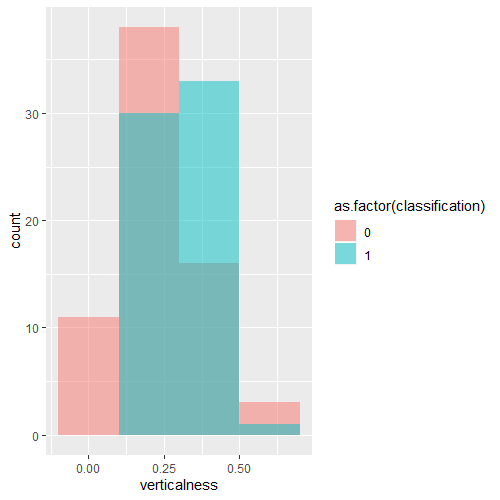
With all 160 observations classified as living or non-living, I was able to start building the model. I shuffled a sample of the original dataset and assigned the first 80% to the training dataset and the remaining 20% to the test dataset. The histogram for the ‘verticalness’ feature shows a significant overlap for both classifications between the values X and Y (roughly). From a simple assessment of these results one might already be able to suggest that the ‘verticalness’ feature is not a good predictor of whether a doodle belongs to either the living or non-living category.

Figure - A histogram of the verticalness feature, with non-living things coloured red and living things coloured blue

The results of the model show significant p values (p < 0.01) for both the Intercept and the verticalness coefficients.

A screen shot of a social media post

Description automatically generatedThe model was built with the training dataset and the results were close to what I had expected. The model can never truly classify an

Figure - The results table of the logistic regression

## Section 1.2 – Building a classifier using the model from 1.1

**TODO – Check which dataset to run over**

Finding a suitable cut-off value for p to provide the best accuracy for the model was difficult, since there was no clear distinction between living and non-living for a given verticalness value (except for the range 0.5 ~ 0.14, to which the model was still not certain of the classification). Rather than guess the best p-value, I decided to check all possible values of p from 0.01 to 0.99 (inclusive) in increments of 0.01. The table of results (see ‘1.2\_p\_accuracy.csv’ for full table) showed that a p value of 0.46 had the highest classification accuracy of 68.1% (3 s.f)

