

図 “da_conv.slx”

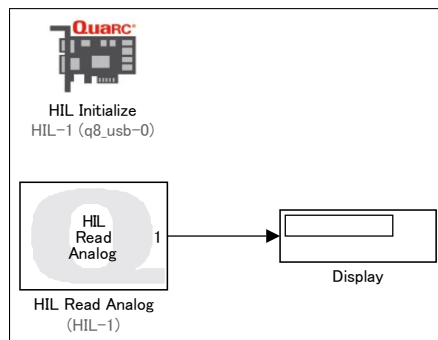


図 “ad_conv.slx”

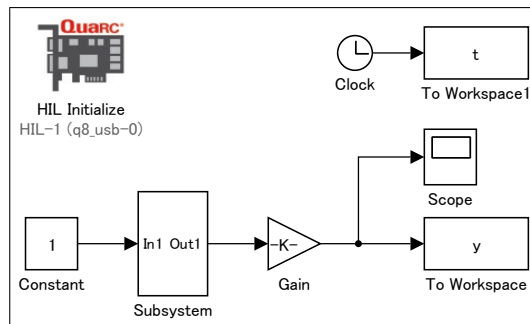


図 “ad_da_conv.slx”

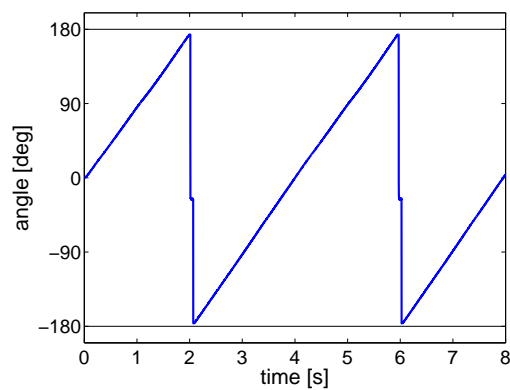
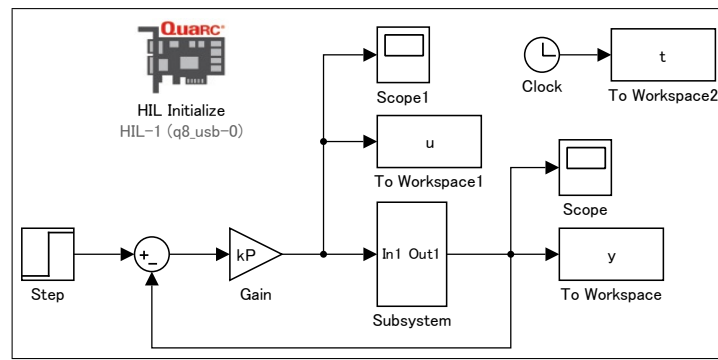
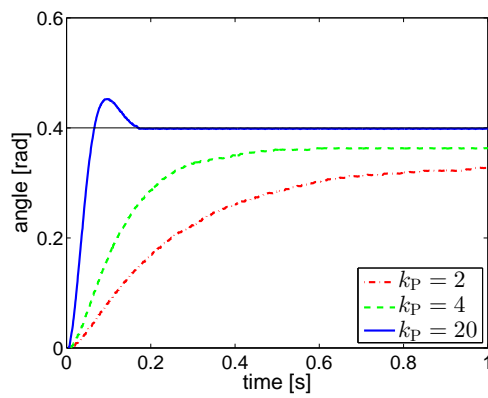


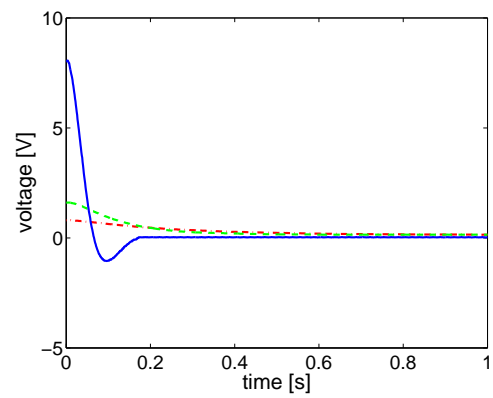
図 A/D, D/A 変換の動作確認



☒ “ex_pcont.slx”



(a) アーム角度 $\theta(t)$ [rad]



(b) 入力電圧 $v(t)$ [V]

☒ P 制御の実験結果

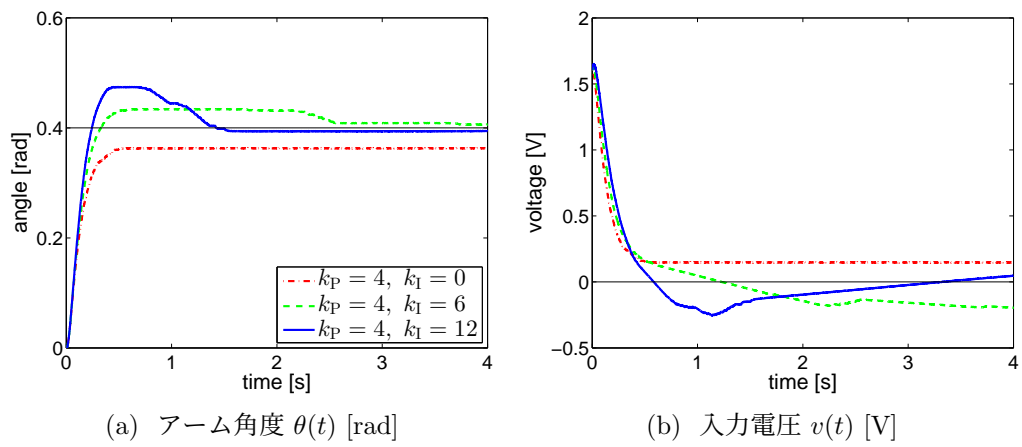
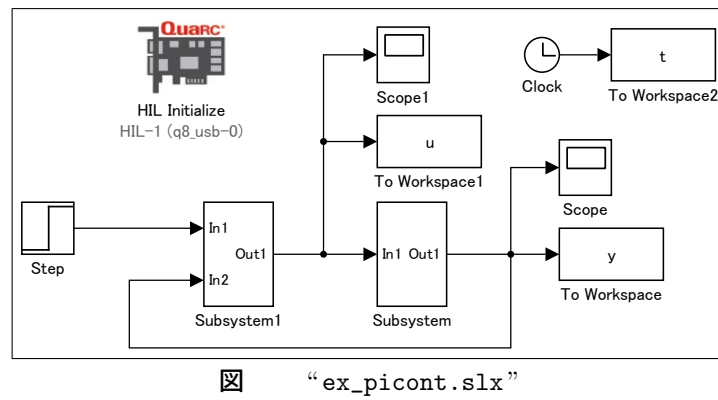


図 PI 制御の実験結果