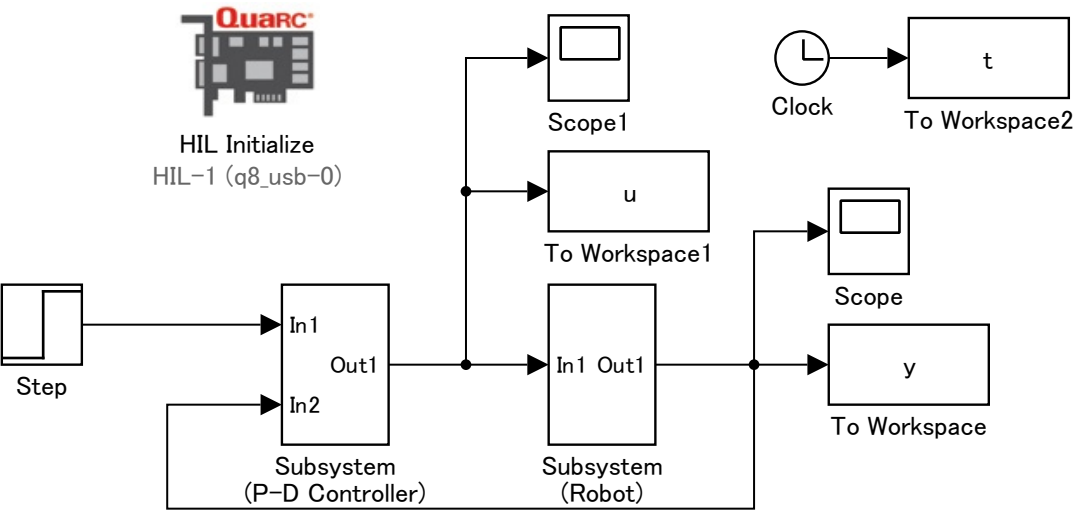
QuaRC
HIL Initialize
HIL-1 (q8_usb-0)
Scope1
Clock
t
To Workspace2
u
To Workspace1
Scope
Step
In1
Out1
In2
Subsystem
(P-D Controller)
In1 Out1
Subsystem
(Robot)
y
To Workspace