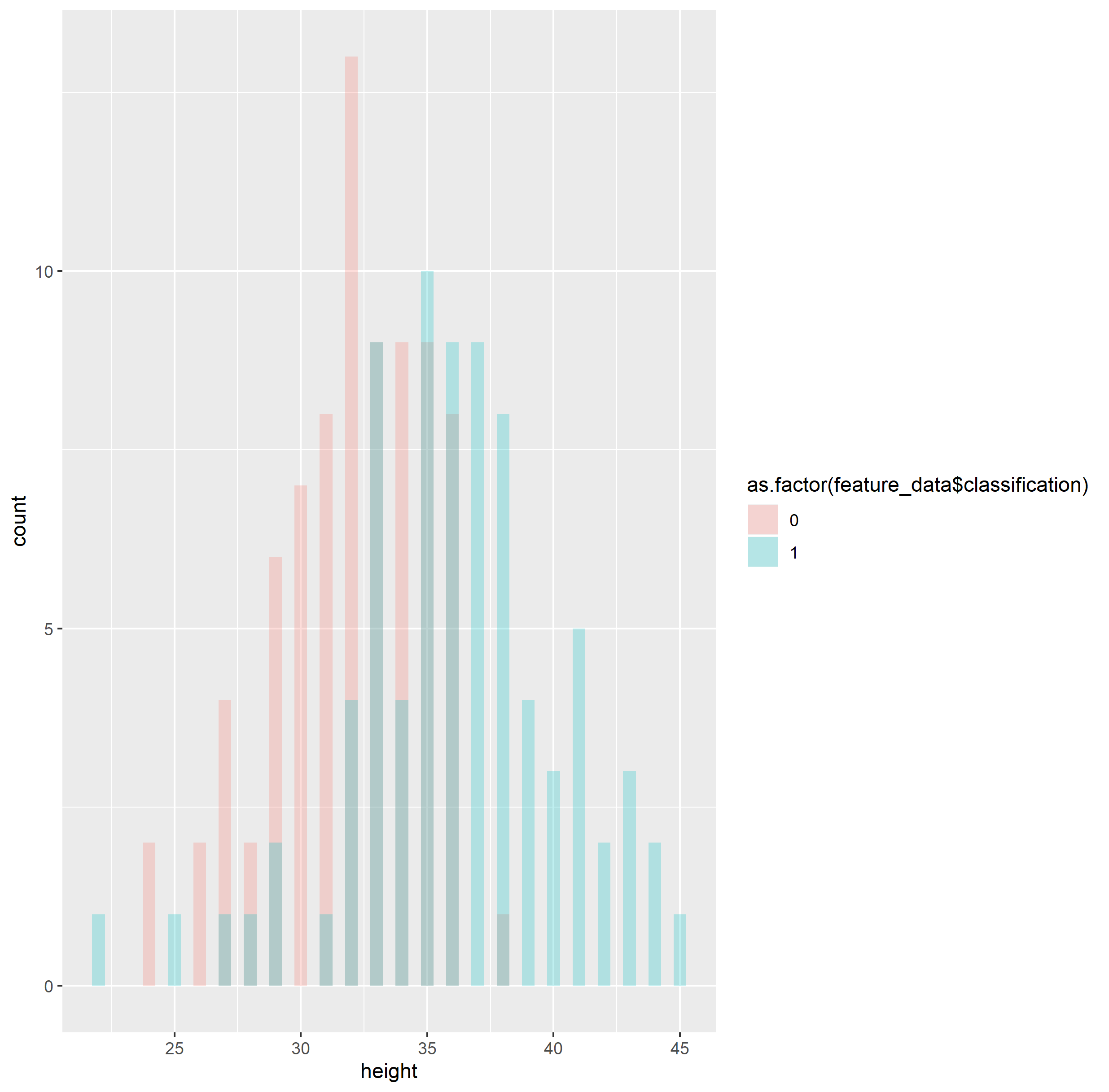
## Section 1.3

I felt that assessing the feature data from assignment 2 (sample statistics, histograms etc.) would be detrimental to finding the absolute best three features on which to build a classifier. Initial attempts at this task (choosing the values that I thought were best) showed somewhat decent classification accuracy. Initially I chose to use the three features which had the least skew in the data, but after seeing the results fall in the range 60% ~ 70%, I began to wonder how would find the features with the highest accuracy.

I discovered the combn() function could return all the unique subsets of a given vector, which in the case of the feature data, was 1140. From there it was a similar model building procedure as before, except I built models for all 1140 feature combinations using 5-fold cross-validation and testing every p value between 0.01 and 0.99 for accuracy. After some 20 – 30 minutes, the code finished running and I had a table of ~11400 entries (see ‘combotable.csv’ for full results). The initial results showed that the combination of span, cols\_with\_5 and neigh5 had the highest cross-validated classification accuracy for the data.

## Section 1.4

## Section 1.5

Determining which features might improve the accuracy of the model in 1.3 was interesting, as I initially believed that the accuracy of 96%, I observed in 1.3 was as high as it might go. However, I realised that the addition of a fourth feature to the model could yield an improvement, but as I experienced in 1.3, finding a good fourth feature on the basis of visual assessment was difficult, since I would need to find a feature which had distinct values for living and non-living objects. The height feature, for example, showed strong visual variation between the groups, as well as a near normal distribution, so I would have thought it to be the likely fourth candidate.

Although not explicitly required in the task, further model testing with a fourth feature from the remaining ones showed that height did in fact yield the highest improvement in accuracy (up to 98.75%).

# Section 2

## Section 2.1

## Section 2.2

## Section 2.3

# Section 3

## Section 3.1

## Section 3.2

## Section 3.3

## Section 3.4

# Conclusions