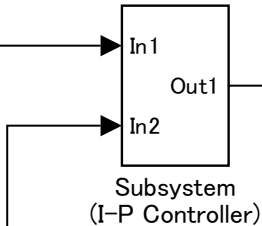




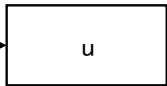
HIL Initialize
HIL-1 (q8_usb-0)



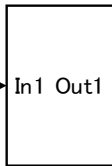
Step



Scope1



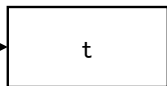
To Workspace1



Subsystem
(Robot)



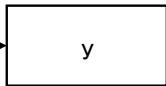
Clock



To Workspace2



Scope



To Workspace